

This diagram was created to the best of my knowledge, but I do not take any responsibility for potential damage or malfunctions. Do not rely 100% on this diagram - always verify your wiring independently!

- **Boards from [printed-droid.com](#):** The blue-highlighted boxes represent boards from [printed-droid.com](#). Where possible, I have included the specific board revision I used. Please compare carefully with your versions - different revisions may require different wiring (have a look in the [files section](#) ☺)
- **Not all wires are shown:** Standard connections, such as power/ground/signal for servos, are not explicitly drawn. For Teecore boards, please refer to the [official documentation](#).
- **Wire gauge selection:** The wire gauge used in this diagram was chosen for my setup. Depending on your configuration, different wire sizes may be required.
- **Connections & jumpers:** Not all available connections or jumper settings of the boards are included in the diagram. Further details can be found at [printed-droid.com](#) ☺ and [nextgenstomchek.net](#).

- **Power supply & polarity:** Make sure to use the correct voltage for your components and avoid reversing polarity. Incorrect power connections can damage your electronics.
- **Fuses & protection measures:** Depending on your power requirements, it may be advisable to include fuses or protection circuits (e.g., PTC fuses) to prevent damage from overcurrent or short circuits. Some components, such as voltage regulators or motor drivers, may generate heat during operation. Ensure adequate cooling if necessary.
- **EMI & Interference:** Long or poorly shielded cables can cause interference. If you experience signal transmission issues, check your cable routing and consider using shielded wires.
- **Grounding & Noise:** Avoid ground loops, especially when using multiple boards and power sources. Improper grounding can lead to erratic behavior or signal issues.
- **Separate power circuits:** If your R2-D2 needs multiple independent power circuits (e.g., 5V for logic, 12V for motors), ensure they are properly isolated to prevent voltage drops or overvoltage damage.

