# Usevalad Milasheuski 10816982

#### -sendAck.nc

In the code 4 variables are used:  $last\_digit = 2$ , which is the last digit of the ID, counter and  $rec\_id$  which are counters (one variable for each node. As we receive the REQ we assign the RESP its counter.) and  $req\_ack$ , which keeps track of the number of acks received by node 1. When the system is booted we start the node 1 by switching on its radio and triggering a timer corresponding to the periodic sending of the REQ message. For the message we also use a flag to indicate that an ACK is expected. Once the msg is sent we check if we received an ack. If no, which is true for the first Y = 16 seconds, the statement is displayed and we leave the function waiting a second for the timer to send another REQ.

One the node 2 is booted, we switch on the radio and do nothing, since the timer was checked to be used by the node 1 using *TOS\_NODE\_ID*. When the REQ is received by node 2 it sends back an ack and upon reception we increment *req\_ack*, checking if it is equal to *last\_digit+1*. We display the counter and, if the previous statement is true, we stop the timer, otherwise timer is intact. Then node 2 extracts the counter from the REQ, generates the measurement, creates a message and sends it with a flag. As before, once the message is received, its content is displayed and an ACK is sent back. and stop sending REQs.

### - sendAckApp.nc

For wiring the components. Simmilar to all the previous example, with several new interfaces, like *FackeSensorC* for the sensor and *ActiveMessageC* to work with ACKs.

#### -sendAck.h

The message is a structure having 3 fields:  $msg\_type$ , which represents if the message is REQ/RESP;  $msg\_counter$ , for signing the message with the iteration and value, which has the measurement from the sensor.

## -RunSimulationScript.py

Only two lines are modified: time2 = 16\*t.ticksPerSecond(); - to make the mote 2 start at the corresponding time;  $for\ in\ range(0,10000)$ : - increased the number of events displayed.

ALL THE OTHER FILES, LIKE NOISE OR TOPOLOGY ARE REMAINED UNMODIFIED.