

# Optimization and Computational Linear Algebra for Data Science

## OUTLINE

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May 14, 2019

### 1. VECTOR SPACES

1. General definitions
2. Linear dependency
3. Proof of Theorem [2.1](#)

### 2. LINEAR TRANSFORMATIONS

1. Linear transformations
2. Matrix representation
3. Kernel and image

### 3. RANK

1. More on basis
2. Definition of the rank
3. Properties of the rank
4. Transpose of a matrix, symmetric matrices

### 4. NORM AND DOT PRODUCT

1. Norm
2. Dot product
3. Orthogonality
4. Orthogonal projection and distance to a subspace

### 5. MATRICES AND ORTHOGONALITY

1. Gram-Schmidt orthogonalisation method
2. Orthogonal matrices