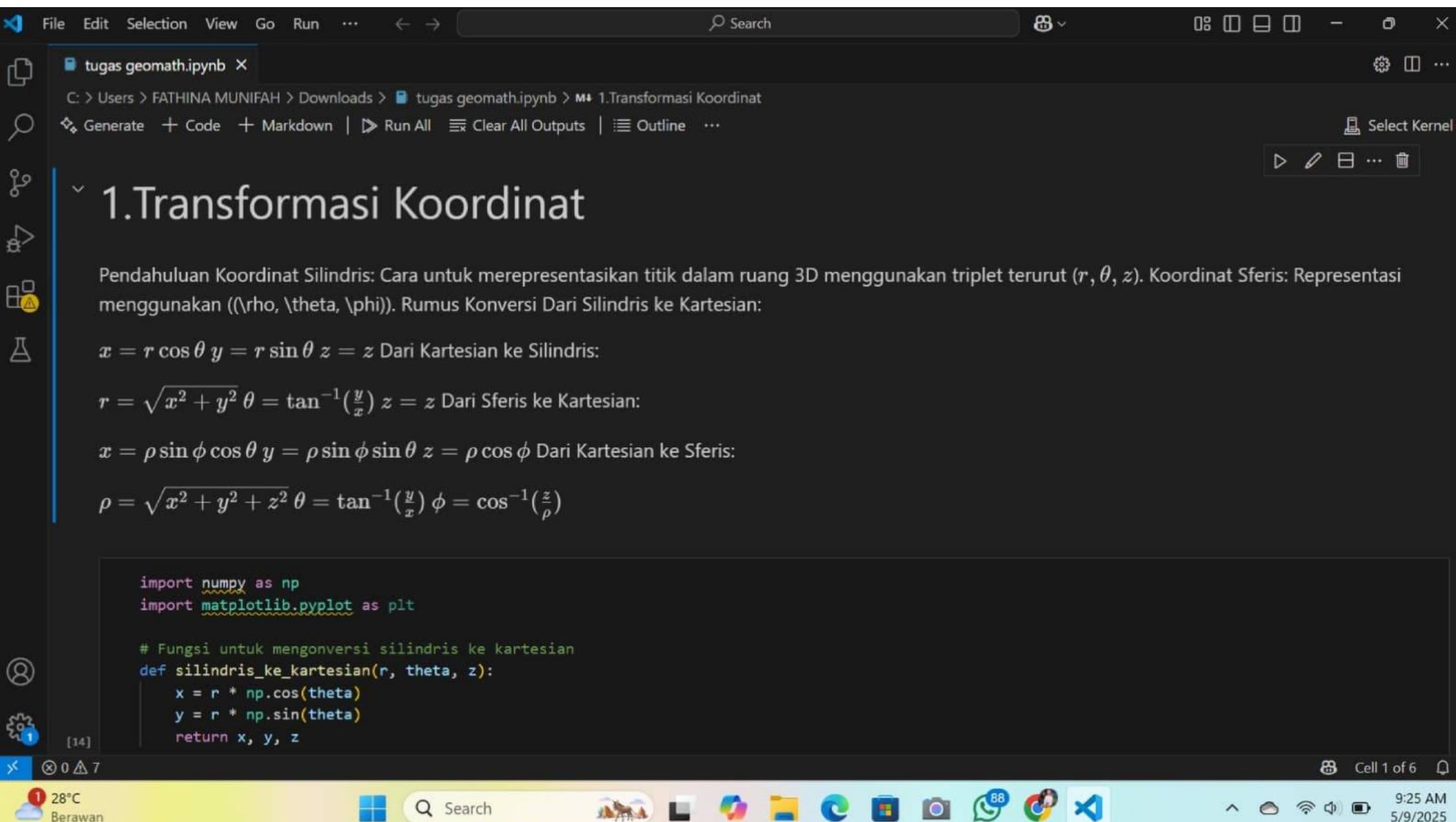


1. Fathina Munifah
2. Yasmine khairatun
3. Gladiva Warouw
4. Budi Triadi
5. Ilham Saputra
6. Afrizal



tugas geomath.ipynb X

C: > Users > FATHINA MUNIFAH > Downloads > tugas geomath.ipynb > 1.Transformasi Koordinat

Generate + Code + Markdown | Run All Clear All Outputs | Outline ...

Select Kernel

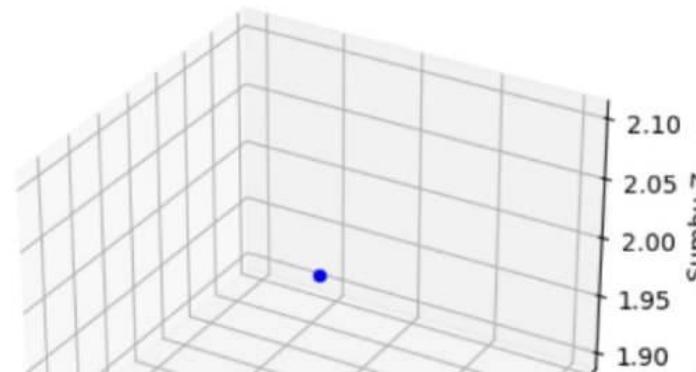
```
import numpy as np
import matplotlib.pyplot as plt

fig = plt.figure()
ax = fig.add_subplot(111, projection='3d')
ax.scatter(x, y, z, color='b')
ax.set_xlabel('Sumbu X')
ax.set_ylabel('Sumbu Y')
ax.set_zlabel('Sumbu Z')
plt.title('Koordinat Silindris')
plt.show()
```

[15]

Python

Koordinat Silindris



...



X 0 ▲ 7

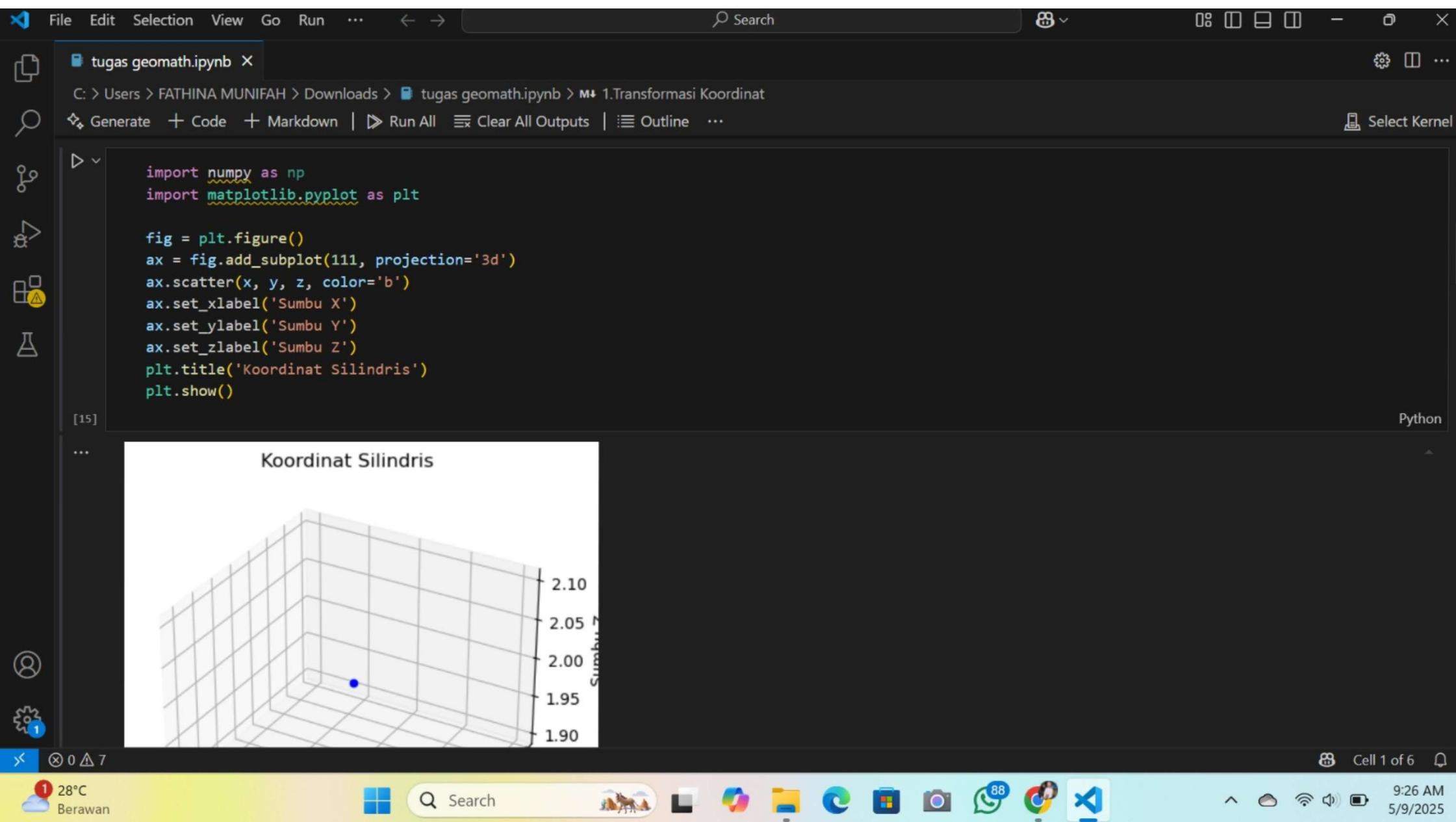
1 28°C
Berawan

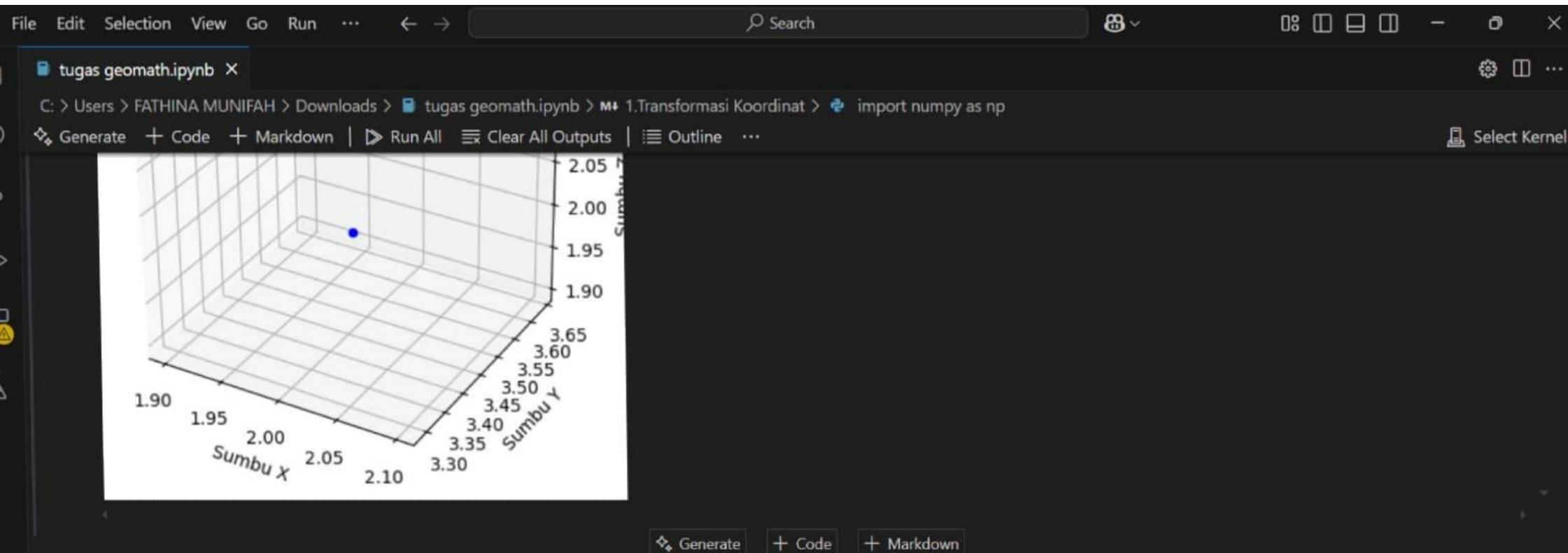


Search



9:26 AM
5/9/2025



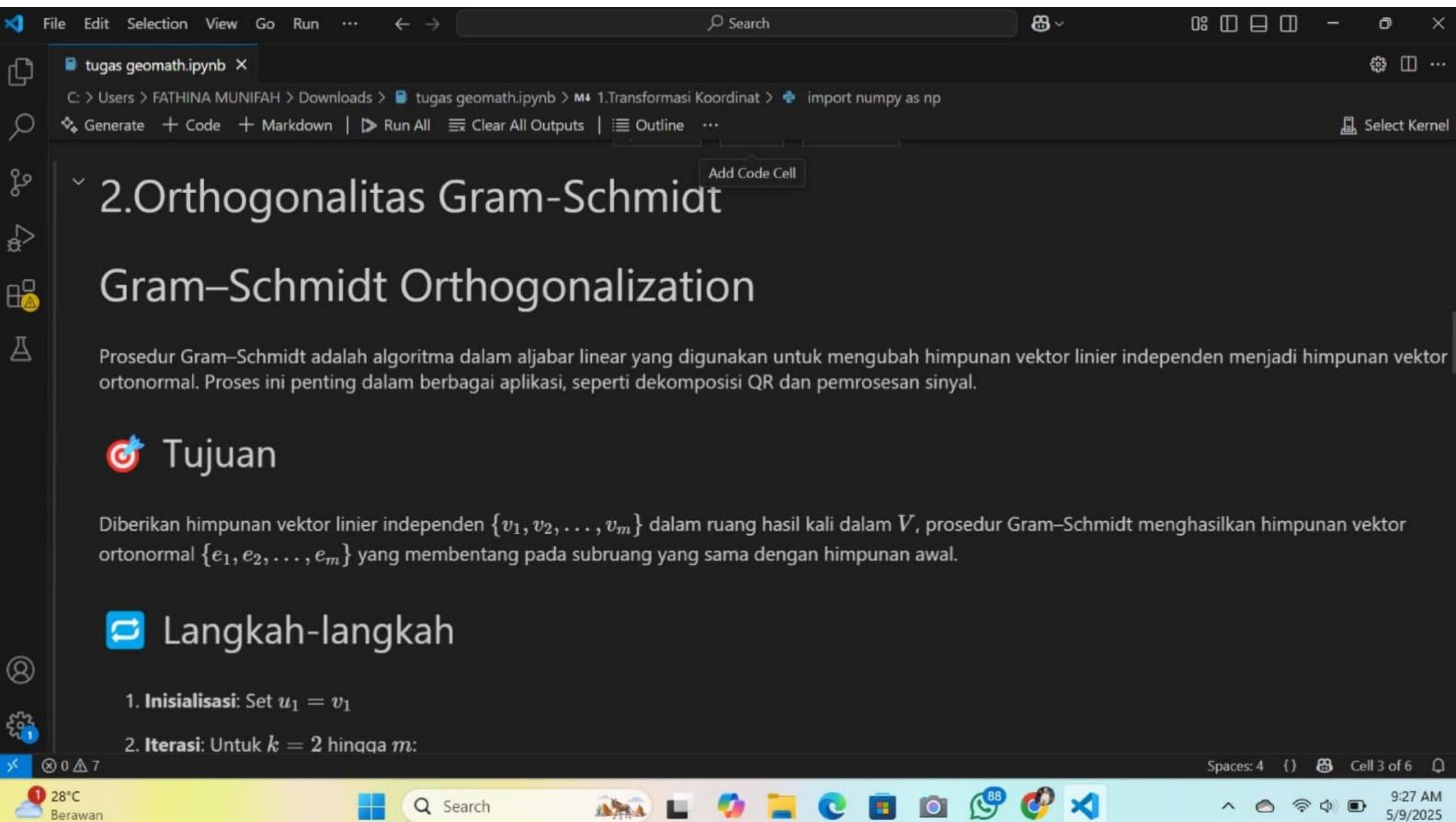


2. Orthogonalitas Gram-Schmidt

Gram-Schmidt Orthogonalization

Prosedur Gram-Schmidt adalah algoritma dalam aljabar linear yang digunakan untuk mengubah himpunan vektor linier independen menjadi himpunan vektor ortonormal. Proses ini penting dalam berbagai aplikasi, seperti dekomposisi QR dan pemrosesan sinyal.

Spaces: 4 { } Cell 3 of 6



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tugas geomath.ipynb X

C: > Users > FATHINA MUNIFAH > Downloads > tugas geomath.ipynb > 1.Transformasi Koordinat > import numpy as np

Generate + Code + Markdown | Run All Clear All Outputs | Outline ... Select Kernel

Langkah-langkah

- Inisialisasi:** Set $u_1 = v_1$
- Iterasi:** Untuk $k = 2$ hingga m :
 - Hitung proyeksi v_k ke setiap u_j sebelumnya:
$$\text{proj}_{u_j}(v_k) = \frac{\langle v_k, u_j \rangle}{\langle u_j, u_j \rangle} u_j$$
 - Kurangi semua proyeksi dari v_k untuk mendapatkan u_k :
$$u_k = v_k - \sum_{j=1}^{k-1} \text{proj}_{u_j}(v_k)$$
- Normalisasi:** Untuk setiap u_k , hitung:

$$e_k = \frac{u_k}{\|u_k\|}$$

Hasilnya adalah himpunan $\{e_1, e_2, \dots, e_m\}$ yang ortonormal dan membentang pada subruang yang sama dengan himpunan awal.

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1 28°C Berawan

Search

9:27 AM 5/9/2025

The screenshot shows a Jupyter Notebook interface with the following details:

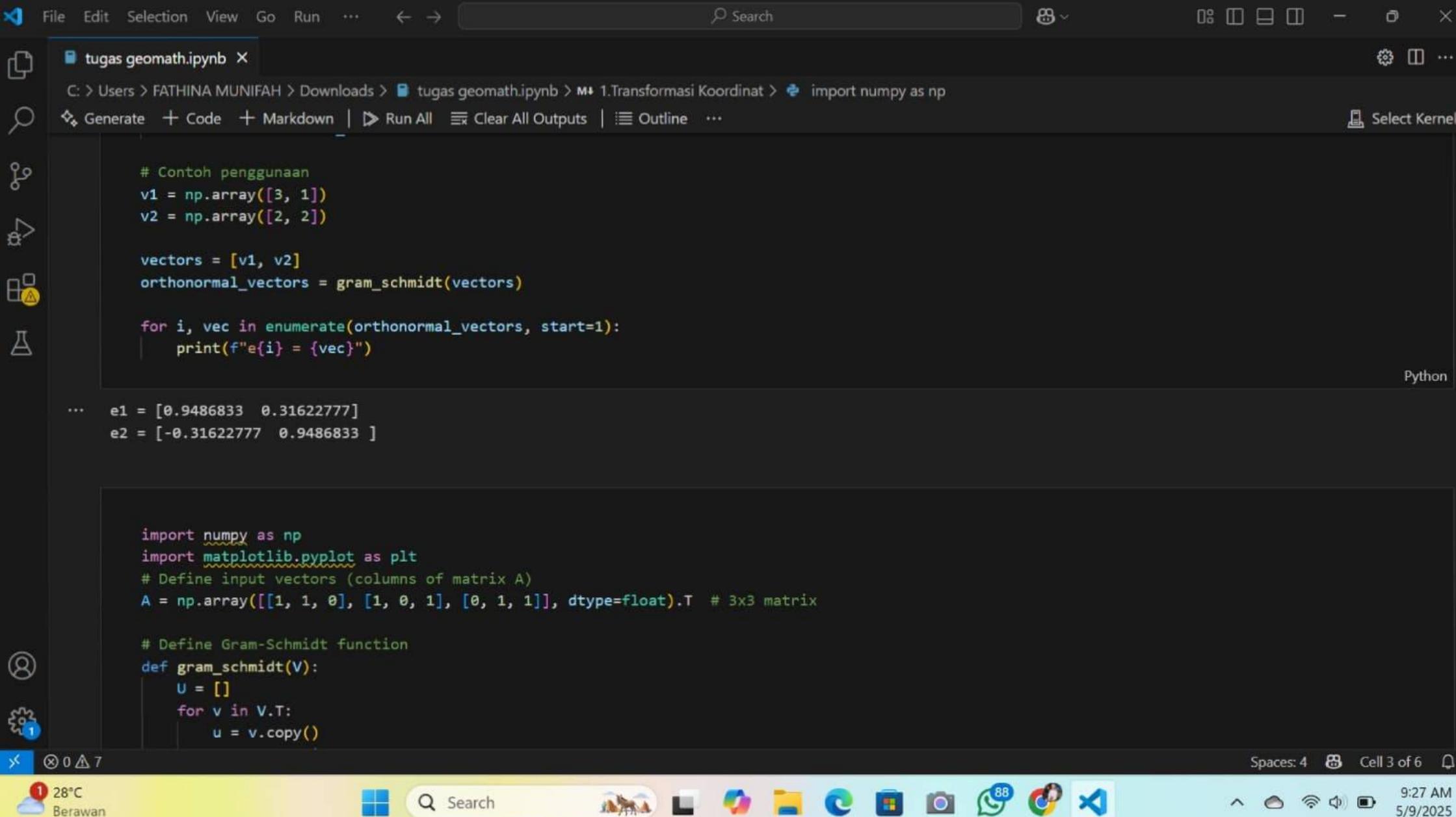
- File Bar:** File, Edit, Selection, View, Go, Run, ...
- Search Bar:** Search
- Toolbar Icons:** Copy, Paste, Find, Select Kernel, etc.
- Path Bar:** C: > Users > FATHINA MUNIFAH > Downloads > tugas geomath.ipynb > 1.Transformasi Koordinat > import numpy as np
- Cell Buttons:** Generate, Code, Markdown, Run All, Clear All Outputs, Outline, ...
- Code Content:**

```
import numpy as np

def gram_schmidt(vectors):
    """
    Melakukan orthonormalisasi Gram-Schmidt pada himpunan vektor.
    """
    orthonormal_basis = []
    for v in vectors:
        w = v.copy()
        for u in orthonormal_basis:
            proj = np.dot(w, u) * u
            w = w - proj
        norm = np.linalg.norm(w)
        if norm < 1e-10:
            raise ValueError("Vektor linier dependen terdeteksi.")
        u = w / norm
        orthonormal_basis.append(u)
    return orthonormal_basis

# Contoh penggunaan
v1 = np.array([3, 1])
v2 = np.array([2, 2])

vectors = [v1, v2]
orthonormal_vectors = gram_schmidt(vectors)
```
- Bottom Status Bar:** Spaces: 4, Cell 3 of 6, 9:27 AM, 5/9/2025
- System Icons:** Weather (28°C), Taskbar icons (Search, File Explorer, Edge, Camera, Chat, Google Chrome, File Explorer), and Network/Power status.



```
import numpy as np
import matplotlib.pyplot as plt
# Define input vectors (columns of matrix A)
A = np.array([[1, 1, 0], [1, 0, 1], [0, 1, 1]], dtype=float).T # 3x3 matrix

# Define Gram-Schmidt function
def gram_schmidt(V):
    U = []
    for v in V.T:
        u = v.copy()
        for prev_u in U:
            proj = np.dot(u, prev_u) / np.dot(prev_u, prev_u) * prev_u
            u = u - proj
        U.append(u)
    return np.column_stack(U)

# Apply Gram-Schmidt process
orthogonal_vectors = gram_schmidt(A)

# Display original and orthogonalized vectors
print("Original Vectors (columns):\n", A)
print("\nOrthogonalized Vectors (columns):\n", orthogonal_vectors)

# Visualize in 3D
fig = plt.figure(figsize=(8, 6))
ax = fig.add_subplot(111, projection='3d')
```

```
# Visualize in 3D
fig = plt.figure(figsize=(8, 6))
ax = fig.add_subplot(111, projection='3d')

origin = np.zeros(3)
colors = ['r', 'g', 'b']

for i in range(3):
    ax.quiver(*origin, *A[:, i], color=colors[i], label=f'Original v{i+1}', alpha=0.5)
    ax.quiver(*origin, *orthogonal_vectors[:, i], color=colors[i], linestyle='dashed', label=f'Ortho u{i+1}')

ax.set_xlim([-2, 2])
ax.set_ylim([-2, 2])
ax.set_zlim([-2, 2])
ax.set_xlabel('X')
ax.set_ylabel('Y')
ax.set_zlabel('Z')
ax.set_title('Gram-Schmidt Orthogonalization')
ax.legend()
plt.show()
```

Python

Original Vectors (columns):

```
[[1. 1. 0.]
 [1. 0. 1.]
 [0. 1. 1.]]
```

Spaces: 4 ⚙ Cell 3 of 6 ⌂

```
import numpy as np

def gram_schmidt(vectors):
    """
    Melakukan ortogonalisasi Gram-Schmidt pada himpunan vektor.
    """
    orthonormal_basis = []
    for v in vectors:
        w = v.copy()
        for u in orthonormal_basis:
            proj = np.dot(w, u) * u
            w = w - proj
        norm = np.linalg.norm(w)
        if norm < 1e-10:
            raise ValueError("Vektor linier dependen terdeteksi.")
        u = w / norm
        orthonormal_basis.append(u)
    return orthonormal_basis

# Contoh penggunaan
v1 = np.array([3, 1])
v2 = np.array([2, 2])

vectors = [v1, v2]
orthonormal_vectors = gram_schmidt(vectors)
```

A screenshot of a Jupyter Notebook interface. The top bar includes standard menu items like File, Edit, Selection, View, Go, Run, and a search bar. Below the menu is a toolbar with icons for file operations, a progress bar, and window controls. The main area shows a code cell titled "tugas geomath.ipynb". The code uses NumPy to demonstrate the Gram-Schmidt process. It defines two vectors, v1 and v2, and then generates orthonormal vectors e1 and e2. A second code cell below defines a function for the Gram-Schmidt process and applies it to a matrix A.

```
# Contoh penggunaan
v1 = np.array([3, 1])
v2 = np.array([2, 2])

vectors = [v1, v2]
orthonormal_vectors = gram_schmidt(vectors)

for i, vec in enumerate(orthonormal_vectors, start=1):
    print(f"e{i} = {vec}")

...
e1 = [0.9486833  0.31622777]
e2 = [-0.31622777  0.9486833 ]
```

```
import numpy as np
import matplotlib.pyplot as plt
# Define input vectors (columns of matrix A)
A = np.array([[1, 1, 0], [1, 0, 1], [0, 1, 1]], dtype=float).T # 3x3 matrix

# Define Gram-Schmidt function
def gram_schmidt(V):
    U = []
    for v in V.T:
        u = v.copy()
```

Spaces: 4 Cell 3 of 6

```
import numpy as np
import matplotlib.pyplot as plt
# Define input vectors (columns of matrix A)
A = np.array([[1, 1, 0], [1, 0, 1], [0, 1, 1]], dtype=float).T # 3x3 matrix

# Define Gram-Schmidt function
def gram_schmidt(V):
    U = []
    for v in V.T:
        u = v.copy()
        for prev_u in U:
            proj = np.dot(u, prev_u) / np.dot(prev_u, prev_u) * prev_u
            u = u - proj
        U.append(u)
    return np.column_stack(U)

# Apply Gram-Schmidt process
orthogonal_vectors = gram_schmidt(A)

# Display original and orthogonalized vectors
print("Original Vectors (columns):\n", A)
print("\nOrthogonalized Vectors (columns):\n", orthogonal_vectors)

# Visualize in 3D
fig = plt.figure(figsize=(8, 6))
ax = fig.add_subplot(111, projection='3d')
```

```
# Visualize in 3D
fig = plt.figure(figsize=(8, 6))
ax = fig.add_subplot(111, projection='3d')

origin = np.zeros(3)
colors = ['r', 'g', 'b']

for i in range(3):
    ax.quiver(*origin, *A[:, i], color=colors[i], label=f'Original v{i+1}', alpha=0.5)
    ax.quiver(*origin, *orthogonal_vectors[:, i], color=colors[i], linestyle='dashed', label=f'Ortho u{i+1}')

ax.set_xlim([-2, 2])
ax.set_ylim([-2, 2])
ax.set_zlim([-2, 2])
ax.set_xlabel('X')
ax.set_ylabel('Y')
ax.set_zlabel('Z')
ax.set_title('Gram-Schmidt Orthogonalization')
ax.legend()
plt.show()
```

Python

Original Vectors (columns):

```
[[1. 1. 0.]
 [1. 0. 1.]
 [0. 1. 1.]]
```

Spaces: 4 ⚙ Cell 3 of 6 ⌂

```
# Visualize in 3D
fig = plt.figure(figsize=(8, 6))
ax = fig.add_subplot(111, projection='3d')

origin = np.zeros(3)
colors = ['r', 'g', 'b']

for i in range(3):
    ax.quiver(*origin, *A[:, i], color=colors[i], label=f'Original v{i+1}', alpha=0.5)
    ax.quiver(*origin, *orthogonal_vectors[:, i], color=colors[i], linestyle='dashed', label=f'Ortho u{i+1}')

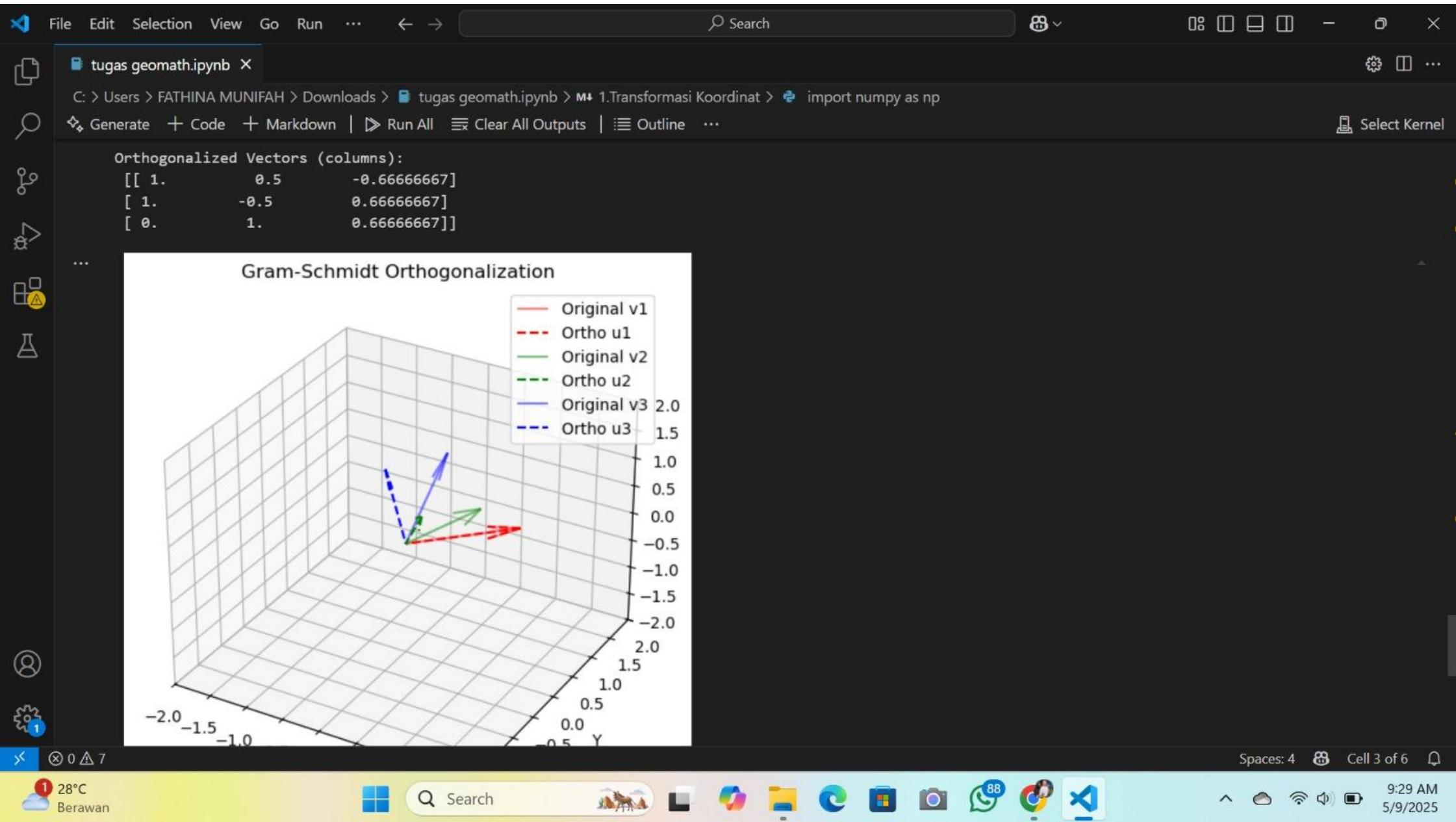
ax.set_xlim([-2, 2])
ax.set_ylim([-2, 2])
ax.set_zlim([-2, 2])
ax.set_xlabel('X')
ax.set_ylabel('Y')
ax.set_zlabel('Z')
ax.set_title('Gram-Schmidt Orthogonalization')
ax.legend()
plt.show()
```

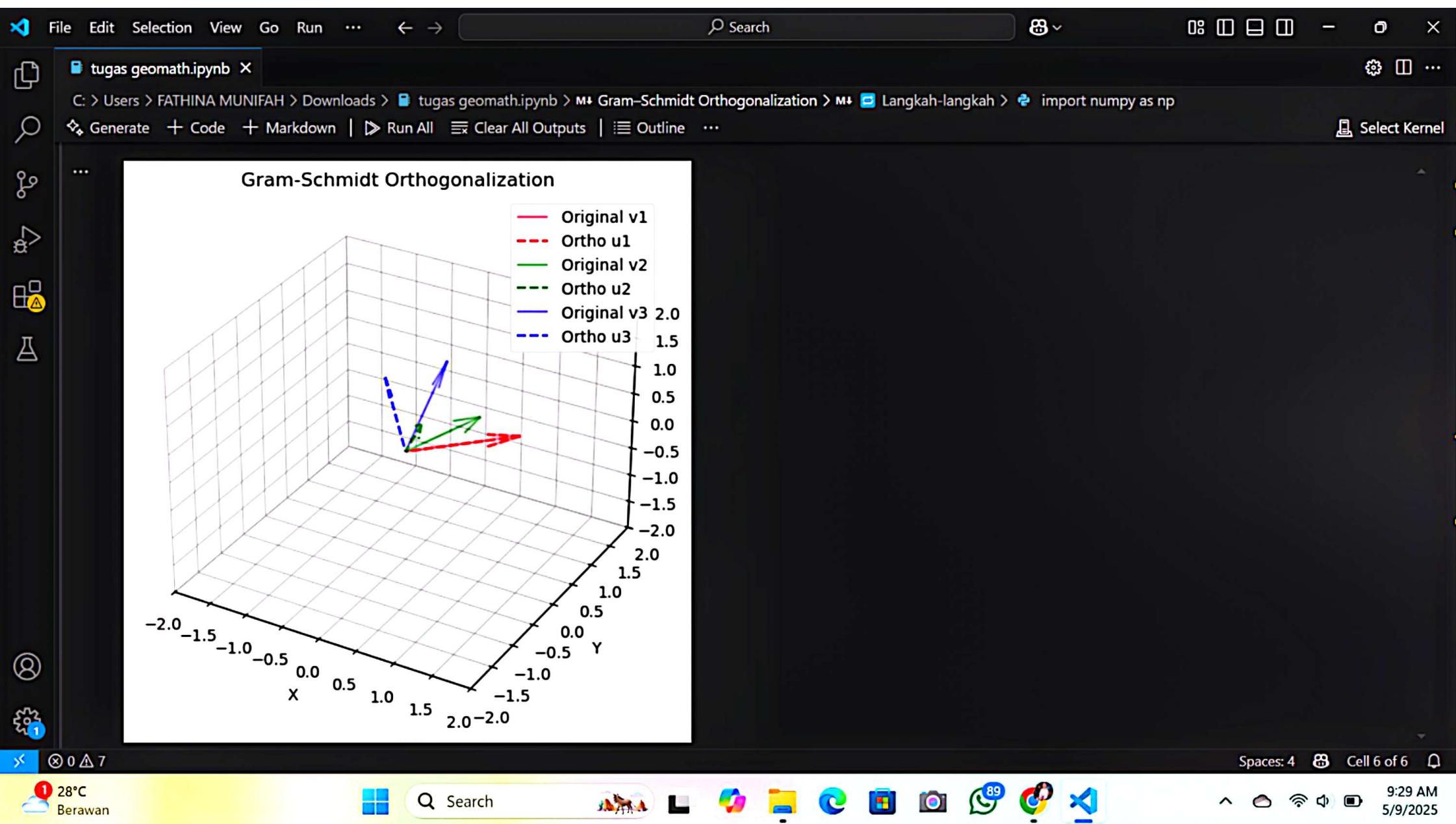
Python

Original Vectors (columns):

```
[[1. 1. 0.]
 [1. 0. 1.]
 [0. 1. 1.]]
```

Spaces: 4 ⚙ Cell 3 of 6 ⌂





EXERCISE 114

2. $\begin{pmatrix} 3 & 6 \\ 1 & 4 \end{pmatrix}$

Jawab

Mencari Eigenvalues

$$\left| A - \lambda I \right| = 0$$

$$\begin{vmatrix} 3 - \lambda & 6 \\ 1 & 4 - \lambda \end{vmatrix} = (3 - \lambda)(4 - \lambda) - 6(1)$$

$$= (12 - 3\lambda - 4\lambda + \lambda^2) - 6 = \lambda^2 - 7\lambda + 6 = 0$$

$$(\lambda - 6)(\lambda - 1) = 0$$

$$\lambda_1 = 6$$

$$\lambda_2 = 1$$

Mencari Eigenvector

8. untuk $\lambda = 6$

Subtitusi ke $(A - 6I)$

$$\begin{pmatrix} -3 & 6 \\ 1 & -2 \end{pmatrix} \quad -3x + 6y = 0 \Rightarrow x = 2y$$

$$\text{Eigenvector: } \begin{pmatrix} 2 \\ 1 \end{pmatrix}$$

tan $\lambda = 1$

$$(A - I) = \begin{pmatrix} 2 & 6 \\ 1 & 3 \end{pmatrix}$$

$$2x + 6y = 0 \rightarrow x = -3$$

$$y = 1, \quad x = -3$$

$$\text{eigenvector : } \begin{pmatrix} -3 \\ 1 \end{pmatrix}$$

File Edit Selection View Go Run ... ← → 🔍 geomath 🌐

EXPLORER ... OPEN EDITORS 1 unsaved tugas.ipynb • tugas.ipynb > M+ Exercise 114 > M+ Soal Nomor 2 Generate + Code + Markdown | Run All Restart Clear All Outputs Jupyter Variables Outline ... geomath (Python 3.13.2) ▶ ✎ ⚡ ⚡ ⚡

GEOMATH
geomath
helloworld.ipynb
sinh_cosh_plot.png
tugas.ipynb
UTS GEOMATH.ipynb
uts.ipynb

Soal Nomor 2

Tentukan nilai eigen dan vektor eigen dari matriks berikut:

[

]

$$\begin{pmatrix} 3 & 6 \\ 1 & 4 \end{pmatrix}$$

```
import numpy as np

A2 = np.array([[3, 6], [1, 4]])
vals2, vecs2 = np.linalg.eig(A2)
print(vals2)
print(vecs2)
```

[3] ✓ 0.0s

[1. 6.]
[[-0.9486833 -0.89442719]
[0.31622777 -0.4472136]]

Python

OUTLINE
TIMELINE
X 0 ⚡ 0 27°C Berawan

Spaces: 4 🌐 Cell 17 of 21 9:28 PM

Tugas Geomatika25.5 Eigenvalues and eigenvectorspractice Exercise 114

For each of the following matrices, determine their (a) eigenvalues
 (b) eigenvectors

$$3.) \begin{pmatrix} 3 & 1 \\ -2 & 0 \end{pmatrix}$$

$$7.) \begin{pmatrix} 1 & 1 & 2 \\ 0 & 2 & 2 \\ -1 & 1 & 3 \end{pmatrix}$$

Answer

$$3.) \begin{pmatrix} 3 & 1 \\ -2 & 0 \end{pmatrix} \cdot \text{eigenvalue } (\lambda) \quad \det(A - \lambda I) = 0 \quad \text{Pers. Kharakteristk}$$

$$A - \lambda I = \begin{bmatrix} 3 - \lambda & 1 \\ -2 & -\lambda \end{bmatrix}$$

$$\det(A - \lambda I) = (3 - \lambda)(-\lambda) - (-2)(1) = -3\lambda + \lambda^2 + 2$$

• eigenvektor

$$\lambda = 1$$

$$(A - 1)\vec{v} = 0$$

$$\begin{bmatrix} 3-1 & 1 \\ -2 & 0-1 \end{bmatrix} = \begin{bmatrix} 2 & 1 \\ -2 & -1 \end{bmatrix}$$

$$= \lambda^2 - 3\lambda + 2 = 0$$

$$= (\lambda-1)(\lambda-2) = 0$$

$$\lambda_1 = 1 \quad \lambda_2 = 2$$

$$2x + y = 0 \rightarrow y = -2x \quad * \lambda = 2$$

$$\vec{v}_1 = \begin{bmatrix} 1 \\ -2 \end{bmatrix}$$

$$A - 2I = \begin{bmatrix} 1 & 1 \\ -2 & -2 \end{bmatrix}$$

$$x + y = 0 \rightarrow y = -x$$

$$\vec{v}_2 = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

EXERCISE 114 NOMOR 3

```
import numpy as np

# Definisikan matriks
A = np.array([[3, 1], [-2, 0]])

# Hitung eigenvalues dan eigenvectors
eigenvalues, eigenvectors = np.linalg.eig(A)

print("Eigenvalues:")
print(eigenvalues)
print("\nEigenvectors:")
print(eigenvectors)
```

[2]

✓ 0.0s

...

Eigenvalues:

[2. 1.]

Eigenvectors:

[[0.70710678 -0.4472136]
[-0.70710678 0.89442719]]

5. a. $A = \begin{pmatrix} 1 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 1 \end{pmatrix}$

$$|A - \lambda I| = 0$$

$$= \begin{vmatrix} 1-\lambda & -1 & 0 \\ -1 & 2-\lambda & -1 \\ 0 & -1 & 1-\lambda \end{vmatrix}$$

$$= (1-\lambda) \begin{vmatrix} 2-\lambda & -1 \\ -1 & 1-\lambda \end{vmatrix} - (-1) \begin{vmatrix} -1 & -1 \\ 0 & 1-\lambda \end{vmatrix}$$

Minor pertama :

$$(2-\lambda)(1-\lambda) - (-1)(-1) = (\lambda^2 - 3\lambda + 1)$$

Minor kedua :

$$(-1)(1-\lambda) = -(1-\lambda)$$

Maka :

$$(1-\lambda)(\lambda^2 - 3\lambda + 1) + (1-\lambda) = (1-\lambda)(\lambda^2 - 3\lambda + 2)$$

$$= (1-\lambda)(\lambda-2)(\lambda-1)$$

Jadi $\lambda = 0$

$$\lambda = 1$$

$$\lambda = 3$$

mencari Eigenvector

$$\lambda = 0$$

$$A = \begin{pmatrix} 1 & -1 & 0 \\ -2 & 2 & -1 \\ 0 & -1 & 1 \end{pmatrix}$$

- $x - y = 0 \rightarrow x = y$
- $-x + 2y - z = 0$
- $-y + z = 0 \rightarrow z = y$

$$y = 1$$

Eigenvector: $\begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$

$$\lambda = 1$$

$$(A - I) = \begin{pmatrix} 0 & -1 & 0 \\ -1 & 1 & -1 \\ 0 & -1 & 0 \end{pmatrix}$$

$$-y = 0 \rightarrow y = 0$$

$$-x - z = 0 \rightarrow z = -x$$

Eigenvector $\begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix}$

$$\lambda = 3$$

$$(A - 3I) = \begin{pmatrix} -2 & -1 & 0 \\ -1 & -1 & -1 \\ 0 & -1 & -2 \end{pmatrix}$$

$$-2x - y = 0 \rightarrow y = -2x$$

$$-x - y - z = 0$$

Eigenvector:

$$-x + 2x - z = 0 \rightarrow z = x$$

$$x = 1$$

$$\begin{pmatrix} 1 \\ -2 \\ 1 \end{pmatrix}$$

File Edit Selection View Go Run ... 🔍 geomath ⚡ 0:00 0:00 - ⚡ ... EXPLORER tugas.ipynb • OPEN EDITORS 1 unsaved tugas.ipynb > Exercise 114 > Soal Nomor 2 Generate + Code + Markdown | Run All Restart Clear All Outputs Jupyter Variables Outline ... geomath (Python 3.13.2)

GEOMATH

> geomath
helloworld.ipynb
sinh_cosh_plot.png
tugas.ipynb
UTS GEOMATH.ipynb
uts.ipynb

Soal nomor 5

$$\begin{pmatrix} 1 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 1 \end{pmatrix}$$

```
import numpy as np

A5 = np.array([[1, -1, 0], [-1, 2, -1], [0, -1, 1]])
vals5, vecs5 = np.linalg.eig(A5)
print(vals5)
print(vecs5)
```

[2] ✓ 0.0s

... [3.0000000e+00 1.0000000e+00 -1.64111068e-16]
[[-4.08248290e-01 -7.07106781e-01 5.77350269e-01]
[8.16496581e-01 4.24983316e-16 5.77350269e-01]
[-4.08248290e-01 7.07106781e-01 5.77350269e-01]]

7. $\begin{vmatrix} 1 & 1 & 2 \\ 0 & 2 & 2 \\ -1 & 1 & 3 \end{vmatrix}$ • eigenvalue

$$\det(A - \lambda I) = 0$$

$$(A - \lambda I) = \begin{vmatrix} 1-\lambda & 1 & 2 \\ 0 & 2-\lambda & 2 \\ -1 & 1 & 3-\lambda \end{vmatrix}$$

$$\det(A - \lambda I) = \begin{vmatrix} 1-\lambda & 1 & 2 \\ 0 & 2-\lambda & 2 \\ -1 & 1 & 3-\lambda \end{vmatrix}$$

expandi baris pertama

$$= (1-\lambda) \begin{vmatrix} 2-\lambda & 2 \\ 1 & 3-\lambda \end{vmatrix} - (-1) \begin{vmatrix} 0 & 2 \\ 0 & 2-\lambda \end{vmatrix} + 1 \begin{vmatrix} 0 & 2 \\ -1 & 3-\lambda \end{vmatrix}$$

$$= (1-\lambda)(2-\lambda)(3-\lambda) - (2)(1) = (2-\lambda)(3-\lambda) - 2$$

$$= \begin{vmatrix} 0 & 2 \\ -1 & 3-\lambda \end{vmatrix} = 0(3-\lambda) - (2)(-1) = 2$$

$$= \begin{vmatrix} 0 & 2-\lambda \\ -1 & 1 \end{vmatrix} = 0(1) - (-1)(2-\lambda) = 2-\lambda$$

$$\det = (1-\lambda)[(2-\lambda)(3-\lambda) - 2] - 2 + 2(2-\lambda)$$

$$= (2-\lambda)(3-\lambda) = 6 - 5\lambda + \lambda^2$$

$$\det = (1-\lambda)(\lambda^2 - 5\lambda + 4) - 2 + 4 - 2\lambda$$

$$= (1-\lambda)(\lambda^2 - 5\lambda + 4) + 2 - 2\lambda$$

$$(1-\lambda)(\lambda^2 - 5\lambda + 4) = \lambda^2 - 5\lambda + 4 - \lambda^3 + 5\lambda^2 - 4\lambda -$$

$$= -\lambda^3 + 6\lambda^2 - 9\lambda + 4$$

$$-\lambda^3 + 6\lambda^2 - 9\lambda + 4 + 2 - 2\lambda = -\lambda^3 + 6\lambda^2 - 11\lambda + 6$$

$$\rightarrow -\lambda^3 + 6\lambda^2 - 11\lambda + 6 = 0 \text{ atau } \lambda^3 - 6\lambda^2 + 11\lambda - 6 = 0$$

faktorium $\lambda = 1$

$$1^3 - 6(1)^2 + 11(1) - 6 = 0$$

$$(\lambda-1)(\lambda^2-5\lambda+6) = 0 \rightarrow (\lambda-1)(\lambda-2)(\lambda-3) = 0$$

eigenvektor

* $\lambda = 1$

$$A - 1 \begin{bmatrix} 0 & 1 & 2 \\ 0 & 1 & 2 \\ -1 & 1 & 2 \end{bmatrix} \begin{array}{l} y + 2z = 0 \rightarrow y = -2z \\ -x + y + 2z = 0 \end{array}$$

$$y = -2z \Rightarrow -x - 2z + 2z = 0 \Rightarrow x = 0$$

$$\left| \begin{array}{lll} x = 0 & y = -2 & z = 1 \end{array} \right. \quad \vec{v}_1 = \begin{bmatrix} 0 \\ -2 \\ 1 \end{bmatrix}$$

* $\lambda = 2$

$$A - 2I = \begin{bmatrix} -1 & 1 & 2 \\ 0 & 0 & 2 \\ -1 & 1 & 1 \end{bmatrix} \begin{array}{l} -x + y + 2z = 0 \\ 2z = 0 \rightarrow z = 0 \\ -x + y = 0 \rightarrow x = y \end{array}$$

$$\left| \begin{array}{lll} x = 1 & y = 1 & z = 0 \end{array} \right. \quad \vec{v}_2 = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$$

* $\lambda = 3$

$$A - 3I = \begin{bmatrix} -2 & 1 & 2 \\ 0 & -1 & 2 \\ -1 & 1 & 0 \end{bmatrix} \begin{array}{l} -2x + y + 2z = 0 \\ -y + 2z = 0 \rightarrow y = 2z \\ -x + y = 0 \rightarrow y = x \end{array}$$

$$x = y = 2z \rightarrow x = 2z$$

$$\left| \begin{array}{lll} x = 2 & y = 2 & z = 1 \end{array} \right. \quad \vec{v}_3 = \begin{bmatrix} 2 \\ 2 \\ 1 \end{bmatrix}$$

EXERCISE 114 NOMOR 7



```
import numpy as np

# Definisikan matriks
A = np.array([[1, 1, 2], [0, 2, 2], [-1, 1, 3]])

# Hitung eigenvalues dan eigenvectors
eigenvalues, eigenvectors = np.linalg.eig(A)

print("Eigenvalues:")
print(eigenvalues)
print("\nEigenvectors:")
print(eigenvectors)
```

[6]

✓ 0.0s

...

Eigenvalues:

[3. 2. 1.]

Eigenvectors:

```
[[ 6.66666667e-01 -7.07106781e-01 -2.76850919e-16]
 [ 6.66666667e-01 -7.07106781e-01  8.94427191e-01]
 [ 3.33333333e-01 -1.12262114e-16 -4.47213595e-01]]
```