

1.2 L (memoryless filter)  $M=N=4, K=1$  (since  $K=1$ , convolution becomes the product)

$$\underline{y}_1 = \begin{bmatrix} y_1[1] \\ y_1[2] \\ y_1[3] \\ y_1[4] \end{bmatrix} = \begin{bmatrix} x_1[1] \\ x_1[2] \\ x_1[3] \\ x_1[4] \end{bmatrix} h_{11} + \dots + \begin{bmatrix} x_{u1}[1] \\ x_{u1}[2] \\ x_{u1}[3] \\ x_{u1}[4] \end{bmatrix} h_{1u} + \begin{bmatrix} w_1[1] \\ w_1[2] \\ w_1[3] \\ w_1[4] \end{bmatrix} \Rightarrow \underline{y}_1 = \underbrace{\begin{bmatrix} x_1 & x_2 & x_3 & x_4 \end{bmatrix}}_X \begin{bmatrix} h_{11} \\ h_{12} \\ h_{13} \\ h_{1u} \end{bmatrix} + \underline{w}_1$$

Generalizing for  $y_1, y_2, y_3, y_4$  all together:

$$\underline{y} = \begin{bmatrix} \underline{y}_1 \\ \underline{y}_2 \\ \underline{y}_3 \\ \underline{y}_4 \end{bmatrix} = \begin{bmatrix} X & 0 & 0 & 0 \\ 0 & X & 0 & 0 \\ 0 & 0 & X & 0 \\ 0 & 0 & 0 & X \end{bmatrix} \begin{bmatrix} h_{11} \\ h_{12} \\ h_{13} \\ h_{1u} \end{bmatrix} + \begin{bmatrix} w_1[1] \\ w_1[2] \\ w_1[3] \\ w_1[4] \end{bmatrix}$$

$M \times 1$   $M \times N$   $N \times 1$   $M \times 1$   $M \times 1$

$$\hat{h}_{ML} = (X^T C^{-1} X)^{-1} X^T C^{-1} y$$

$M \times N$   $N \times N$   $N \times 1$   $M \times 1$   $M \times 1$

Cov matrix for the noise

$w_1[1]$	1	0	0	0	0	0	0
$w_1[2]$	0	1	0	0	0	0	0
$w_1[3]$	0	0	1	0	0	0	0
$w_1[4]$	0	0	0	1	0	0	0
$w_2[1]$	0	0	0	0	1	0	0
$w_2[2]$	0	0	0	0	0	1	0
$w_2[3]$	0	0	0	0	0	0	1
$w_2[4]$	0	0	0	0	0	0	0
$w_3[1]$	0	0	0	0	0	0	0
$w_3[2]$	0	0	0	0	0	0	0
$w_3[3]$	0	0	0	0	0	0	0
$w_3[4]$	0	0	0	0	0	0	0
$w_4[1]$	0	0	0	0	0	0	0
$w_4[2]$	0	0	0	0	0	0	0
$w_4[3]$	0	0	0	0	0	0	0
$w_4[4]$	0	0	0	0	0	0	0

$\text{kron}(I_M, X)$

toeplitz matrix (see the code)

1.2 L (memory filter)  $M=N=K=4$

$$\underline{y}_1 = \begin{bmatrix} y_1[1] \\ y_1[2] \\ y_1[3] \\ y_1[4] \end{bmatrix} = \begin{bmatrix} x_1[1] & 0 & \dots & 0 \\ x_1[2] & x_1[1] & \dots & x_1[K-1] \\ 0 & x_1[2] & \dots & x_1[K-1] \\ 0 & 0 & \dots & x_1[K-1] \end{bmatrix} \begin{bmatrix} h_{11} \\ h_{12} \\ h_{13} \\ h_{1u} \end{bmatrix} + \underline{X}_2 \begin{bmatrix} h_{11} \\ h_{12} \\ h_{13} \\ h_{1u} \end{bmatrix} + \underline{X}_3 \underline{h}_{13} + \underline{X}_u \underline{h}_{1u} + \begin{bmatrix} w_1[1] \\ w_1[2] \\ w_1[3] \\ w_1[4] \end{bmatrix}$$

$Q+K-1 \times K$  (conv. matrix)  $K \times 1$   $K \times 1$   $K \times 1$   $K \times 1$   $K \times 1$

$$\underline{y}_1 = \begin{bmatrix} \underline{X}_1 & \underline{X}_2 & \underline{X}_3 & \underline{X}_4 \end{bmatrix} \begin{bmatrix} h_{11} \\ h_{12} \\ h_{13} \\ h_{1u} \end{bmatrix} + \underline{w}_1$$

$Q+K-1 \times KN$   $KN \times 1$   $Q+K-1 \times 1$   $KN \times 1$

Generalizing:

$$\begin{bmatrix} y_1 \\ y_2 \\ y_3 \\ y_4 \end{bmatrix} = \begin{bmatrix} \underline{X}_1 & \underline{X}_2 & \underline{X}_3 & \underline{X}_4 & 0 & 0 & 0 & 0 \\ 0 & \underline{X}_1 & \underline{X}_2 & \underline{X}_3 & \underline{X}_4 & 0 & 0 & 0 \\ 0 & 0 & \underline{X}_1 & \underline{X}_2 & \underline{X}_3 & \underline{X}_4 & 0 & 0 \\ 0 & 0 & 0 & \underline{X}_1 & \underline{X}_2 & \underline{X}_3 & \underline{X}_4 & 0 \end{bmatrix} \begin{bmatrix} h_{11} \\ h_{12} \\ h_{13} \\ h_{1u} \end{bmatrix} + \begin{bmatrix} w_1[1] \\ w_1[2] \\ w_1[3] \\ w_1[4] \end{bmatrix}$$

$M(Q+K-1) \times 1$   $M(Q+K-1) \times KN$   $KN \times 1$   $M(Q+K-1) \times 1$

$X = I_M \otimes X_{conv}$   $KN \times 1$

Similarly to 1.2 L, cov. matrix will have the same structure and the size of  $M(Q+K-1) \times M(Q+K-1)$

$$\hat{h}_{ML} = X^T C^{-1} X)^{-1} X^T C^{-1} y$$

$KN \times 1$   $M(Q+K-1) \times M(Q+K-1)$   $M(Q+K-1) \times 1$   $M(Q+K-1) \times 1$