### Data Structures and Algorithms

# Lecture 2

- Array
- Dynamic array
- Matrix

- Container
- Iterator

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# Arrays

#### Specific:

- elements occupy a contiguous memory block
- any element of the array can be accessed "directly"

based on index

in **Θ(1)** 

the address of the element can be computed simply

```
TElem x[100];
```

x: TElem[100]

(in pseudocode, our conventions)

- The first element is at position 0
- Address of i-th element : address\_of\_array + i \* size\_of TElem

What would be the formula for computing the address of the element x[i] if the first position would be 1?



# Arrays

- An array is one of the simplest and most basic data structures.
- An array can hold a fixed number of elements of the same type and these elements occupy a contiguous memory block.
- Arrays are often used as a basis for other (more complex) data structures.

```
Array in C / C++
TElem x[100];
```

- When a new array is created we have to specify two things:
  - The type of the elements in the array
  - The maximum number of elements that can be stored in the array (capacity of the array)
- The memory occupied by the array will be the capacity times the size of one element.
- The array itself is memorized by the address of the first element.

# Array in C / C++ . Example

An array of integer values (integer values occupy 4 bytes)

```
Size of int: 4
Address of array: 00D9FE6C
Address of element from position 0: 00D9FE6C 14286444
Address of element from position 1: 00D9FE70 14286448
Address of element from position 2: 00D9FE74 14286452
Address of element from position 3: 00D9FE78 14286456
Address of element from position 4: 00D9FE7C 14286460
Address of element from position 5: 00D9FE80 14286464
Address of element from position 6: 00D9FE84 14286468
Address of element from position 7: 00D9FE88 14286472
```

• Can you guess the address of the element from position 8?

# **Arrays**

```
In C/C++:
    TElem x[100];
```

x: TElem[100]

 This is a static structure: once the capacity of the array is specified, you cannot add or delete slots from it (you can add and delete elements from the slots, but the number of slots, the capacity, remains the same)

### Disadvantage:

- we need to know/estimate from the beginning the number of elements:
  - if the capacity is too small: we cannot store every element we want to
  - If the capacity is too big: we waste memory

#### Solution?

Use dynamic arrays!

# Dynamic array

### Specific:

- can grow or shrink (at execution time)
- and are still arrays (use contiguous memory locations)

#### How can we work with them?

Use libraries

```
e.g.: C++ , STL library, vector
```

Please do not use it for DSA labs!

Implement them by using pointers (and pointer operations)

```
C++, operations with pointers
e.g.:
    TElem *x;
    x = new TElem[cap];
    delete[] x;
```

# Dynamic array: DS or ADT?

### Dynamic Array is a data structure:

• It is strongly related to: how data is actually stored in the computer (in a single contiguous memory block) and how it can be accessed and processed

### In C / C++:

```
int cap;
int nrElem;
TElem *elems;
```

(Maybe encapsulated in a class)

#### In pseudocode:

DynamicArray:

cap: Integer nrElem: Integer elems: TElem[]

(The default DS for us)

In most programming languages

it exists as a separate container as well.

We can see it as ADT (domain + operations).

# **ADT DynamicArray**

### For specification please see:

### ADT DynamicArray.pdf

### Operations:

- init
- destroy
- size
- getElement
- setElement
- addToPosition
- deleteFromPosition
- deleteFromEnd
- addToEnd
- iterator

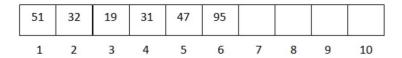
(when implemented over a dynamic array)

- Θ(1)
- Θ(1)
- Θ(1)
- Θ(1)
- Θ(1)
- O(n)
- O(n)
- Θ(1)
- **Θ(1)** amortized
- Θ(1)

Indexed access for a lot of operations

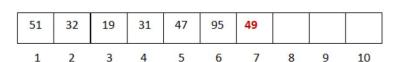
# DynamicArray: addToEnd

### e.g.:

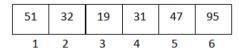


- · capacity (cap): 10
- nrElem: 6

 Add the element 49 to the end of the dynamic array



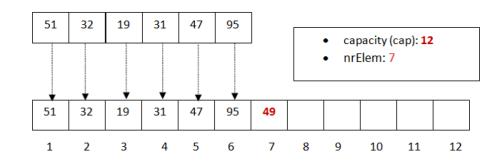
- · capacity (cap): 10
- nrElem: 7



- · capacity (cap): 6
- nrElem: 6

 Add the element 49 to the end of the dynamic array

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# DynamicArray: addToEnd

### Consider the next subalgorithm:

```
Use @ ... like
subalgorithm addToEnd (da, e) is:
                                                                                here for array
  if da.nrElem = da.cap then
                                                                                  allocation
   //the dynamic array is full. We need to resize it
                                                                                  specified in
      da.cap \leftarrow da.cap * 2
                                                                                  pseudocode
      newElems \leftarrow @ an array with da.cap empty slots
      //we need to copy existing elements into newElems
      for index \leftarrow 1. da.nrElem execute
         newElems[index] \leftarrow da.elems[index]
      end-for
     //we need to replace the old element array with the new one
      //depending on the prog. lang., we may need to free the old elems array
      da.elems ← newElems
   end-if
  //now we certainly have space for the element e
                                                                    After a resize operation the
  da.nrElem ← da.nrElem + 1
                                                                    elements of the Dynamic Array
                                                                    will still occupy a contiguous
  da.elems[da.nrElem] \leftarrow e
                                                                    memory zone, but it will be a
end-subalgorithm
                                                                    different one than before.
```

What is the complexity of addToEnd?

# DynamicArray, addToEnd: amortized analysis

- In amortized time complexity analysis we consider a sequence of operations and compute the average time for these operations.
- Consider c<sub>i</sub> the cost ( number of instructions) for the i<sup>th</sup> call to addToEnd

$$c_i = \begin{cases} i, & \text{if i-1 is an exact power of 2} \\ 1 & \text{otherwise} \end{cases}$$

Cost of n operations is:

$$\sum_{i=1}^{n} c_i \le n + \sum_{j=0}^{\lfloor \log_2 n \rfloor} 2^j < n + 2n = 3n$$

Since the total cost of n operations is 3n, we can say that the cost of one operation is 3, which is constant.

=> the amortized complexity is **Θ(1)** 

# DynamicArray: addToEnd & resize

- All operations that allows adding elements in a container will have to consider a resize of the dynamic structure
- => implement a subalgorithm resize(da)

### <u>e.g.</u>: C++

```
void DynamicArray::resize() {
    TElem *newElems = new TElem[2 * cap];
    for (int i = 0; i < nrElem; i++)
        newElems[i] = elems[i];
    cap = 2 * cap;
    delete[] elems;
    elems = newElems;
}

void DynamicArray::addToLast(TElem e) {
    if (nrElem == cap)
        resize();
    this->elems[nrElem++] = e;
}

Describe same alg.
in pseudocode!
```

What is the complexity of addToEnd?

# DynamicArray: resize

• While it is not mandatory to double the capacity, it is important to define the new capacity as **a product** of the old one with a constant number greater than 1 (just adding one new slot, or a constant number of new slots is not OK).

How do dynamic arrays in other programming languages grow at resize?

- Microsoft Visual C++ multiply by 1.5
   (initially 1, then 2, 3, 4, 6, 9, 13, etc.)
- Java multiply by 1.5 (initially 10, then 15, 22, 33, etc.)
- C# multiply by 2 (initially 0, 4, 8, 16, 32, etc.)

# DynamicArray: expansion and contraction

#### **Consider DELETE operation:**

it is enough to remove the specified item

- It is often desirable to contract the table, to reduce the wasted space
- Table contraction is analogous to table expansion allocate a new, smaller table and then copy the items

#### A natural strategy (?!)

- Expansion: double the table capacity when an item is inserted into a full table
- Contraction: halve the capacity when a deletion would cause the table to become less than half full.

#### How empty should the array become before resize?

Which of the following two strategies do you think is better? Why?

- Wait until the table is only half full (da.nrElem ≈ da.cap/2) and resize it to the half of its capacity
- Wait until the table is only a quarter full (da.nrElem ≈ da.cap/4) and resize it to the half of its capacity

### Containers and iterators

#### Container



• is a group of data (collection of elements). There we can add new elements and/or we can remove elements.

#### Iterator:

is defined over a container

abstraction

- a mechanism for accessing the elements of the container
  - > is an interface between containers and algorithms

Iterators are used to offer a common and generic way of moving through all the elements of a container, independently of the representation of the container.

 Iterators usually benefits from the property that in an object-oriented language, it is possible to have many different implementations for one interface (the same).

#### Remark:

not all containers have iterators (e.g.?)

### Containers and iterators

See: ADT Iterator.pdf

#### **ADT Iterator**

interface designed specifically to be used in a loop
 (access to all elements in a container in order to process them)

### See the next subalg.:

//go to the next element

next(it)

end-while

end-subalgorithm

```
subalgorithm printContainer(c) is:

//pre: c is a container

//post: the elements of c were printed

//we create an iterator using the iterator method of the container

iterator(c, it)

while valid(it) execute

//get the current element from the iterator

elem ← getCurrent(it)

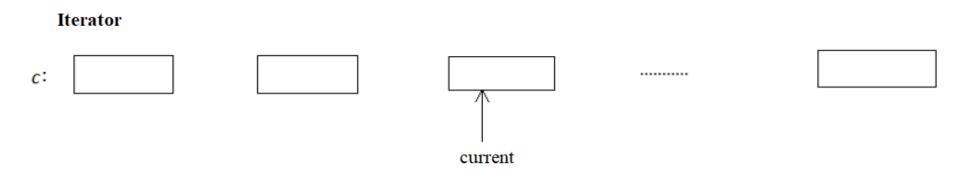
print elem
```

It the interface of an iterator is the same, independently of the exact container or its representation, this subalgorithm can be used to print the elements of any container.

## Iterators. Implementation aspects.

### An iterator usually contains:

- a reference to the container it iterates over
- a reference to a current element from the container



How can we represent an iterator for a DymanicArray

How can we represent that current element from the iterator?

# Iterators. Implementation aspects.

# 

- How can we define an iterator for a Dynamic Array?
   Let us see a short, simplified example
  - C++ example : files in DynArrayExample folder

#### Think about:

- What are the time-complexities for iterator operations?
- How can we print the content of a Dynamic Array?
- What is the complexity of print algorithms?
- What happens when we iterate a container, but the container is modified (add/remove) before the iteration is done?

# Type of iterators

- The iterator presented above describes the simplest iterator: unidirectional and read-only
- A <u>unidirectional iterator</u> can be used to iterate through a container in one direction only (usually forward, but we can define a reverse iterator as well).
- A <u>bidirectional iterator</u> can be used to iterate in both directions. Besides the next operation it has an operation called previous and it could also have a last operation (the pair of first).
- A <u>random access iterator</u> can be used to move multiple steps (not just one step forward or one step backward).
- A <u>read-only iterator</u> can be used to iterate through the container, but cannot be used to change it.
- A <u>read-write iterator</u> can be used to add/delete elements to/from the container.

# Type of iterators. Example

### Example: Java util

```
Interface Iterator<E> boolean hasNext()
E next()
void remove()
```

```
// assume a list of Strings in Java:
// ArrayList<String> list

Iterator<String> it = list.iterator();
while(it.hasNext()) {
    System.out.println(it.next());
}
```

# Iterators. Read-write operations. Example

```
// assume a list of Strings in Java:
// ArrayList<String> list
// with elements: A, B, C, D
System.out.println(list);
//Get iterator
Iterator<String> iterator = list.iterator();
//Iterate over all elements
while(iterator.hasNext())
    //Get current element
    String value = iterator.next();
    System.out.println( value );
    //Remove element
    if(value.equals("B")) {
        iterator.remove();
System.out.println(list);
```

```
[A, B, C, D]
A
B
C
D
[A, C, D]
```

#### Example: remove in Java util

Interface Iterator<E>

boolean hasNext()

E next()

void remove()

#### Iterator remove()

- It removes from the underlying collection the last element returned by the iterator.
- This method can be called only once per call to next().
- If the remove() method is not preceded by the next() method, then the exception IllegalStateException is thrown.
- If the underlying collection is modified while the iteration is in progress in any way other than by calling remove() method, iterator will throw an **ConcurrentModificationException**.

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## Iterators. Read-write operations.

#### Problem:

Remove all of the even integers from a container.

Consider dynamic array as a container. Is the next subalgorithm correct?

- Use indexed acces to elements of a dynamic array named da.
- Assume 1-based indexing.

Think about an implementation of remove in DynamicArray example and about an implementation of removeEvens by using it.

# Matrix

#### Specific:

- two-dimensional array.
- each element has a unique position, determined by two indexes: its line and column.

```
e.g.: C/C++ TElem x[3][3];
```

- usually a sequential representation is used for a Matrix
   (we memorize all the lines one after the other in a consecutive memory block).
- If this sequential representation is used, for a matrix with N lines and M columns, the element from position (i; j) can be found at the memory address:

```
address_of_element_from_position (i, j) =
    address_of_the_matrix + ( i * M + j)* size_of_an_element
```

The above formula works for 0-based indexing, but can be adapted to 1-based indexing as well.

Imagine a DT Matrix. What operations should we have for a Matrix?

### **ADT Matrix**

#### Please see:

Lecture02\_ADTMatrix (assumes 1-based indexing)
ADTMatrix interface (Lab) (assumes 0-based indexing)

 $\mathcal{D}_{MAT} = \{ \text{ mat } | \text{ mat is a matrix with elements of the type TElem} \}$ 

### Operations:

- init(mat, nrL, nrC)
- nrLines(mat)
- nrColumns(mat)
- element(mat, i, j)
- modify(mat, i, j, val)

There is no operation to add an element or to remove an element. In the interface we only have the modify operation which changes a value from a position.

### Other possible operations:

- get the first position of a given element
- create an iterator that goes through the elements by columns
- create an iterator the goes through the elements by lines

# **Sparse Matrix**

If the matrix contains many values of 0 (or  $0_{\text{TElem}}$ ), we have a sparse matrix, where it is more (space) efficient to memorize only the elements that are different from 0.

• We can memorize (line, column, value) triples, where value is different from 0 (or 0TElem).

For efficiency, we memorize the elements sorted by the (line, column) pairs (if the lines are different we order by line, if they are equal we order by column).

compressed sparse line representation /
 compressed sparse column representation

# Sparse Matrix, Triples

e.g.

Number of lines: 6

Number of columns: 8

0	33	0	100	1	0	0	9
2	0	2	0	2	0	7	0
0	4	0	0	3	0	0	0
17	0	0	10	0	16	0	7
0	0	0	0	0	0	0	0
0	1	0	13	0	8	0	29

### Triples: (line, column, value)

can be stored in a dynamic array

(or in other data structures)

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18
Line	1	1	1	1	2	2	2	2	3	3	4	4	4	4	6	6	6	6
Col	2	4	5	8	1	3	5	7	2	5	1	4	6	8	2	4	6	8
Value	33	100	1	9	2	2	2	7	4	3	17	10	16	7	1	13	8	29

# Sparse Matrix, Triples

#### <u>e.g.</u>:

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18
Line	1	1	1	1	2	2	2	2	3	3	4	4	4	4	6	6	6	6
Col	2	4	5	8	1	3	5	7	2	5	1	4	6	8	2	4	6	8
Value	33	100	1	9	2	2	2	7	4	3	17	10	16	7	1	13	8	29

• Modify the value from position (1, 5) to 0

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17
Line	1	1	1	2	2	2	2	3	3	4	4	4	4	6	6	6	6
Col	2	4	8	1	3	5	7	2	5	1	4	6	8	2	4	6	8
Value	33	100	9	2	2	2	7	4	3	17	10	16	7	1	13	8	29

• Modify the value from position (3, 3) to 19

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18
Line	1	1	1	2	2	2	2	3	3	3	4	4	4	4	6	6	6	6
Col	2	4	8	1	3	5	7	2	3	5	1	4	6	8	2	4	6	8
Value	33	100	9	2	2	2	7	4	19	3	17	10	16	7	1	13	8	29

• Modify the value from position (6, 4) to 1

? ⊙

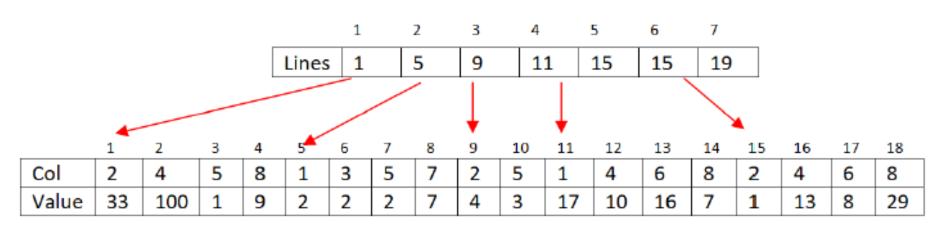
#### e.g.

Number of lines: 6

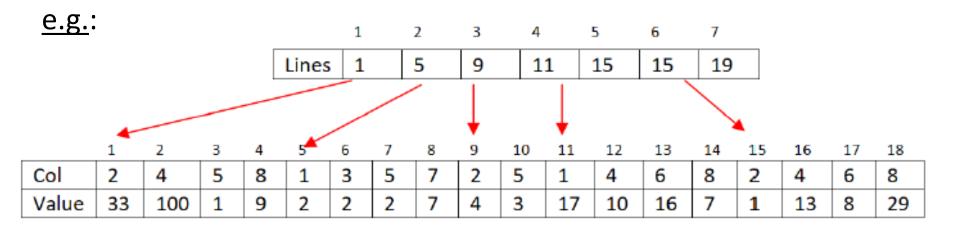
Number of columns: 8

0	33	0	100	1	0	0	9
2	0	2	0	2	0	7	0
0	4	0	0	3	0	0	0
17	0	0	10	0	16	0	7
0	0	0	0	0	0	0	0
0	1	0	13	0	8	0	29

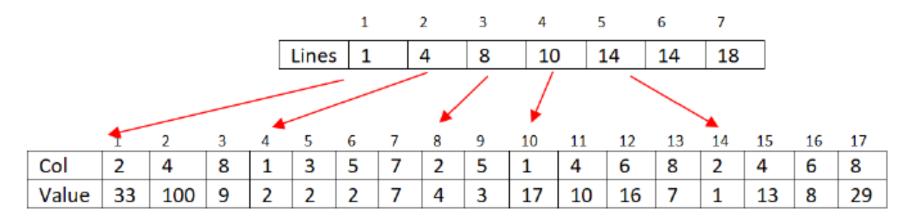
# Compressed sparse line



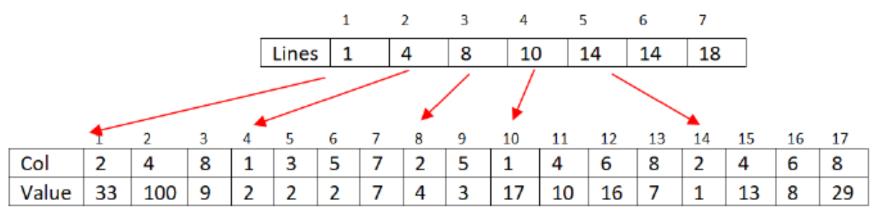
- Use Col and Value arrays.
- For the lines, have an array of number of lines + 1
   in which at position i we have the position from the Col
   array where the sequence of elements from line i begins.
- Thus, elements from line i are in the Col and Value arrays between the positions [Line[i], Line[i+1]).
- In order for this representation to work, in the Col and Value arrays the elements have to be stored by rows (first elements of the first row, then elements of second row, etc.)



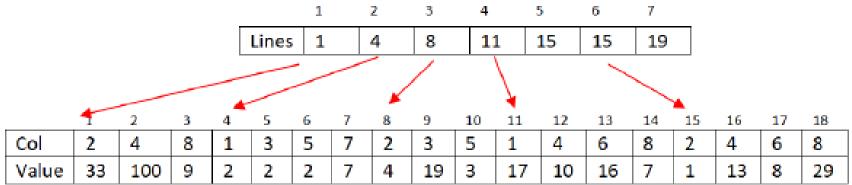
Modify the value from position (1, 5) to 0



### <u>e.g.</u>:



Modify the value from position (3, 3) to 19



• Modify the value from position (3, 6) to 0

? ⊙

#### Representation:

- an array with nrColumns + 1 elements, in which at position i we have the position from the Lines array where the sequence of elements from column i begins.
- two arrays Lines and Values for the non-zero elements, in which first the elements of the first column are stored, than elements from the second column, etc.

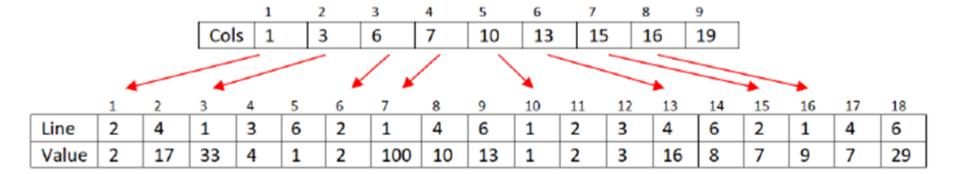
Elements from column i are in the Lines and Value arrays between the positions [Col[i], Col[i+1]).

<u>e.g.</u>:

Number of lines: 6

Number of columns: 8

0	33	0	100	1	0	0	9
2	0	2	0	2	0	7	0
0	4	0	0	3	0	0	0
17	0	0	10	0	16	0	7
0	0	0	0	0	0	0	0
0	1	0	13	0	8	0	29



## Sparse Matrix, ex.

For the next sparse matrix, describe (draw) the representation by using:

- triplets
- compressed sparse row
- compressed sparse column

7	0	0	0
5	9	0	6
0	8	0	0
7	0	0	0