

Optimization and Computational Linear Algebra for Data Science

OUTLINE

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1. VECTOR SPACES

1. General definitions
2. Linear dependency
3. Proof of Theorem [2.1](#)

2. LINEAR TRANSFORMATIONS

1. Linear transformations
2. Matrix representation
3. Kernel and image

3. RANK

1. More on basis
2. Definition of the rank
3. Properties of the rank
4. Transpose of a matrix
5. Symmetric matrices

4. NORM AND DOT PRODUCT

1. Norm
2. Dot product
3. Orthogonality
4. Orthogonal projection and distance to a subspace

5. MATRICES AND ORTHOGONALITY

1. Gram-Schmidt orthogonalisation method
2. Orthogonal matrices