Contents

1 Some useful things

```java
import java.util.*;
import java.io.*;

public class Template {
| FastScanner in;
| PrintWriter out;

| public void solve() throws IOException {
| | int n = in.nextInt();
| | out.println(n);
| }

| public void run() {
| | try {
| | | in = new FastScanner();
| | | out = new PrintWriter(System.out);

| | | solve();

| | | out.close();
| | } catch (IOException e) {
| | | e.printStackTrace();
| | }
| }

| class FastScanner {
| | BufferedReader br;
| | StringTokenizer st;

| | FastScanner() {
| | | br = new BufferedReader(new
    ↪ InputStreamReader(System.in));
| | }

| | String next() {
| | | while (st == null || !st.hasMoreTokens()) {
| | | | try {
| | | | | st = new
          ↪ StringTokenizer(br.readLine());
| | | | } catch (IOException e) {
| | | | | e.printStackTrace();
| | | | }
| | | }
| | | return st.nextToken();
| | }

| | int nextInt() {
| | | return Integer.parseInt(next());
| | }
| }

| public static void main(String[] arg) {
| | new Template().run();
| }
}
```

```cpp
#include <algorithm>
#include <cstdio>

/** Interface */

inline int readInt();
inline int readUInt();
inline bool isEof();

/** Read */

static const int buf_size = 100000;
static char buf[buf_size];
static int buf_len = 0, pos = 0;

inline bool isEof() {
  if (pos == buf_len) {
    pos = 0, buf_len = fread(buf, 1, buf_size,
    ↪ stdin);
    if (pos == buf_len)
      return 1;
  }
  return 0;
}

inline int getChar() { return isEof() ? -1 :
↪ buf[pos++]; }

inline int readChar() {
  int c = getChar();
  while (c != -1 && c <= 32)
    c = getChar();
  return c;
}

inline int readUInt() {
  int c = readChar(), x = 0;
  while ('0' <= c && c <= '9')
    x = x * 10 + c - '0', c = getChar();
  return x;
}

inline int readInt() {
  int s = 1, c = readChar();
  int x = 0;
  if (c == '-')
    s = -1, c = getChar();
  while ('0' <= c && c <= '9')
    x = x * 10 + c - '0', c = getChar();
  return s == 1 ? x : -x;
}

// 10M int [0..1e9)
// cin 3.02
// scanf 1.2
// cin sync_with_stdio(false) 0.71
// fastRead getchar 0.53
// fastRead fread 0.15
```

```cpp
inline void fasterLLDivMod(ull x, uint y, uint
↪ &out_d, uint &out_m) {
| uint xh = (uint)(x >> 32), xl = (uint)x, d, m;
#ifdef __GNUC__
| asm(
| | "divl %4; \n\t"
```

```
    : "=a" (d), "=d" (m)
    : "d" (xh), "a" (xl), "r" (y)
  );
#else
  __asm {
    mov edx, dword ptr[xh];
    mov eax, dword ptr[xl];
    div dword ptr[y];
    mov dword ptr[d], eax;
    mov dword ptr[m], edx;
  };
#endif
  out_d = d; out_m = m;
}

// have no idea what sse flags are really cool; list of some of them
// -- very good with bitsets
#pragma GCC optimize("O3")
#pragma GCC target("sse,sse2,sse3,ssse3,sse4,popcnt,abm,mmx")
```

```
#include "ext/pb_ds/assoc_container.hpp"
using namespace __gnu_pbds;

template <typename T> using ordered_set = tree<T, null_type, less<T>, rb_tree_tag, tree_order_statistics_node_update>;
template <typename K, typename V> using ordered_map = tree<K, V, less<K>, rb_tree_tag, tree_order_statistics_node_update>;

// HOW TO USE ::
// -- order_of_key(10) returns the number of elements in set/map strictly less than 10
// -- *find_by_order(10) returns 10-th smallest element in set/map (0-based)

bitset<N> a;
for (int i = a._Find_first(); i != a.size(); i = a._Find_next(i)) {
  cout << i << endl;
}
```

2 Data structures

2.1 Hash table

```
template <const int max_size, class HashType, class Data,
          const Data default_value>
struct hashTable {
  HashType hash[max_size];
  Data f[max_size];
  int size;

  int position(HashType H) const {
    int i = H % max_size;
    while (hash[i] && hash[i] != H)
      if (++i == max_size)
        i = 0;
    return i;
  }

  Data &operator[](HashType H) {
    assert(H != 0);
    int i = position(H);
    if (!hash[i]) {
      hash[i] = H;
      f[i] = default_value;
      size++;
    }
    return f[i];
  }
};

hashTable<13, int, int, 0> h;
```

3 Geometry

3.1 Common tangents of two circles

```
vector<Line> commonTangents(pt A, dbl rA, pt B, dbl rB) {
  vector<Line> res;
  pt C = B - A;
  dbl z = C.len2();
  for (int i = -1; i <= 1; i += 2) {
    for (int j = -1; j <= 1; j += 2) {
      dbl r = rB * j - rA * i;
      dbl d = z - r * r;
      if (ls(d, 0))
        continue;
      d = sqrt(max(0.01, d));
      pt magic = pt(r, d) / z;
      pt v(magic % C, magic * C);
      dbl CC = (rA * i - v % A) / v.len2();
      pt O = v * -CC;
      res.pb(Line(O, O + v.rotate()));
    }
  }
  return res;
}

// HOW TO USE ::
// --      *D*----------------*F*
// --     *...*-             -*...*
// --    *.....* -         - *.....*
// --   *.......*  -     -  *.......*
// --   *...A...*   --     *...B...*
// --   *.......*  -     -  *.......*
// --    *.....* -         - *.....*
// --     *...*-             -*...*
// --      *C*----------------*E*
// --   res = {CE, CF, DE, DF}
```

3.2 Convex hull 3D in $O(n^2)$

```
struct Plane {
    pt O, v;
    vector<int> id;
};

vector<Plane> convexHull3(vector<pt> p) {
    vector<Plane> res;
    int n = p.size();
    for (int i = 0; i < n; i++)
        p[i].id = i;
    for (int i = 0; i < 4; i++) {
        vector<pt> tmp;
        for (int j = 0; j < 4; j++)
            if (i != j)
                tmp.pb(p[j]);
        res.pb({tmp[0],
                        (tmp[1] - tmp[0]) * (tmp[2] - tmp[0]),
                        {tmp[0].id, tmp[1].id, tmp[2].id}});
        if ((p[i] - res.back().O) % res.back().v > 0) {
            res.back().v = res.back().v * -1;
            swap(res.back().id[0], res.back().id[1]);
        }
    }
    vector<vector<int>> use(n, vector<int>(n, 0));
    int tmr = 0;
    for (int i = 4; i < n; i++) {
        int cur = 0;
        tmr++;
        vector<pair<int, int>> curEdge;
        for (int j = 0; j < sz(res); j++) {
            if ((p[i] - res[j].O) % res[j].v > 0) {
                for (int t = 0; t < 3; t++) {
                    int v = res[j].id[t];
                    int u = res[j].id[(t + 1) % 3];
                    use[v][u] = tmr;
                    curEdge.pb({v, u});
                }
            } else {
                res[cur++] = res[j];
            }
        }
        res.resize(cur);
        for (auto x : curEdge) {
            if (use[x.S][x.F] == tmr)
                continue;
            res.pb({p[i], (p[x.F] - p[i]) * (p[x.S] - p[i]), {x.F, x.S, i}});
        }
    }
    return res;
}

// plane in 3d
// (A, v) * (B, u) -> (O, n)

pt n = v * u;
pt m = v * n;
double t = (B - A) % u / (u % m);
pt O = A - m * t;
```

3.3 Dynamic convex hull trick

```
const ll is_query = -(1LL << 62);

struct Line {
    ll m, b;
    mutable function<const Line *()> succ;

    bool operator<(const Line &rhs) const {
        if (rhs.b != is_query)
            return m < rhs.m;
        const Line *s = succ();
        if (!s)
            return 0;
        ll x = rhs.m;
        return b - s->b < (s->m - m) * x;
    }
};

struct HullDynamic : public multiset<Line> {
    bool bad(iterator y) {
        auto z = next(y);
        if (y == begin()) {
            if (z == end())
                return 0;
            return y->m == z->m && y->b <= z->b;
        }
        auto x = prev(y);
        if (z == end())
            return y->m == x->m && y->b <= x->b;
        return (x->b - y->b) * (z->m - y->m) >= (y->b - z->b) * (y->m - x->m);
    }

    void insert_line(ll m, ll b) {
        auto y = insert({m, b});
        y->succ = [=] { return next(y) == end() ? 0 : &*next(y); };
        if (bad(y)) {
            erase(y);
            return;
        }
        while (next(y) != end() && bad(next(y)))
            erase(next(y));
        while (y != begin() && bad(prev(y)))
            erase(prev(y));
    }

    ll eval(ll x) {
        auto l = *lower_bound((Line){x, is_query});
        return l.m * x + l.b;
    }
};
```

3.4 Minimal covering disk

```
pair<pt, dbl> minDisc(vector<pt> p) {
    int n = p.size();
```

```
  pt O = pt(0, 0);
  dbl R = 0;
  random_shuffle(all(p));
  for (int i = 0; i < n; i++) {
    if (ls(R, (O - p[i]).len())) {
      O = p[i];
      R = 0;
      for (int j = 0; j < i; j++) {
        if (ls(R, (O - p[j]).len())) {
          O = (p[i] + p[j]) / 2;
          R = (p[i] - p[j]).len() / 2;
          for (int k = 0; k < j; k++) {
            if (ls(R, (O - p[k]).len())) {
              Line l1((p[i] + p[j]) / 2,
                          (p[i] + p[j]) / 2 + (p[i] - p[j]).rotate());
              Line l2((p[k] + p[j]) / 2,
                          (p[k] + p[j]) / 2 + (p[k] - p[j]).rotate());
              O = l1 * l2;
              R = (p[i] - O).len();
            }
          }
        }
      }
    }
  }
  return {O, R};
}
```

3.5 Draw svg pictures

```
struct SVG {
  FILE *out;
  ld sc = 50;
  void open() {
    out = fopen("image.svg", "w");
    fprintf(out, "<svg xmlns='http://www.w3.org/2000/svg' viewBox='-1000 -1000 2000 2000'>\n");
  }
  void line(point a, point b) {
    a = a * sc, b = b * sc;
    fprintf(out, "<line x1='%f' y1='%f' x2='%f' y2='%f' stroke='black'/>\n", a.x, -a.y, b.x, -b.y);
  }
  void circle(point a, ld r = -1, string col = "red") {
    r = sc * (r == -1 ? 0.3 : r);
    a = a * sc;
    fprintf(out, "<circle cx='%f' cy='%f' r='%f' fill='%s'/>\n", a.x, -a.y, r, col.c_str());
  }
  void text(point a, string s) {
    a = a * sc;
    fprintf(out, "<text x='%f' y='%f' font-size='100px'>%s</text>\n", a.x, -a.y, s.c_str());
  }
  void close() {
    fprintf(out, "</svg>\n");
    fclose(out);
    out = 0;
  }
  ~SVG() {
    if (out) {
      close();
    }
  }
} svg;
```

4 Graphs

4.1 2-Chinese algorithm

```
namespace twoc {
struct Heap {
  static Heap *null;
  ll x, xadd;
  int ver, h;
#ifdef ANS
  int ei;
#endif
  Heap *l, *r;
  Heap(ll xx, int vv) : x(xx), xadd(0), ver(vv), h(1), l(null), r(null) {}
  Heap(const char *) : x(0), xadd(0), ver(0), h(0), l(this), r(this) {}
  void add(ll a) {
    x += a;
    xadd += a;
  }
  void push() {
    if (l != null)
      l->add(xadd);
    if (r != null)
      r->add(xadd);
    xadd = 0;
  }
};
Heap *Heap::null = new Heap("wqeqw");
Heap *merge(Heap *l, Heap *r) {
  if (l == Heap::null)
    return r;
  if (r == Heap::null)
    return l;
  l->push();
  r->push();
  if (l->x > r->x)
    swap(l, r);
  l->r = merge(l->r, r);
  if (l->l->h < l->r->h)
    swap(l->l, l->r);
  l->h = l->r->h + 1;
  return l;
}
Heap *pop(Heap *h) {
  h->push();
  return merge(h->l, h->r);
}
```

```
const int N = 666666;
struct DSU {
  int p[N];
  void init(int nn) { iota(p, p + nn, 0); }
  int get(int x) { return p[x] == x ? x : p[x] =
   ↪  get(p[x]); }
  void merge(int x, int y) { p[get(y)] = get(x);
   ↪  }
} dsu;
Heap *eb[N];
int n;
#ifdef ANS
struct Edge {
  int x, y;
  ll c;
};
vector<Edge> edges;
int answer[N];
#endif
void init(int nn) {
  n = nn;
  dsu.init(n);
  fill(eb, eb + n, Heap::null);
  edges.clear();
}
void addEdge(int x, int y, ll c) {
  Heap *h = new Heap(c, x);
#ifdef ANS
  h->ei = sz(edges);
  edges.push_back({x, y, c});
#endif
  eb[y] = merge(eb[y], h);
}
ll solve(int root = 0) {
  ll ans = 0;
  static int done[N], pv[N];
  memset(done, 0, sizeof(int) * n);
  done[root] = 1;
  int tt = 1;
#ifdef ANS
  int cnum = 0;
  static vector<ipair> eout[N];
  for (int i = 0; i < n; ++i)
    eout[i].clear();
#endif
  for (int i = 0; i < n; ++i) {
    int v = dsu.get(i);
    if (done[v])
      continue;
    ++tt;
    while (true) {
      done[v] = tt;
      int nv = -1;
      while (eb[v] != Heap::null) {
        nv = dsu.get(eb[v]->ver);
        if (nv == v) {
          eb[v] = pop(eb[v]);
          continue;
        }
        break;
      }
      if (nv == -1)
        return LINF;
      ans += eb[v]->x;
      eb[v]->add(-eb[v]->x);
#ifdef ANS
      int ei = eb[v]->ei;
      eout[edges[ei].x].push_back({++cnum, ei});
#endif
      if (!done[nv]) {
        pv[v] = nv;
        v = nv;
        continue;
      }
      if (done[nv] != tt)
        break;
      int v1 = nv;
      while (v1 != v) {
        eb[v] = merge(eb[v], eb[v1]);
        dsu.merge(v, v1);
        v1 = dsu.get(pv[v1]);
      }
    }
  }
#ifdef ANS
  memset(answer, -1, sizeof(int) * n);
  answer[root] = 0;
  set<ipair> es(all(eout[root]));
  while (!es.empty()) {
    auto it = es.begin();
    int ei = it->second;
    es.erase(it);
    int nv = edges[ei].y;
    if (answer[nv] != -1)
      continue;
    answer[nv] = ei;
    es.insert(all(eout[nv]));
  }
  answer[root] = -1;
#endif
  return ans;
}
/* Usage: twoc::init(vertex_count);
 *        twoc::addEdge(v1, v2, cost);
 *        twoc::solve(root); - returns cost or
↪  LINF
 * twoc::answer contains index of ingoing edge
↪  for each vertex
 */
} // namespace twoc
```

4.2 Dominator tree

```
namespace domtree {
const int K = 18;
const int N = 1 << K;

int n, root;
vector<int> e[N], g[N];
int sdom[N], dom[N];
int p[N][K], h[N], pr[N];
int in[N], out[N], tmr, rev[N];
```

```
void init(int _n, int _root) {
    n = _n;
    root = _root;
    tmr = 0;
    for (int i = 0; i < n; i++) {
        e[i].clear();
        g[i].clear();
        in[i] = -1;
    }
}

void addEdge(int u, int v) {
    e[u].push_back(v);
    g[v].push_back(u);
}

void dfs(int v) {
    in[v] = tmr++;
    for (int to : e[v]) {
        if (in[to] != -1)
            continue;
        pr[to] = v;
        dfs(to);
    }
    out[v] = tmr - 1;
}

int lca(int u, int v) {
    if (h[u] < h[v])
        swap(u, v);
    for (int i = 0; i < K; i++)
        if ((h[u] - h[v]) & (1 << i))
            u = p[u][i];
    if (u == v)
        return u;
    for (int i = K - 1; i >= 0; i--) {
        if (p[u][i] != p[v][i]) {
            u = p[u][i];
            v = p[v][i];
        }
    }
    return p[u][0];
}

void solve(int _n, int _root, vector<pair<int,
↪ int>> _edges) {
    init(_n, _root);
    for (auto ed : _edges)
        addEdge(ed.first, ed.second);

    dfs(root);
    for (int i = 0; i < n; i++)
        if (in[i] != -1)
            rev[in[i]] = i;
    segtree tr(tmr); // a[i]:=min(a[i],x) and
    ↪ return a[i]
    for (int i = tmr - 1; i >= 0; i--) {
        int v = rev[i];
        int cur = i;
        for (int to : g[v]) {
            if (in[to] == -1)
                continue;
            if (in[to] < in[v])
                cur = min(cur, in[to]);
            else
                cur = min(cur, tr.get(in[to]));
        }
        sdom[v] = rev[cur];
        tr.upd(in[v], out[v], in[sdom[v]]);
    }
    for (int i = 0; i < tmr; i++) {
        int v = rev[i];
        if (i == 0) {
            dom[v] = v;
            h[v] = 0;
        } else {
            dom[v] = lca(sdom[v], pr[v]);
            h[v] = h[dom[v]] + 1;
        }
        p[v][0] = dom[v];
        for (int j = 1; j < K; j++)
            p[v][j] = p[p[v][j - 1]][j - 1];
    }
    for (int i = 0; i < n; i++)
        if (in[i] == -1)
            dom[i] = -1;
}
} // namespace domtree
```

4.3 General matching

```
// COPYPASTED FROM E-MAXX
namespace general_matching {
const int MAXN = 256;
int n;
vector<int> g[MAXN];
int match[MAXN], p[MAXN], base[MAXN], q[MAXN];
bool used[MAXN], blossom[MAXN];

int lca(int a, int b) {
    bool used[MAXN] = {0};
    for (;;) {
        a = base[a];
        used[a] = true;
        if (match[a] == -1)
            break;
        a = p[match[a]];
    }
    for (;;) {
        b = base[b];
        if (used[b])
            return b;
        b = p[match[b]];
    }
}

void mark_path(int v, int b, int children) {
    while (base[v] != b) {
        blossom[base[v]] = blossom[base[match[v]]] =
        ↪ true;
        p[v] = children;
        children = match[v];
        v = p[match[v]];
```

```cpp
  }
}

int find_path(int root) {
  memset(used, 0, sizeof used);
  memset(p, -1, sizeof p);
  for (int i = 0; i < n; ++i)
    base[i] = i;

  used[root] = true;
  int qh = 0, qt = 0;
  q[qt++] = root;
  while (qh < qt) {
    int v = q[qh++];
    for (size_t i = 0; i < g[v].size(); ++i) {
      int to = g[v][i];
      if (base[v] == base[to] || match[v] == to)
        continue;
      if (to == root || (match[to] != -1 &&
      ↪  p[match[to]] != -1)) {
        int curbase = lca(v, to);
        memset(blossom, 0, sizeof blossom);
        mark_path(v, curbase, to);
        mark_path(to, curbase, v);
        for (int i = 0; i < n; ++i)
          if (blossom[base[i]]) {
            base[i] = curbase;
            if (!used[i]) {
              used[i] = true;
              q[qt++] = i;
            }
          }
      } else if (p[to] == -1) {
        p[to] = v;
        if (match[to] == -1)
          return to;
        to = match[to];
        used[to] = true;
        q[qt++] = to;
      }
    }
  }
  return -1;
}

vector<pair<int, int>> solve(int _n,
↪  vector<pair<int, int>> edges) {
  n = _n;
  for (int i = 0; i < n; i++)
    g[i].clear();
  for (auto o : edges) {
    g[o.first].push_back(o.second);
    g[o.second].push_back(o.first);
  }
  memset(match, -1, sizeof match);
  for (int i = 0; i < n; ++i) {
    if (match[i] == -1) {
      int v = find_path(i);
      while (v != -1) {
        int pv = p[v], ppv = match[pv];
        match[v] = pv, match[pv] = v;
        v = ppv;
      }
    }
  }
  vector<pair<int, int>> ans;
  for (int i = 0; i < n; i++) {
    if (match[i] > i) {
      ans.push_back(make_pair(i, match[i]));
    }
  }
  return ans;
}
} // namespace general_matching
```

4.4 Hungarian algorithm

```cpp
namespace hungary {
const int N = 210;

int a[N][N];
int ans[N];

int calc(int n, int m) {
  ++n, ++m;
  vector<int> u(n), v(m), p(m), prev(m);
  for (int i = 1; i < n; ++i) {
    p[0] = i;
    int x = 0;
    vector<int> mn(m, INF);
    vector<int> was(m, 0);
    while (p[x]) {
      was[x] = 1;
      int ii = p[x], dd = INF, y = 0;
      for (int j = 1; j < m; ++j)
        if (!was[j]) {
          int cur = a[ii][j] - u[ii] - v[j];
          if (cur < mn[j])
            mn[j] = cur, prev[j] = x;
          if (mn[j] < dd)
            dd = mn[j], y = j;
        }
      for (int j = 0; j < m; ++j) {
        if (was[j])
          u[p[j]] += dd, v[j] -= dd;
        else
          mn[j] -= dd;
      }
      x = y;
    }
    while (x) {
      int y = prev[x];
      p[x] = p[y];
      x = y;
    }
  }
  for (int j = 1; j < m; ++j) {
    ans[p[j]] = j;
  }
  return -v[0];
}
// How to use:
// * Set values to a[1..n][1..m] (n <= m)
```

```
// * Run calc(n, m) to find minimum
// * Optimal edges are (i, ans[i]) for i = 1..n
// * Everything works on negative numbers
//
// !!! I don't understand this code, it's
↪   copypasted from e-maxx
} // namespace hungary
```

4.5 Link-Cut Tree

```
#include <cassert>
#include <cstdio>
#include <iostream>

using namespace std;

// BEGIN ALGO

const int MAXN = 110000;

typedef struct _node {
  _node *l, *r, *p, *pp;
  int size;
  bool rev;
  _node();
  explicit _node(nullptr_t) {
    l = r = p = pp = this;
    size = rev = 0;
  }
  void push() {
    if (rev) {
      l->rev ^= 1;
      r->rev ^= 1;
      rev = 0;
      swap(l, r);
    }
  }
  void update();
} * node;
node None = new _node(nullptr);
node v2n[MAXN];
_node::_node() {
  l = r = p = pp = None;
  size = 1;
  rev = false;
}
void _node::update() {
  size = (this != None) + l->size + r->size;
  l->p = r->p = this;
}
void rotate(node v) {
  assert(v != None && v->p != None);
  assert(!v->rev);
  assert(!v->p->rev);
  node u = v->p;
  if (v == u->l)
    u->l = v->r, v->r = u;
  else
    u->r = v->l, v->l = u;
  swap(u->p, v->p);
  swap(v->pp, u->pp);
  if (v->p != None) {
    assert(v->p->l == u || v->p->r == u);
    if (v->p->r == u)
      v->p->r = v;
    else
      v->p->l = v;
  }
  u->update();
  v->update();
}
void bigRotate(node v) {
  assert(v->p != None);
  v->p->p->push();
  v->p->push();
  v->push();
  if (v->p->p != None) {
    if ((v->p->l == v) ^ (v->p->p->r == v->p))
      rotate(v->p);
    else
      rotate(v);
  }
  rotate(v);
}
inline void Splay(node v) {
  while (v->p != None)
    bigRotate(v);
}
inline void splitAfter(node v) {
  v->push();
  Splay(v);
  v->r->p = None;
  v->r->pp = v;
  v->r = None;
  v->update();
}
void expose(int x) {
  node v = v2n[x];
  splitAfter(v);
  while (v->pp != None) {
    assert(v->p == None);
    splitAfter(v->pp);
    assert(v->pp->r == None);
    assert(v->pp->p == None);
    assert(!v->pp->rev);
    v->pp->r = v;
    v->pp->update();
    v = v->pp;
    v->r->pp = None;
  }
  assert(v->p == None);
  Splay(v2n[x]);
}
inline void makeRoot(int x) {
  expose(x);
  assert(v2n[x]->p == None);
  assert(v2n[x]->pp == None);
  assert(v2n[x]->r == None);
  v2n[x]->rev ^= 1;
}
inline void link(int x, int y) {
  makeRoot(x);
  v2n[x]->pp = v2n[y];
```

```
}
inline void cut(int x, int y) {
    expose(x);
    Splay(v2n[y]);
    if (v2n[y]->pp != v2n[x]) {
        swap(x, y);
        expose(x);
        Splay(v2n[y]);
        assert(v2n[y]->pp == v2n[x]);
    }
    v2n[y]->pp = None;
}
inline int get(int x, int y) {
    if (x == y)
        return 0;
    makeRoot(x);
    expose(y);
    expose(x);
    Splay(v2n[y]);
    if (v2n[y]->pp != v2n[x])
        return -1;
    return v2n[y]->size;
}

// END ALGO

_node mem[MAXN];

int main() {
    freopen("linkcut.in", "r", stdin);
    freopen("linkcut.out", "w", stdout);

    int n, m;
    scanf("%d %d", &n, &m);

    for (int i = 0; i < n; i++)
        v2n[i] = &mem[i];

    for (int i = 0; i < m; i++) {
        int a, b;
        if (scanf(" link %d %d", &a, &b) == 2)
            link(a - 1, b - 1);
        else if (scanf(" cut %d %d", &a, &b) == 2)
            cut(a - 1, b - 1);
        else if (scanf(" get %d %d", &a, &b) == 2)
            printf("%d\n", get(a - 1, b - 1));
        else
            assert(false);
    }
    return 0;
}
```

4.6 Smith algorithm (Game on cyclic graph)

```
const int N = 1e5 + 10;

struct graph {
    int n;

    vi v[N];
    vi vrev[N];

    void read() {
        int m;
        scanf("%d%d", &n, &m);
        forn(i, m) {
            int x, y;
            scanf("%d%d", &x, &y);
            --x, --y;
            v[x].pb(y);
            vrev[y].pb(x);
        }
    }

    int deg[N], cnt[N], used[N], f[N];
    int q[N], st, en;

    set<int> s[N];

    void calc() {
        for (int x = 0; x < n; ++x)
            f[x] = -1, cnt[x] = 0;
        int val = 0;
        while (1) {
            st = en = 0;
            for (int x = 0; x < n; ++x) {
                deg[x] = 0;
                used[x] = 0;
                for (int y : v[x])
                    if (f[y] == -1)
                        deg[x]++;
            }
            for (int x = 0; x < n; ++x)
                if (!deg[x] && f[x] == -1 && cnt[x] ==
                ↪ val) {
                    q[en++] = x;
                    f[x] = val;
                }
            if (!en)
                break;
            while (st < en) {
                int x = q[st];
                st++;
                for (int y : vrev[x]) {
                    if (used[y] == 0 && f[y] == -1) {
                        used[y] = 1;
                        cnt[y]++;
                        for (int z : vrev[y]) {
                            deg[z]--;
                            if (f[z] == -1 && deg[z] == 0 &&
                            ↪ cnt[z] == val) {
                                f[z] = val;
                                q[en++] = z;
                            }
                        }
                    }
                }
            }
            val++;
        }
        for (int x = 0; x < n; ++x)
            eprintf("%d%c", f[x], " \n"[x + 1 == n]);
        for (int x = 0; x < n; ++x)
```

```
      if (f[x] == -1) {
        for (int y : v[x])
          if (f[y] != -1)
            s[x].insert(f[y]);
      }
  }
} g1, g2;

string get(int x, int y) {
  int f1 = g1.f[x], f2 = g2.f[y];
  if (f1 == -1 && f2 == -1)
    return "draw";
  if (f1 == -1) {
    if (g1.s[x].count(f2))
      return "first";
    return "draw";
  }
  if (f2 == -1) {
    if (g2.s[y].count(f1))
      return "first";
    return "draw";
  }
  if (f1 ^ f2)
    return "first";
  return "second";
}
```

4.7 Stoer-Vagner algorithm (Global min-cut)

```
const int MAXN = 500;
int n, g[MAXN][MAXN];
int best_cost = 1000000000;
vector<int> best_cut;

void mincut() {
  vector<int> v[MAXN];
  for (int i = 0; i < n; ++i)
    v[i].assign(1, i);
  int w[MAXN];
  bool exist[MAXN], in_a[MAXN];
  memset(exist, true, sizeof exist);
  for (int ph = 0; ph < n - 1; ++ph) {
    memset(in_a, false, sizeof in_a);
    memset(w, 0, sizeof w);
    for (int it = 0, prev; it < n - ph; ++it) {
      int sel = -1;
      for (int i = 0; i < n; ++i)
        if (exist[i] && !in_a[i] && (sel == -1 || w[i] > w[sel]))
          sel = i;
      if (it == n - ph - 1) {
        if (w[sel] < best_cost)
          best_cost = w[sel], best_cut = v[sel];
        v[prev].insert(v[prev].end(), v[sel].begin(), v[sel].end());
        for (int i = 0; i < n; ++i)
          g[prev][i] = g[i][prev] += g[sel][i];
        exist[sel] = false;
      } else {
        in_a[sel] = true;
        for (int i = 0; i < n; ++i)
          w[i] += g[sel][i];
        prev = sel;
      }
    }
  }
}
```

5 Matroids

5.1 Matroids intersection

```
// check(ctaken, 1) -- first matroid
// check(ctaken, 2) -- second matroid
vector<char> taken(m);
while (1) {
  vector<vector<int>> e(m);
  for (int i = 0; i < m; i++) {
    for (int j = 0; j < m; j++) {
      if (taken[i] && !taken[j]) {
        auto ctaken = taken;
        ctaken[i] = 0;
        ctaken[j] = 1;
        if (check(ctaken, 2)) {
          e[i].push_back(j);
        }
      }
      if (!taken[i] && taken[j]) {
        auto ctaken = taken;
        ctaken[i] = 1;
        ctaken[j] = 0;
        if (check(ctaken, 1)) {
          e[i].push_back(j);
        }
      }
    }
  }
  vector<int> type(m);
  // 0 -- cant, 1 -- can in \2, 2 -- can in \1
  for (int i = 0; i < m; i++) {
    if (!taken[i]) {
      auto ctaken = taken;
      ctaken[i] = 1;
      if (check(ctaken, 2))
        type[i] |= 1;
    }
    if (!taken[i]) {
      auto ctaken = taken;
      ctaken[i] = 1;
      if (check(ctaken, 1))
        type[i] |= 2;
    }
  }
  vector<int> w(m);
  for (int i = 0; i < m; i++) {
    w[i] = taken[i] ? ed[i].c : -ed[i].c;
  }
  vector<pair<int, int>> d(m, {INF, 0});
  for (int i = 0; i < m; i++) {
    if (type[i] & 1)
      d[i] = {w[i], 0};
```

```
    }
    vector<int> pr(m, -1);
    while (1) {
        vector<pair<int, int>> nd = d;
        for (int i = 0; i < m; i++) {
            if (d[i].first == INF)
                continue;
            for (int to : e[i]) {
                if (nd[to] > make_pair(d[i].first + w[to], d[i].second + 1)) {
                    nd[to] = make_pair(d[i].first + w[to], d[i].second + 1);
                    pr[to] = i;
                }
            }
        }
        if (d == nd)
            break;
        d = nd;
    }
    int v = -1;
    for (int i = 0; i < m; i++) {
        if ((d[i].first < INF && (type[i] & 2)) && (v == -1 || d[i] < d[v]))
            v = i;
    }
    if (v == -1)
        break;
    while (v != -1) {
        sum += w[v];
        taken[v] ^= 1;
        v = pr[v];
    }
    ans[--cnt] = sum;
}
```

6 Numeric

6.1 Berlekamp-Massey Algorithm

```
vector<int> berlekamp(vector<int> s) {
    int l = 0;
    vector<int> la(1, 1);
    vector<int> b(1, 1);
    for (int r = 1; r <= (int)s.size(); r++) {
        int delta = 0;
        for (int j = 0; j <= l; j++) {
            delta = (delta + 1LL * s[r - 1 - j] * la[j]) % MOD;
        }
        b.insert(b.begin(), 0);
        if (delta != 0) {
            vector<int> t(max(la.size(), b.size()));
            for (int i = 0; i < (int)t.size(); i++) {
                if (i < (int)la.size())
                    t[i] = (t[i] + la[i]) % MOD;
                if (i < (int)b.size())
                    t[i] = (t[i] - 1LL * delta * b[i] % MOD + MOD) % MOD;
            }
            if (2 * l <= r - 1) {
                b = la;
                int od = inv(delta);
                for (int &x : b)
                    x = 1LL * x * od % MOD;
                l = r - l;
            }
            la = t;
        }
    }
    assert((int)la.size() == l + 1);
    assert(l * 2 + 30 < (int)s.size());
    reverse(la.begin(), la.end());
    return la;
}

vector<int> mul(vector<int> a, vector<int> b) {
    vector<int> c(a.size() + b.size() - 1);
    for (int i = 0; i < (int)a.size(); i++) {
        for (int j = 0; j < (int)b.size(); j++) {
            c[i + j] = (c[i + j] + 1LL * a[i] * b[j]) % MOD;
        }
    }
    vector<int> res(c.size());
    for (int i = 0; i < (int)res.size(); i++)
        res[i] = c[i] % MOD;
    return res;
}

vector<int> mod(vector<int> a, vector<int> b) {
    if (a.size() < b.size())
        a.resize(b.size() - 1);

    int o = inv(b.back());
    for (int i = (int)a.size() - 1; i >= (int)b.size() - 1; i--) {
        if (a[i] == 0)
            continue;
        int coef = 1LL * o * (MOD - a[i]) % MOD;
        for (int j = 0; j < (int)b.size(); j++) {
            a[i - (int)b.size() + 1 + j] =
                    (a[i - (int)b.size() + 1 + j] + 1LL * coef * b[j]) % MOD;
        }
    }
    while (a.size() >= b.size()) {
        assert(a.back() == 0);
        a.pop_back();
    }
    return a;
}

vector<int> bin(int n, vector<int> p) {
    vector<int> res(1, 1);
    vector<int> a(2);
    a[1] = 1;
    while (n) {
        if (n & 1)
            res = mod(mul(res, a), p);
        a = mod(mul(a, a), p);
        n >>= 1;
    }
```

```
    return res;
}

int f(vector<int> t, int m) {
    vector<int> v = berlekamp(t);
    vector<int> o = bin(m - 1, v);
    int res = 0;
    for (int i = 0; i < (int)o.size(); i++)
        res = (res + 1LL * o[i] * t[i]) % MOD;
    return res;
}
```

6.2 Chinese remainder theorem

```
int CRT(int a1, int m1, int a2, int m2) {
    return (a1 - a2 % m1 + m1) * (ll)rev(m2, m1) %
      m1 * m2 + a2;
}
```

6.3 Multiplication by modulo

```
ll mul(ll a, ll b, ll m) { // works for MOD 8e18
    ll k = (ll)((long double)a * b / m);
    ll r = a * b - m * k;
    if (r < 0)
        r += m;
    if (r >= m)
        r -= m;
    return r;
}
```

6.4 Numerical integration

```
function<dbl(dbl, dbl, function<dbl(dbl)>)> f =
  [&](dbl L, dbl R, function<dbl(dbl)> g) {
    const int ITERS = 1000000;
    dbl ans = 0;
    dbl step = (R - L) * 1.0 / ITERS;
    for (int it = 0; it < ITERS; it++) {
        double xl = L + step * it;
        double xr = L + step * (it + 1);
        dbl x1 = (xl + xr) / 2;
        dbl x0 = x1 - (x1 - xl) * sqrt(3.0 / 5);
        dbl x2 = x1 + (x1 - xl) * sqrt(3.0 / 5);
        ans += (5 * g(x0) + 8 * g(x1) + 5 * g(x2)) /
          18 * step;
    }
    return ans;
};
```

6.5 Pollard's rho algorithm

```
namespace pollard {
using math::p;

vector<pair<ll, int>> getFactors(ll N) {
    vector<ll> primes;

    const int MX = 1e5;
    const ll MX2 = MX * (ll)MX;

    assert(MX <= math::maxP && math::pc > 0);

    function<void(ll)> go = [&go, &primes](ll n) {
        for (ll x : primes)
            while (n % x == 0)
                n /= x;
        if (n == 1)
            return;
        if (n > MX2) {
            auto F = [&](ll x) {
                ll k = ((long double)x * x) / n;
                ll r = (x * x - k * n + 3) % n;
                return r < 0 ? r + n : r;
            };
            ll x = mt19937_64()() % n, y = x;
            const int C = 3 * pow(n, 0.25);

            ll val = 1;
            forn(it, C) {
                x = F(x), y = F(F(y));
                if (x == y)
                    continue;
                ll delta = abs(x - y);
                ll k = ((long double)val * delta) / n;
                val = (val * delta - k * n) % n;
                if (val < 0)
                    val += n;
                if (val == 0) {
                    ll g = __gcd(delta, n);
                    go(g), go(n / g);
                    return;
                }
                if ((it & 255) == 0) {
                    ll g = __gcd(val, n);
                    if (g != 1) {
                        go(g), go(n / g);
                        return;
                    }
                }
            }
        }
        primes.pb(n);
    };

    ll n = N;

    for (int i = 0; i < math::pc && p[i] < MX; ++i)
        if (n % p[i] == 0) {
            primes.pb(p[i]);
            while (n % p[i] == 0)
                n /= p[i];
        }

    go(n);

    sort(primes.begin(), primes.end());

    vector<pair<ll, int>> res;
    for (ll x : primes) {
```

```
    int cnt = 0;
    while (N % x == 0) {
      cnt++;
      N /= x;
    }
    res.push_back({x, cnt});
  }
  return res;
}
} // namespace pollard
```

6.6 Polynom division and inversion

```
poly inv(poly A, int n) // returns A^-1 mod x^n
{
  assert(sz(A) && A[0] != 0);
  A.cut(n);

  auto cutPoly = [](poly &from, int l, int r) {
    poly R;
    R.v.resize(r - l);
    for (int i = l; i < r; ++i) {
      if (i < sz(from))
        R[i - l] = from[i];
    }
    return R;
  };

  function<int(int, int)> rev = [&rev](int x, int
   ↪  m) -> int {
    if (x == 1)
      return 1;
    return (1 - rev(m % x, x) * (ll)m) / x + m;
  };

  poly R({rev(A[0], mod)});
  for (int k = 1; k < n; k <<= 1) {
    poly A0 = cutPoly(A, 0, k);
    poly A1 = cutPoly(A, k, 2 * k);
    poly H = A0 * R;
    H = cutPoly(H, k, 2 * k);
    poly R1 = (((A1 * R).cut(k) + H) * (poly({0})
     ↪  - R)).cut(k);
    R.v.resize(2 * k);
    forn(i, k) R[i + k] = R1[i];
  }
  return R.cut(n).norm();
}

pair<poly, poly> divide(poly A, poly B) {
  if (sz(A) < sz(B))
    return {poly({0}), A};

  auto rev = [](poly f) {
    reverse(all(f.v));
    return f;
  };

  poly q =
      rev((inv(rev(B), sz(A) - sz(B) + 1) *
       ↪  rev(A)).cut(sz(A) - sz(B) + 1));
  poly r = A - B * q;

  return {q, r};
}
```

6.7 Simplex method

```
vector<double> simplex(vector<vector<double>> a)
↪  {
  int n = a.size() - 1;
  int m = a[0].size() - 1;
  vector<int> left(n + 1), up(m + 1);
  iota(up.begin(), up.end(), 0);
  iota(left.begin(), left.end(), m);
  auto pivot = [&](int x, int y) {
    swap(left[x], up[y]);
    double k = a[x][y];
    a[x][y] = 1;
    vector<int> vct;
    for (int j = 0; j <= m; j++) {
      a[x][j] /= k;
      if (!eq(a[x][j], 0))
        vct.push_back(j);
    }
    for (int i = 0; i <= n; i++) {
      if (eq(a[i][y], 0) || i == x)
        continue;
      k = a[i][y];
      a[i][y] = 0;
      for (int j : vct)
        a[i][j] -= k * a[x][j];
    }
  };
  while (1) {
    int x = -1;
    for (int i = 1; i <= n; i++)
      if (ls(a[i][0], 0) && (x == -1 || a[i][0] <
       ↪  a[x][0]))
        x = i;
    if (x == -1)
      break;
    int y = -1;
    for (int j = 1; j <= m; j++)
      if (ls(a[x][j], 0) && (y == -1 || a[x][j] <
       ↪  a[x][y]))
        y = j;
    if (y == -1)
      assert(0); // infeasible
    pivot(x, y);
  }
  while (1) {
    int y = -1;
    for (int j = 1; j <= m; j++)
      if (ls(0, a[0][j]) && (y == -1 || a[0][j] >
       ↪  a[0][y]))
        y = j;
    if (y == -1)
      break;
    int x = -1;
    for (int i = 1; i <= n; i++)
```

```
            if (ls(0, a[i][y]) && (x == -1 || a[i][0] / a[i][y] < a[x][0] / a[x][y]))
                x = i;
        if (x == -1)
            assert(0); // unbounded
        pivot(x, y);
    }
    vector<double> ans(m + 1);
    for (int i = 1; i <= n; i++)
        if (left[i] <= m)
            ans[left[i]] = a[i][0];
    ans[0] = -a[0][0];
    return ans;
}
// j=1..m: x[j]>=0
// i=1..n: sum(j=1..m) A[i][j]*x[j] <= A[i][0]
// max sum(j=1..m) A[0][j]*x[j]
// res[0] is answer
// res[1..m] is certificate
```

7 Strings

7.1 Duval algorithm (Lyndon factorization)

```
void duval(string s) {
    int n = (int)s.length();
    int i = 0;
    while (i < n) {
        int j = i + 1, k = i;
        while (j < n && s[k] <= s[j]) {
            if (s[k] < s[j])
                k = i;
            else
                ++k;
            ++j;
        }
        while (i <= k) {
            cout << s.substr(i, j - k) << ' ';
            i += j - k;
        }
    }
}
```

7.2 Palindromic tree

```
namespace eertree {
const int INF = 1e9;
const int N = 5e6 + 10;
char _s[N];
char *s = _s + 1;
int to[N][2];
int suf[N], len[N];
int sz, last;

const int odd = 1, even = 2, blank = 3;

void go(int &u, int pos) {
    while (u != blank && s[pos - len[u] - 1] != s[pos]) {
        u = suf[u];
    }
}

int add(int pos) {
    go(last, pos);
    int u = suf[last];
    go(u, pos);
    int c = s[pos] - 'a';
    int res = 0;
    if (!to[last][c]) {
        res = 1;
        to[last][c] = sz;
        len[sz] = len[last] + 2;
        suf[sz] = to[u][c];
        sz++;
    }
    last = to[last][c];
    return res;
}

void init() {
    to[blank][0] = to[blank][1] = even;
    len[blank] = suf[blank] = INF;
    len[even] = 0, suf[even] = odd;
    len[odd] = -1, suf[odd] = blank;
    last = even;
    sz = 4;
}
} // namespace eertree
```

7.3 Suffix automaton

```
struct state {
    state() { std::fill(next, next + 26, -1); }

    int len = 0, link = -1;
    bool term = false;

    int next[26];
};

vector<state> st;
int last;

void sa_init() {
    last = 0;
    st.clear();
    st.resize(1);
}

void sa_extend(char c) {
    int cur = st.size();
    st.resize(st.size() + 1);

    st[cur].len = st[last].len + 1;
    int p;
    for (p = last; p != -1 && st[p].next[c - 'a'] == -1; p = st[p].link)
        st[p].next[c - 'a'] = cur;
    if (p == -1)
        st[cur].link = 0;
```

```
  else {
    int q = st[p].next[c - 'a'];
    if (st[p].len + 1 == st[q].len)
      st[cur].link = q;
    else {
      int clone = st.size();
      st.resize(st.size() + 1);
      st[clone].len = st[p].len + 1;
      std::copy(st[q].next, st[q].next + 26,
        ↪ st[clone].next);
      st[clone].link = st[q].link;
      for (; p != -1 && st[p].next[c - 'a'] == q;
        ↪ p = st[p].link)
        st[p].next[c - 'a'] = clone;
      st[q].link = st[cur].link = clone;
    }
  }
  last = cur;
}

for (int v = last; v != -1; v = st[v].link) //
↪ set termination flag.
  st[v].term = 1;
```

7.4 Suffix tree

```
#include <bits/stdc++.h>

using namespace std;

#define forn(i, n) for (int i = 0; i < (int)(n);
↪ i++)

const int N = 1e5, VN = 2 * N;

char s[N + 1];
map<char, int> t[VN];
int l[VN], r[VN], p[VN]; // edge p[v] -> v
↪ matches to [l[v], r[v]) of string
int cc, n, suf[VN], vn = 2, v = 1, pos; // going
↪ by edge from p[v] to v, now standing in pos

void go(int v) {
  int no = cc++;
  for (auto p : t[v]) {
    v = p.second;
    printf("%d %d %d\n", no, l[v], min(n, r[v]));
    go(v);
  }
}

int main() {
  assert(freopen("suftree.in", "r", stdin));
  assert(freopen("suftree.out", "w", stdout));

  gets(s);
  forn(i, 127) t[0][i] = 1; // 0 = fictitious, 1
    ↪ = root
  l[1] = -1;
  for (n = 0; s[n]; n++) {
    char c = s[n];
    auto new_leaf = [&](int v) {
      p[vn] = v, l[vn] = n, r[vn] = N, t[v][c] =
        ↪ vn++;
    };
  go:;
    if (r[v] <= pos) {
      if (!t[v].count(c)) {
        new_leaf(v), v = suf[v], pos = r[v];
        goto go;
      }
      v = t[v][c], pos = l[v] + 1;
    } else if (c == s[pos]) {
      pos++;
    } else {
      int x = vn++;
      l[x] = l[v], r[x] = pos, l[v] = pos;
      p[x] = p[v], p[v] = x;
      t[p[x]][s[l[x]]] = x, t[x][s[pos]] = v;
      new_leaf(x);
      v = suf[p[x]], pos = l[x];
      while (pos < r[x])
        v = t[v][s[pos]], pos += r[v] - l[v];
      suf[x] = (pos == r[x] ? v : vn);
      pos = r[v] - (pos - r[x]);
      goto go;
    }
  }
  printf("%d\n", vn - 1);
  go(1);
}
```

Table of Integrals*

Basic Forms

$$\int x^n dx = \frac{1}{n+1}x^{n+1} \tag{1}$$

$$\int \frac{1}{x} dx = \ln|x| \tag{2}$$

$$\int u dv = uv - \int v du \tag{3}$$

$$\int \frac{1}{ax+b} dx = \frac{1}{a}\ln|ax+b| \tag{4}$$

Integrals of Rational Functions

$$\int \frac{1}{(x+a)^2} dx = -\frac{1}{x+a} \tag{5}$$

$$\int (x+a)^n dx = \frac{(x+a)^{n+1}}{n+1}, n \neq -1 \tag{6}$$

$$\int x(x+a)^n dx = \frac{(x+a)^{n+1}((n+1)x-a)}{(n+1)(n+2)} \tag{7}$$

$$\int \frac{1}{1+x^2} dx = \tan^{-1} x \tag{8}$$

$$\int \frac{1}{a^2+x^2} dx = \frac{1}{a}\tan^{-1}\frac{x}{a} \tag{9}$$

$$\int \frac{x}{a^2+x^2} dx = \frac{1}{2}\ln|a^2+x^2| \tag{10}$$

$$\int \frac{x^2}{a^2+x^2} dx = x - a\tan^{-1}\frac{x}{a} \tag{11}$$

$$\int \frac{x^3}{a^2+x^2} dx = \frac{1}{2}x^2 - \frac{1}{2}a^2\ln|a^2+x^2| \tag{12}$$

$$\int \frac{1}{ax^2+bx+c} dx = \frac{2}{\sqrt{4ac-b^2}}\tan^{-1}\frac{2ax+b}{\sqrt{4ac-b^2}} \tag{13}$$

$$\int \frac{1}{(x+a)(x+b)} dx = \frac{1}{b-a}\ln\frac{a+x}{b+x}, \ a \neq b \tag{14}$$

$$\int \frac{x}{(x+a)^2} dx = \frac{a}{a+x} + \ln|a+x| \tag{15}$$

$$\int \frac{x}{ax^2+bx+c} dx = \frac{1}{2a}\ln|ax^2+bx+c| - \frac{b}{a\sqrt{4ac-b^2}}\tan^{-1}\frac{2ax+b}{\sqrt{4ac-b^2}} \tag{16}$$

Integrals with Roots

$$\int \sqrt{x-a}\, dx = \frac{2}{3}(x-a)^{3/2} \tag{17}$$

$$\int \frac{1}{\sqrt{x \pm a}} dx = 2\sqrt{x \pm a} \tag{18}$$

$$\int \frac{1}{\sqrt{a-x}} dx = -2\sqrt{a-x} \tag{19}$$

$$\int x\sqrt{x-a}\, dx = \frac{2}{3}a(x-a)^{3/2} + \frac{2}{5}(x-a)^{5/2} \tag{20}$$

$$\int \sqrt{ax+b}\, dx = \left(\frac{2b}{3a} + \frac{2x}{3}\right)\sqrt{ax+b} \tag{21}$$

$$\int (ax+b)^{3/2} dx = \frac{2}{5a}(ax+b)^{5/2} \tag{22}$$

$$\int \frac{x}{\sqrt{x \pm a}} dx = \frac{2}{3}(x \mp 2a)\sqrt{x \pm a} \tag{23}$$

$$\int \sqrt{\frac{x}{a-x}} dx = -\sqrt{x(a-x)} - a\tan^{-1}\frac{\sqrt{x(a-x)}}{x-a} \tag{24}$$

$$\int \sqrt{\frac{x}{a+x}} dx = \sqrt{x(a+x)} - a\ln\left[\sqrt{x} + \sqrt{x+a}\right] \tag{25}$$

$$\int x\sqrt{ax+b}\, dx = \frac{2}{15a^2}(-2b^2+abx+3a^2x^2)\sqrt{ax+b} \tag{26}$$

$$\int \sqrt{x(ax+b)}\, dx = \frac{1}{4a^{3/2}}\left[(2ax+b)\sqrt{ax(ax+b)} - b^2\ln\left|a\sqrt{x} + \sqrt{a(ax+b)}\right|\right] \tag{27}$$

$$\int \sqrt{x^3(ax+b)}\, dx = \left[\frac{b}{12a} - \frac{b^2}{8a^2x} + \frac{x}{3}\right]\sqrt{x^3(ax+b)} + \frac{b^3}{8a^{5/2}}\ln\left|a\sqrt{x} + \sqrt{a(ax+b)}\right| \tag{28}$$

$$\int \sqrt{x^2 \pm a^2}\, dx = \frac{1}{2}x\sqrt{x^2 \pm a^2} \pm \frac{1}{2}a^2\ln\left|x + \sqrt{x^2 \pm a^2}\right| \tag{29}$$

$$\int \sqrt{a^2-x^2}\, dx = \frac{1}{2}x\sqrt{a^2-x^2} + \frac{1}{2}a^2\tan^{-1}\frac{x}{\sqrt{a^2-x^2}} \tag{30}$$

$$\int x\sqrt{x^2 \pm a^2}\, dx = \frac{1}{3}\left(x^2 \pm a^2\right)^{3/2} \tag{31}$$

$$\int \frac{1}{\sqrt{x^2 \pm a^2}} dx = \ln\left|x + \sqrt{x^2 \pm a^2}\right| \tag{32}$$

$$\int \frac{1}{\sqrt{a^2-x^2}} dx = \sin^{-1}\frac{x}{a} \tag{33}$$

$$\int \frac{x}{\sqrt{x^2 \pm a^2}} dx = \sqrt{x^2 \pm a^2} \tag{34}$$

$$\int \frac{x}{\sqrt{a^2-x^2}} dx = -\sqrt{a^2-x^2} \tag{35}$$

$$\int \frac{x^2}{\sqrt{x^2 \pm a^2}} dx = \frac{1}{2}x\sqrt{x^2 \pm a^2} \mp \frac{1}{2}a^2\ln\left|x + \sqrt{x^2 \pm a^2}\right| \tag{36}$$

$$\int \sqrt{ax^2+bx+c}\, dx = \frac{b+2ax}{4a}\sqrt{ax^2+bx+c} + \frac{4ac-b^2}{8a^{3/2}}\ln\left|2ax+b+2\sqrt{a(ax^2+bx^+c)}\right| \tag{37}$$

$$\int x\sqrt{ax^2+bx+c} = \frac{1}{48a^{5/2}}\Big(2\sqrt{a}\sqrt{ax^2+bx+c} \times \left(-3b^2+2abx+8a(c+ax^2)\right) + 3(b^3-4abc)\ln\left|b+2ax+2\sqrt{a}\sqrt{ax^2+bx+c}\right|\Big) \tag{38}$$

$$\int \frac{1}{\sqrt{ax^2+bx+c}} dx = \frac{1}{\sqrt{a}}\ln\left|2ax+b+2\sqrt{a(ax^2+bx+c)}\right| \tag{39}$$

$$\int \frac{x}{\sqrt{ax^2+bx+c}} dx = \frac{1}{a}\sqrt{ax^2+bx+c} - \frac{b}{2a^{3/2}}\ln\left|2ax+b+2\sqrt{a(ax^2+bx+c)}\right| \tag{40}$$

$$\int \frac{dx}{(a^2+x^2)^{3/2}} = \frac{x}{a^2\sqrt{a^2+x^2}} \tag{41}$$

Integrals with Logarithms

$$\int \ln ax\, dx = x\ln ax - x \tag{42}$$

$$\int \frac{\ln ax}{x} dx = \frac{1}{2}(\ln ax)^2 \tag{43}$$

$$\int \ln(ax+b)\, dx = \left(x + \frac{b}{a}\right)\ln(ax+b) - x, a \neq 0 \tag{44}$$

$$\int \ln(x^2+a^2)\, \mathrm{d}x = x\ln(x^2+a^2) + 2a\tan^{-1}\frac{x}{a} - 2x \tag{45}$$

$$\int \ln(x^2-a^2)\, \mathrm{d}x = x\ln(x^2-a^2) + a\ln\frac{x+a}{x-a} - 2x \tag{46}$$

$$\int \ln\left(ax^2+bx+c\right) \mathrm{d}x = \frac{1}{a}\sqrt{4ac-b^2}\tan^{-1}\frac{2ax+b}{\sqrt{4ac-b^2}} - 2x + \left(\frac{b}{2a} + x\right)\ln\left(ax^2+bx+c\right) \tag{47}$$

$$\int x\ln(ax+b)\, dx = \frac{bx}{2a} - \frac{1}{4}x^2 + \frac{1}{2}\left(x^2 - \frac{b^2}{a^2}\right)\ln(ax+b) \tag{48}$$

$$\int x\ln\left(a^2-b^2x^2\right) dx = -\frac{1}{2}x^2 + \frac{1}{2}\left(x^2 - \frac{a^2}{b^2}\right)\ln\left(a^2-b^2x^2\right) \tag{49}$$

Integrals with Exponentials

$$\int e^{ax} dx = \frac{1}{a}e^{ax} \tag{50}$$

$$\int \sqrt{x}e^{ax} dx = \frac{1}{a}\sqrt{x}e^{ax} + \frac{i\sqrt{\pi}}{2a^{3/2}}\operatorname{erf}\left(i\sqrt{ax}\right), \quad \text{where } \operatorname{erf}(x) = \frac{2}{\sqrt{\pi}}\int_0^x e^{-t^2} dt \tag{51}$$

$$\int xe^x dx = (x-1)e^x \tag{52}$$

$$\int xe^{ax} dx = \left(\frac{x}{a} - \frac{1}{a^2}\right)e^{ax} \tag{53}$$

$$\int x^2e^x dx = \left(x^2-2x+2\right)e^x \tag{54}$$

$$\int x^2e^{ax} dx = \left(\frac{x^2}{a} - \frac{2x}{a^2} + \frac{2}{a^3}\right)e^{ax} \tag{55}$$

$$\int x^3e^x dx = \left(x^3-3x^2+6x-6\right)e^x \tag{56}$$

$$\int x^ne^{ax}\, \mathrm{d}x = \frac{x^ne^{ax}}{a} - \frac{n}{a}\int x^{n-1}e^{ax}\, \mathrm{d}x \tag{57}$$

$$\int x^ne^{ax}\, \mathrm{d}x = \frac{(-1)^n}{a^{n+1}}\Gamma[1+n,-ax], \quad \text{where } \Gamma(a,x) = \int_x^\infty t^{a-1}e^{-t}\, \mathrm{d}t \tag{58}$$

$$\int e^{ax^2}\, \mathrm{d}x = -\frac{i\sqrt{\pi}}{2\sqrt{a}}\operatorname{erf}\left(ix\sqrt{a}\right) \tag{59}$$

$$\int e^{-ax^2}\, \mathrm{d}x = \frac{\sqrt{\pi}}{2\sqrt{a}}\operatorname{erf}\left(x\sqrt{a}\right) \tag{60}$$

$$\int xe^{-ax^2}\, \mathrm{d}x = -\frac{1}{2a}e^{-ax^2} \tag{61}$$

$$\int x^2e^{-ax^2}\, \mathrm{d}x = \frac{1}{4}\sqrt{\frac{\pi}{a^3}}\operatorname{erf}(x\sqrt{a}) - \frac{x}{2a}e^{-ax^2} \tag{62}$$

Integrals with Trigonometric Functions

$$\int \sin ax dx = -\frac{1}{a}\cos ax \tag{63}$$

$$\int \sin^2 ax dx = \frac{x}{2} - \frac{\sin 2ax}{4a} \tag{64}$$

$$\int \sin^n ax dx = -\frac{1}{a}\cos ax \ {}_2F_1\left[\frac{1}{2}, \frac{1-n}{2}, \frac{3}{2}, \cos^2 ax\right] \tag{65}$$

$$\int \sin^3 ax dx = -\frac{3\cos ax}{4a} + \frac{\cos 3ax}{12a} \tag{66}$$

$$\int \cos ax dx = \frac{1}{a}\sin ax \tag{67}$$

$$\int \cos^2 ax dx = \frac{x}{2} + \frac{\sin 2ax}{4a} \tag{68}$$

$$\int \cos^p ax dx = -\frac{1}{a(1+p)}\cos^{1+p} ax \times {}_2F_1\left[\frac{1+p}{2}, \frac{1}{2}, \frac{3+p}{2}, \cos^2 ax\right] \tag{69}$$

$$\int \cos^3 ax dx = \frac{3\sin ax}{4a} + \frac{\sin 3ax}{12a} \tag{70}$$

$$\int \cos ax \sin bx dx = \frac{\cos[(a-b)x]}{2(a-b)} - \frac{\cos[(a+b)x]}{2(a+b)}, a \neq b \tag{71}$$

$$\int \sin^2 ax \cos bx dx = -\frac{\sin[(2a-b)x]}{4(2a-b)} + \frac{\sin bx}{2b} - \frac{\sin[(2a+b)x]}{4(2a+b)} \tag{72}$$

$$\int \sin^2 x \cos x dx = \frac{1}{3}\sin^3 x \tag{73}$$

$$\int \cos^2 ax \sin bx dx = \frac{\cos[(2a-b)x]}{4(2a-b)} - \frac{\cos bx}{2b} - \frac{\cos[(2a+b)x]}{4(2a+b)} \tag{74}$$

$$\int \cos^2 ax \sin ax dx = -\frac{1}{3a}\cos^3 ax \tag{75}$$

$$\int \sin^2 ax \cos^2 bx dx = \frac{x}{4} - \frac{\sin 2ax}{8a} - \frac{\sin[2(a-b)x]}{16(a-b)} + \frac{\sin 2bx}{8b} - \frac{\sin[2(a+b)x]}{16(a+b)} \tag{76}$$

$$\int \sin^2 ax \cos^2 ax dx = \frac{x}{8} - \frac{\sin 4ax}{32a} \tag{77}$$

$$\int \tan ax dx = -\frac{1}{a}\ln\cos ax \tag{78}$$

$$\int \tan^2 ax dx = -x + \frac{1}{a}\tan ax \tag{79}$$

$$\int \tan^n ax dx = \frac{\tan^{n+1} ax}{a(1+n)} \times {}_2F_1\left(\frac{n+1}{2}, 1, \frac{n+3}{2}, -\tan^2 ax\right) \tag{80}$$

$$\int \tan^3 ax dx = \frac{1}{a}\ln\cos ax + \frac{1}{2a}\sec^2 ax \tag{81}$$

$$\int \sec x dx = \ln|\sec x + \tan x| = 2\tanh^{-1}\left(\tan\frac{x}{2}\right) \tag{82}$$

$$\int \sec^2 ax dx = \frac{1}{a}\tan ax \tag{83}$$

$$\int \sec^3 x \, \mathrm{dx} = \frac{1}{2}\sec x \tan x + \frac{1}{2}\ln|\sec x + \tan x| \tag{84}$$

$$\int \sec x \tan x dx = \sec x \tag{85}$$

$$\int \sec^2 x \tan x dx = \frac{1}{2}\sec^2 x \tag{86}$$

$$\int \sec^n x \tan x dx = \frac{1}{n}\sec^n x, n \neq 0 \tag{87}$$

$$\int \csc x dx = \ln\left|\tan\frac{x}{2}\right| = \ln|\csc x - \cot x| + C \tag{88}$$

$$\int \csc^2 ax dx = -\frac{1}{a}\cot ax \tag{89}$$

$$\int \csc^3 x dx = -\frac{1}{2}\cot x \csc x + \frac{1}{2}\ln|\csc x - \cot x| \tag{90}$$

$$\int \csc^n x \cot x dx = -\frac{1}{n}\csc^n x, n \neq 0 \tag{91}$$

$$\int \sec x \csc x dx = \ln|\tan x| \tag{92}$$

Products of Trigonometric Functions and Monomials

$$\int x \cos x dx = \cos x + x \sin x \tag{93}$$

$$\int x \cos ax dx = \frac{1}{a^2}\cos ax + \frac{x}{a}\sin ax \tag{94}$$

$$\int x^2 \cos x dx = 2x\cos x + \left(x^2 - 2\right)\sin x \tag{95}$$

$$\int x^2 \cos ax dx = \frac{2x\cos ax}{a^2} + \frac{a^2x^2 - 2}{a^3}\sin ax \tag{96}$$

$$\int x^n cosx dx = -\frac{1}{2}(i)^{n+1}\left[\Gamma(n+1,-ix) + (-1)^n\Gamma(n+1,ix)\right] \tag{97}$$

$$\int x^n cosax dx = \frac{1}{2}(ia)^{1-n}\left[(-1)^n\Gamma(n+1,-iax) - \Gamma(n+1,ixa)\right] \tag{98}$$

$$\int x \sin x dx = -x\cos x + \sin x \tag{99}$$

$$\int x \sin ax dx = -\frac{x\cos ax}{a} + \frac{\sin ax}{a^2} \tag{100}$$

$$\int x^2 \sin x dx = \left(2 - x^2\right)\cos x + 2x\sin x \tag{101}$$

$$\int x^2 \sin ax dx = \frac{2 - a^2x^2}{a^3}\cos ax + \frac{2x\sin ax}{a^2} \tag{102}$$

$$\int x^n \sin x dx = -\frac{1}{2}(i)^n\left[\Gamma(n+1,-ix) - (-1)^n\Gamma(n+1,-ix)\right] \tag{103}$$

Products of Trigonometric Functions and Exponentials

$$\int e^x \sin x dx = \frac{1}{2}e^x(\sin x - \cos x) \tag{104}$$

$$\int e^{bx}\sin ax dx = \frac{1}{a^2+b^2}e^{bx}(b\sin ax - a\cos ax) \tag{105}$$

$$\int e^x \cos x dx = \frac{1}{2}e^x(\sin x + \cos x) \tag{106}$$

$$\int e^{bx}\cos ax dx = \frac{1}{a^2+b^2}e^{bx}(a\sin ax + b\cos ax) \tag{107}$$

$$\int xe^x \sin x dx = \frac{1}{2}e^x(\cos x - x\cos x + x\sin x) \tag{108}$$

$$\int xe^x \cos x dx = \frac{1}{2}e^x(x\cos x - \sin x + x\sin x) \tag{109}$$

Integrals of Hyperbolic Functions

$$\int \cosh ax dx = \frac{1}{a}\sinh ax \tag{110}$$

$$\int e^{ax}\cosh bx dx = \begin{cases} \frac{e^{ax}}{a^2-b^2}[a\cosh bx - b\sinh bx] & a \neq b \\ \frac{e^{2ax}}{4a} + \frac{x}{2} & a = b \end{cases} \tag{111}$$

$$\int \sinh ax dx = \frac{1}{a}\cosh ax \tag{112}$$

$$\int e^{ax}\sinh bx dx = \begin{cases} \frac{e^{ax}}{a^2-b^2}[-b\cosh bx + a\sinh bx] & a \neq b \\ \frac{e^{2ax}}{4a} - \frac{x}{2} & a = b \end{cases} \tag{113}$$

$$\int e^{ax}\tanh bx dx = \begin{cases} \frac{e^{(a+2b)x}}{(a+2b)}{}_2F_1\left[1+\frac{a}{2b}, 1, 2+\frac{a}{2b}, -e^{2bx}\right] - \frac{1}{a}e^{ax}{}_2F_1\left[\frac{a}{2b}, 1, 1E, -e^{2bx}\right] & a \neq b \\ \frac{e^{ax} - 2\tan^{-1}[e^{ax}]}{a} & a = b \end{cases} \tag{114}$$

$$\int \tanh ax \, dx = \frac{1}{a}\ln\cosh ax \tag{115}$$

$$\int \cos ax \cosh bx dx = \frac{1}{a^2+b^2}\left[a\sin ax\cosh bx + b\cos ax\sinh bx\right] \tag{116}$$

$$\int \cos ax \sinh bx dx = \frac{1}{a^2+b^2}\left[b\cos ax\cosh bx + a\sin ax\sinh bx\right] \tag{117}$$

$$\int \sin ax \cosh bx dx = \frac{1}{a^2+b^2}\left[-a\cos ax\cosh bx + b\sin ax\sinh bx\right] \tag{118}$$

$$\int \sin ax \sinh bx dx = \frac{1}{a^2+b^2}\left[b\cosh bx\sin ax - a\cos ax\sinh bx\right] \tag{119}$$

$$\int \sinh ax \cosh ax dx = \frac{1}{4a}\left[-2ax + \sinh 2ax\right] \tag{120}$$

$$\int \sinh ax \cosh bx dx = \frac{1}{b^2-a^2}\left[b\cosh bx\sinh ax - a\cosh ax\sinh bx\right] \tag{121}$$