



# Machine Learning

## Session 3 - Clustering



hadrien.salem@centralelille.fr



[introduction-to-data-science](#)

# Introduction

What did we do last time?

# Course outline

## Machine learning course

Session 1: Regression

Session 2: Supervised classification

Session 3: Clustering

Session 4: Decision trees and ensemble methods

Session 5: Introduction to neural networks

Session 6: Advanced neural networks

Session 7: Introduction to reinforcement learning

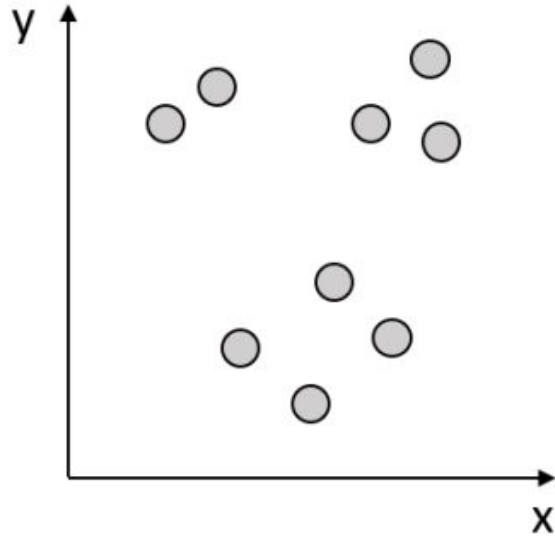
Session 8: Reading science papers



**Project**

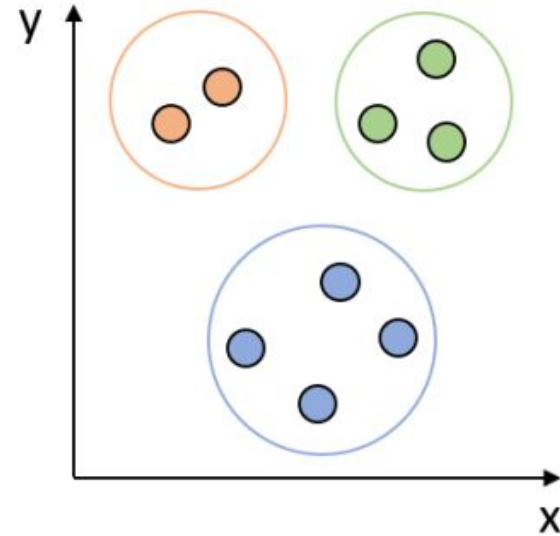
# What is clustering?

Original Data



Clustering

Clustered Data



Clustering is a machine learning task that consists in finding groups of similar data points

Clustering is a task consisting in grouping similar data points together without using predefined labels.

Clustering is equivalent to unsupervised classification

Data points in a group (or cluster) should be more similar to each other than to those in other groups



What are some  
concrete  
applications of  
clustering?



# What are some concrete applications of clustering?

## **Clustering can be used for...**

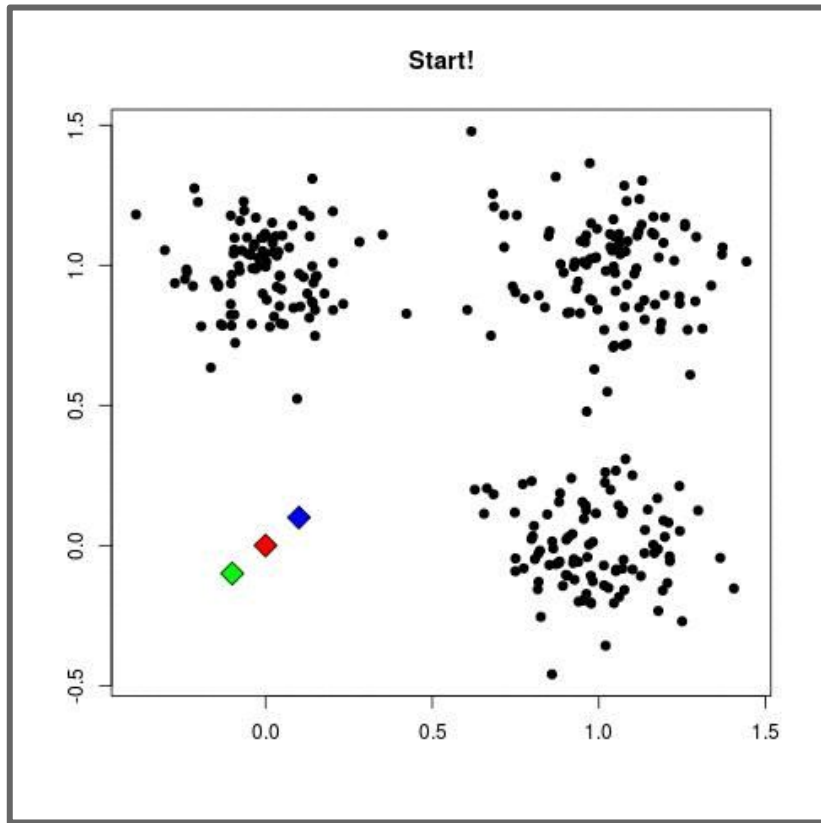
- Creating groups of similar customers (Market / Customer segmentation)
- Anomaly Detection
- Image segmentation
- Organizing collections of documents
- etc.

# Clustering methods

# Clustering algorithms family #1

## Partitional clustering

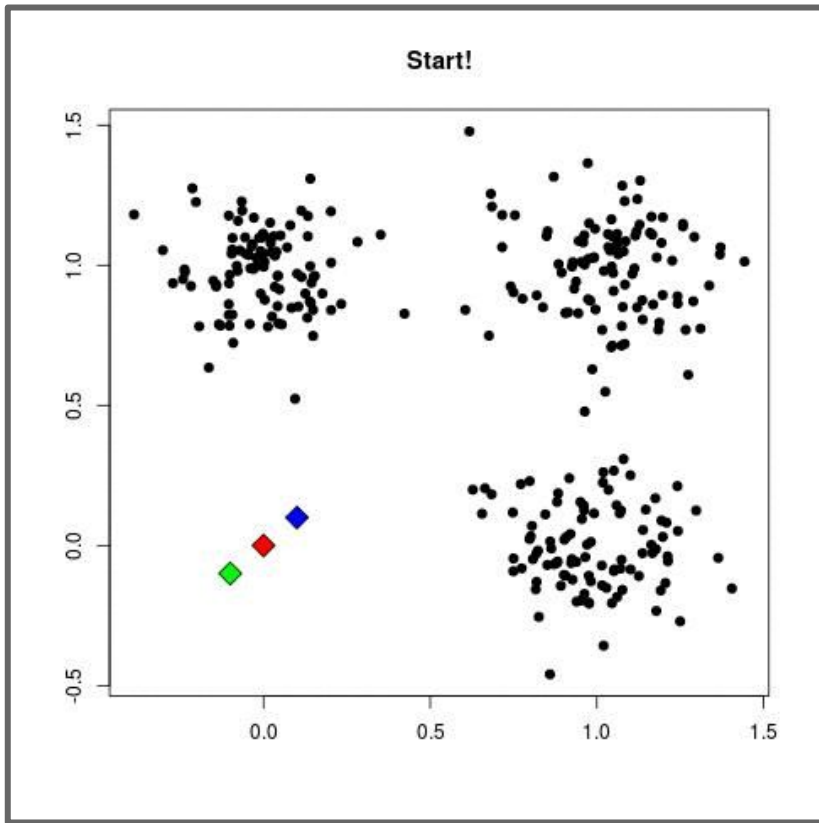
Partitional clustering divides the data into classes based on their similarity  
It requires specifying the number of clusters beforehand



### Procedure

1. Choose a value for K (number of clusters)
2. Select random cluster centers
3. Assign data points to clusters
4. Update cluster centers (mean of the cluster)
5. Repeat steps 3 and 4 until convergence

K-medoids is a variation of K-means where the cluster centers are actual data points.

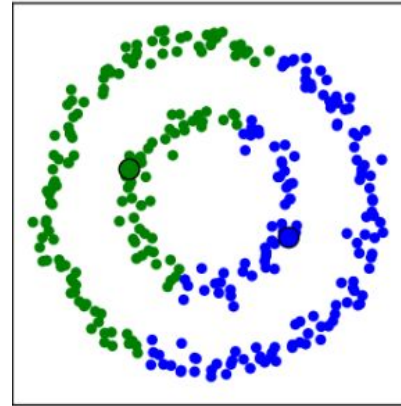


### Strengths

- Simple and fast
- K-medoids is more robust to outliers (no mean)

### Weaknesses

- Choosing K can be difficult
- Computing the mean is sensitive to outliers
- Clusters are assumed to be spherical and of similar sizes

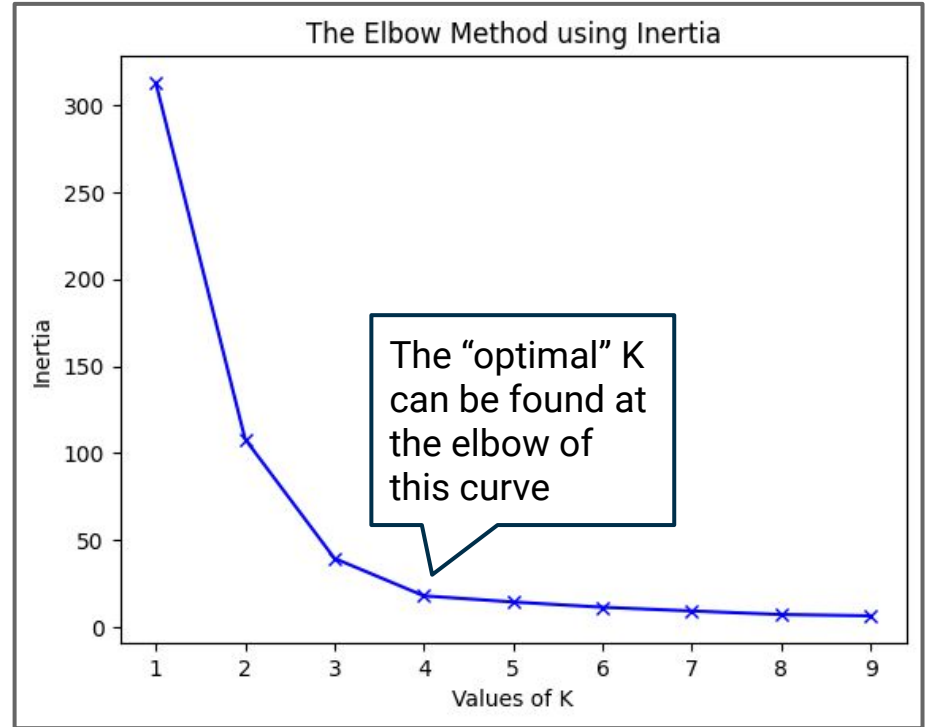


## Inertia

Sum of squared distances between data points and their assigned cluster center

Lower inertia means more compact clusters

**In general, it is difficult to evaluate the performance of clustering algorithms without external labels**



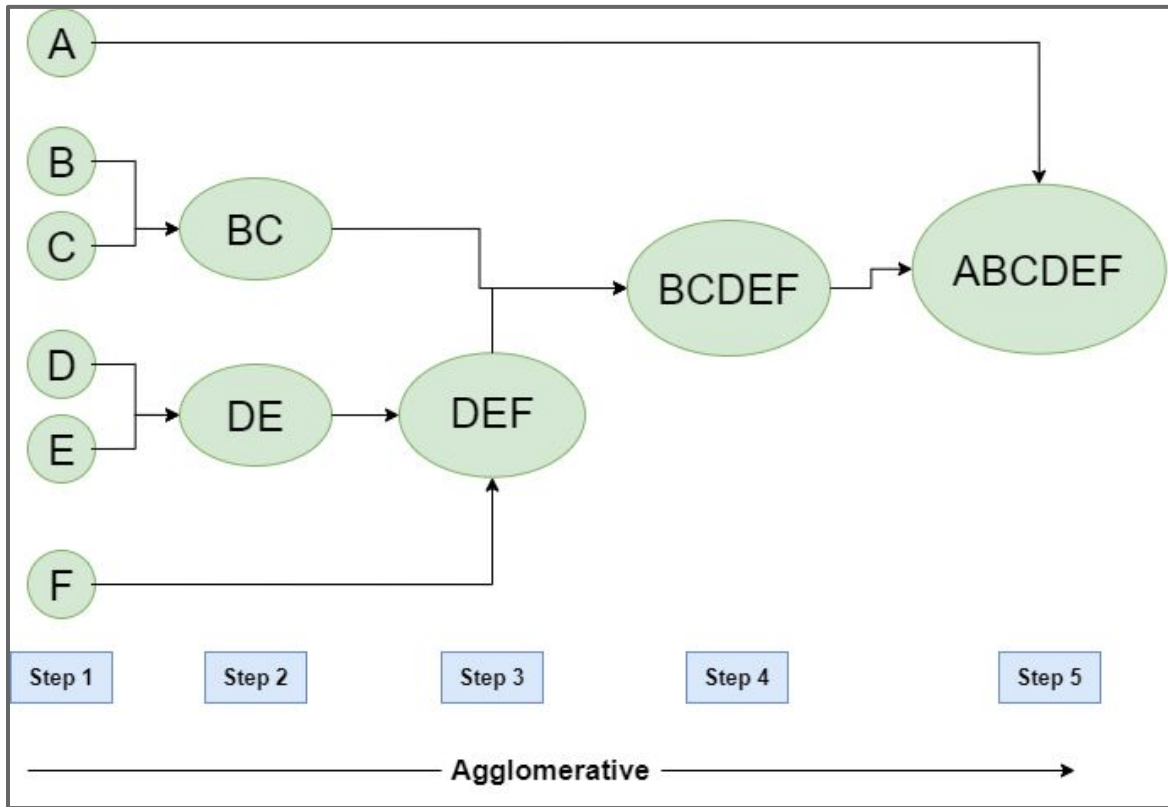
# Clustering algorithms family #2

## Hierarchical clustering

Hierarchical clustering consists in building a hierarchy of clusters by merging or dividing clusters

It does not require specifying the number of clusters beforehand

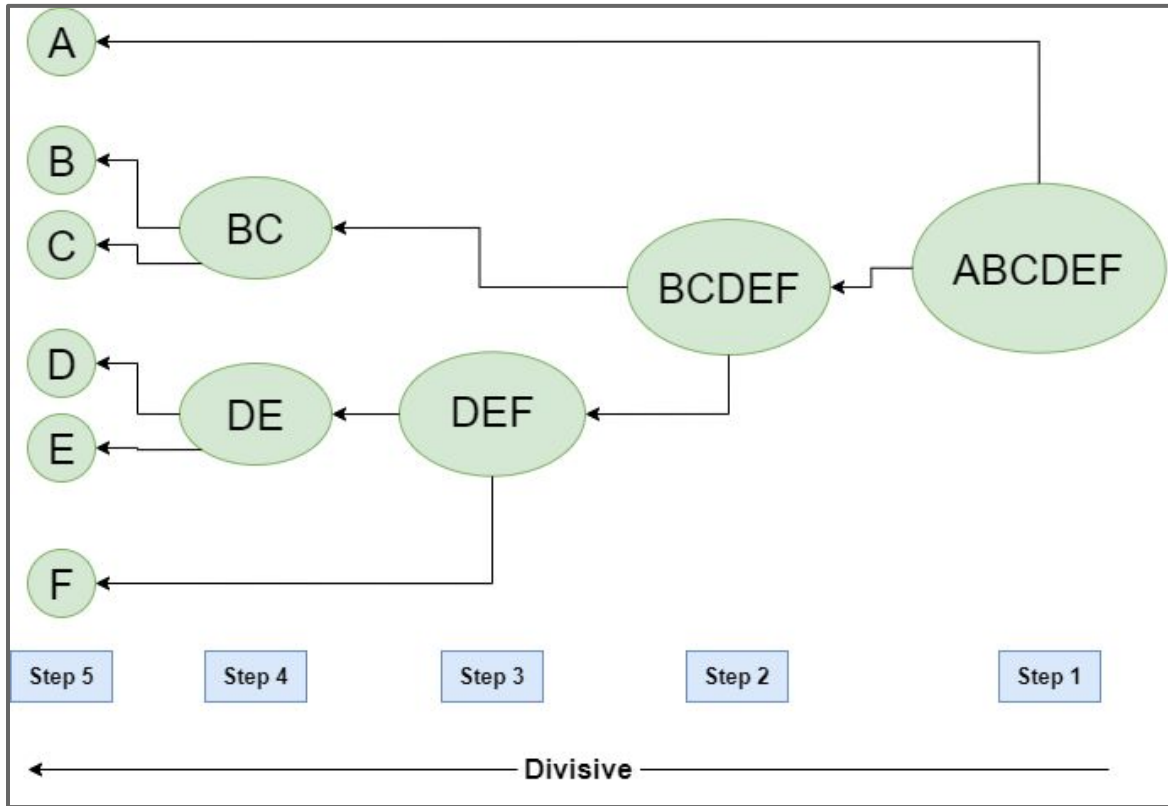




### Agglomerative clustering

1. Each data point starts as a single cluster
2. At each step, the “closest” clusters are merged together
3. Repeat until all data points are grouped into a single cluster

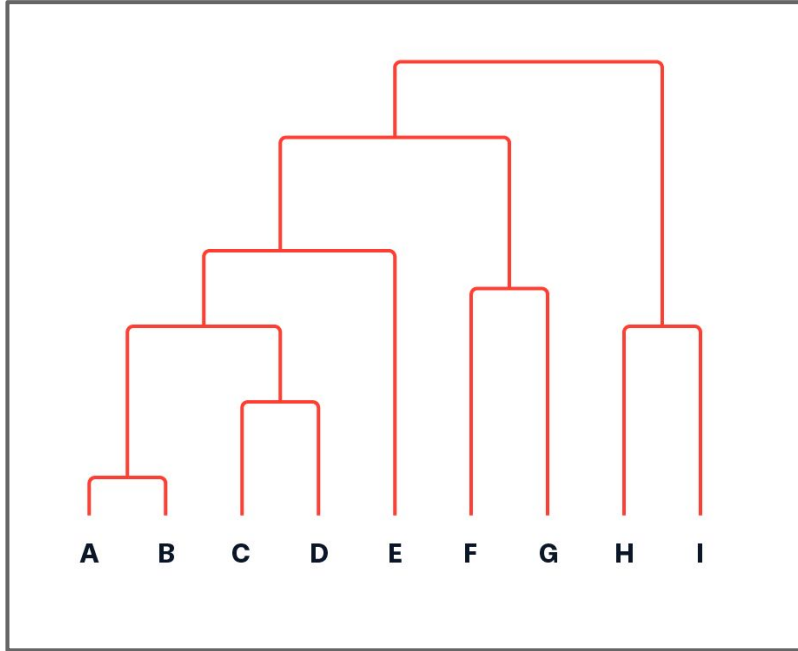
The number of clusters can be selected by choosing at what step the algorithm is stopped



### Agglomerative clustering

1. Start with a cluster containing all data points
2. At each step, the clusters are divided into two smaller clusters with a criteria to define
3. Repeat until all data points are single clusters

The number of clusters can be selected by choosing at what step the algorithm is stopped



### Strengths

- Can display a dendrogram for visualization
- Flexibility with the number of clusters
- Can adapt to nonlinear decision boundaries

### Weaknesses

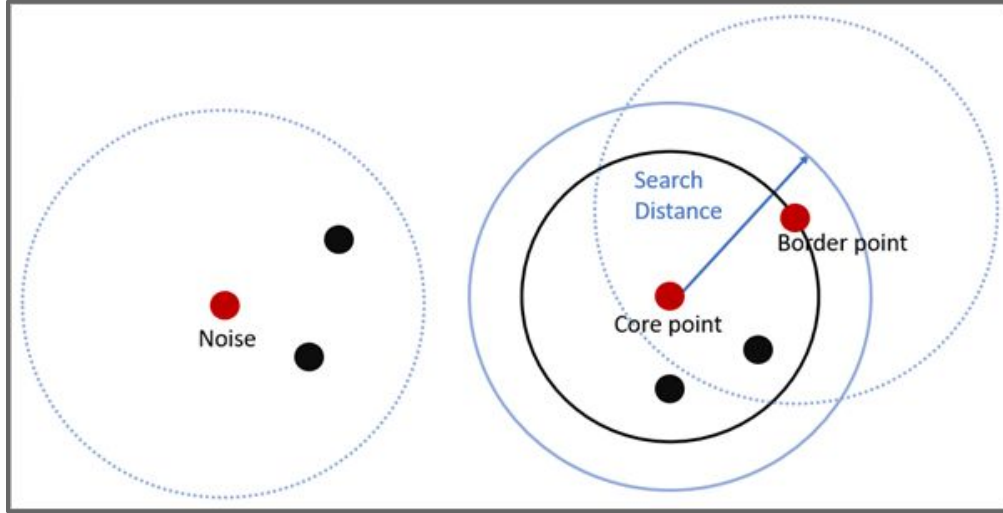
- Can be computationally expensive
- It can be difficult to choose the linking method
- Can be sensitive to outliers

# Clustering algorithms family #3

## Density-based clustering

Density-based clustering consists in grouping data points that are close to each other in areas of high density

It is well-suited for irregularly-shaped clusters

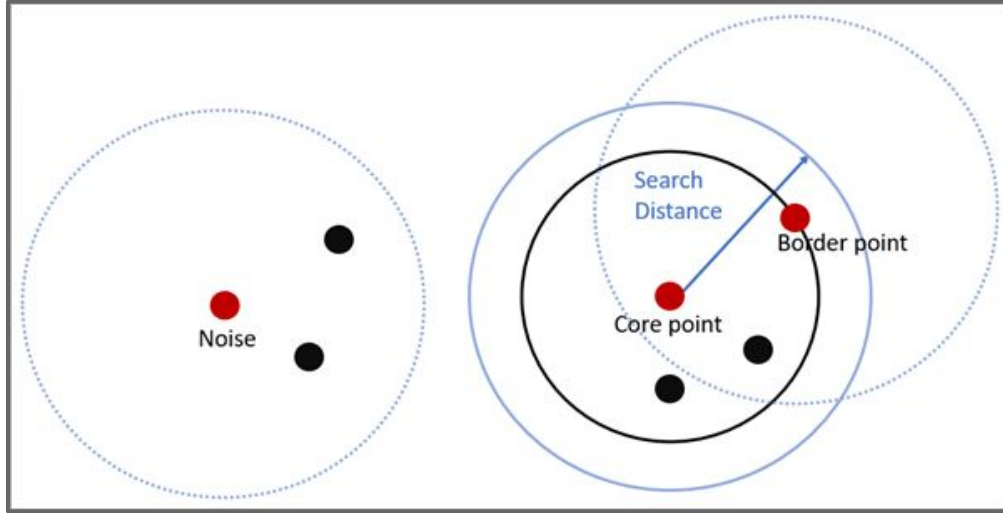


**DBSCAN is an example of density-based clustering algorithm**

**Core points** are the points that have a certain number of other data points within a pre-defined search distance

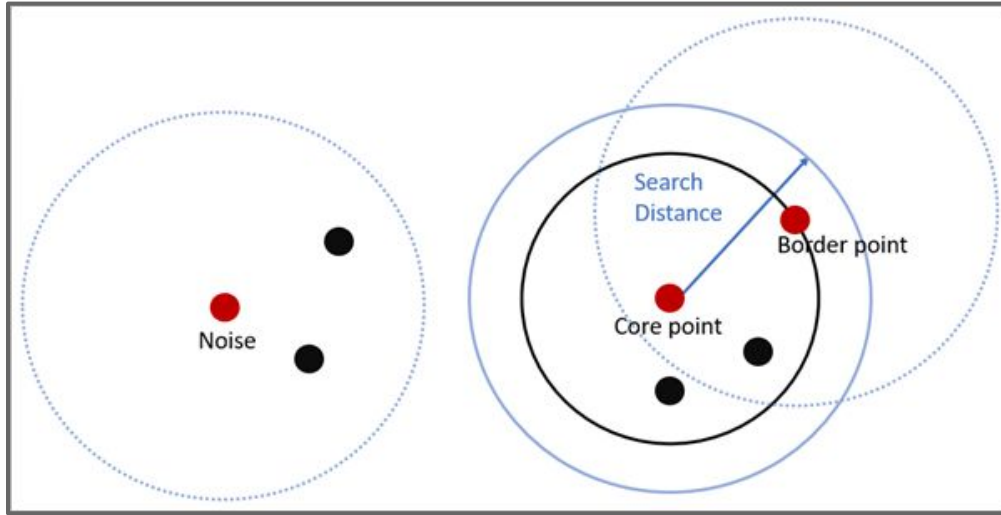
**Border points** are within the search distance of a core point, but does not have enough neighbours to be considered a core point

**Noise points** do not match the previous conditions



## Procedure

1. Pick a point that has not been assigned to a cluster. If it is a core point, start a cluster around it. If not, mark it as noise
2. Expand the cluster by connecting all reachable points (core and border)
3. Repeat until all points are assigned to a cluster or marked as noise

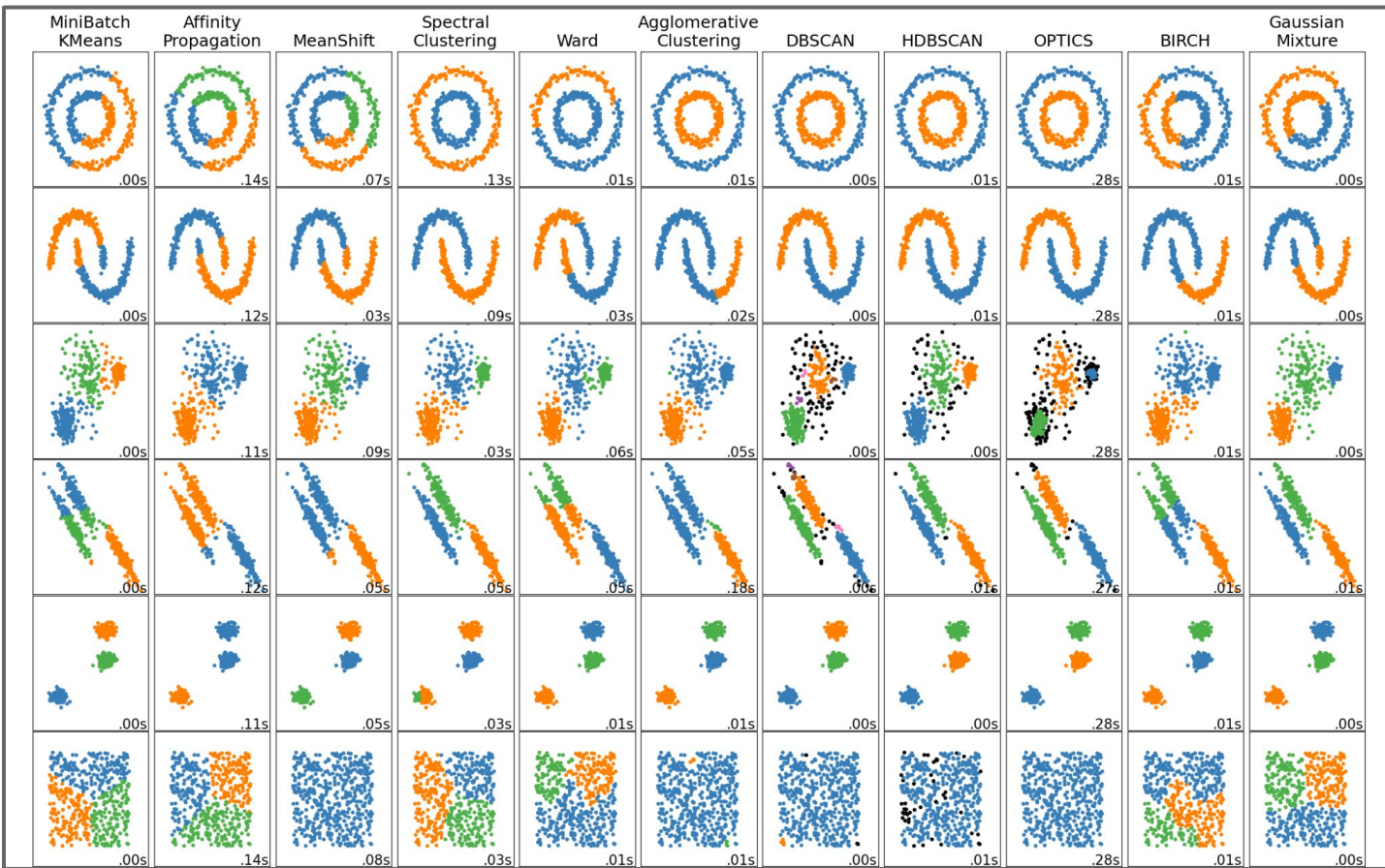


### Strengths

- Works with irregularly-shaped clusters
- Robust to noise and outliers
- No need to define the number of clusters

### Weaknesses

- Not good with high dimensionality
- Struggles with varying densities
- Defining the search distance and number of neighbours can be difficult



All conventional clustering algorithms can be found on [sk-learn](#) with detailed documentation!



# Practical work

The notebook contains all the necessary instructions

# Debrief

# Debrief

**What did we learn today?**

**What could we have done better?**

**What are we doing next time?**