BRYSON FIBANDA OMULUBI SCT212-0075 12020 Lal 3 COMPUTER TECHNOLOGY 4-2

- (E) Identify hazard:
 - (a) LO RI, O(R2)

 DADD R3, R1, R2

 Data Hazard (RAW)

 DADD instruction dep

DADD instruction depends on the result of the LD instruction. The LD loads a value into RI, and the DADD uses that value

- (b) MULT RI, RZ, R3

 DADD RI, RZ, R3

 Data Hazard (WAM)

 Both MULT and DADD unite to R1. If the DADD completes before the MULT, the value unitles by MULT will be overwritten.
- (e) MULT RI, RZ, RZ

 MULT R4, R5, RE

 No Hazard

 The two MULT instructions operate on different registers and do not have any dependencies.
- (d) DADD PU, RZ, R3

 SD 2000 (RO), R1

 Data Hazard (RAW)

 The SD instruction depends on the result of the DADD instruction

 The DADD calculates a value and stores it in R1 which is used by SD.
- (e) DADD RI, RZ, R3.

 SD 2000 (Ri), R4

 No Hazard. The DADD and SD instructions operate on different registers and do not have any dependencies.

(a) Behaviour of a 2-bit saturating counter branch predictors.

It has 4 states: 00 (Strongly not taken), 01 (Weakly Not taken),

10 (Weakly taken) and 11 (Strongly taken).

00: Predict Not Taken, Transition to 01 on Taken.

01: Predict Not Taken, Transition to 10 on Taken, Transition to 00 on Not Taken

10: Predict Takes, Transition to 11 on Taken, Transition to 01 on Not Taken

11: Predict Taken, Transition to 10 on Not Taken.

(b) Branch Predictor:

Initial State = 00 (Strongly Not Taken)

Heration 1 (x [0] is not 0):

Branch Taken (since x [0] < 0 is take)

Predictor State: 01 (Transition from 00 on Taken)

Iteration 2 (x [1] is 0):

Branch Not Taken (since & [1] < 0 is true)

Predictor State: 00 (Transition from of an Not Taken)

Iteration 3 (x[2] is not o):

Branch Taken

Predictor State = 01 (Transition from 00 on Taken)

Iteration 4 (x[3] is 0):

Branch Not Taken

Predictor State: 00 (Transition from at an Not Taken)