You installed a camera in front of your house in order to monitor the speed of cars driving on the road in front of it. You assume that no more than one car is visible in each frame and no other objects are moving. In particular you want to calculate the speed of the car given three different images: bg.jpg (an image taken without any car), 1.jpg (an image of a moving car), 2.jpg (the second image of the same car taken after 2 seconds). Write a Matlab script able to perform the following steps:

- a) Read the 3 input 8-bit color images (each of with the same size [N M]), convert them to double grayscale images and visualize them.
- b) In order to detect the moving objects, calculate D1 and D2 defined respectively as the difference between the 1<sup>st</sup> image and the background and the 2<sup>nd</sup> image and the background.
- c) In order to avoid detection errors due to the movements of small isolated objects, such as leaves, for each of the two images (D1, D2) perform the following operations:
  - I. obtain a threshold t1 (or t2) equal to 1/10 of the maximum absolute values stored in D1 (or D2)
  - II. calculate a binary image, B1 (or B2), associating TRUE value to moving pixels. In order to do so, set to TRUE the pixels having an absolute value greater than the threshold.
  - III. define a rectangle structuring element with size equal to 0.5% of the minimum between M and N.
  - IV. apply a morphological operation of your choice in order to remove isolated TRUE values from B1 (or B2) obtaining M1 (or M2)
- d) Estimate the speed of the car in the following way:
  - I. find the coordinates of TRUE values in M1 and M2
  - II. calculate the coordinates of the central point of the car in the two images by averaging the (x,y) coordinates obtained in the previous point
  - III. knowing that a displacement of 1 pixel corresponds to 0.05 meters (assume that you have calculated this value knowing the intrinsic parameters of the camera and its position in respect to the street), calculate the speed of the car in km/h (remember that the second image is taken 2 seconds after the first one).

## Matlab

## List of possible functions

figure rgb2ind im2double imread imclose zeros rgb2gray imcrop ones imopen imshow find hist min max strel imnoise abs round sum size numel norm

```
close all
clear all
%a)
I1 = imread('1.jpg');
I1 = rgb2gray(I1); I1 = im2double(I1);
I2 = imread('2.jpg');
I2 = rgb2gray(I2); I2 = im2double(I2);
bg = imread('bg_2.jpg');
bg = rgb2gray(bg); bg = im2double(bg);
%b)
D1 = I1 - bg;
D2 = I2 - bg;
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%c) I. and II.
B1 = abs(D1) > 0.1*max(abs(D1(:)));
B2 = abs(D2) > 0.1*max(abs(D2(:)));
%c) III.
n = round( 0.005*min(size(I1)) );
SE = strel('arbitrary', ones(n));
%c) IV.
M1 = imopen(B1, SE);
M2 = imopen(B2, SE);
%d) I. and II.
[i,j] = find(M1);
p 1(2) = sum(i)/numel(i);
p 1(1) = sum(j)/numel(j);
[i,j] = find(M2);
p 2(2) = sum(i)/numel(i);
p_2(1) = sum(j)/numel(j);
%d) III.
p2m = 0.05;
t = 2; %s
v = norm(p_2-p_1)*p2m/t %m/s
v*60*60/1000
```