# GY-NEO6MV2 / 180943

First connect 5V power to the module so that the internal battery can start charging for at least 1 hour best for 2 hours before continuing with this tutorial.

### **Hardware Overview:**

Receiver Type: 50 channels, GPS L1(1575.42Mhz)

Horizontal Position Accuracy: 2.5m

Navigation Update Rate: 1HZ (5Hz maximum)

Capture Time: Cool start: 27sHot start: 1s

Navigation Sensitivity: -161dBm

Communication Protocol: NMEA, UBX Binary, RTCM

Serial Baud Rate: 4800-230400 (default 9600)

Operating Temperature:  $-40^{\circ}\text{C} \sim 85^{\circ}\text{C}$ Operating Voltage:  $2.7\text{V} \sim 3.6\text{V}$ Operating Current: 45mATXD/RXD Impedance:  $510\Omega$ 

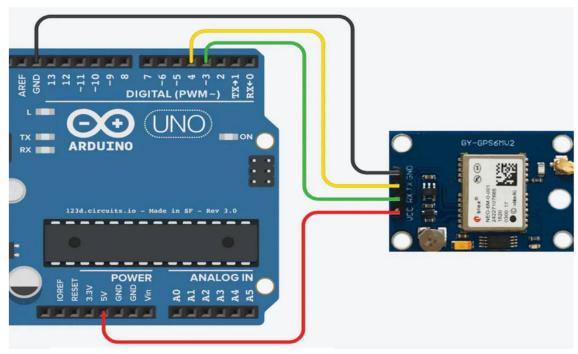
There is an LED on the NEO-6M GPS Module which indicates the status of Position Fix. It'll blink at various states depending on what state it's in:

**No Blinking** – It's searching for satellites.

**Blink every 1s** – Position Fix is found(The module can see enough satellites).

Must be used outside not indoors

Wiring NEO-6M GPS module with Arduino UNO



## **Libaries required:**

<TinyGPS.h> <a href="https://www.arduinolibraries.info/libraries/tiny-qps">https://www.arduinolibraries.info/libraries/tiny-qps</a>

<RTClib.h> download RTClib-2.0.1.zip <a href="https://www.arduinolibraries.info/libraries/rt-clib">https://www.arduinolibraries.info/libraries/rt-clib</a>

Hardware Used:

A shield with RTC and SC Card: ST1046 / XD-204 / 170098

nttps://mantecn.co.za/stock.aspx/Query=511046ana

SD card: https://mantech.co.za/ProductInfo.aspx?Item=340M5017-D

Datasheet for the NEO-6M https://mantech.co.za/Datasheets/Products/GY-NEO6MV2^1.pdf

#### The sketch

```
GPS_logger by LogMaker360
code belongs to this video: https://www.youtube.com/watch?v=dy2iygCZTIM
write by Moz for Youtube changel LogMaker360 26-10-2016
 // I have a Data Logger Module Shield V1.0 for Arduino UNO SD Card
 // and a GY-NEO6MV2 new NEO-6M GPS Module NEO6MV2 gps
 //real time clock is included on the Data logger shield.
 #include <SoftwareSerial.h>
 #include <TinyGPS.h>
                            // https://www.arduinolibraries.info/libraries/tiny-gps
 #include <Wire.h>
 #include <SPI.h>
 #include <SD.h>
 #include "RTClib.h"
                           // download RTClib-2.0.1.zip https://www.arduinolibraries.info/libraries/rt-clib
 #include <OneWire.h>
File dataFile:
DateTime now:
RTC_DS1307 RTC;
const int chipSelect = 10; // 10 pin for the SD card logger shield.
  long lat, lon; // create variable for latitude and longitude object
  SoftwareSerial gpsSerial(3, 4); // create gps sensor connection, UNO D3 to Mod RX, UNO D4 to Mod TX
  TinyGPS gps; // create gps object
  void setup(){
   Serial.begin(9600); // connect serial some olther qps sensor try Serial.begin(9600); and qpsSerial.begin(4800);
   gpsSerial.begin(9600); // connect gps sensor
    Wire.begin(); // real time clock
 RTC.begin(); // also for the real time clock
//check or the Real Time Clock is on
 if (! RTC.isrunning()) {
  Serial.println("RTC is NOT running!");
  // following line sets the RTC to the date & time this sketch was compiled
  // uncomment it & upload to set the time, date and start run the RTC!
  RTC.adjust(DateTime(__DATE__, __TIME__));
 }
//setup SD card
 Serial.print("Initializing SD card...");
 // see if the SD card is present and can be initialized:
 if (!SD.begin(chipSelect)) {
  Serial.println("Card failed, or not present");
  // don't do anything more:
  return:
 }
 Serial.println("card initialized.");
 //Indexing: date (year / month / day)
                                           prints only at the first line.
  now = RTC.now();
  dataFile = SD.open("qpsLOG.txt", FILE_WRITE);
  dataFile.print("Start logging on: ");
  dataFile.print(now.year(),DEC);
  dataFile.print('/');
  dataFile.print(now.month(),DEC);
  dataFile.print('/');
```

```
dataFile.print(now.day(),DEC);
  dataFile.println(" ");
  dataFile.println("Latitude
                                    Longitude
                                                       Time");
  dataFile.close();
  }
  void loop(){
   now = RTC.now();
//log the time and gps coordinaten every 10 seconds
   while(gpsSerial.available()){ // check for gps data
    if(qps.encode(qpsSerial.read())){ // encode qps data
    gps.get_position(&lat,&lon); // get latitude and longitude
    // display position
    Serial.print("Position: ");
    Serial.print("coordinaat");Serial.print(lat/1000000); Serial.print(".");Serial.print(lat%1000000);Serial.print("");// print
latitude to serialmonitor
    Serial.print(", "); Serial.print(lon/1000000); Serial.print("."); Serial.println(lon%1000000); // print longitude to serialmonitor
     dataFile = SD.open("gpsLOG.txt", FILE_WRITE);
     if (dataFile) {
  dataFile.print(lat/1000000); dataFile.print("."); dataFile.print(lat%1000000); dataFile.print(" ");// print latitude to the SD
  dataFile.print("
                         ");
  dataFile.print(lon/1000000); dataFile.print("."); dataFile.print(lon%1000000);// print longitude to SD Card
  dataFile.print("
                          ");
  dataFile.print(now.hour(),DEC);
  dataFile.print(":");
  dataFile.print(now.minute(),DEC);
  dataFile.print(":");
  dataFile.println(now.second(),DEC);
  dataFile.close();
  // print to the serial port too:
  Serial.println("data stored");
 ///Serial.println("minute past");
//}
 // if the file isn't open, pop up an error:
 else {
  Serial.println("error opening gpslog.txt");
 }//}
 delay(10000);
    }
   }
  } // END
```

#### Other Referances:

https://lastminuteengineers.com/neo6m-gps-arduino-tutorial/

check pins int RXPin = 3; //from NEO-6M pin RX

int TXPin = 4; //from NEO-6M pin TX

Burn sketch and go outside with laptop open Serial Monitor

Real Time Clock: RTC test and adjusting Date and time.

https://learn.adafruit.com/adafruit-data-logger-shield/using-the-real-time-clock

Using the SD Card:

https://learn.adafruit.com/adafruit-data-logger-shield/using-the-sd-card

Image of setup connected to a 6V battery as Stand Alone Trakker



wait +-40 - 120 second for blinking to start.

**GPSLOG.TXT files** 

