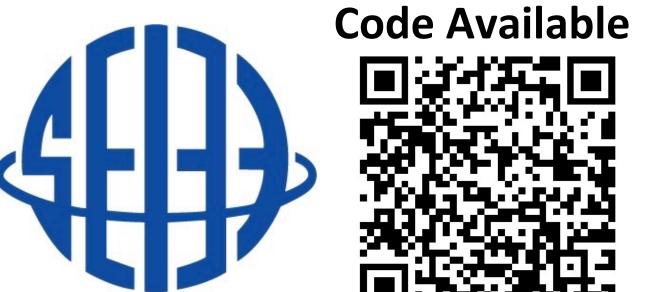


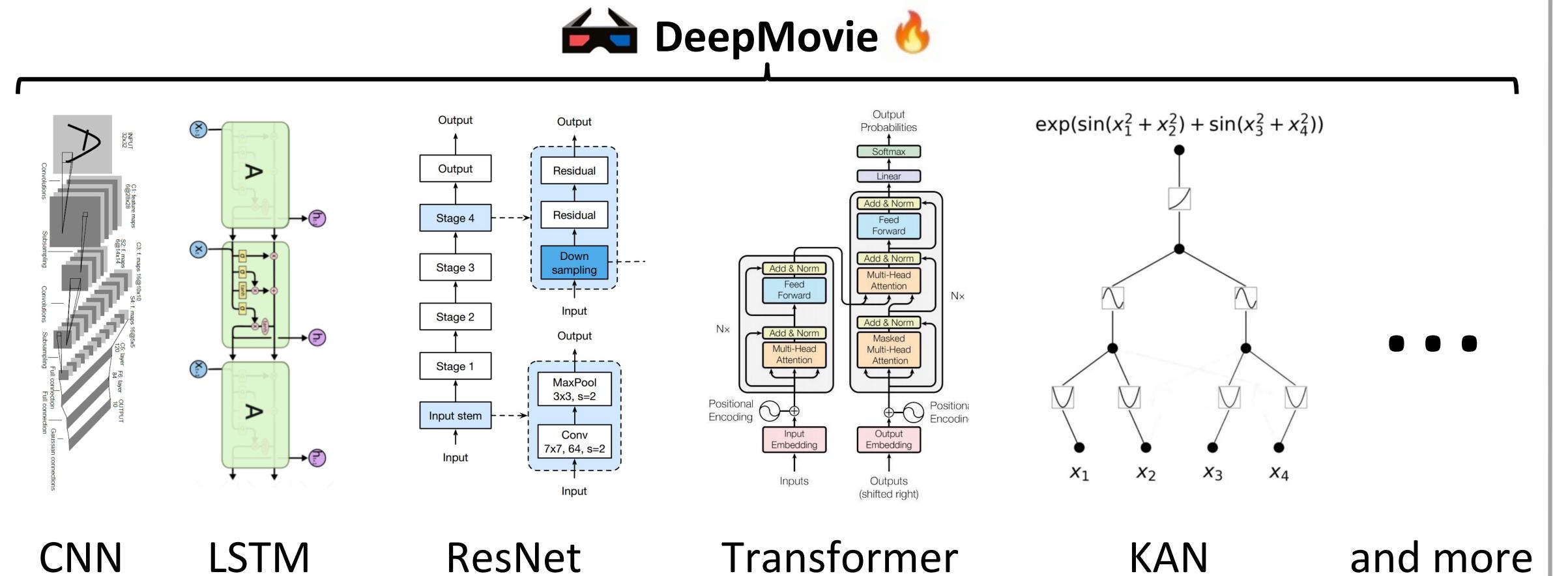
DeepMovie: Plug-and-Play DNN Training Pipeline for Movie Recommendation



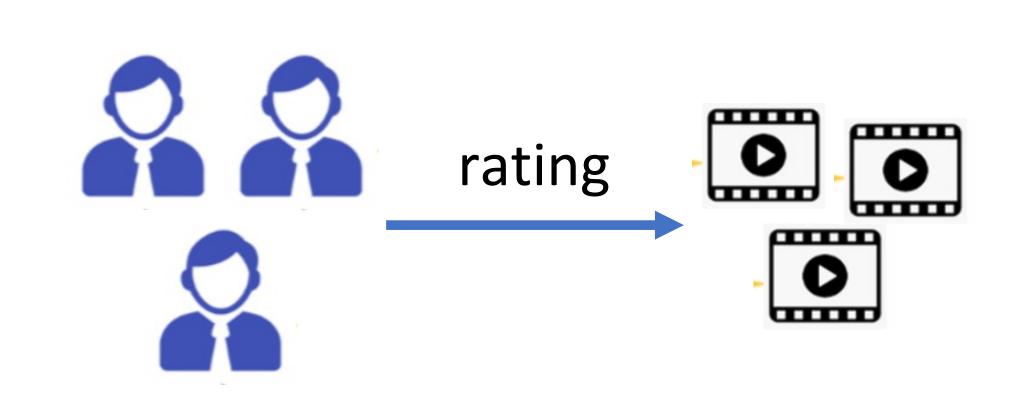
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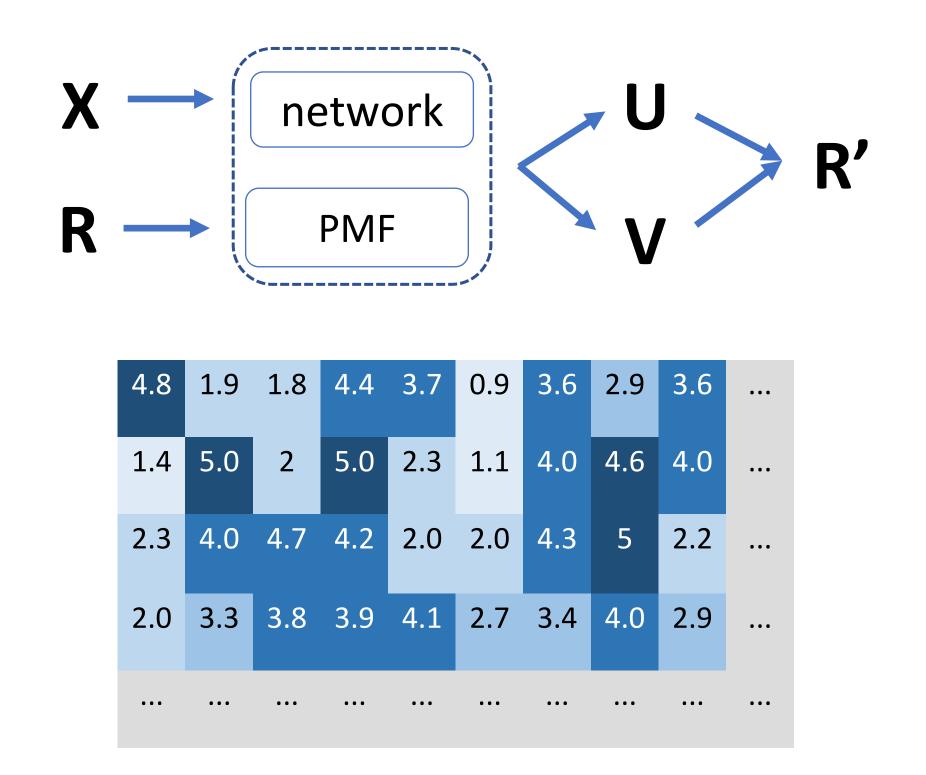
DeepMovie can integrate with many of the most advanced deep learning modules in a plug-and-play manner



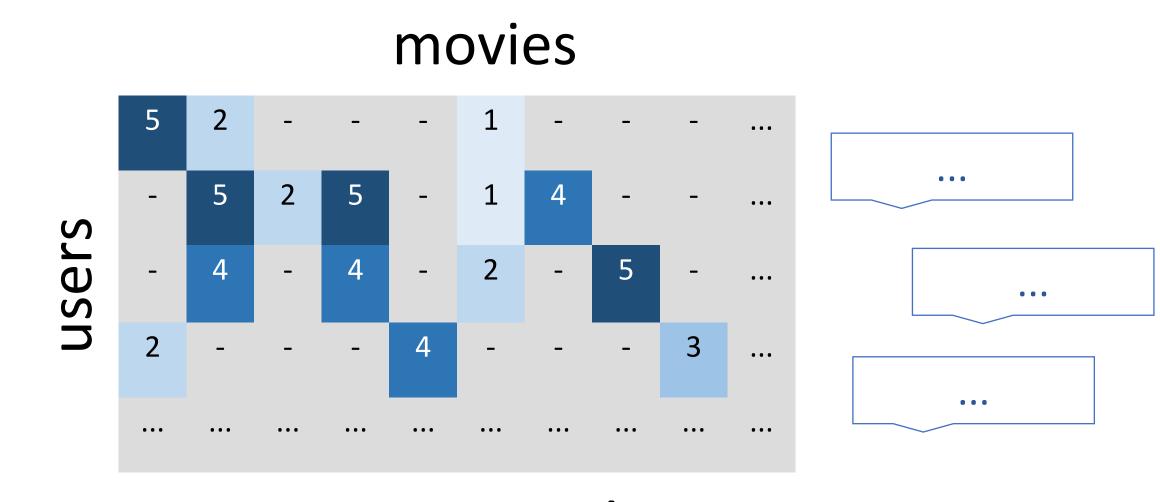




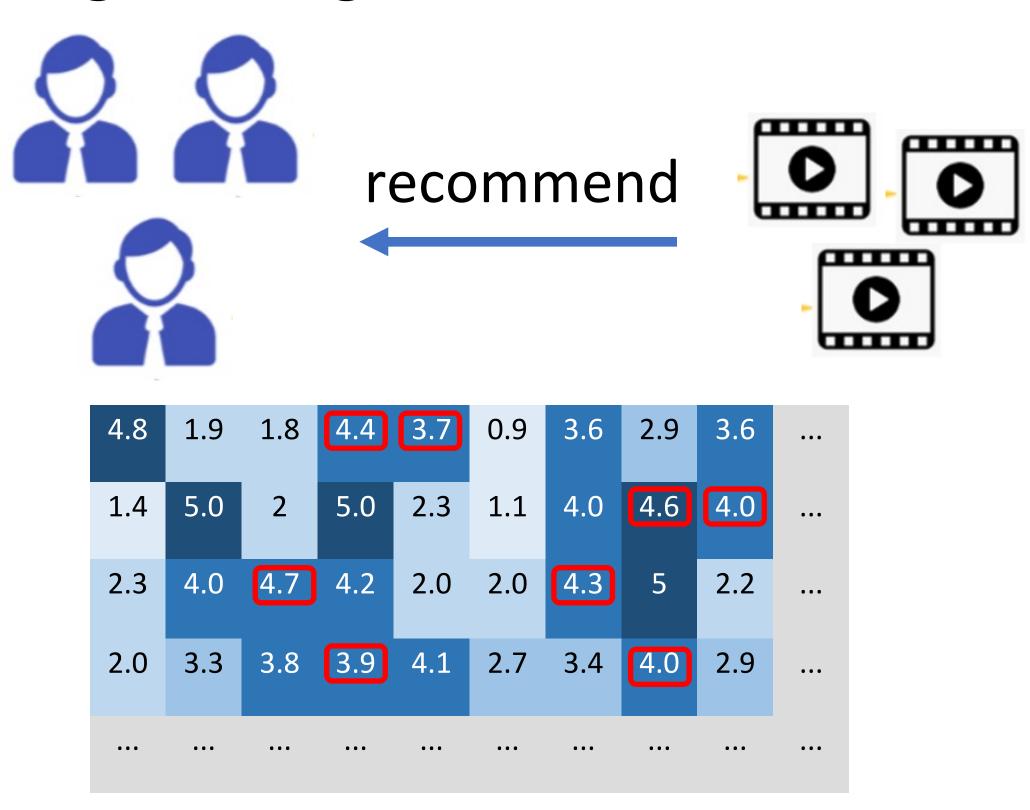




3.get latent matrix with our model and reconstruct ratings



2.get ratings R and reviews X



4.recommend movies for each user with reconstructed ratings

Experimental results on MovieLens dataset

 Performance metrics (in terms of RMSE loss) of DeepMovie based on different base modules on MovieLens-1M and 10M benchmark

| Base Module | MovieLens-1M | MovieLens-10M | |
|----------------|--------------|---------------|--|
| PMF (baseline) | 0.8971 | 0.8311 | |
| CNN (+ MLP) | 0.8733 | 0.7970 | |
| LSTM | 0.8675 | 0.7959 | |
| ResNet | 0.8658 | 0.7931 | |
| Transformer | 0.8601 | 0.7883 | |
| CNN + KAN | 0.8725 | 0.7941 | |

• Single epoch training time of different base modules (single A10 GPU)

| CNN | LSTM | ResNet | Transformer | KAN |
|--------|--------|--------|-------------|--------|
| 2.7720 | 3.8126 | 4.2604 | 10.9185 | 3.1637 |

Method: Integrates neural network into PMF

- probabilistic matrix factorization (PMF)
- find latent models of users and items on a shared latent space



R: user-item rating matrix, NxM U: user latent matrix, KxN

large but sparse \rightarrow small and dense \mathbf{V} : item latent matrix, KxM suppose Gaussian observation noise $pig(R\mid U, V, \sigma^2ig) = \prod^N \prod^M Nig(r_{ij}\mid u_i^T v_j, \sigma^2ig)^{I_{ij}}$

• use network to extract V from reviews X

PMF

 $pig(V \mid W, X, \sigma_V^2ig) = \prod Nig(v_j \mid network(W, X_j), \sigma_V^2 Iig)$ Optimize through maximum a posteriori(MAP)

 $\max_{U,V,W} pig(U,V,W \mid R,X,\sigma^2,\sigma_U^2,\sigma_U^2,\sigma_V^2ig)$ $\min\left(\left\|I\otimes\left(R-U^TV
ight)
ight\|_{Fro}+\lambda_V\|V-network(W,X)\|_{Fro}+\lambda_U\|U\|_{Fro}+\lambda_V\|V\|_{Fro}
ight)$

- Update
- 1. update **U**: $u_i \leftarrow \left(VI_iV^T + \lambda_UI_K\right)^{-1}VR_i$
- 2. update V: $v_j \leftarrow \left(UI_jU^T + \lambda_VI_K\right)^{-1}(UR_j + \lambda_Vnetwork(W, X_j))$
- 3. train the network to fit **V**

repeat until converge

Network

(x)