In [1]:

```
import numpy as np
import matplotlib
import matplotlib.pyplot as plt
```

Task 1

Find the dimensions (height - h, radius - r) that will minimize the surface area of the metal to manufacture a circular cylindrical can of volume V.

Solution

$$\begin{cases} V = \pi r^2 h = const \\ min_{h,r} S(h,r) = 2\pi r h + 2\pi r^2 \end{cases} \implies \begin{cases} h = \frac{V}{\pi r^2} \\ min_r A(r) = \frac{2V}{r} + 2\pi r^2 \end{cases}$$

Point that minimize A(r) must satisfy to the condition

$$dA(h,r) = 0, d^2A(r) > 0$$

$$\frac{dA}{dr} = -\frac{2V}{r^2} + 4\pi r = \frac{-2V + 4\pi r^3}{r^2} = 0$$

$$\begin{cases}
-2V + 4\pi r^3 = 0 \\
r \neq 0 \\
h = \frac{V}{\pi r^2}
\end{cases} \implies \begin{cases}
r = \left(\frac{V}{2\pi}\right)^{\frac{1}{3}} \\
h = \frac{V}{\pi\left(\frac{V}{2\pi}\right)^{\frac{2}{3}}}
\end{cases} \implies \begin{cases}
r = \left(\frac{2V}{4\pi}\right)^{\frac{1}{3}} \\
h = \frac{V}{\pi\left(\frac{1}{2\pi}\right)^{\frac{2}{3}}}
\end{cases}$$
For all $V \ge 0$

Task 2

Consider the unconstrained optimization problem to minimize the function

$$f(x) = \frac{3}{2}(x_1^2 + x_2^2) + (1+a)x_1x_2 - (x_1 + x_2) + b$$

, where a and b are real-valued parameters. Find all values of a and b such that the problem has a unique optimal solution.

Solution

$$f(x_1, x_2) = \frac{3}{2}(x_1^2 + x_2^2) + (1 + a)x_1x_2 - (x_1 + x_2) + b \text{ Criteria for minimum:}$$

$$\begin{cases} df(x_1, x_2) = 0 \\ d^2f(x_1, x_2) \ge 0 \end{cases} \implies \begin{cases} df(x_1, x_2) = (3x_1 + (1 + a)x_2 - 1) dx_1 + (3x_2 + (1 + a)x_1 - 1) dx_2 \\ d^2f(x_1, x_2) = 7 + a \ge 0 \end{cases}$$

In matrix form:

$$\begin{bmatrix} 3 & 1+a \\ 1+a & 3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \end{bmatrix} \implies$$

Cramer's rule

er's rule
$$\begin{cases} \det = 9 - (1+a)^2 \neq 0 \\ \det_{x_1} = 3 - (a+1) \\ \det_{x_2} = 3 - (a+1) \end{cases} \implies x_1 = x_2 = \frac{1}{4+a} \implies a \neq -4 \implies \begin{cases} a \geq -7 \\ a \neq 2 \\ a \neq -4 \\ \text{For all } b \end{cases}$$

Task 3

```
In [65]:
```

Contour plot

```
In [76]:
```

```
x = np.linspace(-10, 0, 101)
y = np.linspace(-10, 0, 101)
xx, yy = np.meshgrid(x, y, indexing='xy')
```

```
In [77]:
```

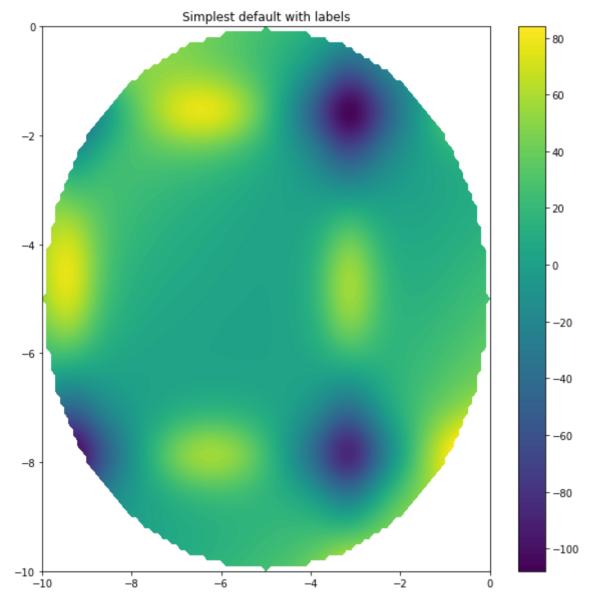
```
points_set = np.empty((0, 2))
for i in range(len(xx)):
    points_set = np.append(points_set, np.array(list(zip(xx[i], yy[i]))), axis=0
)
```

In [83]:

```
zz = np.apply_along_axis(f, 1, points_set)

X = np.reshape(points_set[:, 0], (101, 101))
Y = np.reshape(points_set[:, 1], (101, 101))
Z = np.reshape(zz, (101, 101))

plt.figure(figsize=(10,10))
plt.contourf(X, Y, Z, levels=100)
plt.colorbar()
plt.title('Simplest default with labels');
```



In [89]:

```
def nelder mead(func : callable, x 0 : list,
                alpha=1, beta=0.5, gamma=2, max_iter=-1,
                step=0.01, ro=0.5, tol=1e-9):
    hist = []
    points = np.zeros((len(x 0) + 1, len(x 0)))
    for i in range(len(x_0)):
        points[i, :] = x 0
        points[i, :] += step
    scored = sorted([ (point, func(point)) for point in points ],
                    key=lambda x: x[1])
#
      print(scored)
    if max iter == -1:
        max iter = 25
    iter num = 0
    while iter num < max iter and np.linalg.norm(scored[-1][0] - scored[-2][0])
> tol:
        scored = sorted([ [point, func(point)] for point in points ],
                        key=lambda x: x[1])
        hist.append(scored)
        iter num += 1
        # Sort (1)
        x h = scored[-1][0]
        f_h = scored[-1][1]
         print(x h, f h)
        x 1 = scored[0][0]
        f l = scored[0][1]
        x g = scored[-2][0]
        f g = scored[-2][1]
        # Center of gravity (2)
        x_c = sum([p[0] for p in scored[:-1]]) / (len(scored) - 1)
        # Reflection (3)
        x_r = x_c + alpha * (x_c - x_h)
        f r = func(x r)
        # Comparison (4)
        x_e = x_c + gamma * (x_r - x_c)
        f e = func(x e)
        row h = np.where((points == x h).all(axis=1))[0][0]
        # 4(a)
        if f r < f 1:
            if f e < f 1:
```

```
x_h = x_e
            points[row_h, :] = x_e
            continue
        elif f e > f l:
            x_h = x_r
            points[row_h, :] = x_r
            continue
    #4(b)
    if f_l < f_r < f_g:</pre>
        x h = x r
        points[row_h, :] = x_r
        continue
    # 4(c)
    if f_h > f_r > f_g:
        x h = x r
        points[row h, :] = x r
    # Contraction (5)
    x_s = x_c + beta * (x_h - x_c)
    f s = func(x s)
    # (6)
    if f s < f h:
        x h = x s
        points[row_h, :] = x_s
        continue
    # (7)
    if f s < f_h:
        for i in range(points.shape[0]):
            points[i, :] = x_1 + (points[i, :] - x_1) / 2
scored = sorted([ (point, func(point)) for point in points ],
                    key=lambda x: x[1])
return scored[-1][0], hist
```

Starts from different points

```
In [128]:

global p
p = 0
x_opt, hist = nelder_mead(func=f, x_0=np.array([-3, -2]), step=0.1, max_iter=125
)
f_opt = f(x_opt)

In [129]:
print("x_opt : {} \nf_opt : {} \nOracle calls : {}".format(x_opt, f_opt, p - 1))
```

x_opt : [-2.92845816 -1.918645 f opt : -88.03652366117646

Oracle calls : 206

In [130]:

```
global p
p = 0
x_opt, hist = nelder_mead(func=f, x_0=np.array([-3, -1]), step=0.1, max_iter=125
)
f_opt = f(x_opt)
```

In [131]:

```
print("x_opt : {} \nf_opt : {} \nOracle calls : {}".format(x_opt, f_opt, p - 1))
```

x_opt : [-3.28347604 -1.13341578]
f opt : -80.31254749659469

Oracle calls : 658