

1. (100 points) Consider the LTI system specified by the following LCCDE:

$$\frac{d^2 y(t)}{dt^2} + B \frac{dy(t)}{dt} + 5y(t) = 4 \frac{dx(t)}{dt} + 25x(t)$$

- a. Write down the characteristic equation for this LTI system.
- b. For $B = 6$, calculate the frequency response function $\hat{\mathbf{H}}(\omega)$.
- c. For what value(s) of B does this equation have real roots p_1 and p_2 ? What kind of behavior does the system exhibit when the characteristic equation has real roots?
- d. For what value(s) of B does this equation have complex conjugate roots? What kind of behavior does the system exhibit when the characteristic equation has complex conjugate roots?
- e. For what value(s) of B does this equation have equal roots? What kind of behavior does the system exhibit when the characteristic equation has equal roots?
- f. For $B = 6$, calculate the attenuation coefficient α .
- g. For $B = 6$, calculate the undamped natural frequency ω_0 .
- h. For $B = 6$, calculate the damping coefficient ξ .
- i. For $B = 6$, calculate the step response $y_{step}(t)$.
- j. When $B = 6$, compute $\lim_{t \rightarrow \infty} y_{step}(t)$. To what final value does the system converge?