Logical Agents

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The Wumpus World

Logi

Propositiona Logic

Propositional Inference

Conjunctive Norm

Resolution

Horn Form

Forward chaining

Propositional

Model Checking

Propositional Logic Based Agent

Problem-solving agents



- The problem-solving agents know things, but only in a very limited, inflexible sense.
 - E.g., the 8-puzzle agent cannot deduce that with odd parity cannot be reached from states with even parity
- CSP enables some parts of the agent to work domain-independently
 - Represent states as assignments of values to variables
 - Allow for more efficient algorithms

The Wumpus World

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Conjunctive Norr Form

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Horn For

Forward chaining

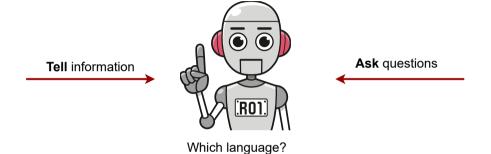
Backward chain

Model Checking

Propositiona Logic Based Agent

Motivation





Need to:

- Digest heterogenous information
- Reason deeply with that information

Natural languages (informal):

Language

- English: Two divides even numbers.
- Vietnamese Hai là số chẵn
- Programming languages (formal):
 - Python: def even(x): return x % 2 == 0
 - C++: bool even(int x) { return x % 2 == 0; }
- Logical languages (formal):
 - First-order-logic: $\forall x \text{ Even}(x) \rightarrow \text{Divides}(x, 2)$

WalkSAT

Two goals of a logic language

• Represent knowledge about the world



• **Reason** with that knowledge



Strength and Problem



- **Strength**: provides expressiveness in a compact way
- Problem 1: deterministic, didn't handle uncertainty (probability addresses this)
- Problem 2: rule-based, didn't allow fine tuning from data (machine learning addresses this)

Supported by logic

Knowledge-based agents

- Knowledge-based agents can combine and recombine information to suit myriad purposes.
 - Accept new tasks in the form of explicitly described goals
 - Achieve competence by learning new knowledge of the environment
 - Adapt to changes by updating the relevant knowledge

The Wumpu World

Log

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Conjunctive Normal Form Resolution Horn Form Forward chaining

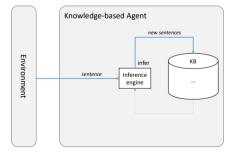
Propositiona Model Checking

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Knowledge-based agents (cont.)



- Knowledge base (KB): A set of sentences or facts in a *formal* language
 - Each sentence represents some assertion about the world.
 - Axiom = the sentence that is not derived from other sentences
- Inference: Using inference engine to derive (infer) new sentences from old ones
 - Add new sentences to the knowledge base and query what is known



A generic knowledge-based agent

```
function KB-AGENT(percept) returns an action
persistent: KB, a knowledge base
             t, a counter, initially 0, indicating time
  Tell(KB, Make-Percept-Sentence(percept, t))
  action \leftarrow Ask(KB, Make-Action-Query(t))
  Tell(KB, Make-Action-Sentence(action, t))
  t \leftarrow t + 1
  return action
```

 Given a percept, the agent adds the percept to its knowledge base, asks the knowledge base for the best action, and tells the knowledge base that it has in fact taken that action.

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Building an Agent



- Procedural approach
 - Encode desired behaviors directly as program code.
- Declarative approach to building an agent
 - Tell it what it needs to know, then it can Ask itself what to do answers should follow from the KB
- ullet Combined approach o Partially autonomous
- $\bullet \ \ \mathsf{Learning} \ \mathsf{approach} \to \mathsf{Fully} \ \mathsf{autonomous}$
 - Provide a knowledge-based agent with mechanisms that allow it to learn for itself





The Wumpus

World

Wumpus World PEAS description



The wumpus world is a cave consisting of rooms connected by passageways

Performance measure

- +1000 for climbing out of the cave with gold
- -1000 for falling into a pit or being eaten by the wumpus
- -1 each action taken
- -10 for using the arrow
- The game ends when agent dies or climbs out of the cave

SSTENCH S		-Breeze	PIT
12. 20. 20.	SSSSS Stench S	PIT	-Breeze
SSTENCH S		Breeze	
START	-Breeze -	PIT	Breeze

3

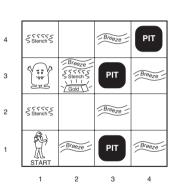
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Wumpus World PEAS description (cont.)



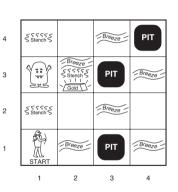
Environment

- A 4×4 grid of rooms
- Agent starts in the square [1,1], facing to the right
- The locations of **gold** and **wumpus** are random
- Each square can be a pit, with probability 0.2



Wumpus World PEAS description (cont.)

- **Actuators**: The agent can
 - Forward
 - Left turn by 90°
 - Right turn by 90°
 - Shooting kills wumpus if you are facing it (the agent has only one arrow)
 - Grabbing picks up gold if in same square
 - Releasing drops the gold in same square

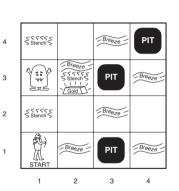


The Wumpus World

Wumpus World PEAS description (cont.)

- Sensors: The agent has five sensors
 - In the square containing the wumpus and in the directly (not diagonally) adjacent squares, the agent will perceive a Stench.
 - In the squares directly adjacent to a pit, the agent will perceive a Breeze.
 - In the square where the gold is, the agent will perceive a Glitter.
 - When an agent walks into a wall, it will perceive a Bump.
 - When the wumpus is killed, it emits a woeful Scream that can be perceived anywhere in the cave

[Stench, Breeze, None, None, None]



Fully Observable

No – only local perception

Characterize the Wumpus World

- Deterministic
 - Yes outcomes exactly specified
- Episodic
 - No sequential at the level of actions
- Static
 - Yes Wumpus and Pits do not move
- Discrete
 - Yes
- Single-agent
 - Yes Wumpus is essentially a natural feature

The Wumpus World

Logic

Proposition Logic

Propositional Inference

Inference

Form

Resolution

Forward chaining Backward chainin

Proposition Model Checking

DPLL WalkSAT

Propositiona Logic Based Agent

Exploring a wumpus world



1,4	2,4	3,4	4,4	
1,3	2,3	3,3	4,3	
1,2 OK	2,2	3,2	4,2	
1,1 A	2,1	3,1	4,1	
OK	OK			
(a)				

A	= Agent
В	= Breeze
G	= Glitter, Gold
oĸ	= Safe square
P	= Pit
S	= Stench
V	= Visited
W	= Wumpus

4,4				
4.3				
4.3				
4.3				
.,-				
4,2				
4,1				
(b)				

Figure 1: The first step taken by the agent in the wumpus world. (a) The initial situation, after percept [*None, None, None, None, None*]. (b) After one move, with percept [*None, Breeze, None, None, None*].

The Wumpus World

Exploring a wumpus world (cont.)

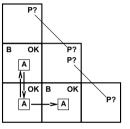


1,4	2,4	3,4	4,4	A = Agent B = Breeze G = Glitter, Gold OK = Safe square
^{1,3} w!	2,3	3,3	4,3	P = Pit S = Stench V = Visited W = Wumpus
1,2 A S OK	2,2 OK	3,2	4,2	=
1,1 V OK	2,1 B V OK	3,1 P!	4,1	
	(a)		,

1,4	2,4 P?	3,4	4,4	
^{1,3} W!	2,3 A S G B	3,3 _{P?}	4,3	
1,2 s v ok	2,2 V OK	3,2	4,2	
1,1 V OK	2,1 B V OK	3,1 P!	4,1	
(b)				

Figure 2: Two later stages in the progress of the agent. (a) After the third move, with percept [Stench, None, None, None, None]. (b) After the fifth move, with percept [Stench, Breeze, Glitter, None, None].

More





- Breeze in (1,2) and $(2,1) \implies$ no safe actions
- Assuming pits uniformly distributed, (2,2) has pit with probability 0.86 vs. 0.31

- Smell in $(1,1) \implies$ cannot move
- Can use a strategy of coercion:
 - shoot straight ahead
 - wumpus was there \implies dead \implies safe
 - wumpus wasn't there \iff safe



Logic

Concept 1

Logics are formal languages for representing information such that conclusions can be drawn

- Syntax defines the sentences (statements, formulas) in the language
- Semantics define the "meaning" of sentences; i.e., define truth of a sentence in a world

The language of arithmetic

- $x + 2 \ge y$ is a sentence
- $x^2 + v >$ is not a sentence
- $x + 2 \ge y$ is true in a world where x = 7, y = 1
- x + 2 > y is false in a world where x = 0, y = 6
- x + 2 > y is true iff the number x + 2 is no less than the number y

The Wumpus

Logic

Proposition Logic

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Forward chaining Backward chaining

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Models



Concept 2

Models are formally structured worlds with respect to which truth can be evaluated

- A model m in propositional logic is an assignment of truth values to propositional symbols
- 3 propositional symbols: A, B, C
- $2^3 = 8$ possible models m_i :

Model	Α	В	C	Model	Α	В	C
m_1	true	true	true	m_5	false	true	true
m_2	true	true	false	m_6	false	true	false
m_3	true	false	true	m_7	false	false	true
m_4	true	false	false	m_8	false	false	false

Interpretation function/semantic



Concept 3

Let α be a sentence and m be a model. An interpretation function $\mathcal{I}(\alpha,m)$ returns:

- true (1) say that m satisfies α or sometimes m is a model of α
- false (0) say that m does not satisfies α
- Given a sentence α , $\mathcal{M}(\alpha)$ is the set of all models of α

WalkSAT

Entailment



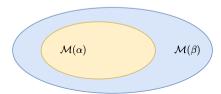
Concept 4

Let α, β be sentences, α entails β

$$\alpha \models \beta$$
 (1)

iff in every model where α is true, β is also true or

$$\mathcal{M}(\alpha) \subseteq \mathcal{M}(\beta) \tag{2}$$



WalkSAT

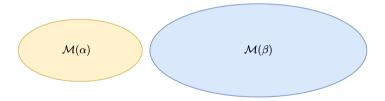
Agent

Contradiction



Concept 5

Let α, β be sentences, α contradicts β iff $\mathcal{M}(\alpha) \cap \mathcal{M}(\beta) = \emptyset$.



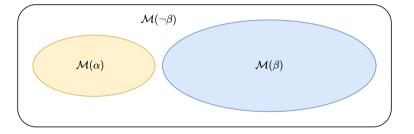
WalkSAT Agent

Contradiction vs. entailment



Theorem 1

Let α, β be sentences, α contradicts β iff α entails $\neg \beta$.



WalkSAT

Contingency



Concept 6

Let α, β be sentences, β is **contingent** on α iff

$$\emptyset \neq \mathcal{M}(\alpha) \cap \mathcal{M}(\beta) \neq \mathcal{M}(\alpha) \tag{3}$$



The Wumpu World

Logic

Propositiona Logic

Propositiona Inference

Conjunctive Nor

Resolution

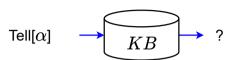
Forward chaining

Backward chaining

Propositions Model Checking

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Tell operation



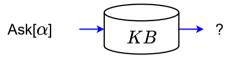
Tell: $\alpha =$ "It is raining".

Tell[KB, Rain]

Possible responses:

- Already knew that: entailment ($KB \models \alpha$)
- **Don't believe that**: contradiction $(KB \models \neg \alpha)$
- Learned something new (update KB): contingent $KB \leftarrow KB, \alpha$

Ask operation



Ask: $\alpha =$ "Is it raining?".

Possible responses:

- **Yes**: entailment ($KB \models \alpha$)
- **No**: contradiction ($KB \models \neg \alpha$)
- I don't know: contingent

The Wumpu World

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Propositiona Model Checking

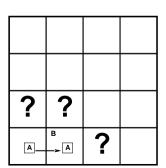
DPLL WalkSAT

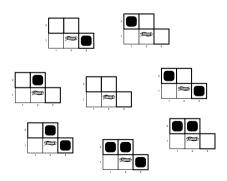
Propositiona Logic Based

Wumpus models



- Situation after the agent detecting nothing in [1,1], moving right and feel breeze in [2,1]
- Consider possible models? (assuming only pits)
 - ullet 3 Boolean choices \Longrightarrow 8 possible models





The Wumpu World

Logic

Propositiona Logic

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Propositional Model Checking

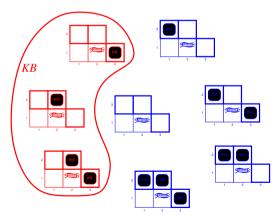
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Knowledge base



 The agent building knowledge base KB from wumpus-world rules + observations



The Wumpus World

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Propositiona

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Forward chaining

Proposition Model

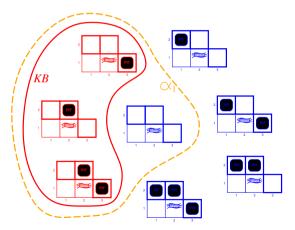
Model Checking DPLL WalkSAT

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Entailment



• $\alpha_1 =$ "[1,2] is safe", $KB \models \alpha_1$, proved by **model checking**



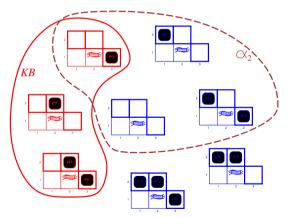
WalkSAT

Agent

Contingency



• $\alpha_2 =$ "[2,2] is safe", $KB \not\models \alpha_2$



Propositional Logic



Inference

Form Resolution

Forward chaining

Backward chaining

Propositiona Model Checking

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Syntax



Propositional logic (a formal language) is the simplest logic – illustrates basic ideas.

The **syntax** of propositional logic defines

Constants:

True, False

• Symbols: stand for propositions

$$A$$
, B , $B_{1,1}$, $P_{2,1}$

Logical connectives (operator)

connectives	meaning	example
_	negation (NOT)	$\neg S$
\wedge	conjunction (AND)	$\mathcal{S}_1 \wedge \mathcal{S}_2$
V	disjunction (OR)	$\mathcal{S}_1 ee \mathcal{S}_2$
\Longrightarrow	implication	$S_1 \implies S_2$
\iff	equivalence, biconditional	$S_1 \iff S_2$

Propositional Logic

Syntax (cont.)



 A BNF (Backus-Naur Form) grammar of sentences in propositional logic, along with operator precedences, from highest to lowest.

Operator Precedence : \neg , \wedge , \vee , \Longrightarrow , \Longleftrightarrow

Conjunctive Norr

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Forward chaining

Propositiona Model

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Semantic

- The semantics defines the rules for determining the truth of a sentence with respect to a particular model m
 - Each model m specifies true/false for each proposition symbol
 - Arbitrary sentence can be evaluateed by recursive process PL-TRUE and truth tables

 Table 1: Truth tables for the five logical connectives

Р	Q	$\neg P$	$P \wedge Q$	$P \lor Q$	$P \implies Q$	$P \iff Q$
false	false	true	false	false	true	true
false	true	true	false	true	true	false
true	false	false	false	true	false	false
true	true	false	true	true	true	true

Propositional Logic

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Semantic (cont.)



```
function PL-True?(\alpha, model) returns true or false if \alpha is a symbol then return Lookup(\alpha, model) if OP(\alpha) = \neg then return NoT(PL-True?(Arg1(\alpha), model)) if OP(\alpha) = \wedge then return AnD(PL-True?(Arg1(\alpha), model), PL-True?(Arg2(\alpha), model)) if OP(\alpha) = \vee then return OR(PL_True?(Arg1(<math>\alpha), model), PL-True?(Arg2(\alpha), model)) if OP(\alpha) = \Longrightarrow then return ... if OP(\alpha) = \Longrightarrow then return ...
```

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Entailment



Problem

Given a set of sentences KB and α . Prove that

$$KB \models \alpha$$

Method 1: model-checking

- Time complexity: $O(2^n)$ (if KB and α contain n symbols \rightarrow there are 2^n models)
- Space complexity: O(n) (depth-first)
- OK for propositional logic; not easy for first-order logic

Method 2: theorem-proving

Search for a sequence of proof steps (applications of inference rules)

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Model checking

```
function TT-ENTAILS?(KB, \alpha) returns true or false
  inputs: KB, the knowledge base, a sentence in propositional logic
           \alpha, the query, a sentence in propositional logic
  symbols \leftarrow a list of the propositional symbols in KB and \alpha
  return TT-CHECK-ALL(KB, \alpha, symbols, \emptyset)
function TT-CHECK-ALL(KB, \alpha, symbols, model)
returns true or false
  if Empty?(symbols) then
    if PL-True?(KB, model) then return PL-True?(\alpha, model)
    else return true
  else
    P \leftarrow \text{First}(symbols)
    rest ← Rest(symbols)
    return (TT-CHECK-ALL(KB, \alpha, rest, model \cup {P = true})
             and
             TT-CHECK-ALL(KB, \alpha, rest, model \cup \{P = false\}))
```

Propositional Logic

Validity



Concept 7

A sentence is valid if it is true in all models. Valid sentences are also known as tautologies

Theorem 2 (Deduction theorem)

For any sentences α and β , $\alpha \models \beta$ if and only if the sentence ($\alpha \implies \beta$) is valid.

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Satisfiability



Concept 8

A sentence is **satisfiable** if it is true in, or satisfied by, *some* model

The SAT problem

The problem of determining the satisfiability of sentences in propositional logic was the first problem proved to be NP-complete

Validity, satisfiability and entailment



Given two sentences α, β

- α is valid iff $\neg \alpha$ is unsatisfiable
- α is satisfiable iff $\neg \alpha$ is not valid
- $\alpha \models \beta$ iff the sentence $(\alpha \land \neg \beta)$ is unsatisfiable (**refutation** or contradiction)

Conjunctive Nor

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A simple knowledge base in Wumpus world



Symbols for each [x, y] location:

- $P_{x,y}$ is true if there is a pit in [x,y].
- $W_{x,y}$ is true if there is a wumpus in [x, y], dead or alive.
- $B_{x,y}$ is true if the agent perceives a breeze in [x,y].
- $S_{x,y}$ is true if the agent perceives a stench in [x,y].

Sentences in Wumpus world

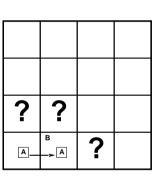
$$s_1 : \neg P_{1,1}$$

$$s_2 : B_{1,1} \iff (P_{1,2} \vee P_{2,1})$$

$$s_3 : B_{2,1} \iff (P_{1,1} \vee P_{2,2} \vee P_{3,1})$$

 s_4 : $\neg B_{1,1}$

s ₅ :	$B_{2,1}$
-------------------------	-----------



Inference in Wumpus world



• A truth table constructed for the knowledge base given in the text. KB is true if s_1 through s_5 are true, which occurs in just 3 of the 128 rows

$B_{1,1}$	$B_{2,1}$	$P_{1,1}$	$P_{1,2}$	$P_{2,1}$	$P_{2,2}$	$P_{3,1}$	s_1	s ₂	s 3	s ₄	s 5	KB
false	false	false	false	false	false	false	true	true	true	true	false	false
false	false	false	false	false	false	true	true	true	false	true	false	false
:	:	:	:	:	:	:	:	:	:	:	:	:
false	true	false	false	false	false	false	true	true	false	true	true	false
false	true	false	false	false	false	true	true	true	true	true	true	true
false	true	false	<u>false</u>	false	true	false	true	true	true	true	true	<u>true</u>
false	true	false	<u>false</u>	false	true	true	true	true	true	true	true	<u>true</u>
false	true	false	false	true	false	false	true	false	false	true	true	false
:	:	:	:	:	:	:	:	:	:	:	:	:
												:
true	true	true	true	true	true	true	false	true	true	false	true	false

- The agent makes some conclusion
 - $KB \models \neg P_{1,2}$ means there is no pit in [1,2]
 - $KB \not\models \neg P_{2,2}$ means there might (or might not) be a pit in [2,2]

- Conjunctive Normal Form
- Horn Form



Inference framework



Concept 9

If ℓ_1, \dots, ℓ_k, m are sentences, then the following is an **inference rule**:

$$\frac{\ell_1, \cdots, \ell_k}{m} \quad \frac{(\text{premises})}{(\text{conclusion})} \tag{4}$$

• Note: Rules operate directly on syntax, not on semantics.

Forward inference



Input: set of inference rules *Rs*.

Repeat until no changes to KB:

Choose set of formulas $\ell_1, \dots, \ell_k \in KB$.

If matching rule $\frac{\ell_1, \cdots, \ell_k}{m}$ exists then add m to KB.

Concept 10

KB **derives/proves** a sentence α , denoted by

$$KB \vdash_{Rs} \alpha$$

iff α eventually gets added to KB.

WalkSAT

Soundness



Concept 11

A set of inference rules Rs is **sound** if whenever $KB \vdash_{Rs} \alpha$, it is also true that $KB \models \alpha$ or

$$\{\alpha \mid \mathsf{KB} \vdash_{\mathsf{Rs}} \alpha\} \subseteq \{\alpha \mid \mathsf{KB} \models \alpha\} \tag{6}$$

WalkSAT

Completeness



Concept 12

A set of inference rules Rs is **complete** if whenever $KB \models \alpha$, it is also true that $KB \vdash_{Rs} \alpha$

$$\{\alpha \mid \mathsf{KB} \models \alpha\} \subseteq \{\alpha \mid \mathsf{KB} \vdash_{\mathsf{Rs}} \alpha\} \tag{7}$$

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World and representation

• if KB is true in the real world, then any sentence α derived from KB by a sound inference procedure is also true in the real world

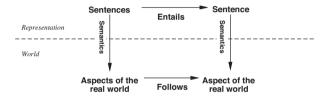


Figure 3: Sentences are physical configurations of the agent, and reasoning is a process of constructing new physical configurations from old ones. Logical reasoning should ensure that the new configurations represent aspects of the world that actually follow from the aspects that the old configurations represent.

Agent

Logical equivalence



Concept 13

Two sentences α and β are logically **equivalent** if they are true in the same set of models. We denotes as $\alpha \equiv \beta$

$$\alpha \equiv \beta$$
 if and only if $\alpha \models \beta$ and $\beta \models \alpha$

Logical equivalence (cont.)



Inference rule approach

- **Theorem proving**: Apply rules of inference directly to the sentences in KB to construct a proof of the desired sentence without consulting models.
 - More efficient than model checking when the number of models is large but the length of the proof is short
 - Legitimate (sound) generation of new sentences from old
- **Proof** = a sequence of inference rule applications to the desired goal
 - Can use inference rules as operators in a standard search algorithm. Typically require translation of sentences into a **normal form**
- Note: Logical systems is monotonicity, which says that the set of entailed sentences can only increase as information is added to the knowledge base. For any sentences α and β ,

if
$$KB \models \alpha$$
 then $KB \land \beta \models \alpha$

vv	

WalkSAT

Modus ponens
$$\frac{\alpha \Longrightarrow \beta, \quad \alpha}{\beta}$$
 Modus tollens
$$\frac{\alpha \Longrightarrow \beta, \quad \neg \beta}{\neg \alpha}$$
 And-introduction
$$\frac{\alpha, \quad \beta}{\alpha \land \beta}$$
 And-elimination
$$\frac{\alpha \land \beta}{\alpha}$$

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The Wumpu World

Log

Propositional Logic

Propositional Inference

Conjunctive Form

Resolutio

Horn Form

Forward chainin Backward chain

Proposition Model

Model Checking

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Proposition Logic Based Agent

Example 1



Given $KB = \{P \land Q, P \implies R, Q \land R \implies S\}$, prove that $KB \models S$

Solution

#	Sentence	Explanation
s_1	$P \wedge Q$	from <i>KB</i>
s_2	$P \implies R$	from <i>KB</i>
s_3	$Q \wedge R \implies S$	from <i>KB</i>
s_4	Р	(1) and-elimination
s 5	R	(4,2) modus ponens
s 6	Q	(1) and-elimination
S 7	$Q \wedge R$	(5,6) and-introduction
s 8	S	(3,7) modus ponens

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The Wumpu World

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Example 2



In Wumpus wolrd, given $KB = \{s_1, s_2, s_3, s_4, s_5\}$, prove that $KB \models \neg P_{1,2}$

Solution

#	Sentence	Explanation
s_1	$ eg P_{1,1}$	from <i>KB</i>
s_2	$\mathcal{B}_{1,1}\iff (\mathcal{P}_{1,2}ee\mathcal{P}_{2,1})$	from <i>KB</i>
s_3	$B_{2,1} \iff (P_{1,1} \vee P_{2,2} \vee P_{3,1})$	from <i>KB</i>
s_4	$ eg B_{1,1}$	from <i>KB</i>
s 5	$B_{2,1}$	from <i>KB</i>
s ₆	$(B_{1,1} \implies (P_{1,2} \vee P_{2,1})) \wedge ((P_{1,2} \vee P_{2,1}) \implies B_{1,1})$	Bi-conditional elimination to s_2
5 7	$(P_{1,2} \vee P_{2,1}) \implies B_{1,1}$	And-elimination to s_6
s 8	$\neg B_{1,1} \implies \neg (P_{1,2} \lor P_{2,1})$	Contrapositives to s_7
5 9	$\neg (P_{1,2} \lor P_{2,1})$	Modus ponens to s_4, s_8
s_{10}	$ eg P_{1,2} \wedge eg P_{2,1}$	De Morgan's rule to s_9
s_{11}	$\neg P_{1,2}$	And-elimination to s_{10}



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Proving by search



Any search algorithms can be applied to find a sequence of steps that constitutes a proof:

- **INITIAL STATE**: the initial knowledge base *KB*.
- **ACTIONS**: the set of actions consists of all the inference rules applied to all the sentences that match the top half of the inference rule.
- **RESULT**: the result of an action is to add the sentence in the bottom half of the inference rule.
- **GOAL**: the goal is a state that contains the sentence we are trying to prove.

Conjunctive Normal Form

Conjunctive Normal Form



Conjunctive Normal Form (CNF—universal)

A BNF (Backus-Naur Form) grammar for conjunctive normal form

```
CNFSentence \rightarrow Clause_1 \wedge ... \wedge Clause_n
          Clause \rightarrow Literal<sub>1</sub> \vee ... \vee Literal<sub>m</sub>
          Literal \rightarrow Symbol | \negSymbol
        Symbol \rightarrow P \mid Q \mid R...
```

Conjunctive Normal

Form

Conversion to CNF

Given a sentence $B_{1,1} \iff (P_{1,2} \vee P_{2,1})$

1. Eliminate \iff , replacing $\alpha \iff \beta$ with $(\alpha \implies \beta) \land (\beta \implies \alpha)$.

$$(B_{1,1} \implies (P_{1,2} \vee P_{2,1})) \wedge ((P_{1,2} \vee P_{2,1}) \implies B_{1,1})$$

2. Eliminate \implies , replacing $\alpha \implies \beta$ with $\neg \alpha \lor \beta$.

$$(\neg B_{1,1} \lor P_{1,2} \lor P_{2,1}) \land (\neg (P_{1,2} \lor P_{2,1}) \lor B_{1,1})$$

3. Move \neg inwards using de Morgan's rules and double-negation:

$$(\neg B_{1,1} \lor P_{1,2} \lor P_{2,1}) \land ((\neg P_{1,2} \land \neg P_{2,1}) \lor B_{1,1})$$

4. Apply distributivity law (\vee over \wedge) and flatten:

$$(\neg B_{1,1} \lor P_{1,2} \lor P_{2,1}) \land (\neg P_{1,2} \lor B_{1,1}) \land (\neg P_{2,1} \lor B_{1,1})$$

Resolution

Resolution inference rule



Resolution inference rule (for CNF):

$$\frac{\ell_1 \vee \cdots \vee \ell_i \vee \cdots \vee \ell_k, \quad m_1 \vee \cdots \vee m_j \vee \cdots \vee m_n}{\ell_1 \vee \cdots \vee \ell_{i-1} \vee \ell_{i+1} \vee \cdots \vee \ell_k \vee m_1 \vee \cdots \vee m_{j-1} \vee m_{j+1} \vee \cdots \vee m_n}$$
(8)

where ℓ_i and m_i are complementary literals

Theorem 3

Resolution inference rule is sound and complete for CNF KB

Resolution

The resolution algorithm

• Proof by contradiction: To show that $KB \models \alpha$, prove that $KB \land \neg \alpha$ is unsatisfiable

```
function PL-RESOLUTION(KB, \alpha) returns true or false
inputs: KB, the knowledge base, a sentence in propositional logic
         \alpha, the query, a sentence in propositional logic
  clauses \leftarrow the set of CNF clauses of KB \land \neg \alpha
  new \leftarrow \emptyset
  loop do
    for each pair of clauses C_i, C_i in clauses do
       resolvents \leftarrow PL-Resolve(C_i, C_i)
       if resolvents contains the empty clause then return true
       new \leftarrow new \cup resolvents
    if new ⊂ clauses then return false
    clauses ← clauses ∪ new
```

Resolution

Example 3



- $KB = \{(B_{1,1} \iff (P_{1,2} \vee P_{2,1})) \land \neg B_{1,1}\} \text{ and } \alpha = \neg P_{1,2}\}$
- Note: many resolution steps are pointless.

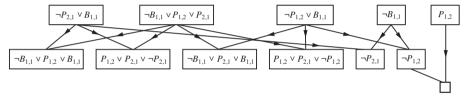


Figure 4: Partial application of PL-RESOLUTION to a simple inference in the wumpus world. $\neg P_{1,2}$ is shown to follow from the first four clauses in the top row

Conjunctive Nor

Resolutio

Horn Form

Forward chaining Backward chaining

Propositional Model Checking

Propositiona Logic Based

Horn Form



 In many practical situations, the full power of resolution is not needed. Some real-world knowledge bases satisfy certain restrictions (Horn form) on the form of sentences

Concept 15

Horn Form (restricted)

conjunction of Horn clauses

A BNF (Backus-Naur Form) grammar for Horn form

$$\begin{array}{cccc} \textit{HornClauseForm} & \rightarrow & \textit{DefiniteClauseForm} \mid \textit{Symbol} \\ \textit{DefiniteClauseForm} & \rightarrow & (\textit{Symbol}_1 \land ... \land \textit{Symbol}_n) \implies \textit{Symbol} \\ & \textit{Symbol} & \rightarrow & \textit{P} \mid \textit{Q} \mid \textit{R}... \end{array}$$

Propositiona

Conjunctive Norr

Form Resolution

Horn Form

Forward chaining

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Propositional Logic Based Agent

Modus ponens inference rule



• Modus ponens inference rule (for Horn Form)

$$\frac{\alpha_1, \dots, \alpha_n, \alpha_1 \wedge \dots \wedge \alpha_n \implies \beta}{\beta} \tag{9}$$

- Can be used with **forward chaining** or **backward chaining**.
- These algorithms are very natural and run in *linear* time

Theorem 4

Modus ponens inference rule is sound and complete for Horn KB

Forward chaining

Forward chaining (FC)

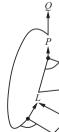
 $P \implies Q$ $I \wedge M \Longrightarrow P$ $B \wedge I \implies M$ $A \wedge P \implies L$ $A \wedge B \implies I$

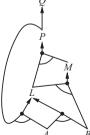
Α B



- Idea: fire any rule whose premises are satisfied in the KB, add its conclusion to the KB, until query is found
- **Example**: Given the following KB, prove that $KB \models Q$

Figure 5: The corresponding AND-OR graph.





Forward chaining

The forward-chaining algorithm



```
function PL-FC-ENTAILS?(KB, q) returns true or false
inputs: KB, the knowledge base, a set of propositional definite clauses
         q, the query, a proposition symbol
  count \leftarrow a \text{ table}, where count[c] is the number of symbols in c's premise
  inferred \leftarrow a table, where inferred[s] is initially false for all symbols
  agenda \leftarrow a queue of symbols, initially symbols known to be true in KB
  while agenda \neq \emptyset do
    p \leftarrow Pop(agenda)
    if p = q then return true
    if inferred[p] = false then
      inferred[p] \leftarrow true
      for each clause c in KB where p is in c.PREMISE do
        decrement count[c]
        if count[c] = 0 then add c.Conclusion to agenda
  return false
```

Resolution
Horn Form

Forward chaining

Backward chaining

Proposition:
Model
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Propositiona Logic Based Agent

Proof of completeness

FC derives every atomic sentence that is entailed by KB

- 1. FC reaches a **fixed point** where no new atomic sentences are derived
- 2. Consider the final state as a model m, assigning true/false to symbols
- **3.** Every clause in the original KB is true in m *Proof*: Suppose a clause $a_1 \wedge ... \wedge a_k \Rightarrow b$ is false in m
 - Then $a_1 \wedge \ldots \wedge a_k$ is true in m and b is false in m
 - Therefore the algorithm has not reached a fixed point!
- 4. Hence *m* is a model of *KB*
- **5.** If $KB \models q$, q is true in *every* model of KB, including m
 - **General idea**: construct any model of KB by sound inference, check α

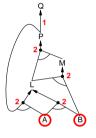
Forward chaining

WalkSAT

Agent

Forward chaining example





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Backward chaining

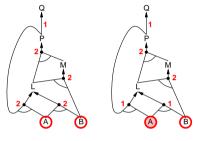
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Forward chaining example

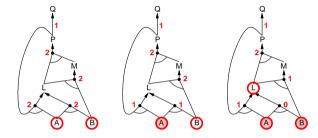




Forward chaining

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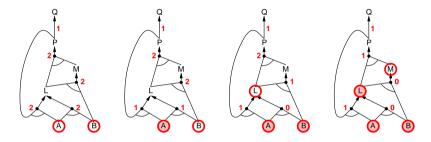
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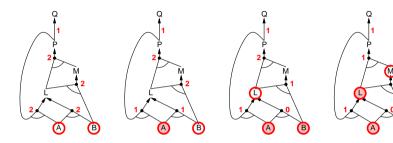


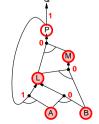


Forward chaining

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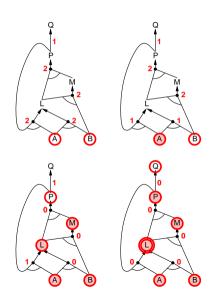
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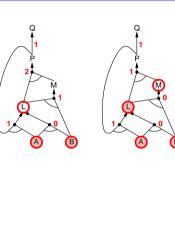
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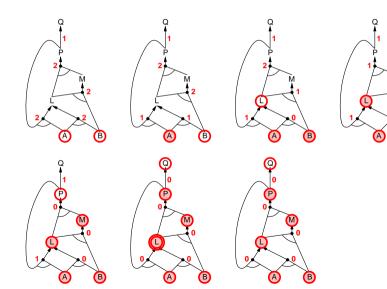
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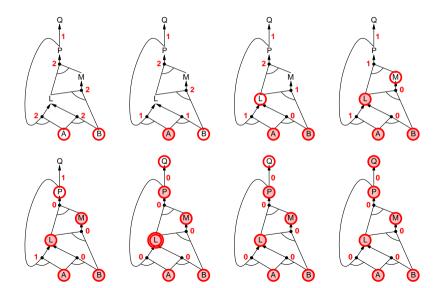
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Backward chaining

Propositiona Model Checking DPLL

Propositiona Logic Based Agent

Backward chaining (BC)



Idea: work backwards from the query q:

- To prove q by BC,
 - \bullet check if q is known already, or
 - prove by BC all premises of some rule concluding q
- Avoid loops: check if new subgoal is already on the goal stack
- Avoid repeated work: check if new subgoal
 - 1. has already been proved true, or
 - 2. has already failed

WalkSAT

Agent

Backward chaining example





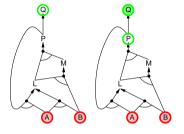


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Backward chaining example





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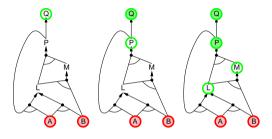
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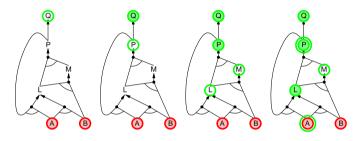






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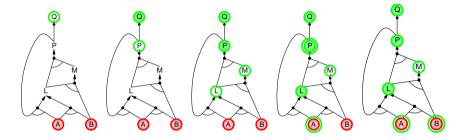


WalkSAT

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Backward chaining example



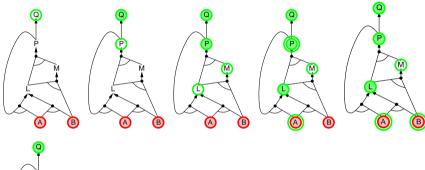


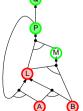
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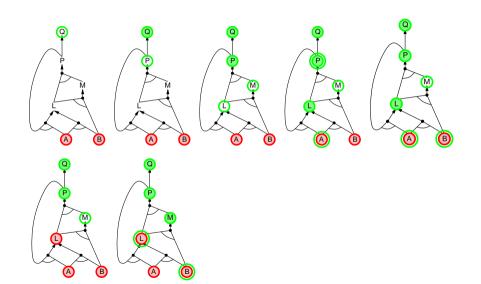
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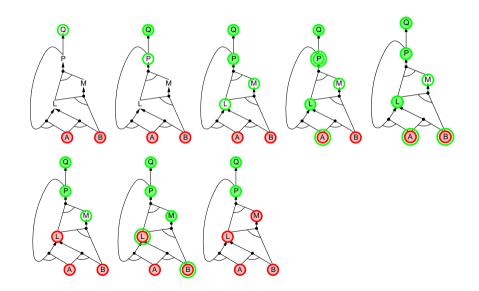
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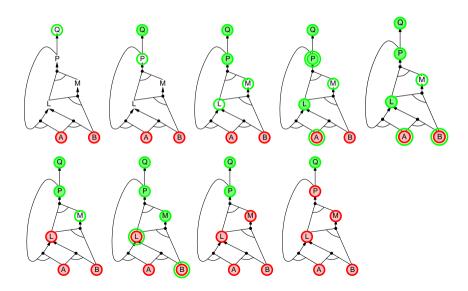
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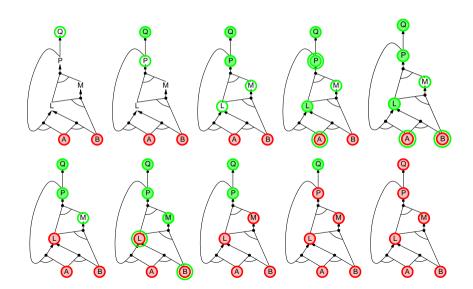
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Forward vs. backward chaining



- FC is data-driven, cf. automatic, unconscious processing,
 - e.g., object recognition, routine decisions
 - May do lots of work that is irrelevant to the goal
- BC is **goal-driven**, appropriate for problem-solving,
 - e.g., Where are my keys? How do I get into a PhD program?
 - Complexity of BC can be *much less* than linear in size of *KB*

Propositional Model Checking

- DPLL
- WalkSAT



Propositional

Model Checking

Efficient propositional inference



The SAT problem is checking satisfiability of sentence α

Two families of efficient algorithms for general propositional inference based on model checking

- 1. Complete backtracking search algorithms
 - DPLL algorithm (proposed by Davis, Putnam, Logemann and Loveland)
- 2. Incomplete local search algorithms (hill-climbing)
 - WalkSAT algorithm
 - Application of SAT: testing entailment, $\alpha \models \beta$, can be done by testing unsatisfiability of $\alpha \wedge \neg \beta$.

Propositional Inference

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Propositional

Model Checking

DPLL

Propositiona Logic Based Agent

The DPLL algorithm



- Determine whether an input propositional logic sentence (in CNF) is satisfiable
- A recursive, depth-first enumeration of possible models.
- Improvements over truth table enumeration
 - 1. Early termination
 - 2. Pure symbol heuristic
 - 3. Unit clause heuristic

The DPLL algorithm (cont.)

Early termination

- A clause is true if any literal is true.
- A sentence is false if any clause is false.
- Avoid examination of entire subtrees in the search space
- E.g., $(B \lor C) \land (B \lor D)$ is true if B is true, regardless C and D

The DPLL algorithm (cont.)



Pure symbol heuristic

- Pure symbol: always appears with the same "sign" in all clauses.
- Make a pure symbol literal true \rightarrow can never make a clause false
- For example, given a sentence $(A \vee \neg B)$, $(\neg B \vee \neg C)$, $(A \vee C) \rightarrow$ the symbols A and B are pure, C is impure.

Unit clause heuristic

- Unit clause: only one literal in the clause \rightarrow the only literal in a unit clause must be $true \rightarrow cause$ "cascade" of forced assignments (unit propagation)
- For example, given a sentence $B, \neg B \lor \neg C$, if the model contains B = true then C = false

Algorithm



```
function DPLL-SATISFIABLE?(s) returns true or false
inputs: s, a sentence in propositional logic.
  clauses \leftarrow the set of clauses in the CNF representation of s
  symbols \leftarrow a list of the proposition symbols in s
  return DPLL(clauses, symbols, 0)
function DPLL(clauses, symbols, model) returns true or false
  if every clause in clauses is true in model then return true
  if some clause in clauses is false in model then return false
  P, value \leftarrow FIND-PURE-SYMBOL(symbols, clauses, model)
  if P \neq \emptyset then
    return DPLL(clauses, symbols -P, model \cup \{P = value\})
  P, value ← FIND-UNIT-CLAUSE(clauses, model)
  if P \neq \emptyset then
    return DPLL(clauses, symbols -P, model \cup \{P = value\})
  P \leftarrow \text{First}(symbols): rest \leftarrow \text{Rest}(symbols)
  return DPLL(clauses, rest, model \cup \{P = true\}) or
          DPLL(clauses, rest, model \cup \{P = false\})
```

Agent

Success of DPLL

- 1962 DPLL invented
- 1992 300 propositions
- 1997 600 propositions (satz)
- 2002 (zChaff) 1,000,000 propositions encodings of hardware verification problems

nowledgesed Agents

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Propositional Model Checking

DPLL WalkSAT

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The WalkSAT algorithm

- **Evaluation function**: The min-conflict heuristic of minimizing the number of unsatisfied clauses
- Balance between greediness and randomness
- When the algorithm returns a model
 - The input sentence is indeed satisfiable
- When it returns failure
 - The sentence is unsatisfiable OR we need to give it more time
- WALKSAT cannot always detect unsatisfiability
- It is most useful when a solution is expected to exist. For example,
 - An agent cannot reliably use WALKSAT to prove that a square is safe in the Wumpus world.
 - Instead, it can say, "I thought about it for an hour and couldn't come up with a possible world in which the square isn't safe."

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WalkSAT

Propositional Logic Based Agent

Algorithm



```
function WalkSAT(clauses, p, max flips)
returns a satisfying model or failure
inputs: clauses, a set of clauses in propositional logic
        p, the probability of choosing to do a "random walk" move,
           typically around 0.5
        max_flips, number of flips allowed before giving up
  model \leftarrow a random assignment of true/false to the symbols
             in clauses
 for i = 1 to max flips do
    if model satisfies clauses then return model
    clause \leftarrow a randomly selected clause from clauses that is false
               in model
    with probability p
      flip the value in model of a randomly selected symbol
        from clause
    else
      flip whichever symbol in clause maximizes
        the number of satisfied clauses
 return failure
```



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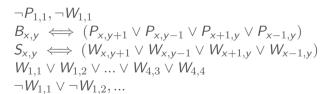
Propositiona Model Checking

Checking DPLL WalkSAT

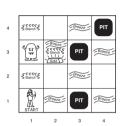
Propositional Logic Based Agent

Propositional Logic Based Agent

- Agent has to act given only local perception
- Agent is installed with two kinds of knowledge base
 - "Hardcode" knowledge base
 IF glitter THEN grab gold
 IF wumpus or pit around THEN avoid it
 - "Softcode" knowledge base KB



For a 4×4 wumpus world, the $\it KB$ begin with a total of 155 sentences containing 64 distinct symbols



Propositional Logic Based Agent

Algorithm



```
function PL-WUMPUS-AGENT(percept) returns an action
inputs: percept, a list, [stench, breeze, glitter]
static: KB, a knowledge base
         x, y, the agent's position (initially 1.1)
         orientation, orientation (initially right)
         visited, an array indicating which squares have been visited,
                   initially false
         action, the agent's most recent action, initially null
         plan, an action sequence, initially empty
  update x, v, orientation, visited based on action
  if stench then Tell(KB, S_{X,V}) else Tell(KB, \neg S_{X,V})
  if breeze then TELL(KB, B_{X,V}) else TELL(KB, \neg B_{X,V})
  if glitter then action ← grab
  else if plan \neq \emptyset then action \leftarrow Pop(plan)
  else if for some fringe square [i,j], Ask(KB, (\neg P_{i,j} \land \neg W_{i,j})) is true or
           for some fringe square [i,j], Ask(KB,(P_{i,j} \vee W_{i,j})) is false then
    plan \leftarrow A*-GRAPH-SEARCH(ROUTE-PROBLEM([x, y], orientation, [i, j], visited))
    action \leftarrow Pop(plan)
  else action \leftarrow a randomly chosen move
return action
```

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