Optimization and Computational Linear Algebra for Data Science Lecture 6: Eigenvalues, eigenvectors and Markov chains

Léo MIOLANE · leo.miolane@gmail.com June 18, 2019

Warning: This material is not meant to be lecture notes. It only gathers the main concepts and results from the lecture, without any additional explanation, motivation, examples, figures...

Eigenvalues and eigenvectors

Definition 1.1

Let $A \in \mathbb{R}^{n \times n}$. A non-zero vector $v \in \mathbb{R}^n$ is said to be an eigenvector of A is there exists $\lambda \in \mathbb{R}$ such that

$$Av = \lambda v$$
.

The scalar λ is called the eigenvalue (of A) associated to v.

Application to Markov chains

First definitions and properties

A finite Markov chain is a process which moves among the elements of a finite set E in the following manner: when at $x \in E$, the next position is chosen according to a fixed probability distribution $P(x,\cdot)$. More formally:

Definition 2.1

A sequence of random variables (X_0, X_1, \dots) is a Markov chain with state space E and transition matrix P if for all $t \geq 0$,

$$\mathbb{P}(X_{t+1} = y \mid X_0 = x_0, \dots, X_t = x_t) = P(x_t, y)$$

for all x_0, \ldots, x_t such that $\mathbb{P}(X_0 = x_0, \ldots, X_t = x_t) > 0$.

The transition matrix P verifies therefore, for all $x \in E$,

$$\sum_{y \in E} P(x, y) = 1. \tag{1}$$

In order to simplify the notations, we will assume that $E = \{1, 2, ..., n\}$ and write for all $i,j \in E, P_{i,j} = P(j,i)$. Note that we switched here the order of i and j. This is not what is usually done in the literature, but this will allow us to be more coherent. Such matrix is said to be stochastic:

Definition 2.2 (Stochastic matrix)

A matrix $P \in \mathbb{R}^{n \times n}$ is said to be stochastic if:

- (i) $P_{i,j} \ge 0$ for all $1 \le i, j \le n$. (ii) $\sum_{i=1}^{n} P_{i,j} = 1$, for all $1 \le j \le n$.

Let $(X_0, X_1, ...)$ be a Markov chain on $\{1, ..., n\}$ with transition matrix P. For $t \ge 0$ we will encode the distribution of X_t in the $1 \times n$ vector

$$x^{(t)} = (x_1^{(t)}, \dots, x_n^{(t)}) = (\mathbb{P}(X_t = 1), \dots, \mathbb{P}(X_t = n)) \in \Delta_n$$

where Δ_n is the "n-simplex"

$$\Delta_n \stackrel{\text{def}}{=} \left\{ x \in \mathbb{R}^n \, \Big| \, \sum_{i=1}^n x_i = 1 \text{ and } x_i \ge 0 \text{ for all } i \right\}.$$

Proposition 2.1

For all $t \ge 0$

$$x^{(t+1)} = Px^{(t)}$$
 and consequently, $x^{(t)} = P^t x^{(0)}$.

Proof. Let $i \in \{1, ..., n\}$.

$$x_i^{(t+1)} = \mathbb{P}(X_{t+1} = i) = \sum_{j=1}^n \mathbb{P}(X_{t+1} = i | X_t = j) \mathbb{P}(X_t = j) = \sum_{i=1}^n P_{i,j} x_j^{(t)} = (x^{(t)} P)_i.$$

Corollary 2.1

Let P be a stochastic matrix. Then

- For all $x \in \Delta_n$, $Px \in \Delta_n$.
- For all $t \ge 1$, P^t is stochastic.

2.2 Invariant measures and the Perron-Frobenius Theorem

We will be interested in the distribution of X_t for t large, that is the limit of $x^{(t)} = x^{(0)}P^t$. As we will see, under suitable conditions on the matrix A, this

Definition 2.3

A vector $\mu \in \Delta_n$ is an invariant measure for the transition matrix P if $\mu = P\mu$, i.e.

for all
$$j \in \{1, ..., n\}$$
, $\mu_i = \sum_{j=1}^n P_{i,j} \mu_j$.

Remark 2.1. An invariant measure is an eigenvector of P with associated eigenvalue 1.

Theorem 2.1 (Perron-Frobenius, stochastic case)

Let P be a stochastic matrix such that there exists $k \ge 1$ such that all the entries of P^k are strictly positive. Then the following holds:

- (i) 1 is an eigenvalue of P and there exists an eigenvector $\mu \in \Delta_n$ associated to 1.
- (ii) The eigenvectors associated to 1 are unique up to scalar multiple (i.e. $Ker(P Id) = Span(\mu)$).
- (iii) For all $x \in \Delta_n$, $P^t x \xrightarrow[t \to \infty]{} \mu$.

Theorem 2.1 is proved in the next section.

Corollary 2.2

Let P be a stochastic matrix such that there exists $k \ge 1$ such that all the entries of P^k are strictly positive. Then there exists a unique invariant measure μ and for all initial condition $x^{(0)} \in \Delta_n$,

$$x^{(t)} \xrightarrow[t \to \infty]{} \mu.$$

2.3 Proof of Theorem 2.1

We first prove the theorem in the case k = 1, when $P_{i,j} > 0$ for all i, j.

Lemma 2.1

The mapping

$$\varphi: \Delta_n \to \Delta_n$$

$$x \mapsto Px$$

is contracting for the ℓ_1 -norm: there exists $c \in (0,1)$ such that for all $x,y \in \Delta_n$:

$$||Px - Py||_1 \le c||x - y||_1.$$

Proof. First notice that φ is well-defined by Corollary 2.1. Let us write $\alpha \stackrel{\text{def}}{=} \min_{i,j} P_{i,j} \in (0,1)$. Let $x,y \in \Delta_n$. We will show that $||Px - Py||_1 \le (1-\alpha)||x-y||_1$, i.e. $||Pz||_1 \le \alpha ||z||_1$ where z = x - y. Compute

$$||Pz||_1 = \sum_{i=1}^n |(Pz)_i| = \sum_{i=1}^n |\sum_{j=1}^n P_{i,j}z_j|.$$

Since $\sum_{j} z_{j} = 0$ we have $\sum_{j} (P_{i,j} - \alpha/n) z_{j} = \sum_{j} P_{i,j} z_{j}$. Hence

$$||Pz||_1 = \sum_{i=1}^n \left| \sum_{j=1}^n (P_{i,j} - \alpha/n) z_j \right| \le \sum_{i=1}^n \sum_{j=1}^n (P_{i,j} - \alpha/n) |z_j| = \sum_{j=1}^n (1 - \alpha) |z_j| = (1 - \alpha) ||z||_1.$$

Using Lemma 2.1, Banach fixed point Theorem tells us that φ admits a unique fixed point μ on Δ_n (i.e. a unique $\mu \in \Delta_n$ such that $P\mu = \mu$) and that for all $x \in \Delta_n$, $P^t x \xrightarrow[t \to \infty]{} \mu$. This proves Theorem 2.1 in the case k = 1.

In the case k > 1 we simply apply the result for k = 1 to P^k .

This gives that there exists a unique $\mu \in \Delta_n$ such that $P^k \mu = \mu$. Multiplying by P on both sides leads to $P^k(P\mu) = P\mu$. Since $P\mu \in \Delta_n$ we obtain that $P\mu = \mu$ by uniqueness of μ . This proves (i). To prove (ii) we consider $x \in \mathbb{R}^n$ such that Px = x. By iteration we get $P^k x = x$ which implies (using the result on P^k) that $x \in (\mu)$. To prove (iii) we fix $\ell \in \{0, \dots, k-1\}$. Let $x \in \Delta_n$. By applying the point (iii) to P^k , we have

$$P^{kt}P^{\ell}x \xrightarrow[t\to\infty]{} \mu.$$

Since this holds for all $\ell \leq k-1$ we obtain that $P^T x \xrightarrow[T \to \infty]{} \mu$ using the Euclidean division of T by k.

3 Example: Google's PageRank algorithm

