

# Session 1: Vector spaces

Optimization and Computational Linear Algebra for Data Science

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A quick look at the menu

# Questions ?

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# Subspaces

# What are the subspaces of $\mathbb{R}^2$ ?

# The span is always a subspace

## Proposition

Let  $x_1, \dots, x_k \in V$ . Then,  $\text{Span}(x_1, \dots, x_k)$  is a subspace of  $V$ .



# Linear dependency

# A useful lemma

## Lemma

Let  $v_1, \dots, v_n \in V$  and let  $x_1, \dots, x_k \in \text{Span}(v_1, \dots, v_n)$ .  
Then, if  $k > n$ ,  $x_1, \dots, x_k$  are linearly dependent.

**Abuse of language:** Instead of saying « $x_1, \dots, x_k$  are linearly dependent», we should have said «the family  $(x_1, \dots, x_k)$  is linearly dependent».

# Basis, dimension

# Proving the theorem

## Theorem

If  $V$  admits a basis  $(v_1, \dots, v_n)$ , then every basis of  $V$  has also  $n$  vectors. We say that  $V$  has dimension  $n$  and write  $\dim(V) = n$ .

**Proof.**



# A bit of vocabulary

## Definition

Let  $S$  be a subspace of  $\mathbb{R}^n$ .

- ✚ We call  $S$  a *line* if  $\dim(S) = 1$ .
- ✚ We call  $S$  an *hyperplane* if  $\dim(S) = n - 1$ .

# Overview of the lectures

# Outline

1. Vectors and vector spaces
2. Linear transformations and matrices
3. The rank
4. Norm and inner product
5. Eigenvalues, eigenvectors and Markov chains
6. The spectral theorem and PCA
7. Graphs and Linear Algebra
8. Convex functions
9. Linear regression
10. Optimality conditions
11. Gradient descent

# Further informations

Course's webpage:

`leomiolane.github.io/linalg-for-ds.html`