

Session 1: Vector spaces

Optimization and Computational Linear Algebra for Data Science

Léo Miolane

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1. Recap of the videos
2. More about the dimension
3. Coordinates
4. Why do we care about all these things ?
Application to data science: image compression

Logistics

The teaching team

✚ **Lecturer:** Léo Miolane – *lm4271nyu.edu*
`leomiolane.github.io/linalg-for-ds.html`

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❖ **Sections leaders:**

Alex



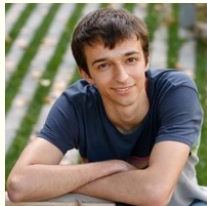
In person

Irina



Remote

Carles



Remote

Course components

Three main components:

1. Videos

2-3 short videos to watch **before** each lecture

2. Lectures

Deepens the concepts introduced in the videos

3. Recitations

Practice!

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Practice!

Grades:

1. Weekly quizzes (5%)

2. Weekly homeworks (40%)

3. Exams: Midterm (20%) + Final (35%)

Weekly timeline

Mon	Tue	Wed	Thu	Fri	Sat	Sun
14	15	16	17	18	19	20
21	22	23	24	25	26	27

Grading

- ❖ Quizzes have to be answered on **Gradescope**.
- ❖ Homeworks questions are available on the **course's webpage** and have to be submitted on **Gradescope**.

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- ❖ Midterm (~ mid-October) and Final will be «take-home exams».
- ❖ Limited time: after downloading the Midterm/Final questions, you will have to upload your work within few hours.

Check out the syllabus on the course webpage!

Questions on logistics ?

Vector spaces and subspaces

Quick recap of video 1.2

A **vector space** is a set V endowed with two 'nice and compatible' operations $+$ and \cdot that verify:

- ❖ For all $u, v \in V$, $u + v \in V$.
- ❖ For all $u \in V$ and all $\lambda \in \mathbb{R}$, $\lambda \cdot u \in V$.

Example: $V = \mathbb{R}^n$, with the usual vector addition $+$ and scalar multiplication \cdot is a vector space.

Quick recap of video 1.2

A subset S of a vector space V is called a **subspace** if it is closed under addition and multiplication by a scalar.

Example: For all $v \in \mathbb{R}^n$,

$$\text{Span}(v) = \{\lambda v \mid \lambda \in \mathbb{R}\}$$

is a subspace of \mathbb{R}^n .

Question ?

Review of Span and linear dependency

Span

The *linear span* of vectors x_1, \dots, x_k as the set of all linear combinations of these vectors.

Linear dependency

- ▣ Vectors x_1, \dots, x_k are *linearly dependent* if one of them can be expressed as a linear combination of the others.
- ▣ They are said to be *linearly independent* otherwise.

Abuse of language: Instead of saying « x_1, \dots, x_k are linearly dependent», we should say «the family (x_1, \dots, x_k) is linearly dependent».

Basis

A family (x_1, \dots, x_n) of vectors of V is a basis of V if

1. x_1, \dots, x_n are linearly independent,
2. $\text{Span}(x_1, \dots, x_n) = V$.

The dimension

A useful lemma

Lemma

Let $v_1, \dots, v_n \in V$ and let $x_1, \dots, x_k \in \text{Span}(v_1, \dots, v_n)$.
Then, if $k > n$, x_1, \dots, x_k are linearly dependent.

Definition of the dimension

Definition

We say that a vector space V has dimension n if it admits a basis (v_1, \dots, v_n) with n vectors.

The dimension is well defined!

Theorem

If V admits a basis (v_1, \dots, v_n) , then every basis of V has also n vectors. We say that V has dimension n and write $\dim(V) = n$.

Proof.



Properties of the dimension

Proposition

Let V be a vector space that has dimension $\dim(V) = n$. Then

- Any family of vectors of V that are linearly independent contains at most n vectors.

i.e. if $x_1, \dots, x_k \in V$ are linearly independent, then $k \leq n$.

- Any family of vectors of V that spans V contains at least n vectors.

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Proof.



Properties of the dimension

Proposition

Let V be a vector space of dimension n and let $x_1, \dots, x_n \in V$.

1. If x_1, \dots, x_n are linearly independent, then (x_1, \dots, x_n) is a basis of V .
2. If $\text{Span}(x_1, \dots, x_n) = V$, then (x_1, \dots, x_n) is a basis of V .

Very useful to show that a family of vector forms a basis:

Example: $x_1 = (12, 37)$ and $x_2 = (-9, 17)$ form a basis of \mathbb{R}^2 .

Proof of the Proposition.



An inequality

Proposition

Let U and V be two subspaces of \mathbb{R}^n . Assume that $U \subset V$. Then

$$\dim(U) \leq \dim(V) \leq n.$$

If **moreover** $\dim(U) = \dim(V)$, then $U = V$.

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Proof.



A bit of vocabulary

Definition

Let S be a subspace of \mathbb{R}^n .

- We call S a *line* if $\dim(S) = 1$.
- We call S a *hyperplane* if $\dim(S) = n - 1$.

Coordinates

Coordinates of a vector in a basis

Definition

If (v_1, \dots, v_n) is a basis of V , then for every $x \in V$ there exists a unique vector $(\alpha_1, \dots, \alpha_n) \in \mathbb{R}^n$ such that

$$x = \alpha_1 v_1 + \dots + \alpha_n v_n.$$

We say that $(\alpha_1, \dots, \alpha_n)$ are the coordinates of x in the basis (v_1, \dots, v_n) .

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Exercise

1. Show that the vectors $v_1 = (1, 1)$ and $v_2 = (1, -1)$ form a basis of \mathbb{R}^2 .
2. Express the coordinates of $u = (x, y)$ in the basis (v_1, v_2) in terms of x and y .

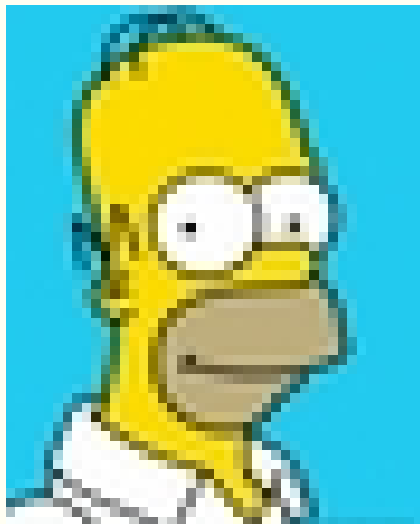
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Why do we care about this ?

Application to image compression

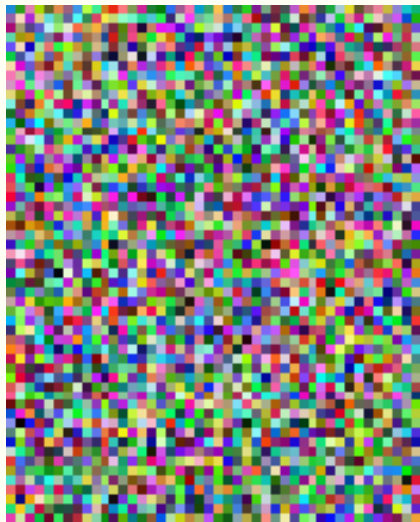
- Image = Grid of pixels
- Represented as a vector $v \in \mathbb{R}^n$, for some large n .
- One need to store n numbers.



$$n = 44 \times 55 = 2420$$

Can we do better?

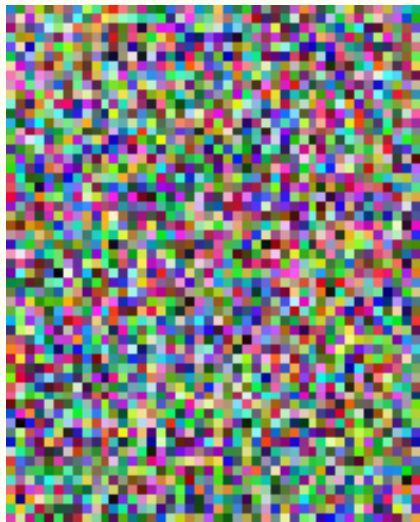
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«Random» image

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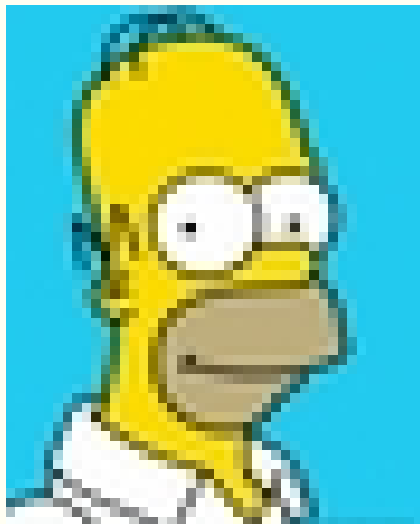
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- ❖ However, we are mainly storing images coming from the « real world »
- ❖ These images have some *structure*.



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«Real» image

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- ❖ There exists a basis (w_1, \dots, w_n) of \mathbb{R}^n in which «real» images $v \in \mathbb{R}^n$ are (approximately) **sparse**.
- ❖ This means that the coordinates $(\alpha_1, \dots, \alpha_n)$ of v in the basis (w_1, \dots, w_n) contains a lot of zeros.

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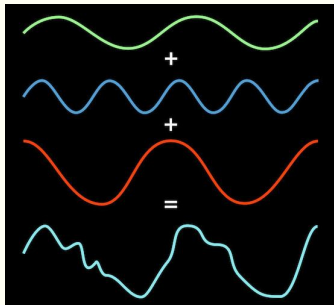
Store only the $k \ll n$ non-zero coordinates of v (in the w_i 's basis') !

A toy example

Consider $n = 2$, that is images $v \in \mathbb{R}^2$ with only 2 pixels.

Examples of good bases

- Fourier bases (used in .jpeg, .mp3)



- JPEG2000 uses **wavelet bases**, and achieves better performance than JPEG.
- In **Homework 4**, you will use wavelets to compress/denoise images.
- The course **DS-GA 1013** deepens these concepts!

Questions?