BLIND STICK

Project Title: Blind Stick

Project Lead: Rutuja Shinde

Learning Objective:

• Simulate LDR and Thermistor workings.

• Use Tinkercad for electronics and Arduino projects.

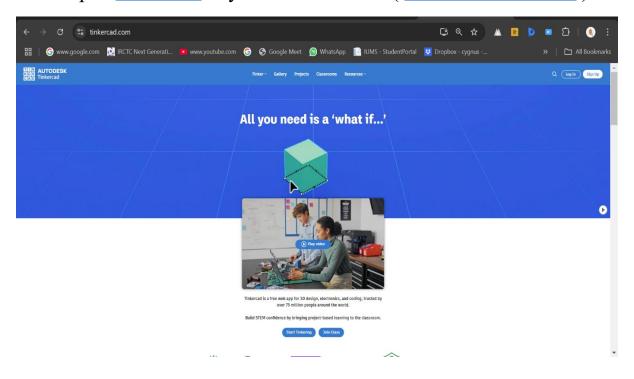
Required Components:

- 1. Arduino nano (virtual, in Tinkercad)
- 2.Breadboard (virtual)
- 3. Connecting Wires
- 4.Buzzer
- 5.Ultrasonic sensor (HC-SR04)

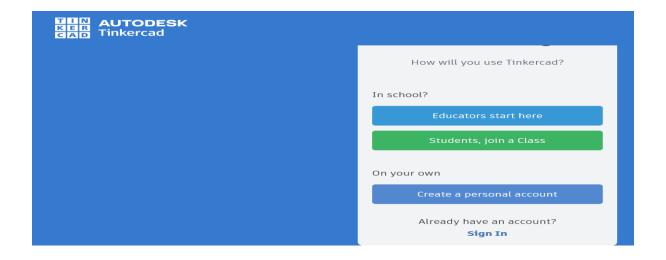
Step-by-Step Guide

Step 1: Set up Your Tinkercad Project

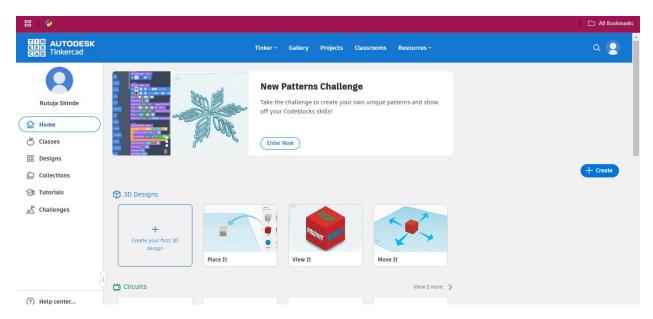
1. Open <u>Tinkercad</u> in your web browser. (<u>www.tinkercad.com</u>)



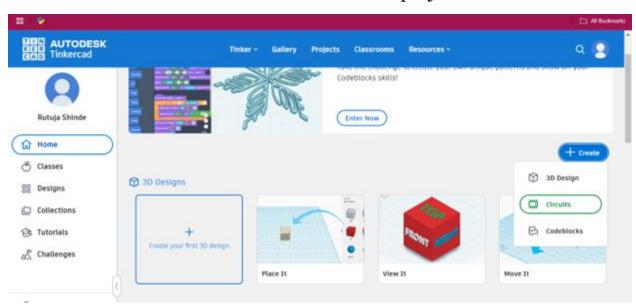
2. Create a free account or log in if you already have one.

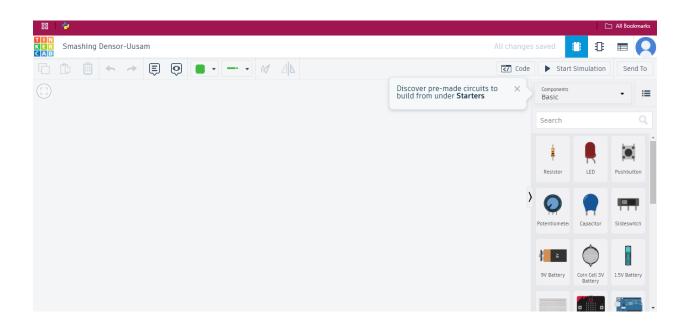


3. Select "Circuits" from the Tinkercad dashboard.

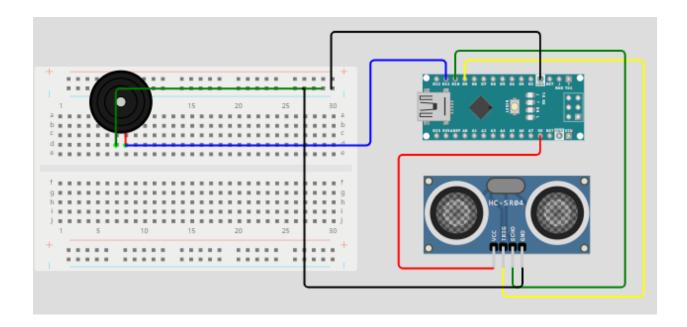


4. Click "Create New Circuit" to start a new project.





Circuit Diagram:



CODE:

```
const int trigPin = 9;
const int echoPin = 10;
const int buzzerPin = 11;
void setup()
{
   Serial.begin(9600);
   pinMode(trigPin, OUTPUT);
   pinMode(echoPin, INPUT);
   pinMode(buzzerPin, OUTPUT);
```

```
Serial.println("Blind Stick is Ready");
void loop()
 digitalWrite(trigPin, LOW);
 delayMicroseconds(2);
 digitalWrite(trigPin, HIGH);
 delayMicroseconds(10);
 digitalWrite(trigPin, LOW);
 long duration = pulseIn(echoPin, HIGH);
 long distance = duration * 0.034 / 2;
 Serial.print("Distance: ");
 Serial.print(distance);
 Serial.println(" cm");
 if (distance > 0 && distance <= 50)
  tone(buzzerPin, 1000);
 } else
  noTone(buzzerPin);
 delay(100);
```

OUTPUT:

