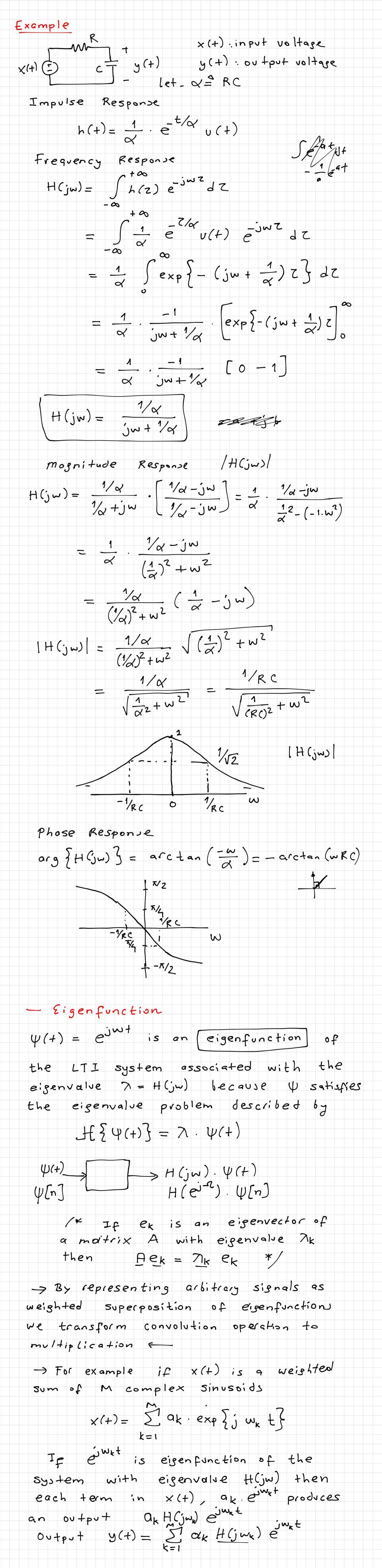
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Fourier Representation of Signals and
   LTI systems
             - Read Introduction
                    (a) p 195
                     white I j
             * Representing signals as weighted
              superposition of complex sinusids.
                 * Euler's Formula
                                 e^{j\theta} = \cos\theta + j\sin\theta
                * Polar Form Im
                                                                                                                                                                  bt 10)
      C = a + j b
        |c| = \sqrt{a^2 + b^2} \cdot mognitude
      ) arg\{c\} = \theta = arctan(\frac{b}{a}): Phase
    Polar form
         Complex Sinusoids and Frequency Response
          of LTI Systems.
                                  \times [n] \rightarrow H \rightarrow y[n] = J{\{x[n]\}}
                                  h[n] is the impulse response
h[n]=J{ { { { { { { { S [n] } { } } } } }
                     For a given input, x[n]
                              y[n] = H\{x[n]\} = x[n] * h[n] = h[n] * x[n]
                              y[n] = \sum_{k=-\infty}^{\infty} h[k] x[n-k]
* Let x[n] = e'-an _a: frequency.
       Then the output +\infty y[n] = H\{e^{j2n}\} = \sum_{k=-\infty}^{\infty} h[k] e^{jn}
                                           = e^{j-2n} + \infty
= e^{j-2k}
= e^{j-2k}
= e^{j-2k}
= e^{j-2k}
          Let's define H(e^{i-2}) = \sum_{k=-\infty}^{+\infty} h(k) \cdot e^{-i-2k}
                                                                                Frequency
Response
                                                                             - Not a function of time,
                                                                                   but FREQUENCY.
                         y[n] = H(ein). einn = H{ein}

\frac{\partial^2 u}{\partial x} = \frac{\partial^2 u}{\partial x} + \frac{\partial^2 u}{\partial 
                                                                                                             Frequency
                                                                                                                        Response
               Frequency Response: H(jw) = Sh(Z) = jwZ dZ
                                     y(+) = f\{e^{jwt}\} = e^{jwt} - H(jw)
                                 eint = H(jw)
                                                                                                                       \int \exp(\cdot) = e^{-\frac{1}{2}}
                   Polar form
                                  H(jw) = |H(jw)| \cdot exp[j.org \{H(jw)\}]
         H{ein+} = H(jw) ein+
                                                   = | H(jw) . exp[j(w++ arg {H(jw)}))
          [H(jw)]: Magnitude Response]
arg {H(jw)}: Phose Response]
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Jethe input to this system is $x(t) = e^{j2t}$ then the output $y(t) = e^{j2(t-3)} = e^{j2t} \cdot e^{j6}$ $e^{j2t} \text{ is the eigenfunction associated with}$ the eigenvalue $H(j6) = e^{-j6}$ - we can show this by $Impulse \text{ Response } h(t) = \delta(t-3)$ $H(jw) = \int_{-\infty}^{\infty} h(z) \cdot e^{-jwz} dz$ $= \int_{-\infty}^{\infty} \delta(t-3) e^{-jwz} dz$ $= e^{-3jw}$ $H(j2) = e^{-3j2} = e^{-6j}$