

ME 3109: Measurement & Instrumentation



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ME 3109: Measurement & Instrumentation

Topic_06: Data Acquisition System^[1]

1	Signals
2	A/D Conversion
3	D/A Conversion
4	DAS

[1] Figliola's "*Theory & Design for Mechanical Measurements*", 5th Edition

1. Signals



(a) Analog signal representation



(b) Analog display

- Continuous in time
- Exact time dependent behavior
- most natural processes
- -10 to $+10$ V or 4 to 20 mA

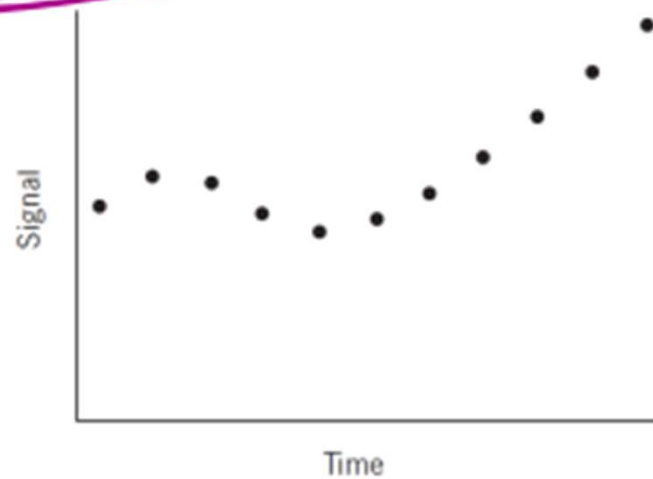
Signals: They are defined by how they convey information

Amplitude, state, frequency,
pulse width, phase

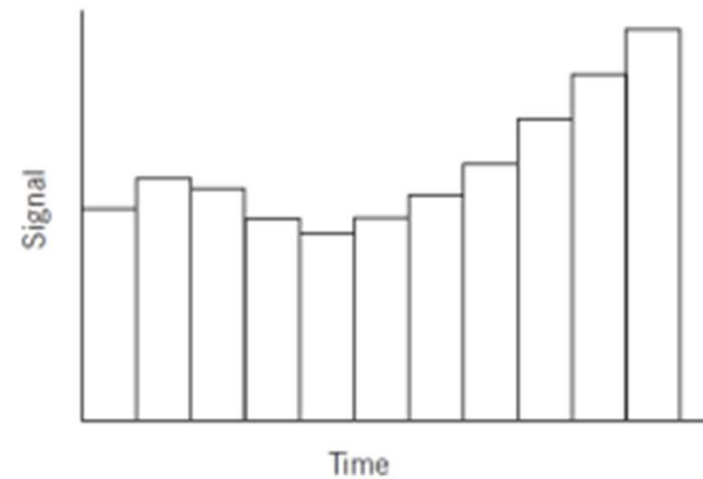
← useful!

1. Signals

Discrete Time Signal



(a) Discrete time signal

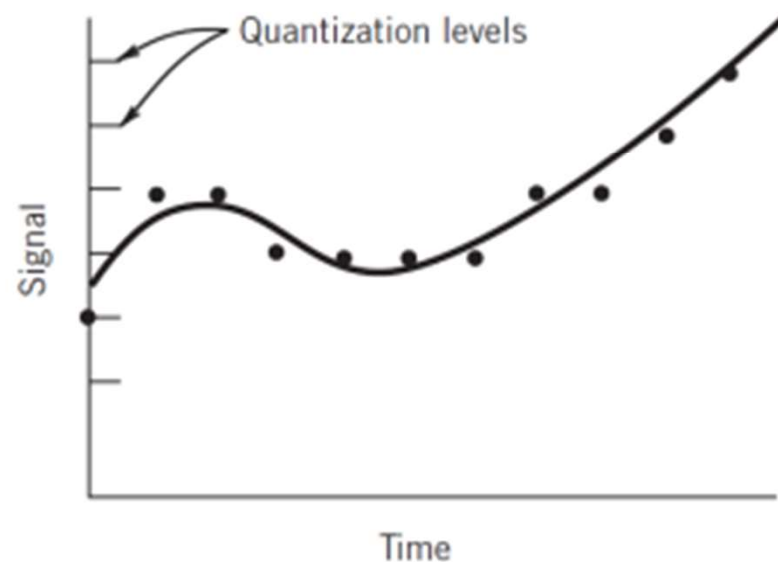


(b) Discrete time waveform

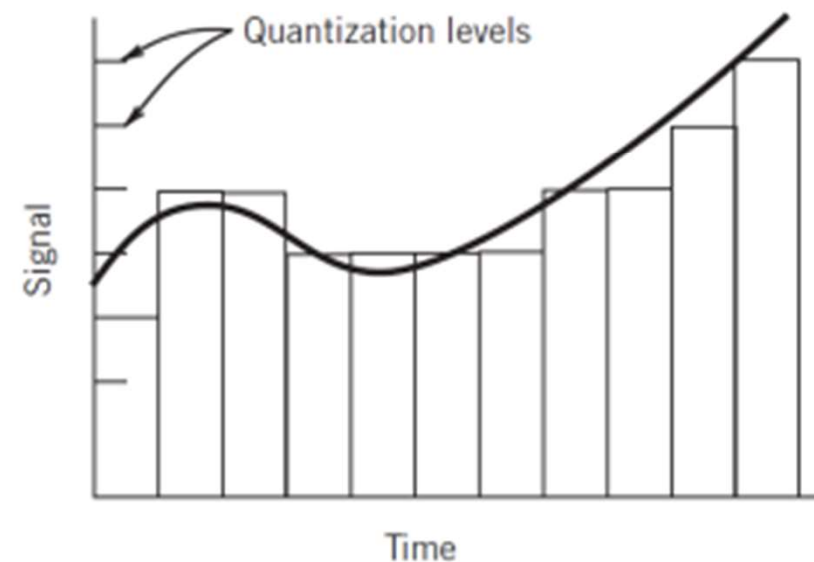
- Information available only at discrete time
- Results from sampling at repeated finite time interval
- No restriction on the amplitude of the signal

1. Signals

Digital Signal



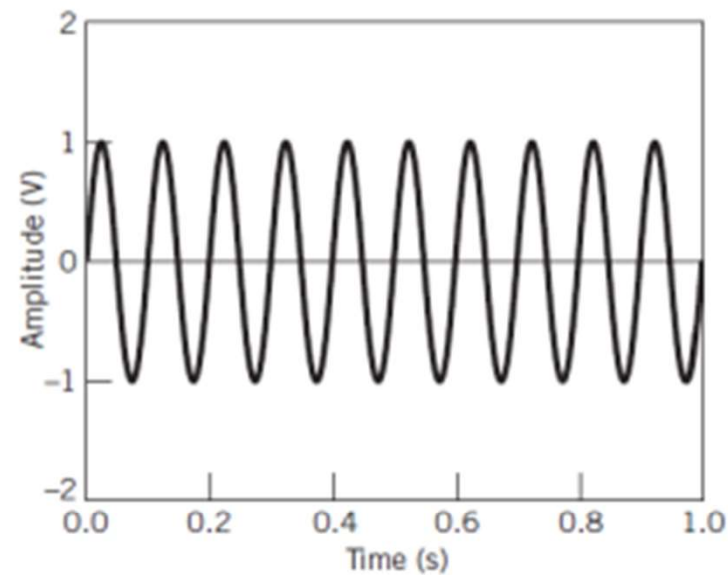
(a) Digital signal



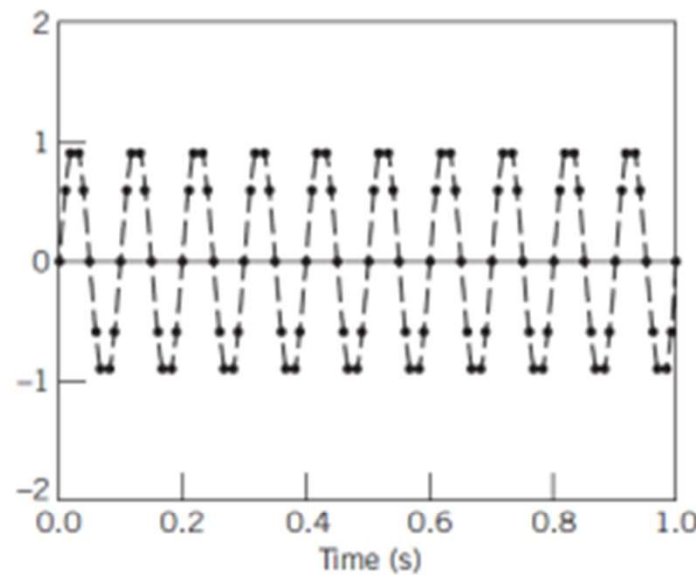
(b) Digital waveform

- Discrete values ^{sampling} in time
- Magnitude of signal is also discrete _{Quantization}

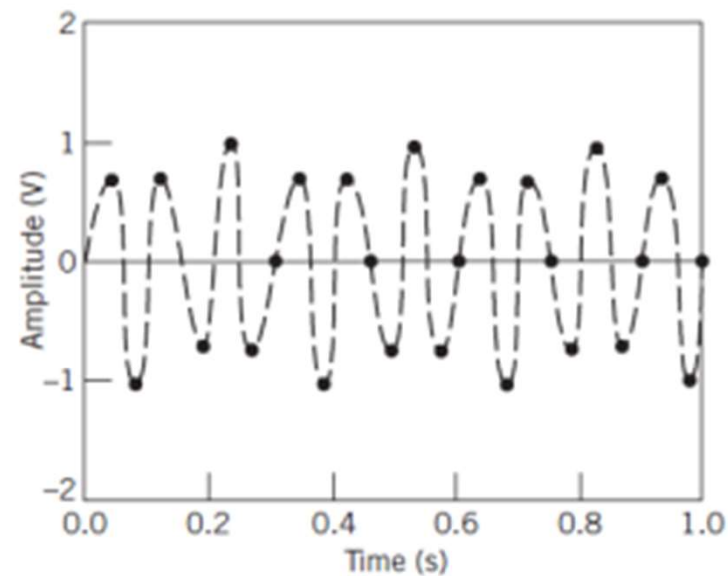
2. A/D Conversion Compromise



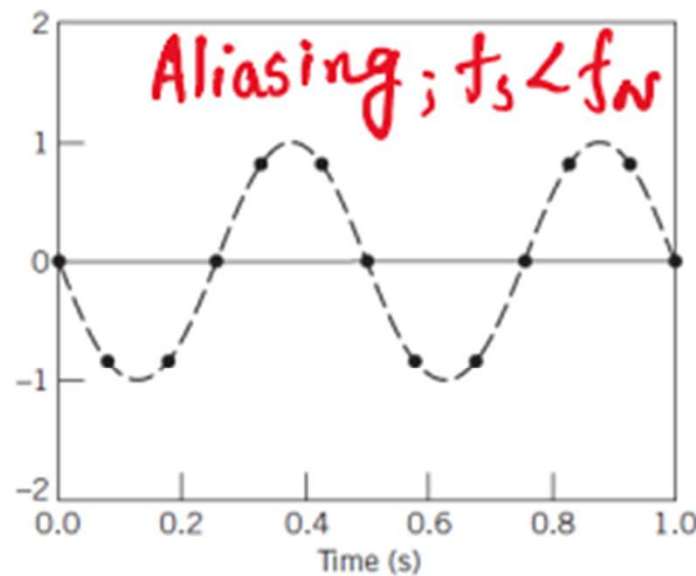
(a) Original 10-Hz sine wave analog signal



(b) $f_s = 100$ Hz



(c) $f_s = 27$ Hz



(d) $f_s = 12$ Hz

Sampling: Acquiring data at discrete intervals in time.

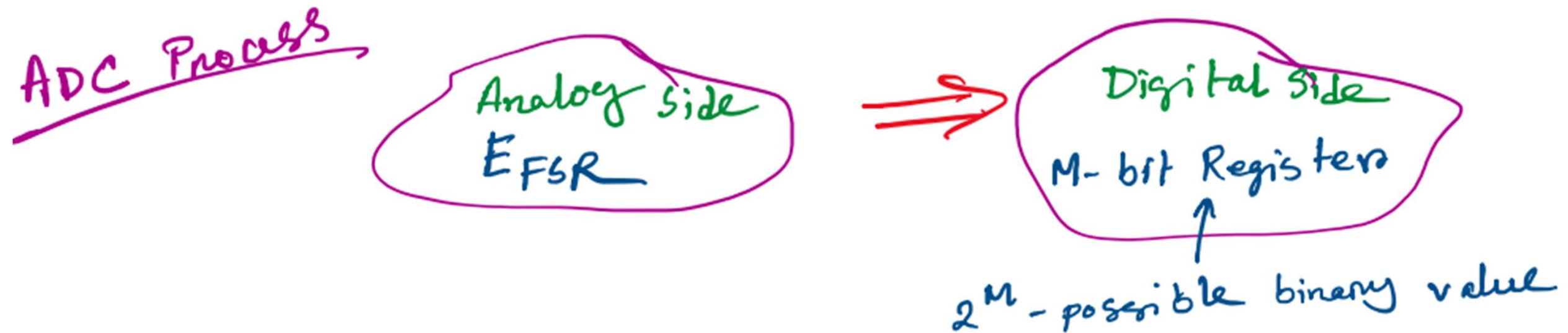
Sampling Rate: Shannon's
sampling Theorem

$$f_s > f_N = 2f_{\max}$$

\downarrow Nyquist frequency

$$\Delta t = \frac{1}{f_s} ; \text{time interval}$$

2. A/D Conversion Compromise

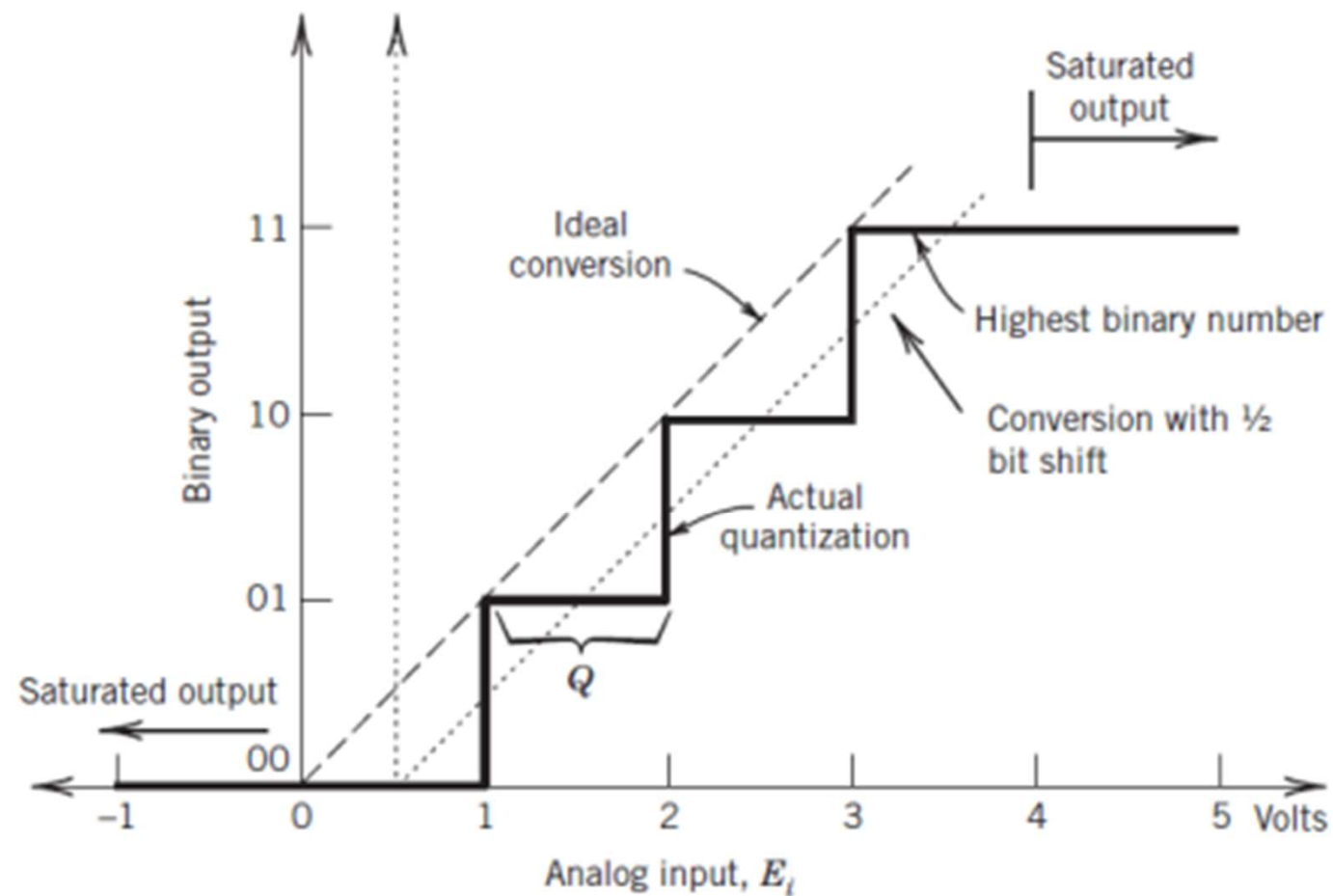


Resolution : Smallest voltage increment that causes a bit change.

$$Q = E_{FSR} / 2^M$$

- Quantization error is the inherent uncertainty in the A/D conversion due to the finite resolution of the system

2. A/D Conversion Errors



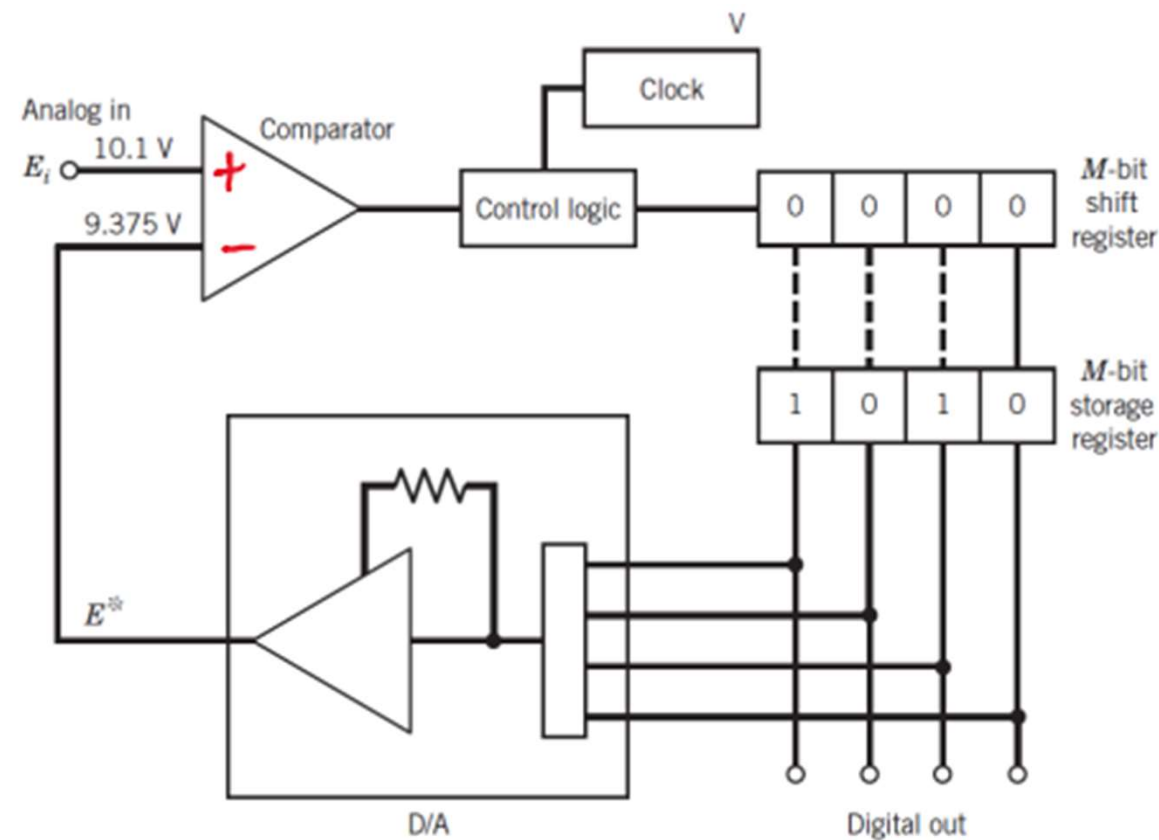
Bits M	Q^a (V/bit)	SNR (dB)
2	2.50	12
4	0.625	24
8	0.0390	48
12	0.00244	72
16	0.153 (10^{-3})	96
18	0.0381 (10^{-3})	108

^aAssumes $E_{FSR} = 10$ V.

$$SNR = 20 \log 2^M \text{ [dB]}$$

* Saturation Error and Conversion Error

2. Successive Approximation ADC



Sequence	Register	E^*	E_i	Comparator
Initial status	0000	0	10.1	
MSB set to 1	1000	7.5	10.1	High
Leave at 1	1000	7.5		
Next highest bit set to 1	1100	11.25		Low
Reset to 0	1000	7.5	10.1	
Next highest bit set to 1	1010	9.375		High
Leave at 1	1010	9.375		
LSB set to 1	1011	10.3125	10.1	Low
Reset to 0	1010	9.375		

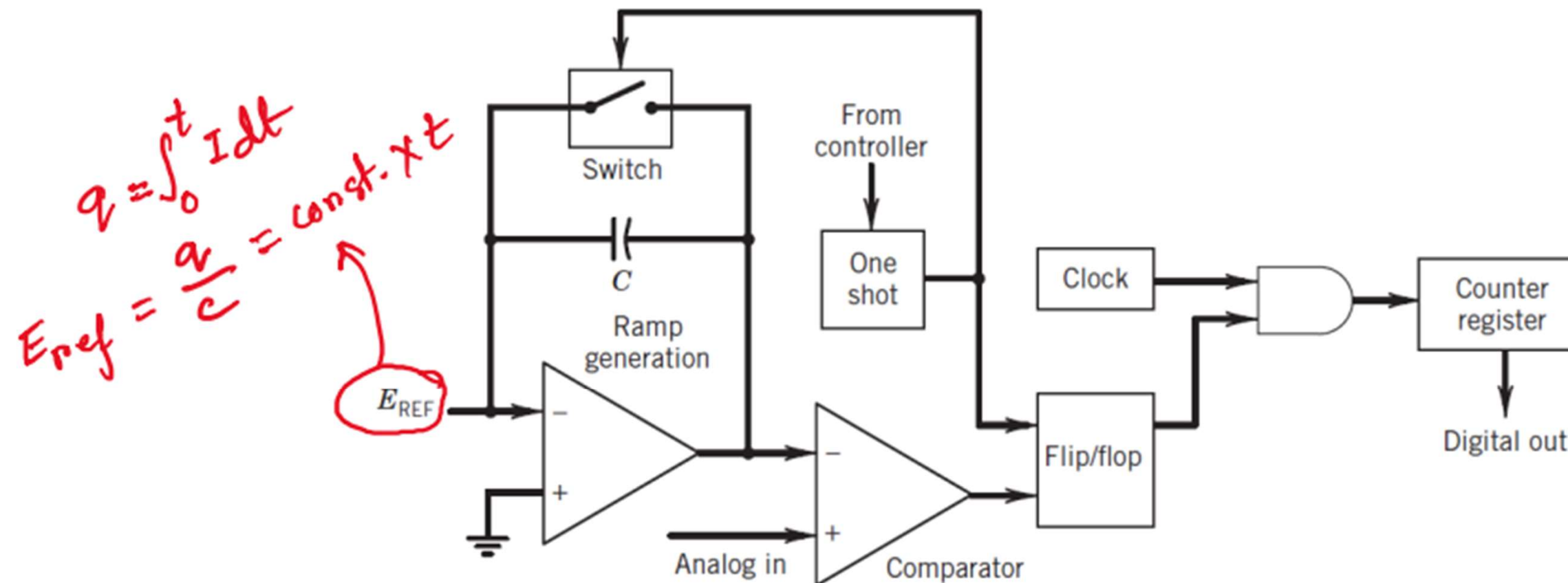
• 4-bit } $Q = \frac{15}{2^4} = 0.9375$
 • 0-15 V }
 $\rightarrow 1000 \rightarrow \frac{8 \times Q = 7.5 \text{ V}}{\text{D/A}}$

* Typically used with a SAR

* Noise is main drawback

2. A/D Conversion

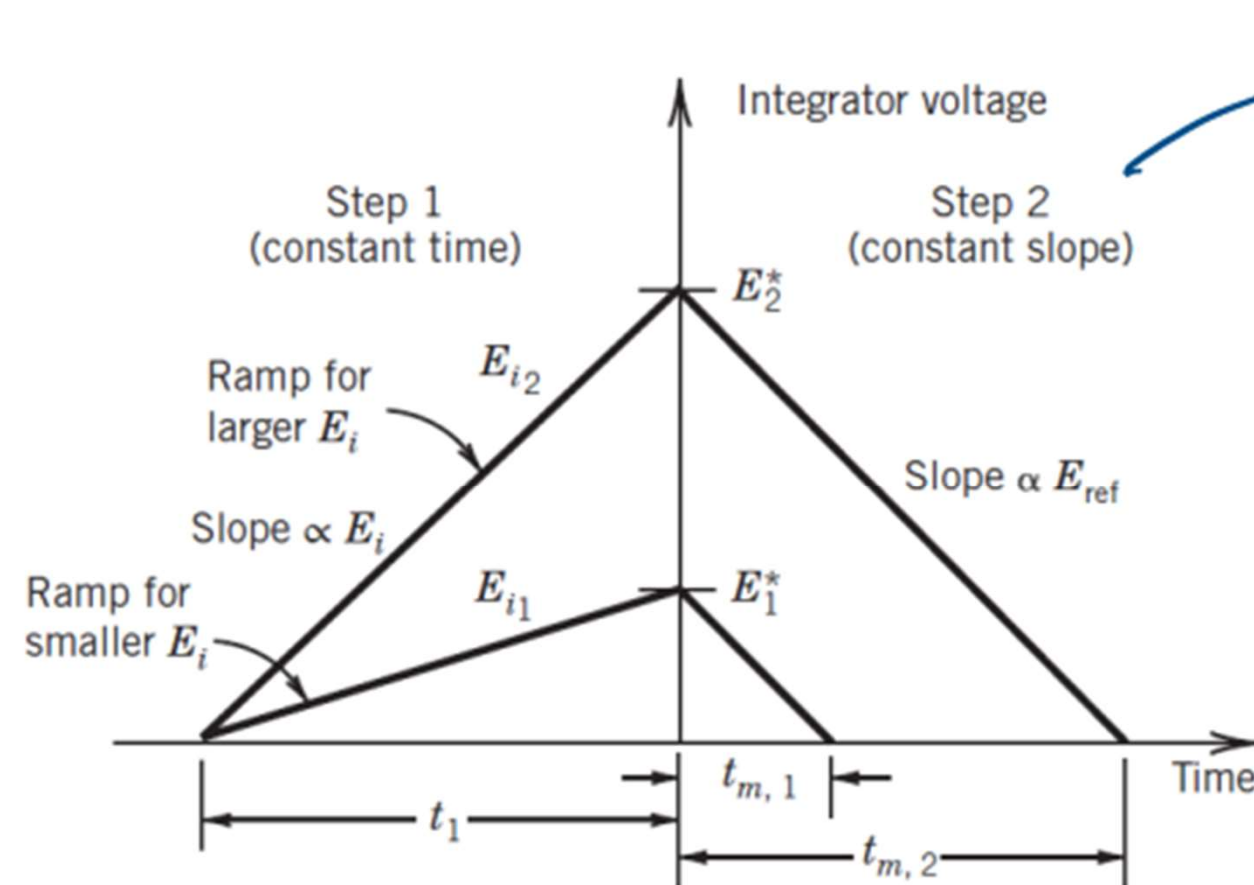
Ramp (Integrating) Converters



Time is integrated by a counter that increases the register value by 1 bit at each time step. Time step size depends on the value of 2^M . When the input voltage and ramp voltage magnitudes cross during a time step, the comparator output goes to zero, which flips a flip-flop halting the process. The register count value then indicates the digital binary equivalent of the input voltage.

2. A/D Conversion

Dual Ramp/Slope Integrating Converters



Step 1: E_i → Integrator → $E_o(t)$

Step 2: E_{ref} → Integrator → $E_o(t)$

$$\frac{E_i}{E_{ref}} = \frac{t_m}{t_1}$$

* Increased accuracy

Ramp Converter Notes

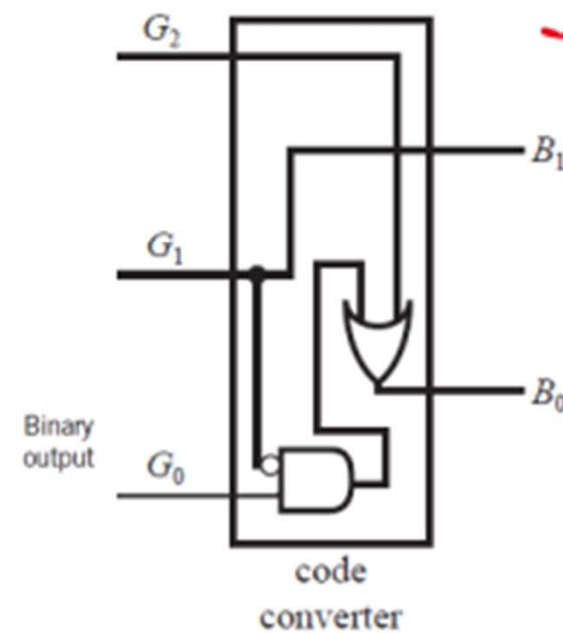
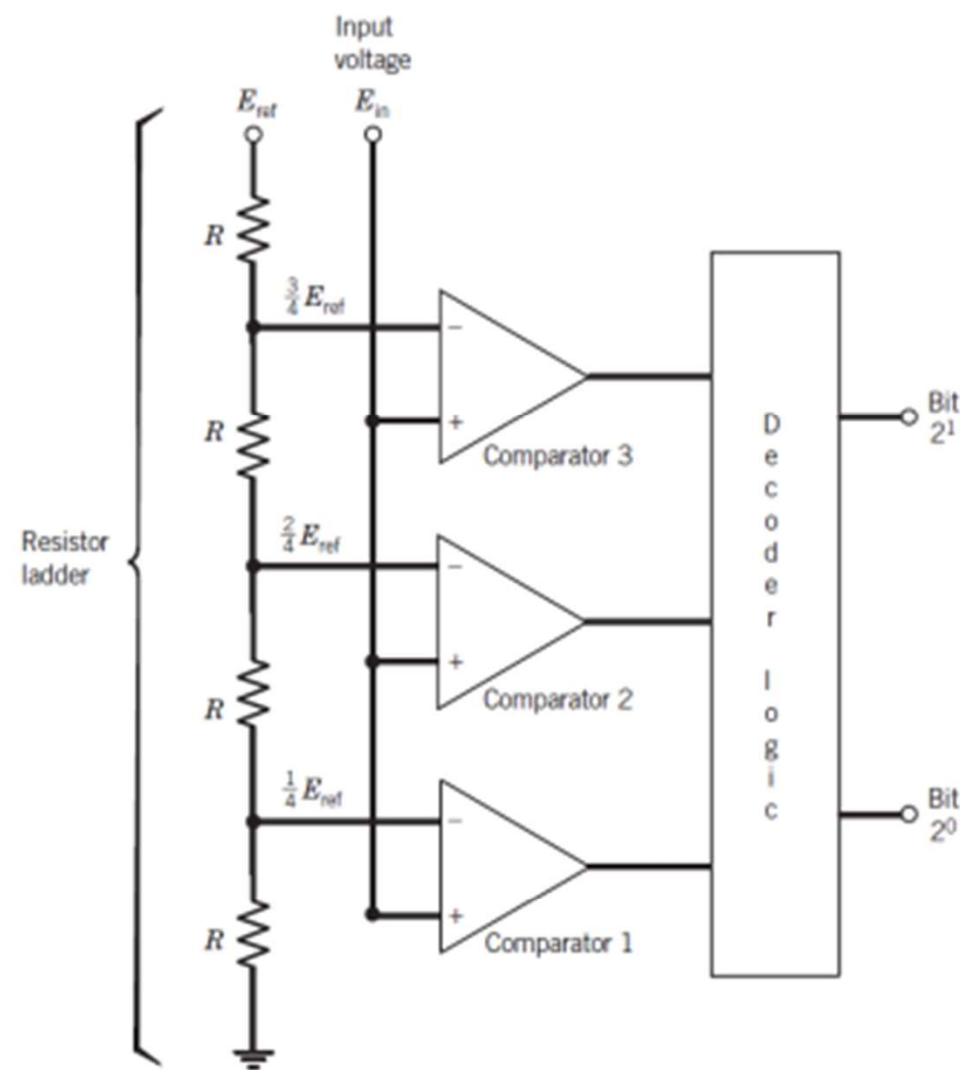
* Slow

* Integration process
average out noise

* Attractive for low-level signal

2. A/D Conversion

Parallel/Flash Converters



$$B_0 = G_0 \cdot \overline{G_1} + G_2$$

$$B_1 = G_1$$

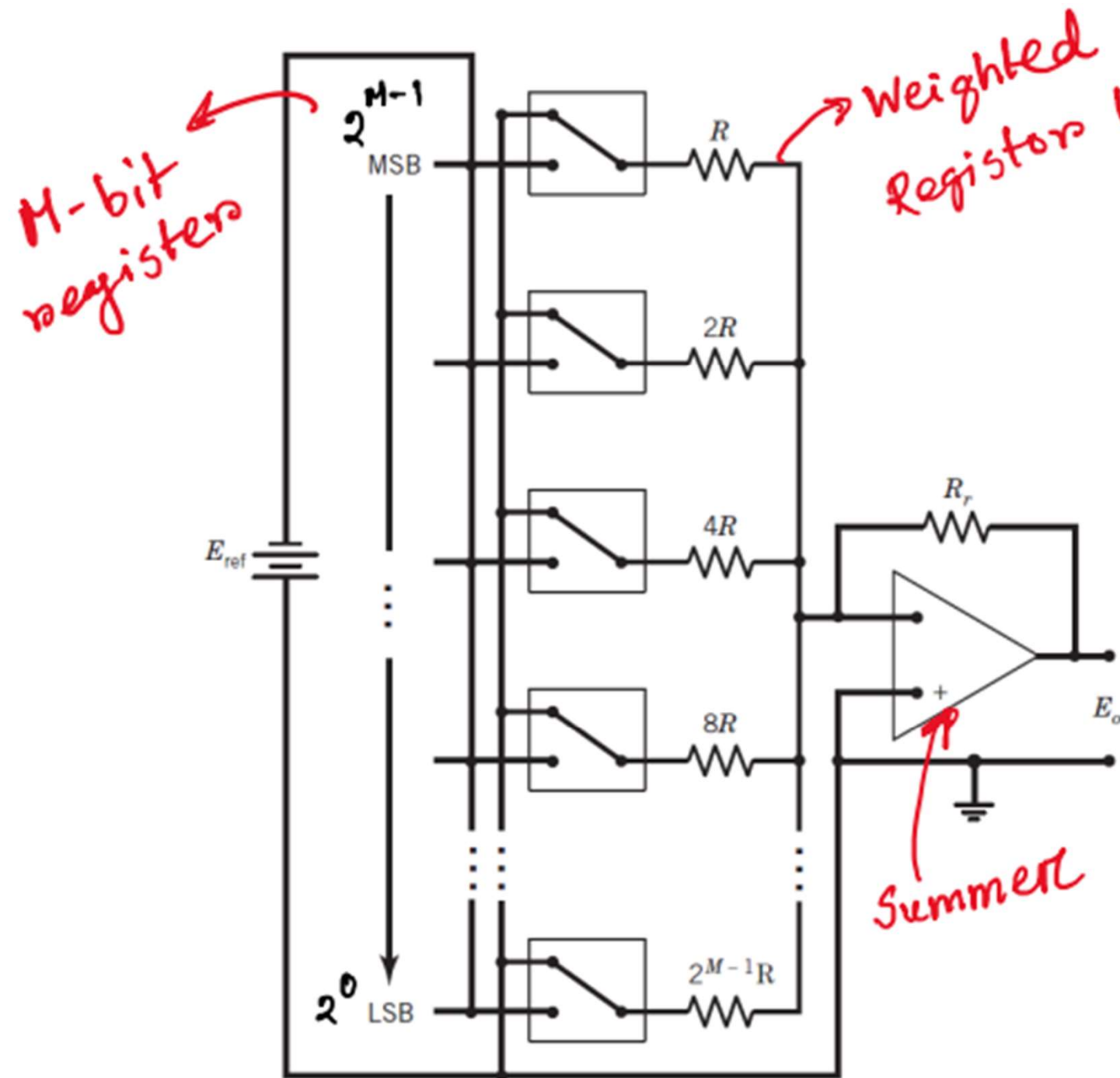
- Fast (Digital O-scope) but costly

2-bit Flash ADC

Comparator			Binary output
1	2	3	
HIGH	HIGH	HIGH	11
LOW	HIGH	HIGH	10
LOW	LOW	HIGH	01
LOW	LOW	LOW	00

- $2^M - 1$ comparators
- 2^M different HIGH/LOW combination
- Logic circuits transfer this information to register

3. D/A Conversion



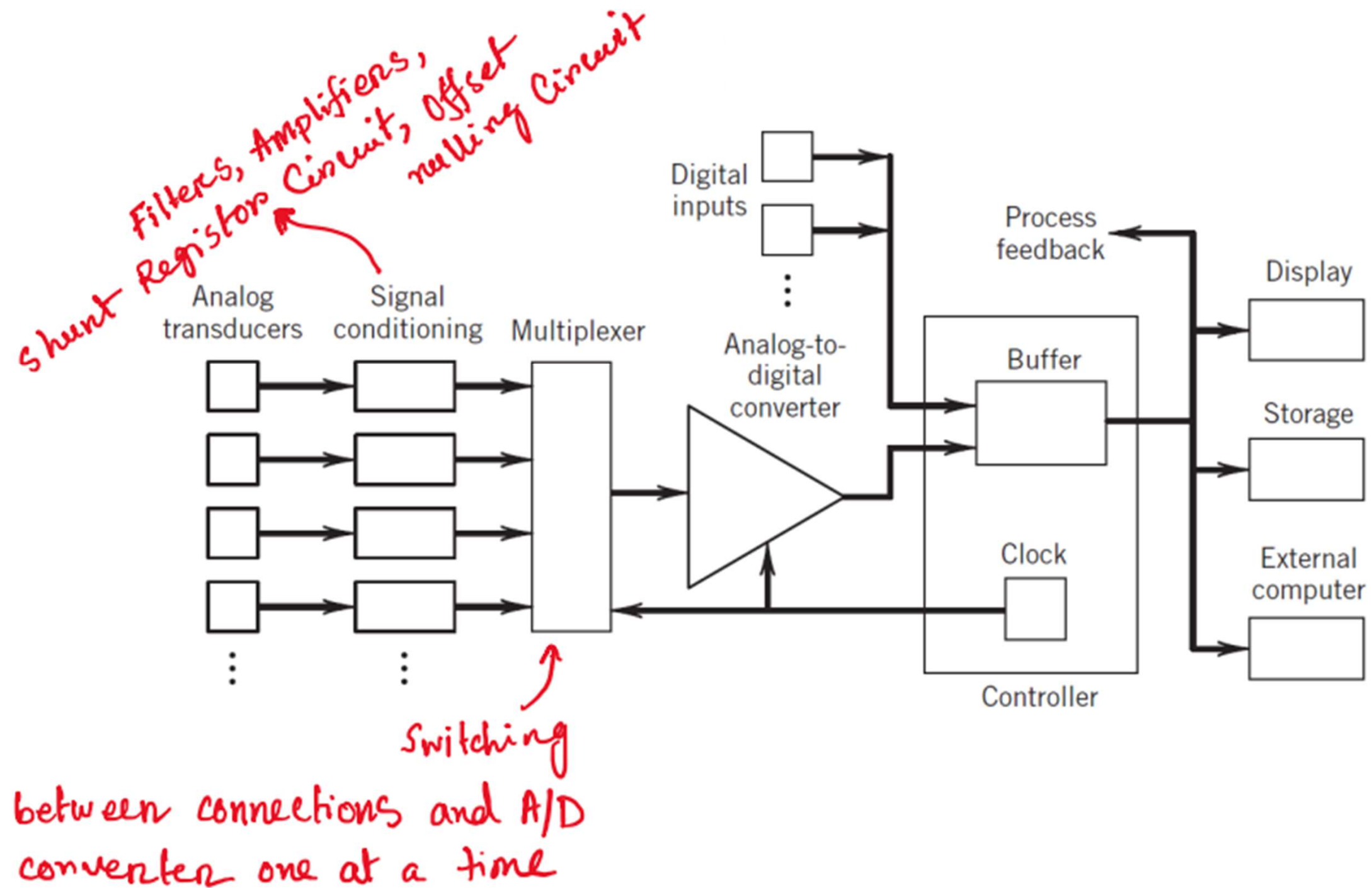
$$I = E_{ref} \sum_{m=1}^M \frac{C_m}{2^{m-1} R}$$

$C_m = 0$ or 1 ; depending on the m th bit value of the register

$$E_o = I R_f$$

The D/A converter will have both digital and analog specifications, the latter expressed in terms of its full-scale analog voltage range output (E_{FSR}). Typical values for E_{FSR} are 0 to 10 V (unipolar) and ± 5 V (bipolar) and for M are 8, 12, 16, and 18 bits.

4. DAS



Reading

Theory and Design for Mechanical Measurements, 7th Edition, *Richard S. Figliola & Donald E. Beasley*

- **Chapter 2**
 - ✓ 2.1, 2.2
- **Chapter 7**
 - ✓ 7.1-7.7
 - ✓ *Example problem: 7.3, 7.4, 7.5, 7.6*

Thank you