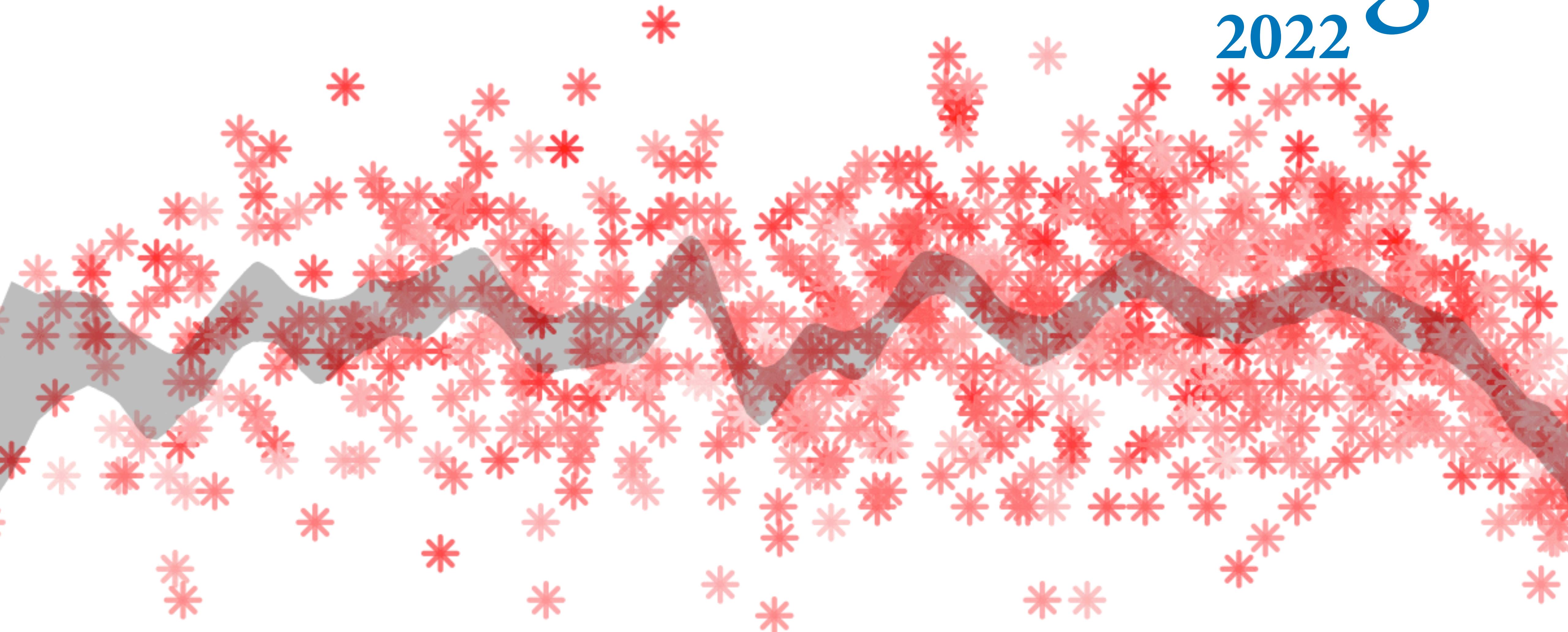


Statistical Rethinking

2022



14: Correlated Varying Effects

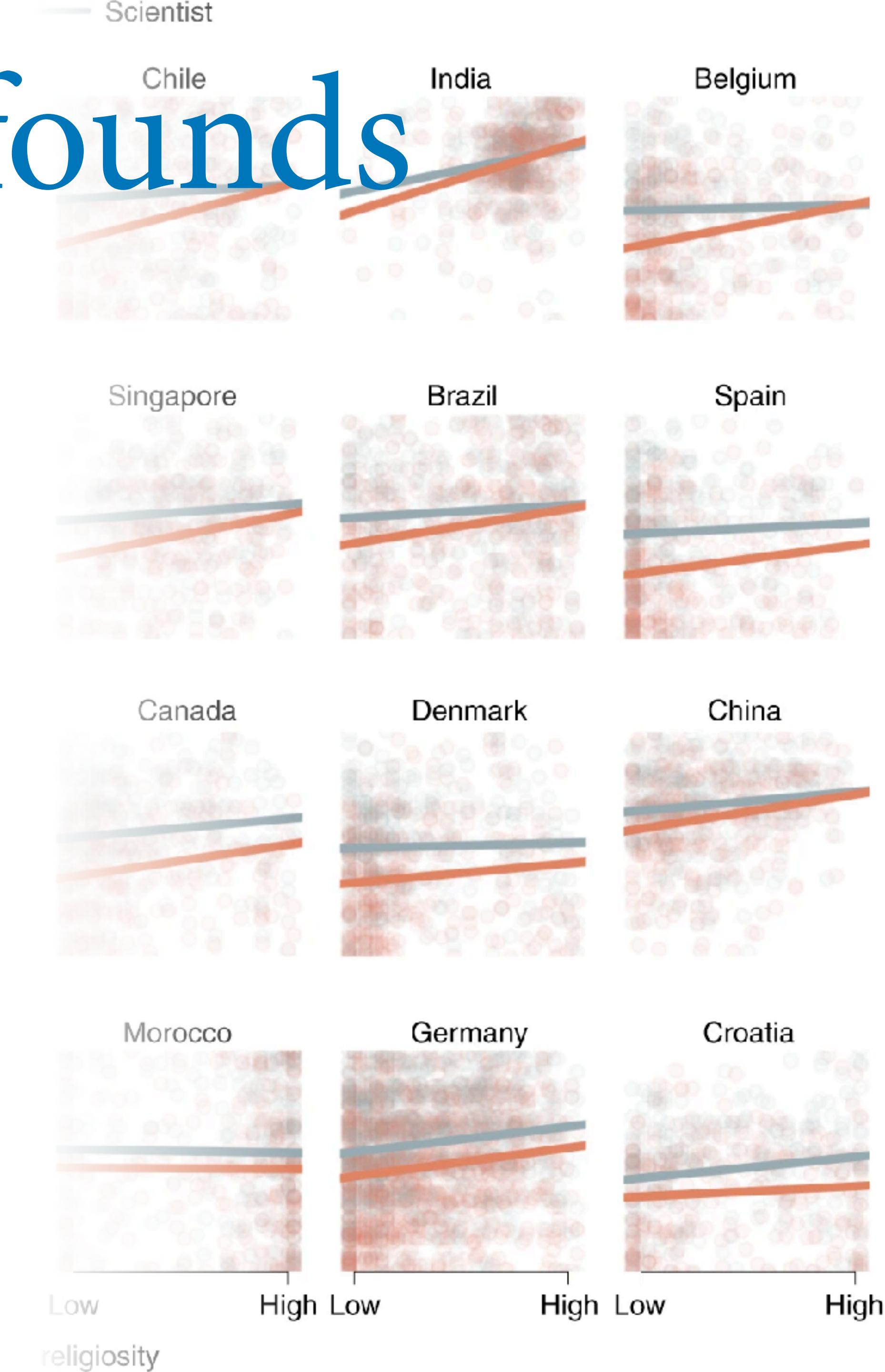


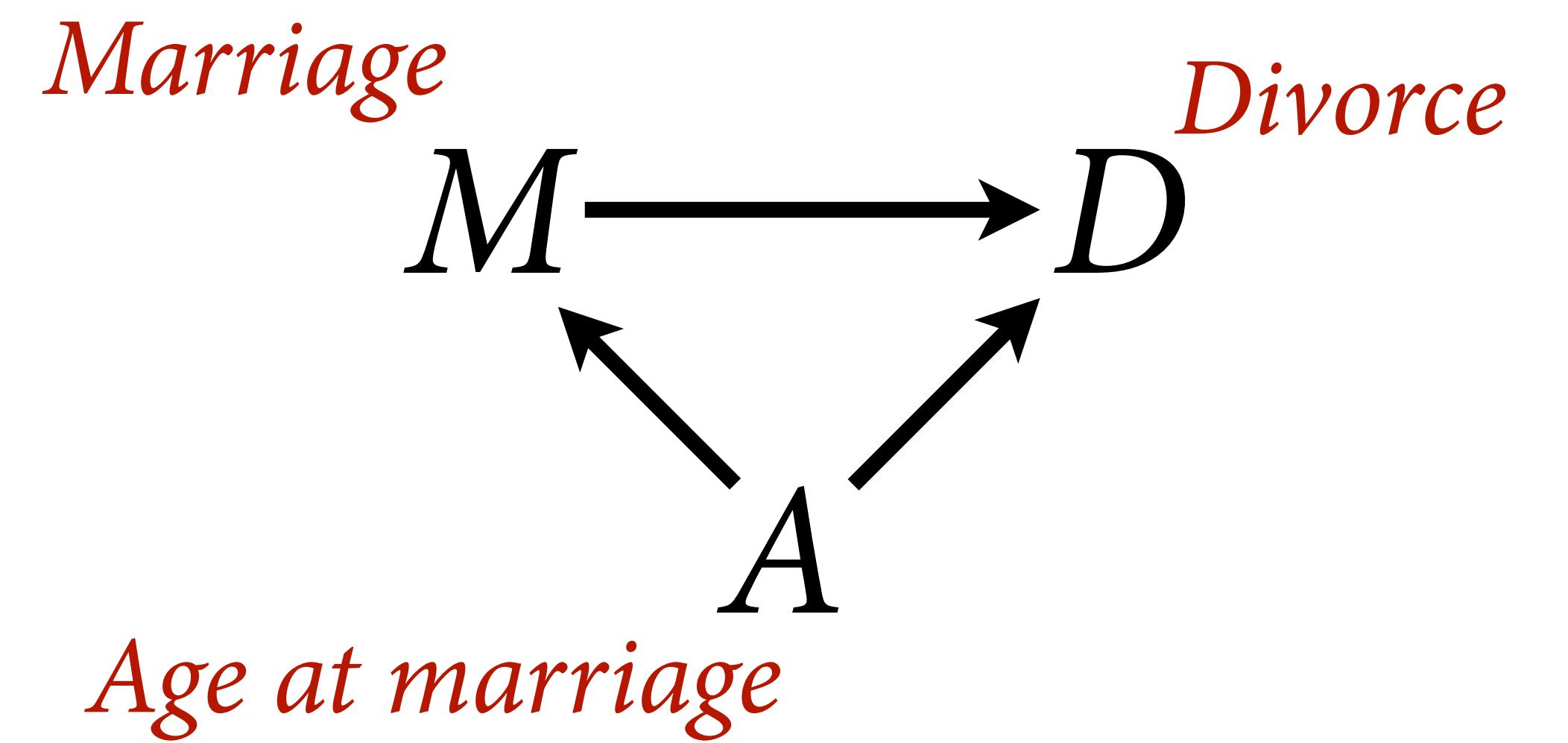
Varying effects as confounds

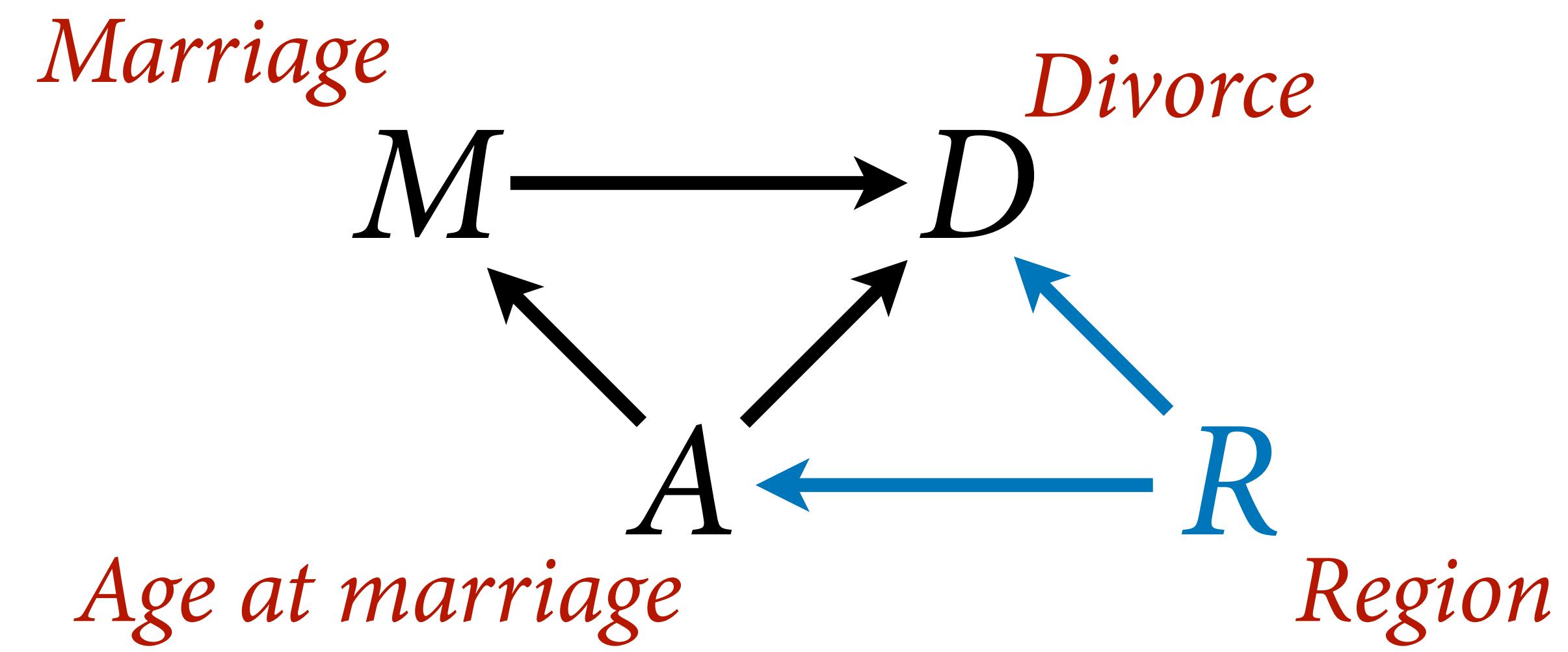
Varying effect strategy: Unmeasured features of **clusters** leave an imprint on the data that can be measured by (1) **repeat observations** of each cluster and (2) **partial pooling** among clusters

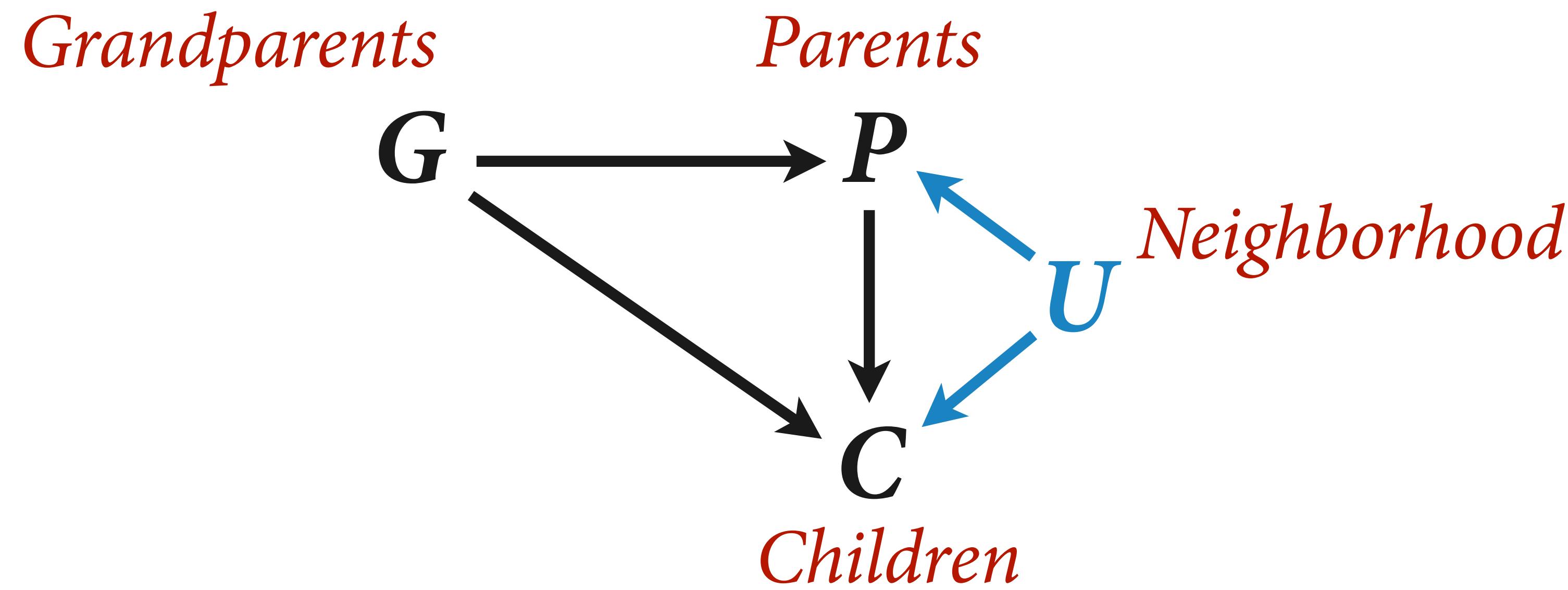
Predictive perspective: Important source of cluster-level variation, regularize

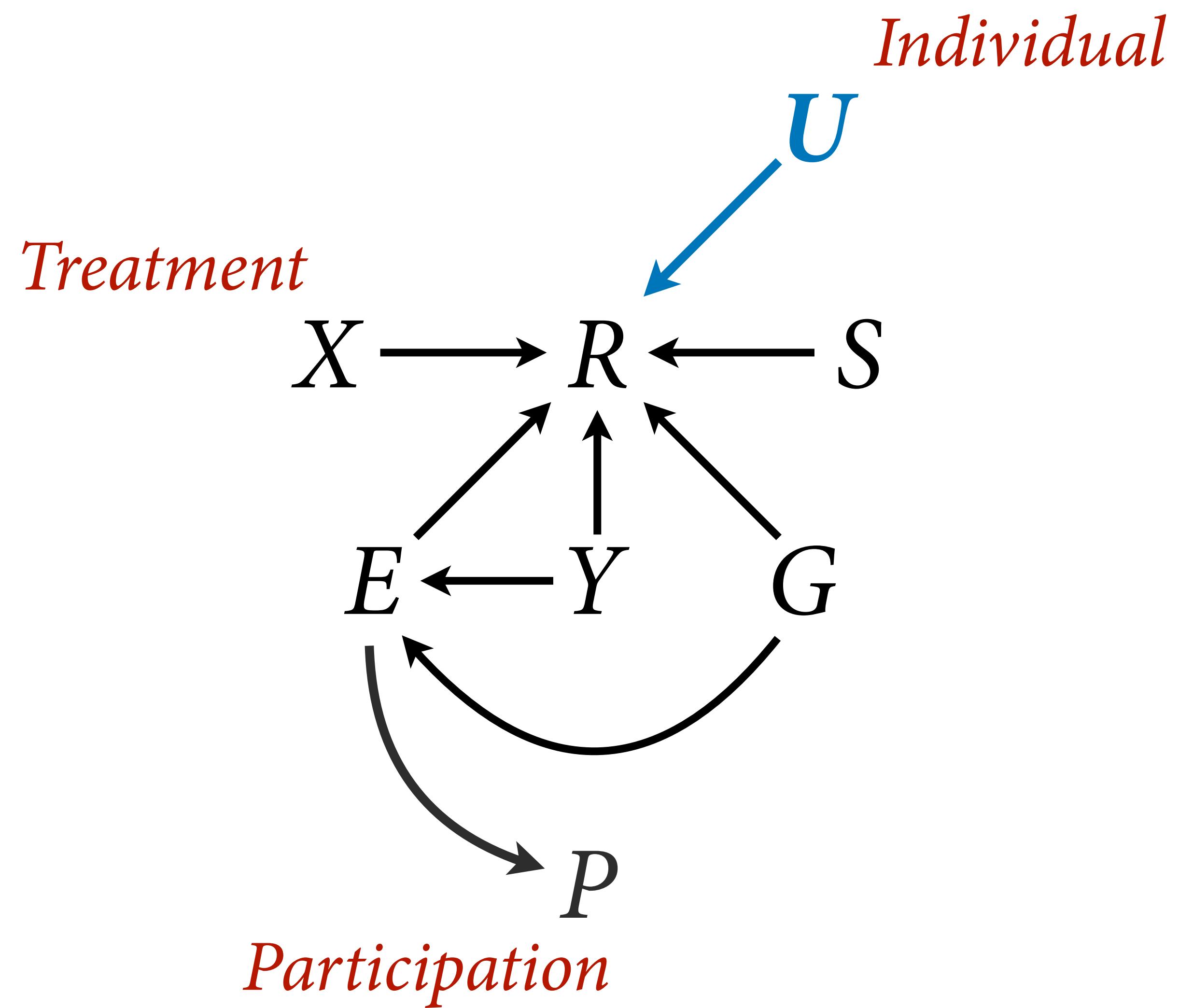
Causal perspective: Competing causes or unobserved confounds

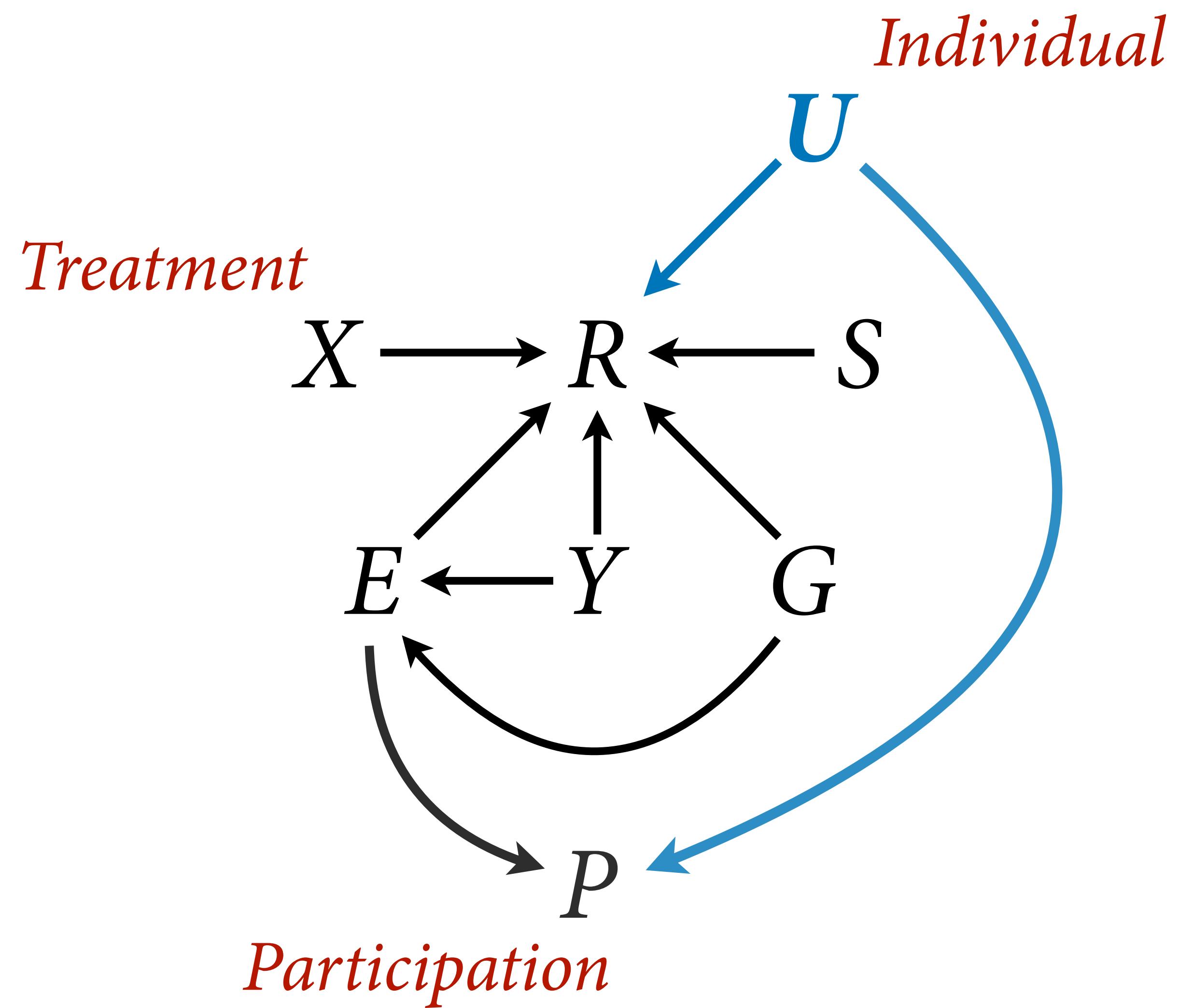


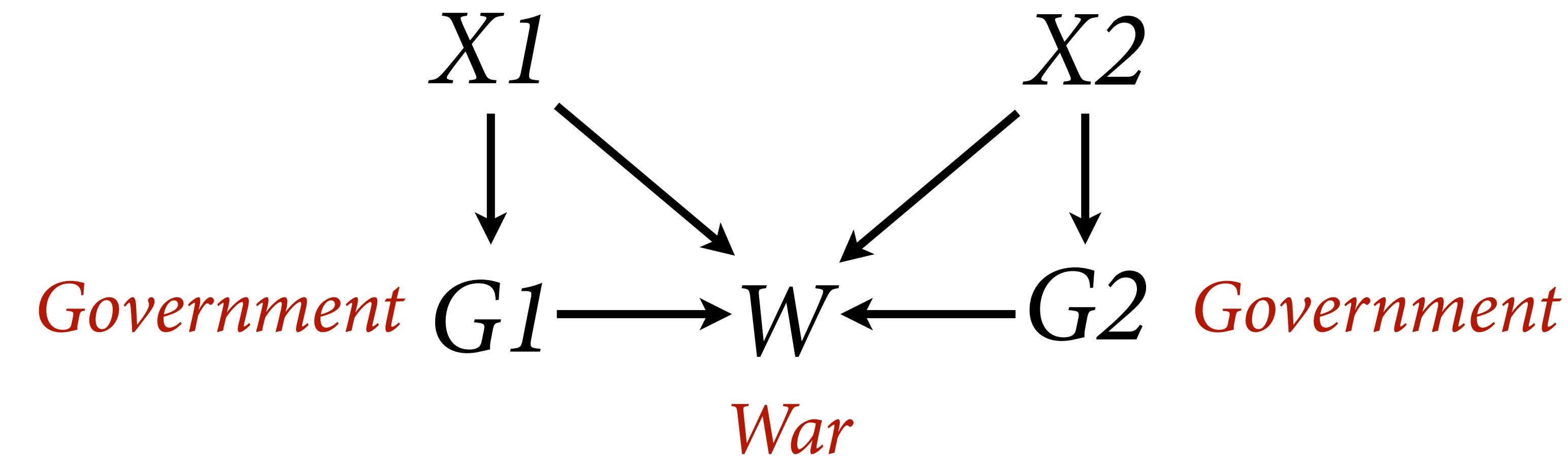


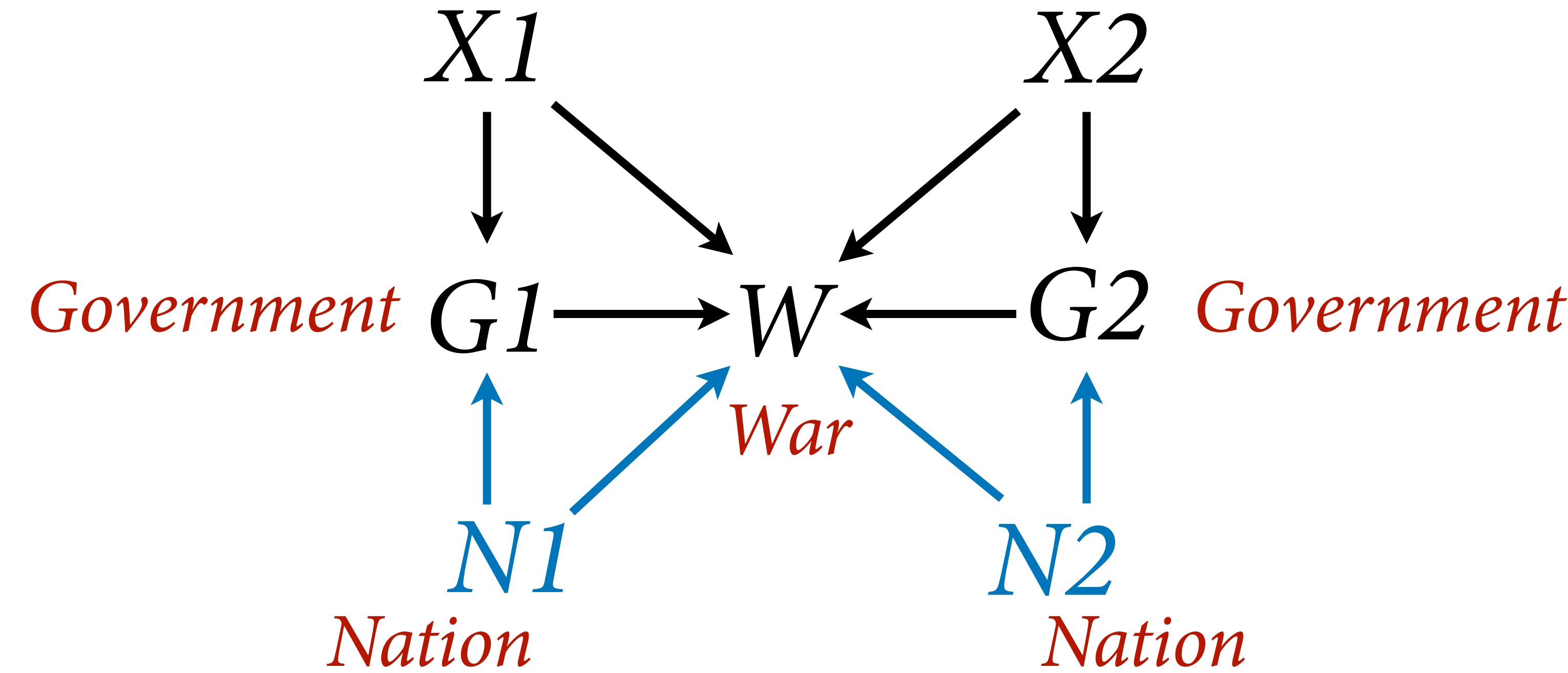












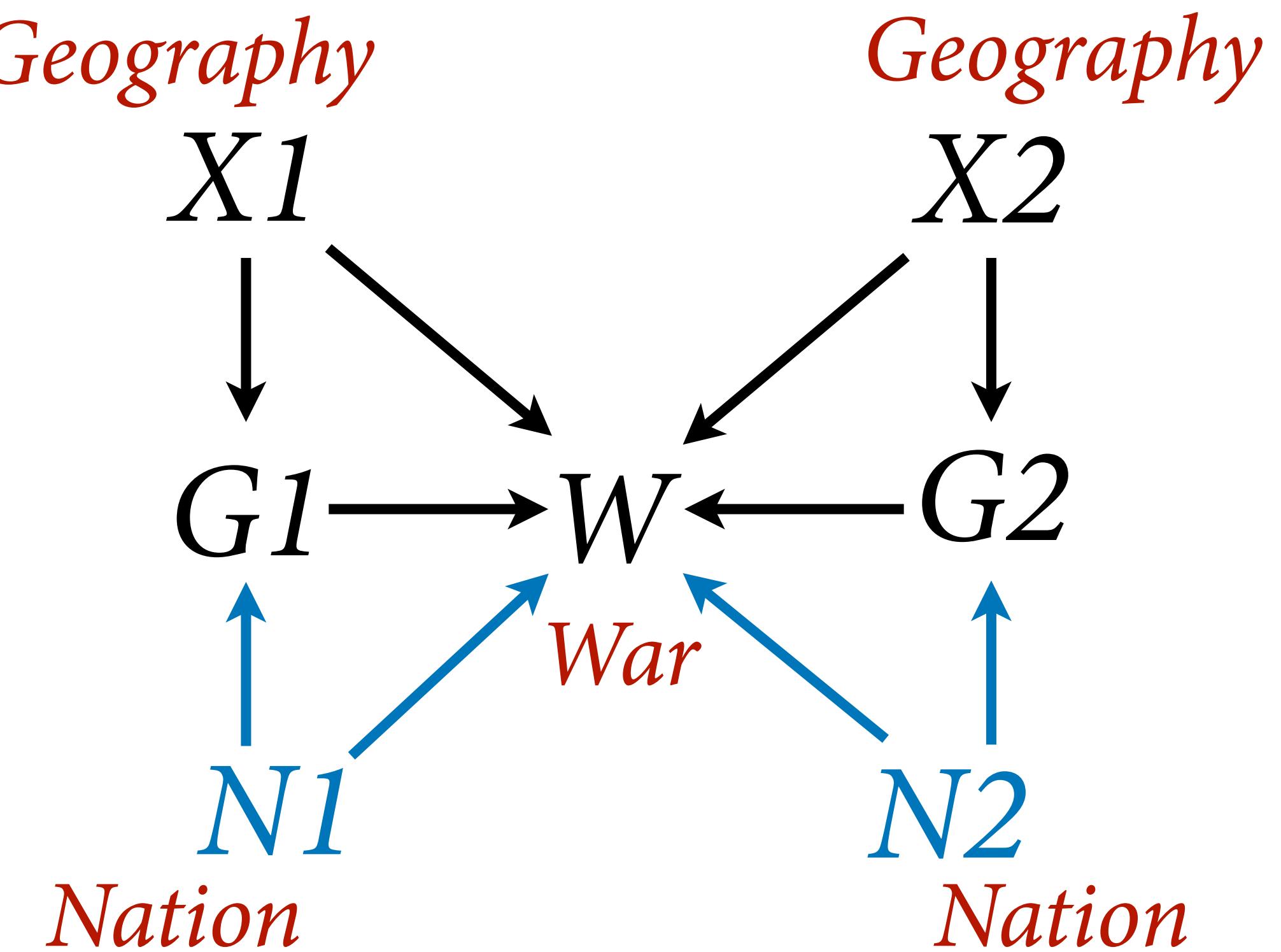
Varying effects as confounds

Causal perspective: Competing causes or actual confounds

Advantage over “fixed effect” approach: Can include other cluster-level (time invariant) causes

Fixed effects: Varying effects with variance fixed at infinity, no pooling

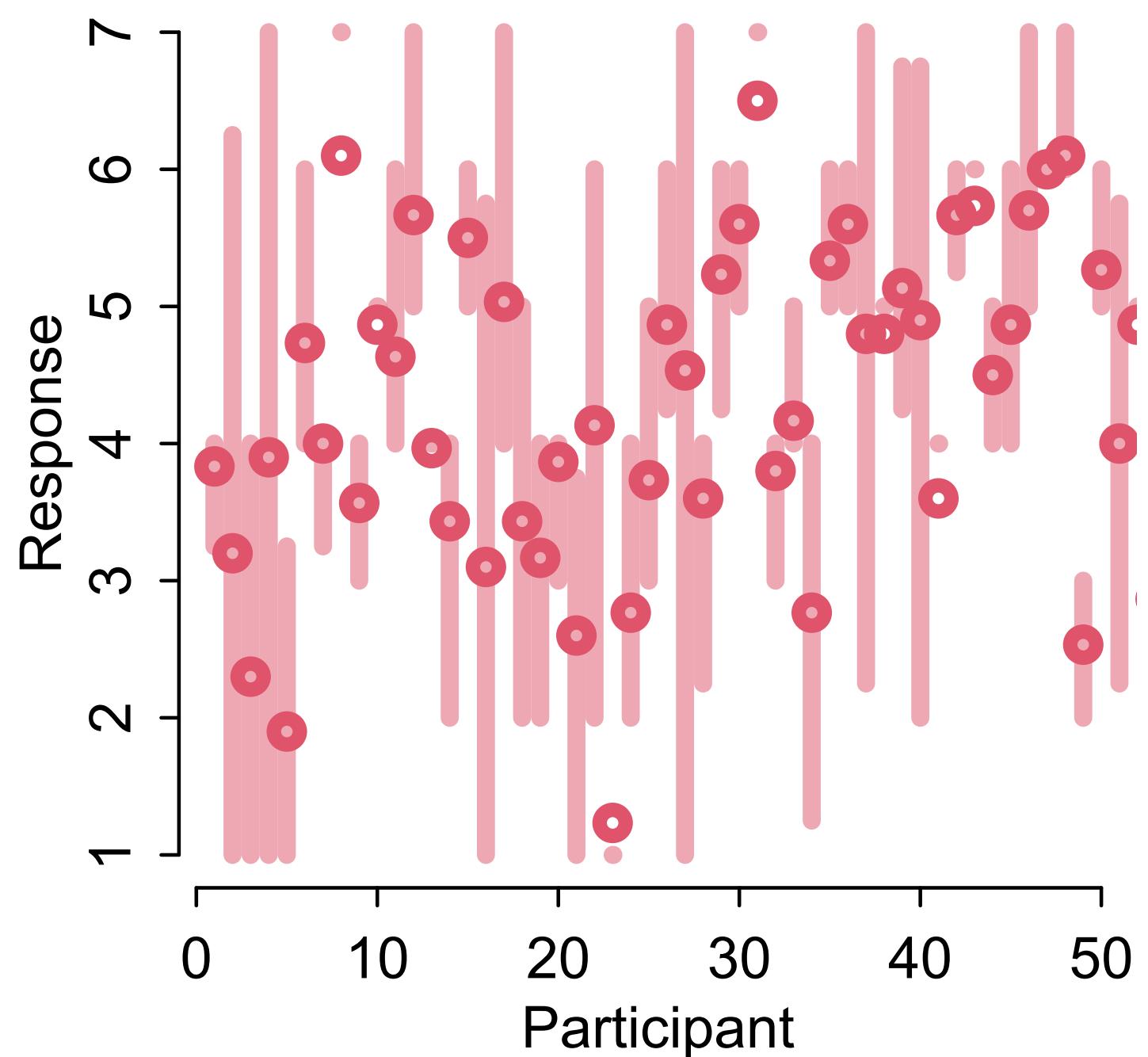
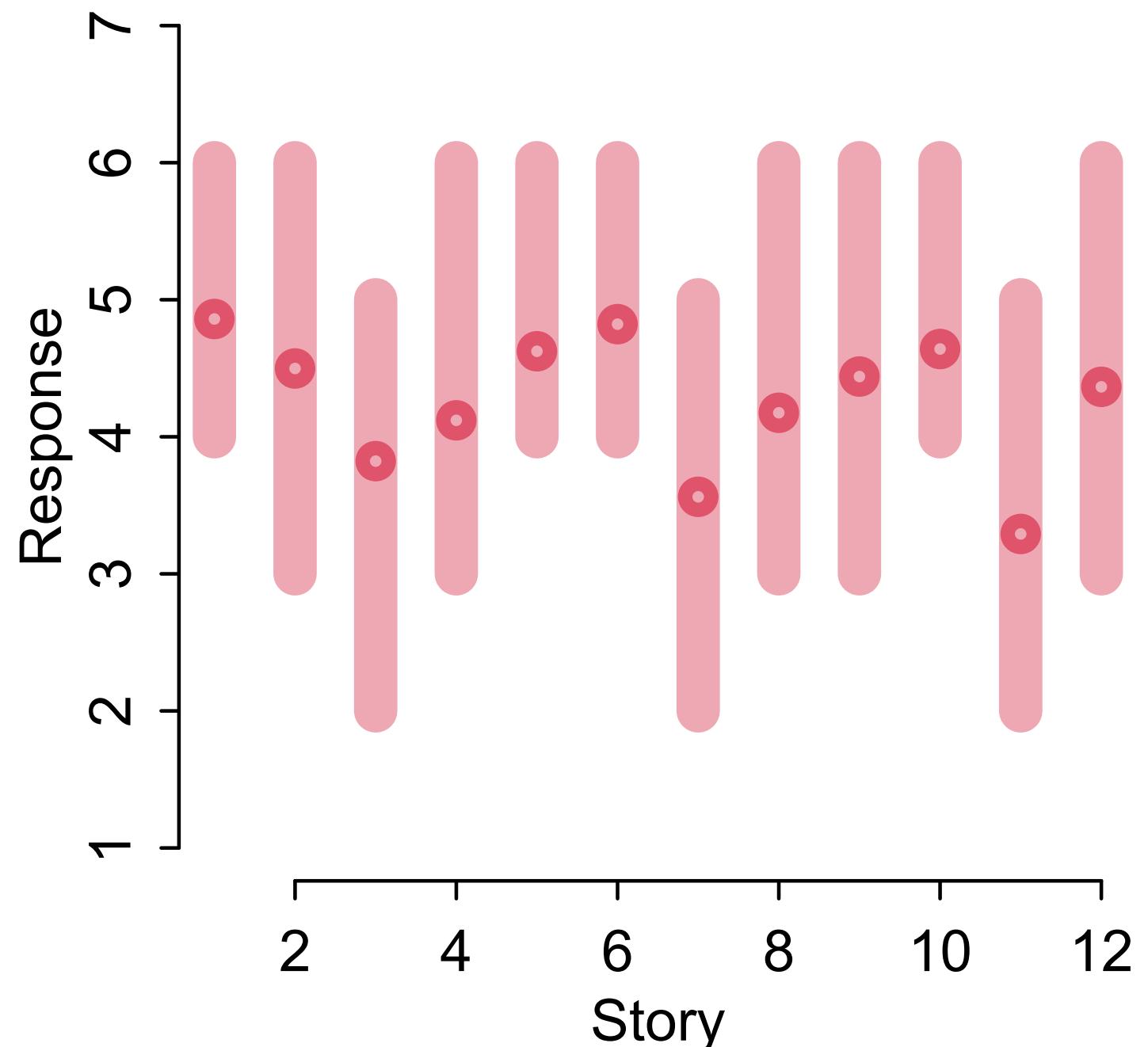
Don't panic: Make a generative model and draw the owl



Cluster	Features
tanks	survival
stories	treatment effect
individuals	average response
departments	admission rate, bias

Add clusters: More index variables, more population priors (previous lecture)

Add features: More parameters, more dimensions *in each* population prior (this lecture)



Adding Features

One prior distribution for each cluster

One feature: **One**-dimensional distribution

$$\alpha_j \sim \text{Normal}(\bar{\alpha}, \sigma)$$

Two features: **Two**-D distribution

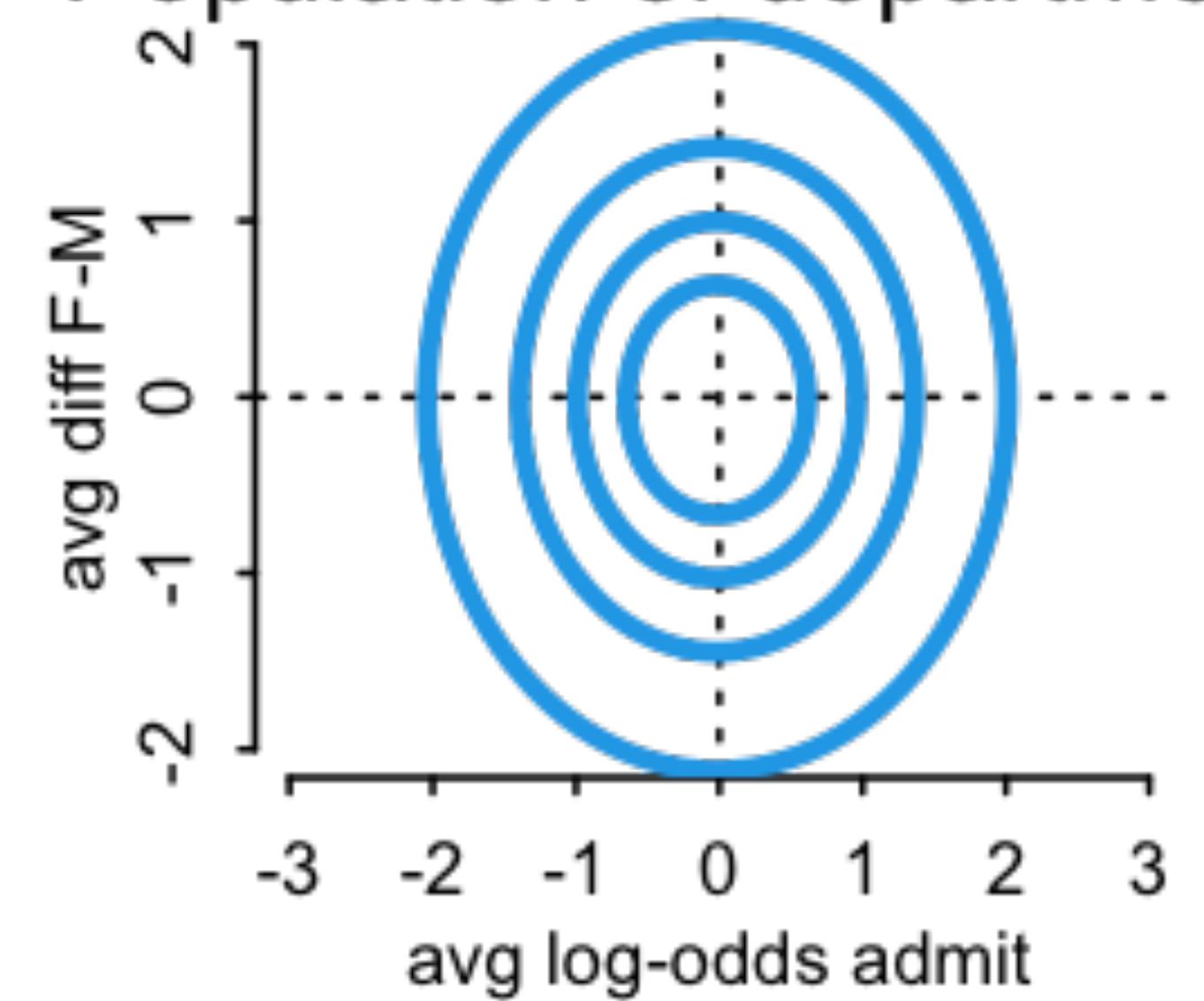
$$[\alpha_j, \beta_j] \sim \text{MVNormal}([\bar{\alpha}, \bar{\beta}], \Sigma)$$

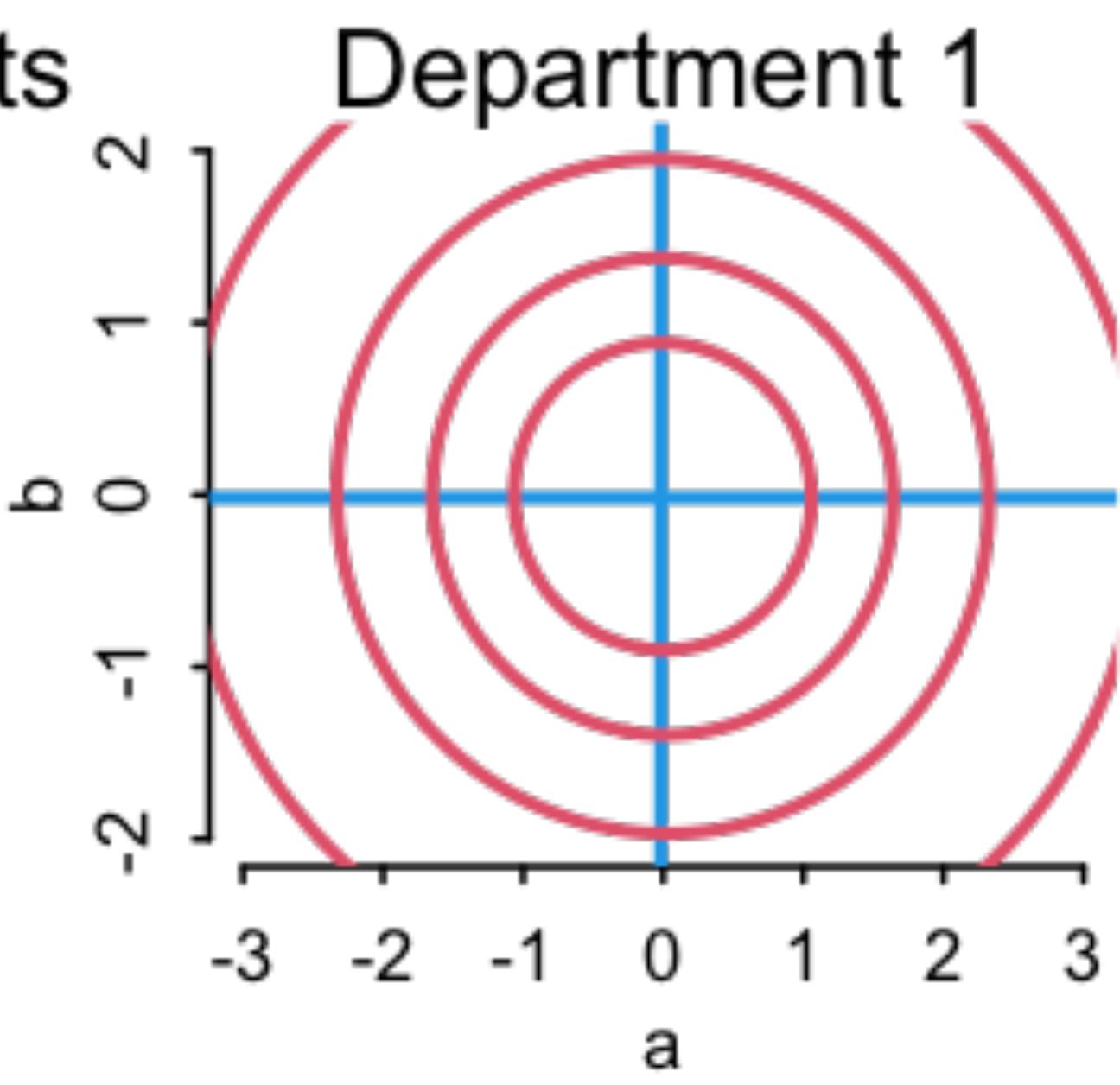
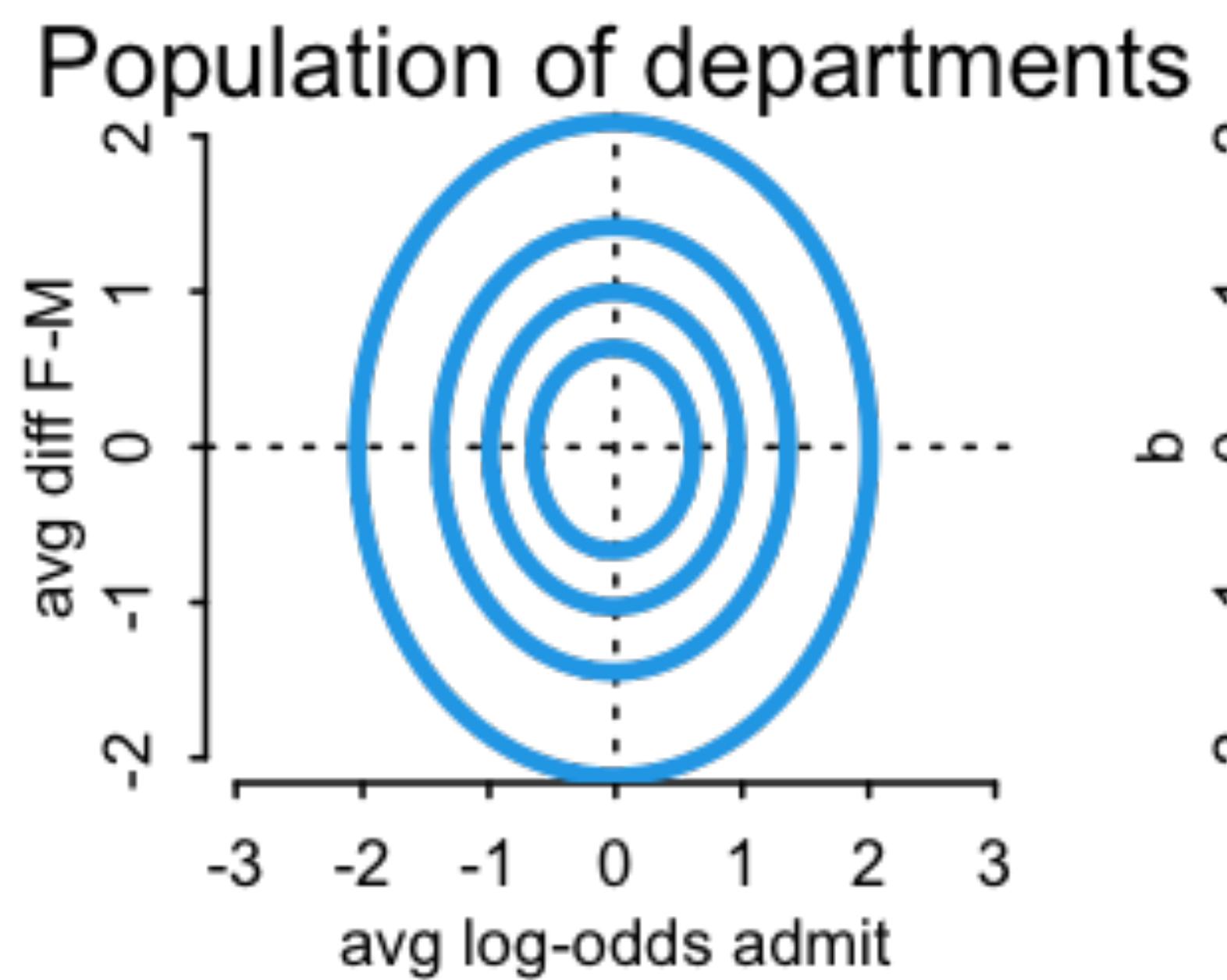
N features: **N** -dimensional distribution

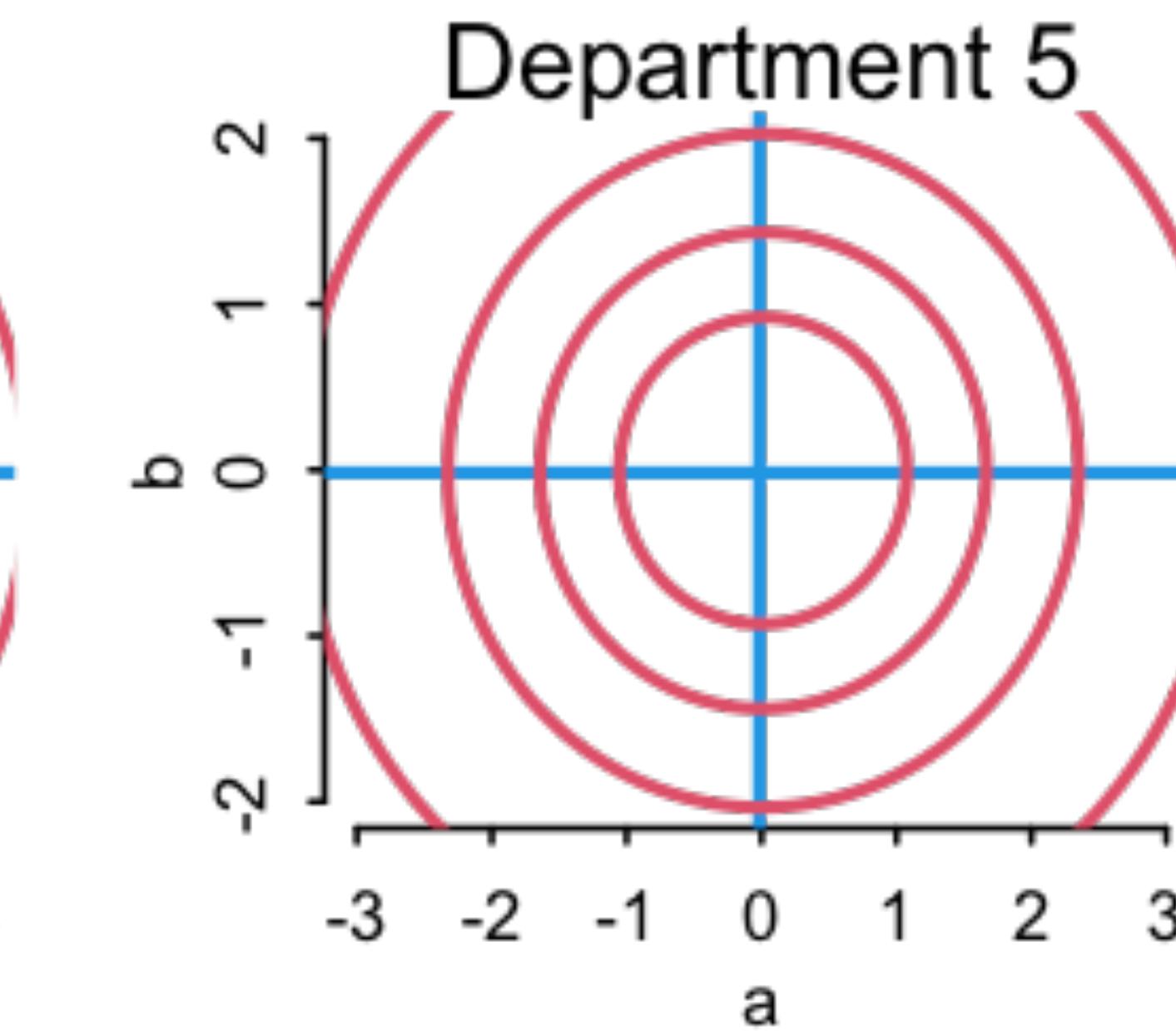
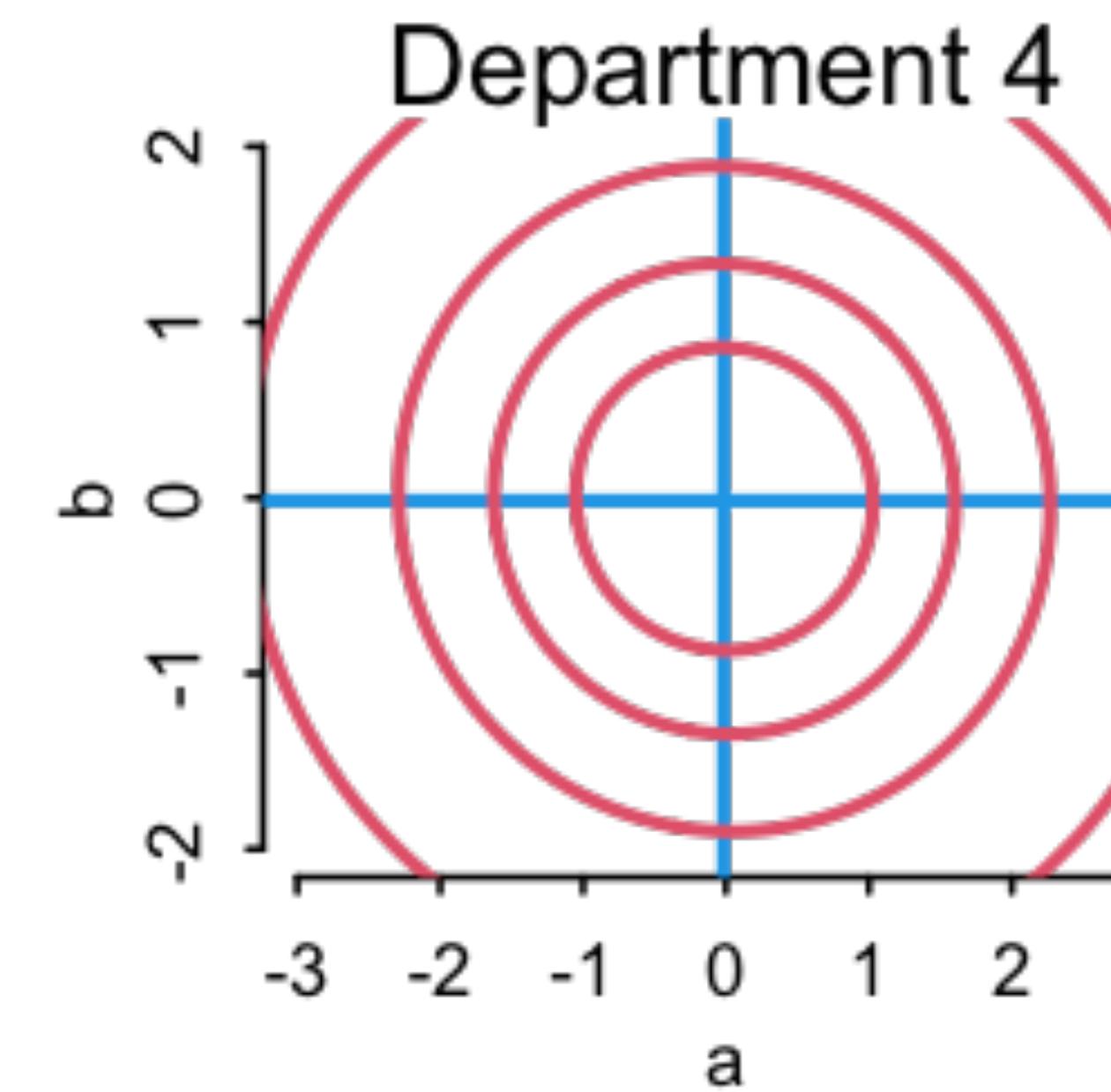
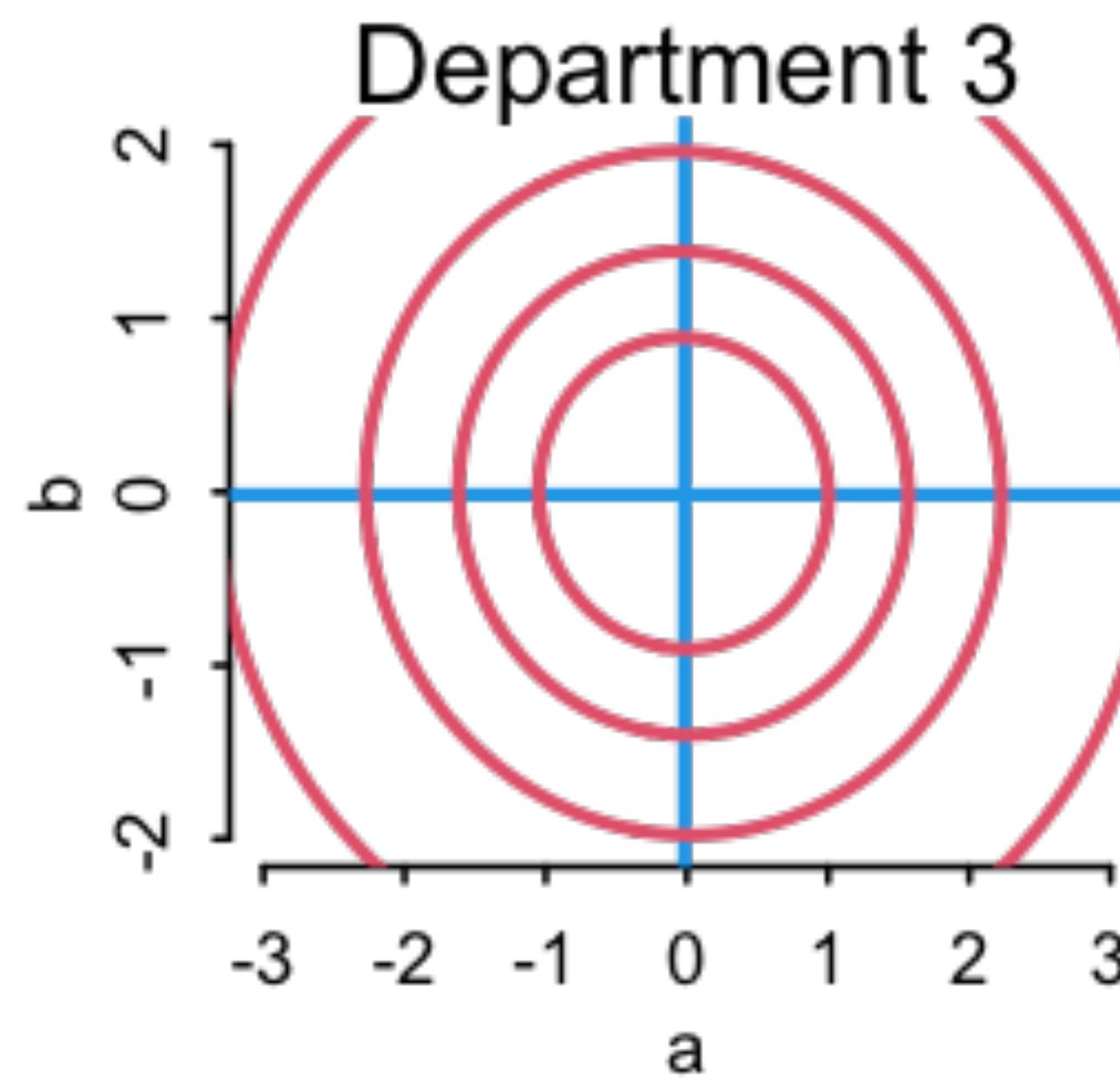
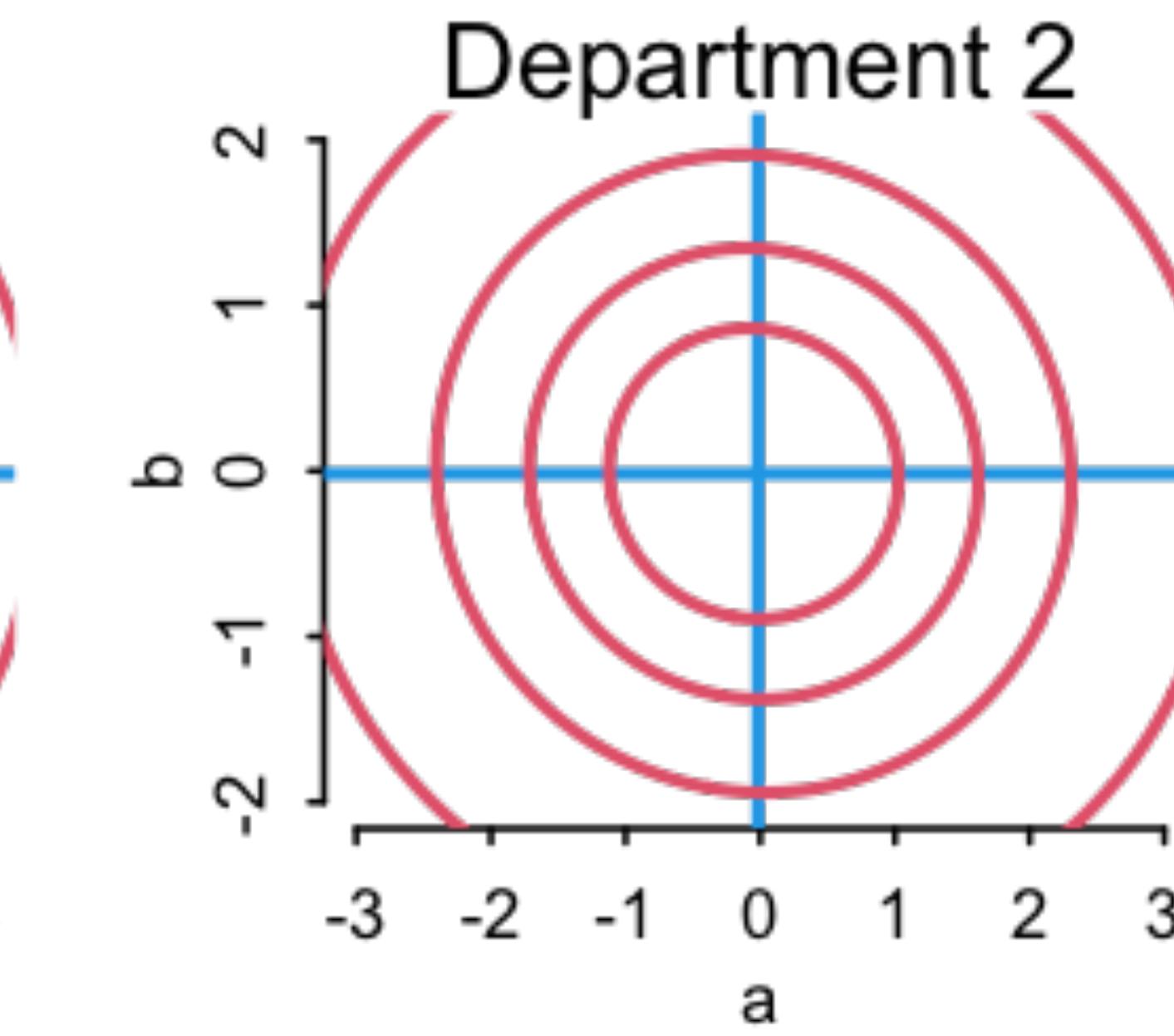
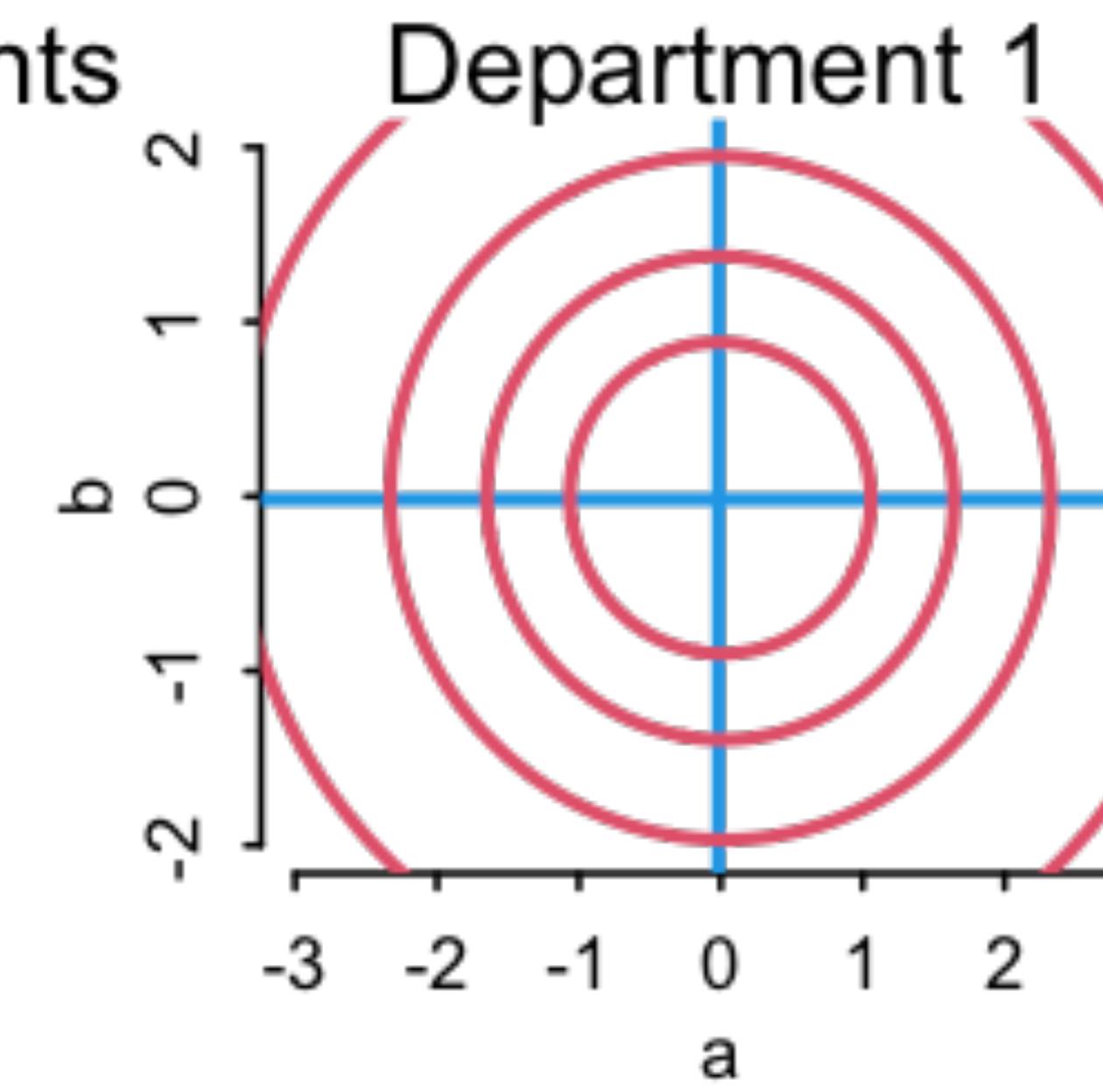
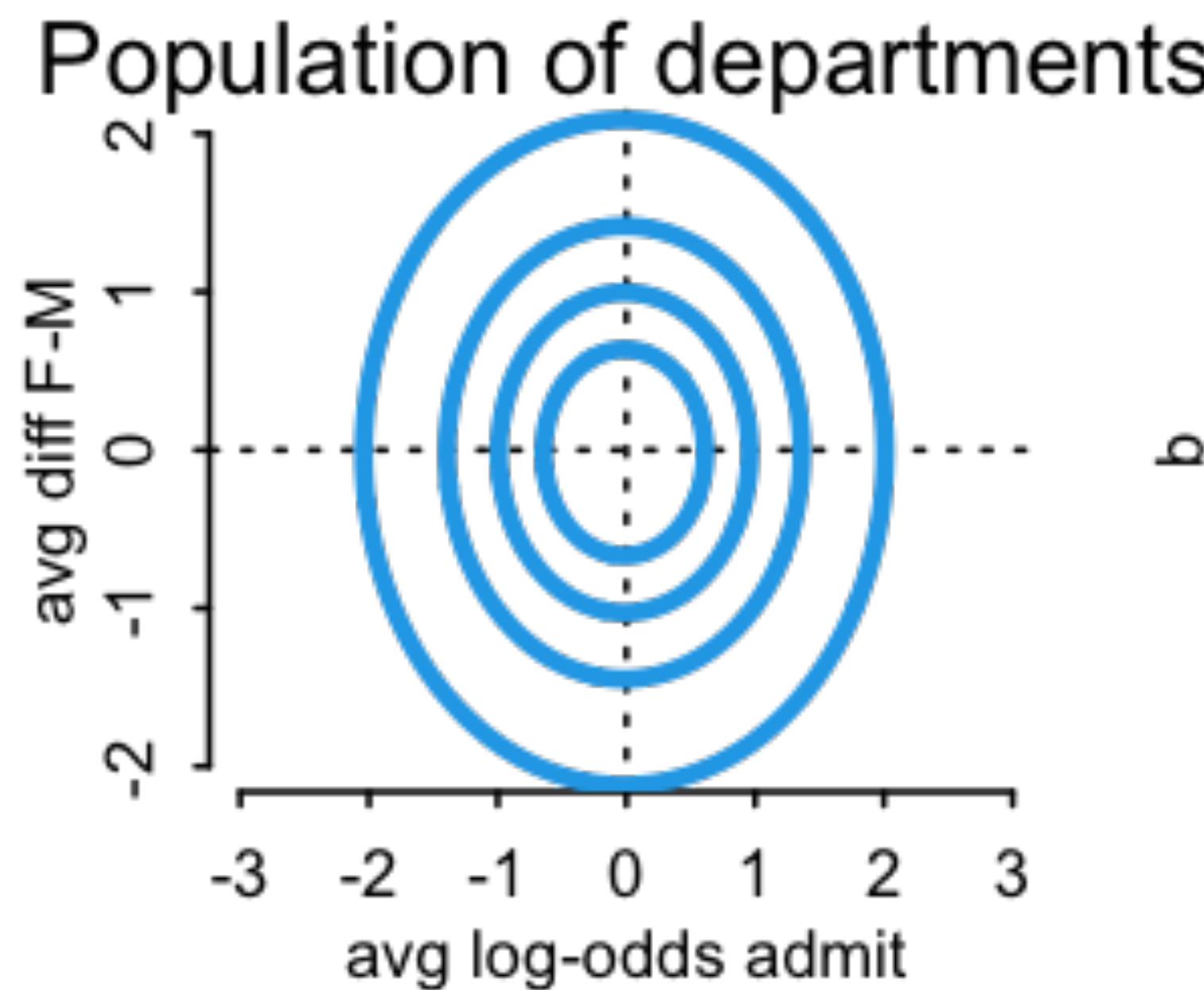
$$\alpha_{j,1..N} \sim \text{MVNormal}(\bar{\alpha}, \Sigma)$$

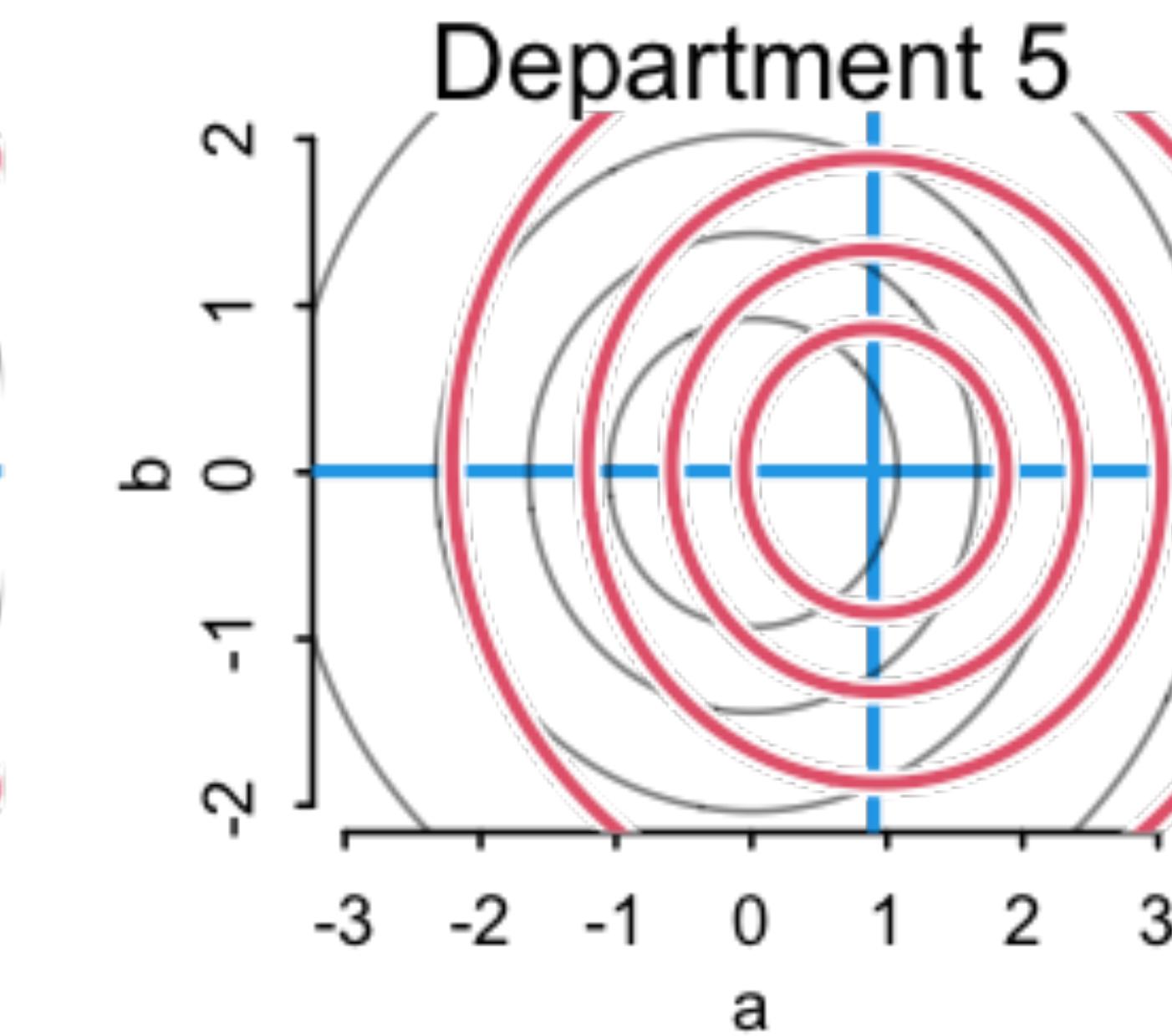
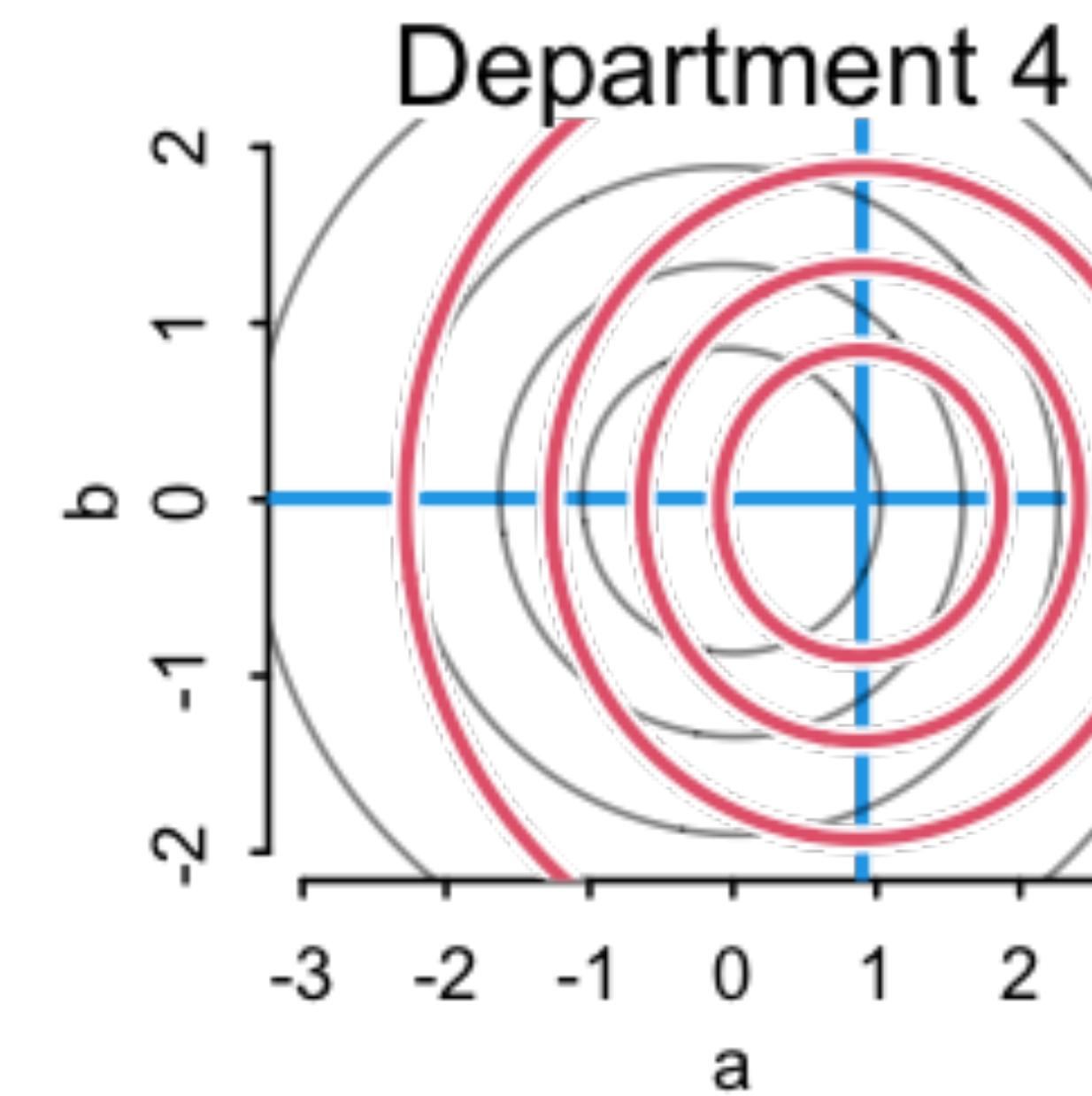
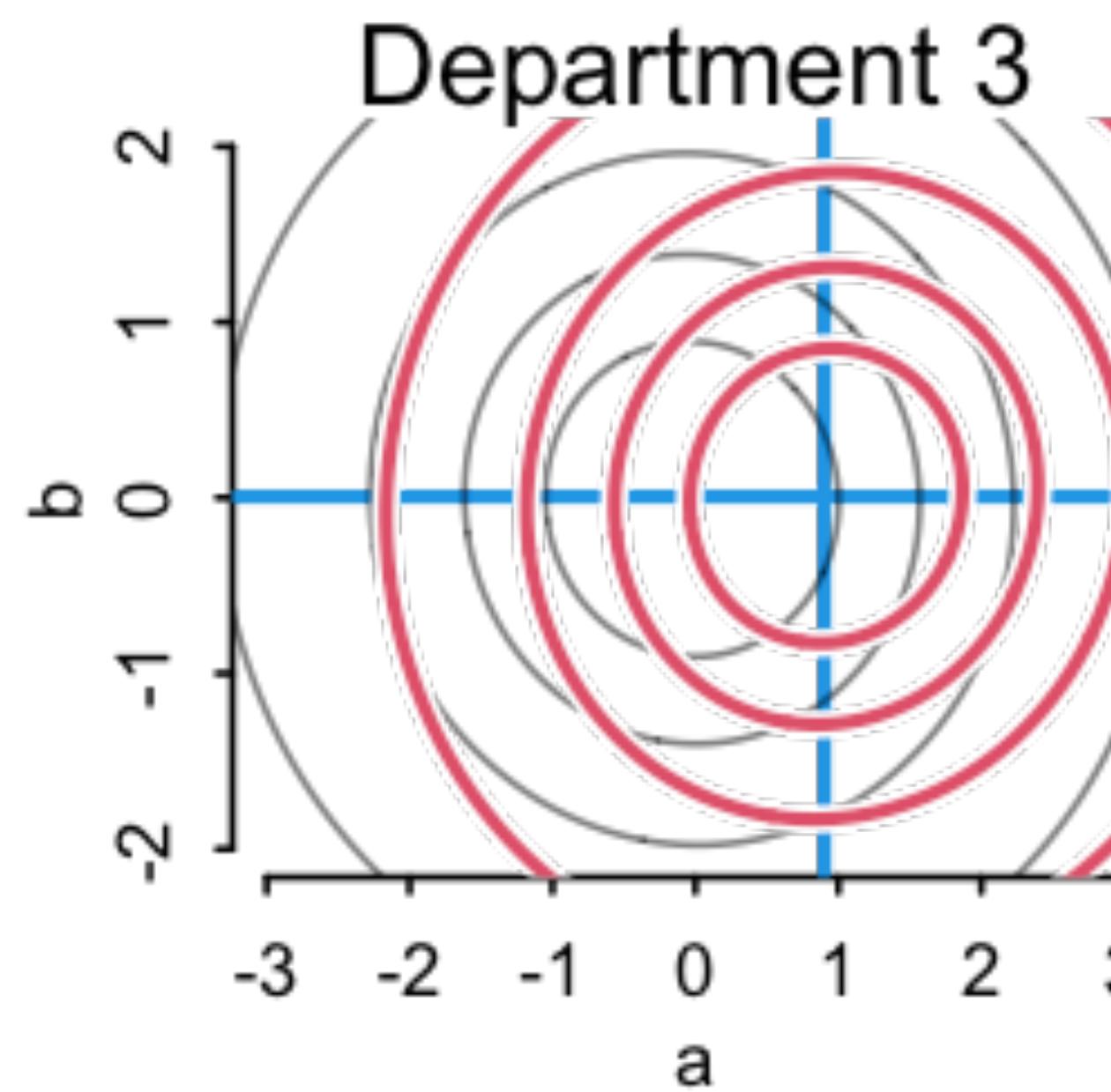
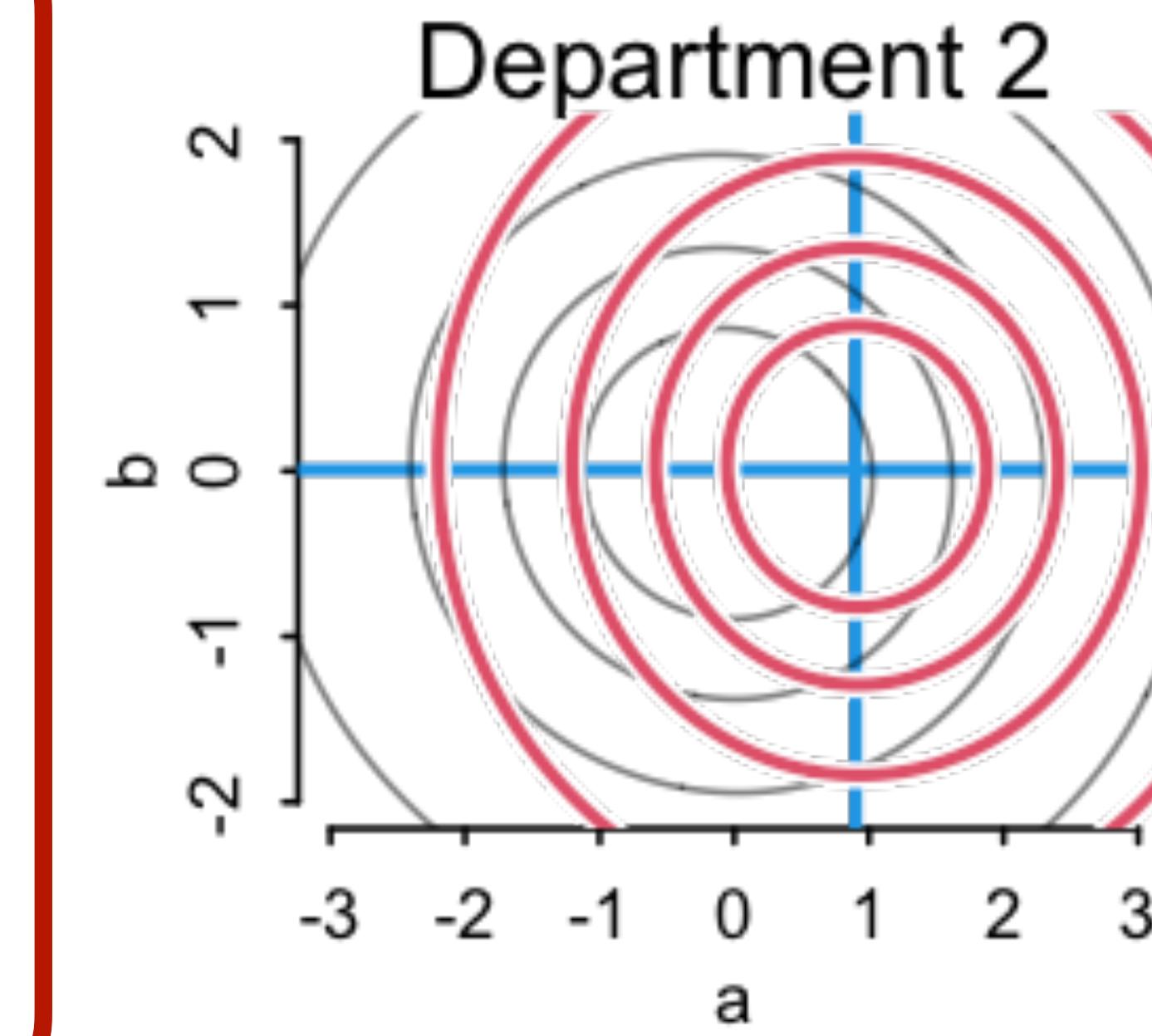
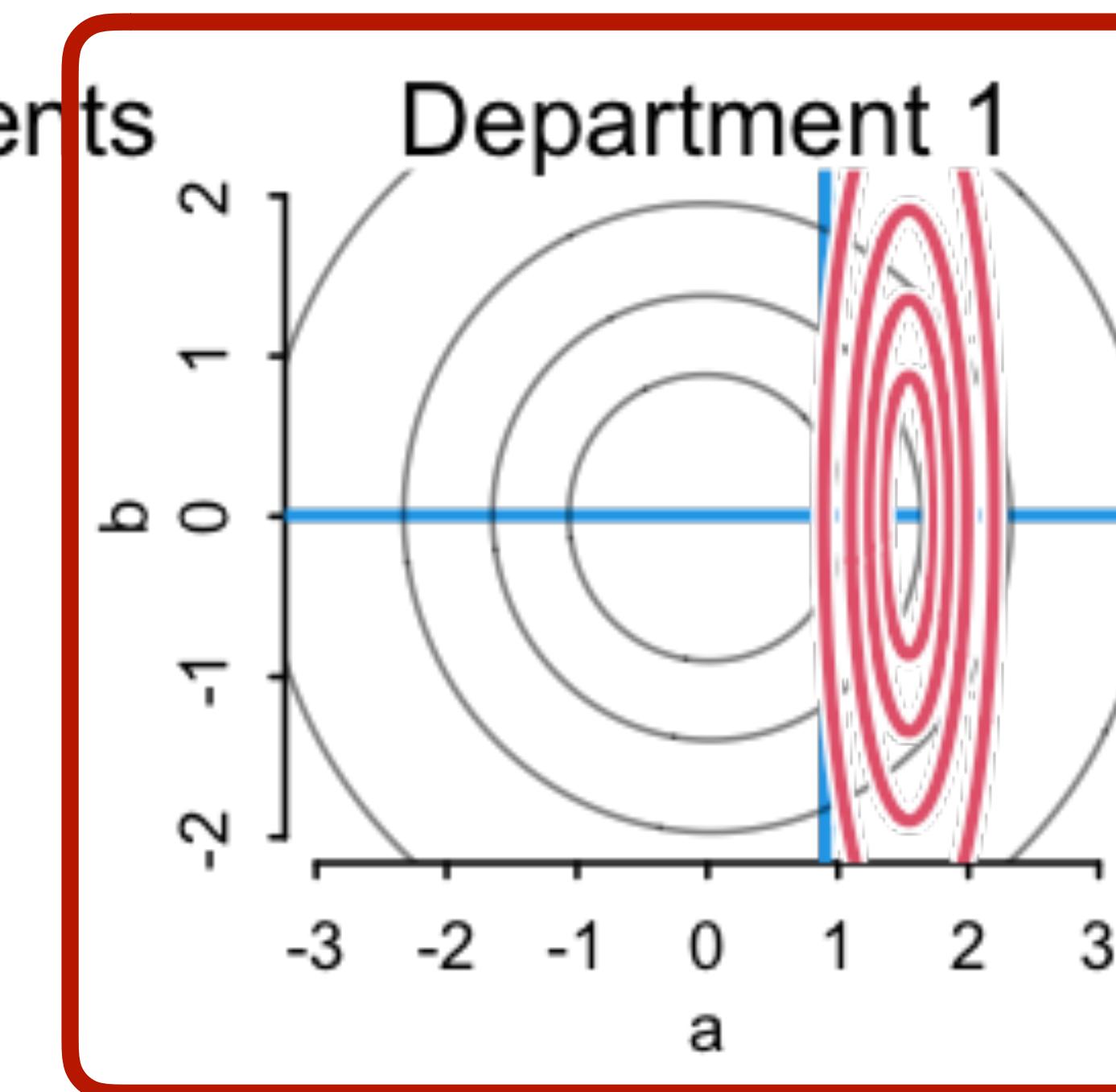
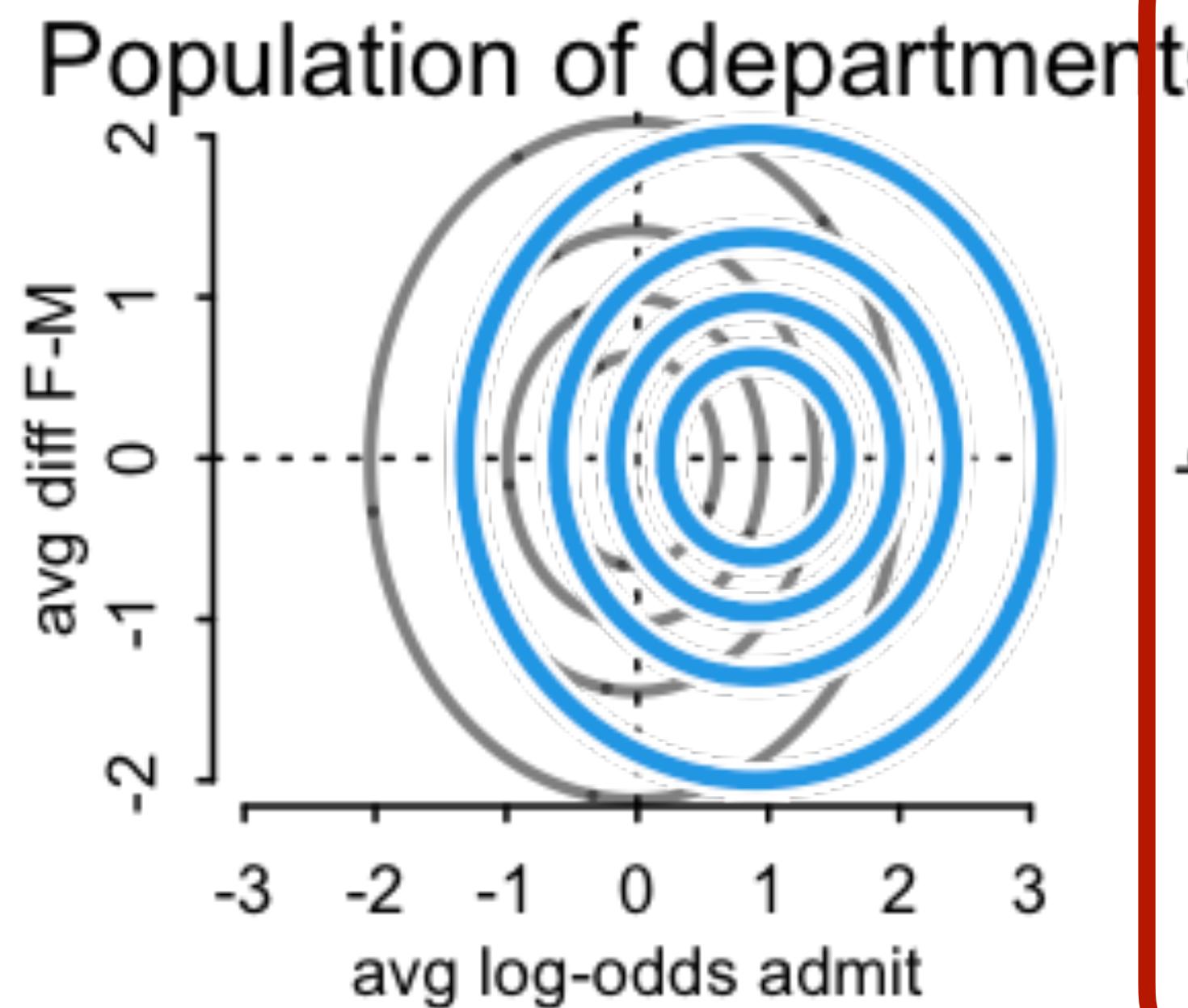
Hard part: Learning associations

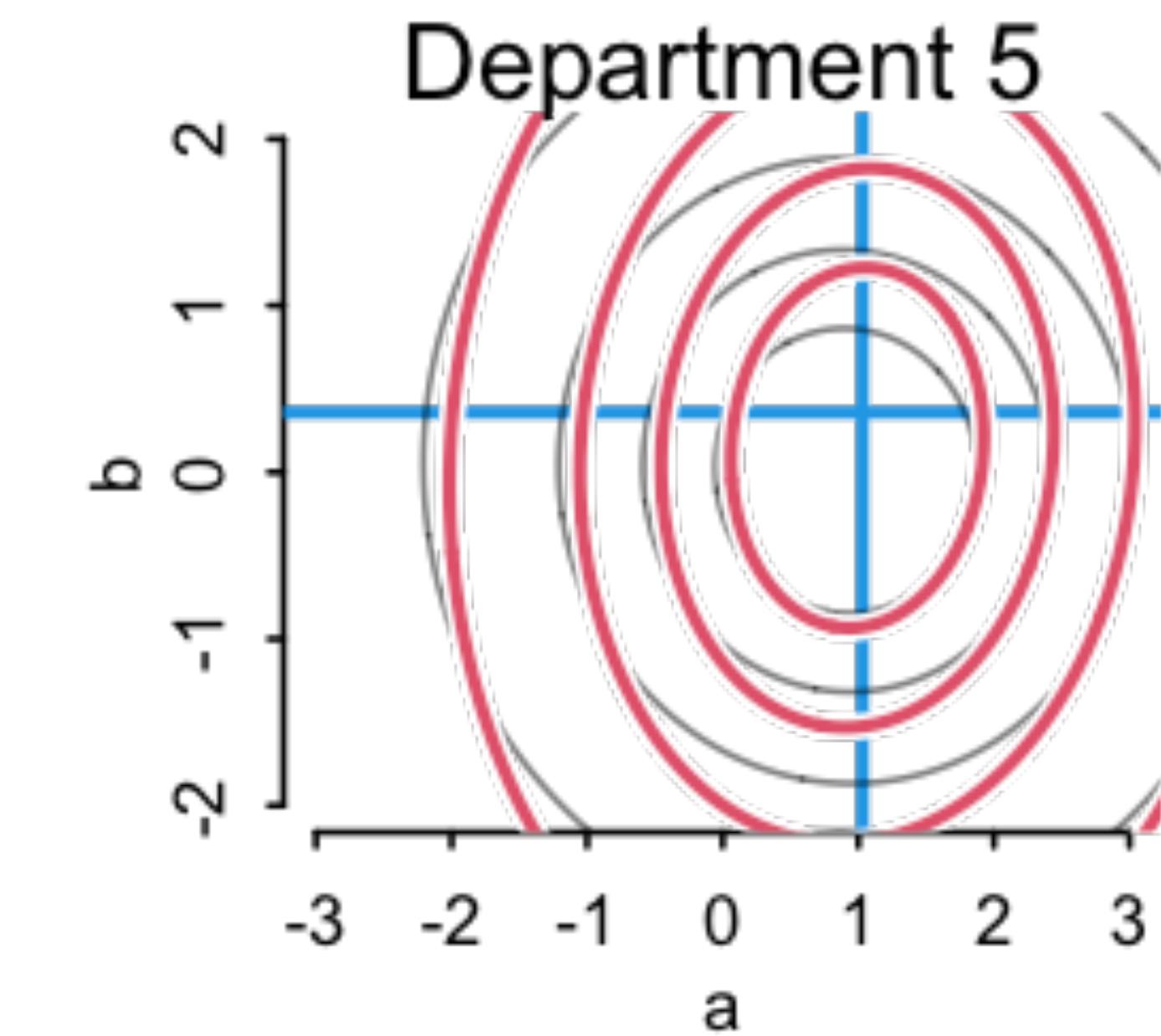
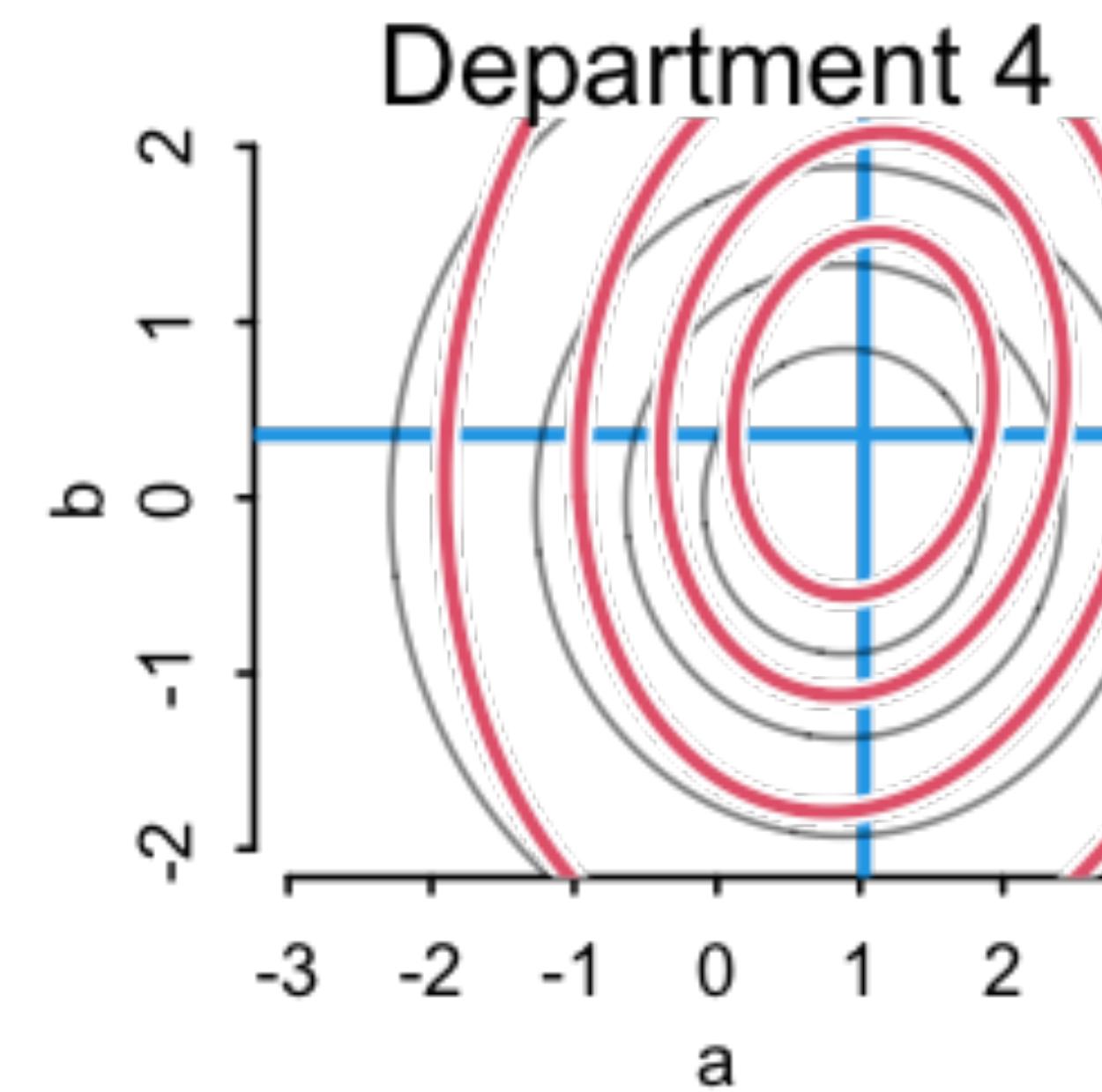
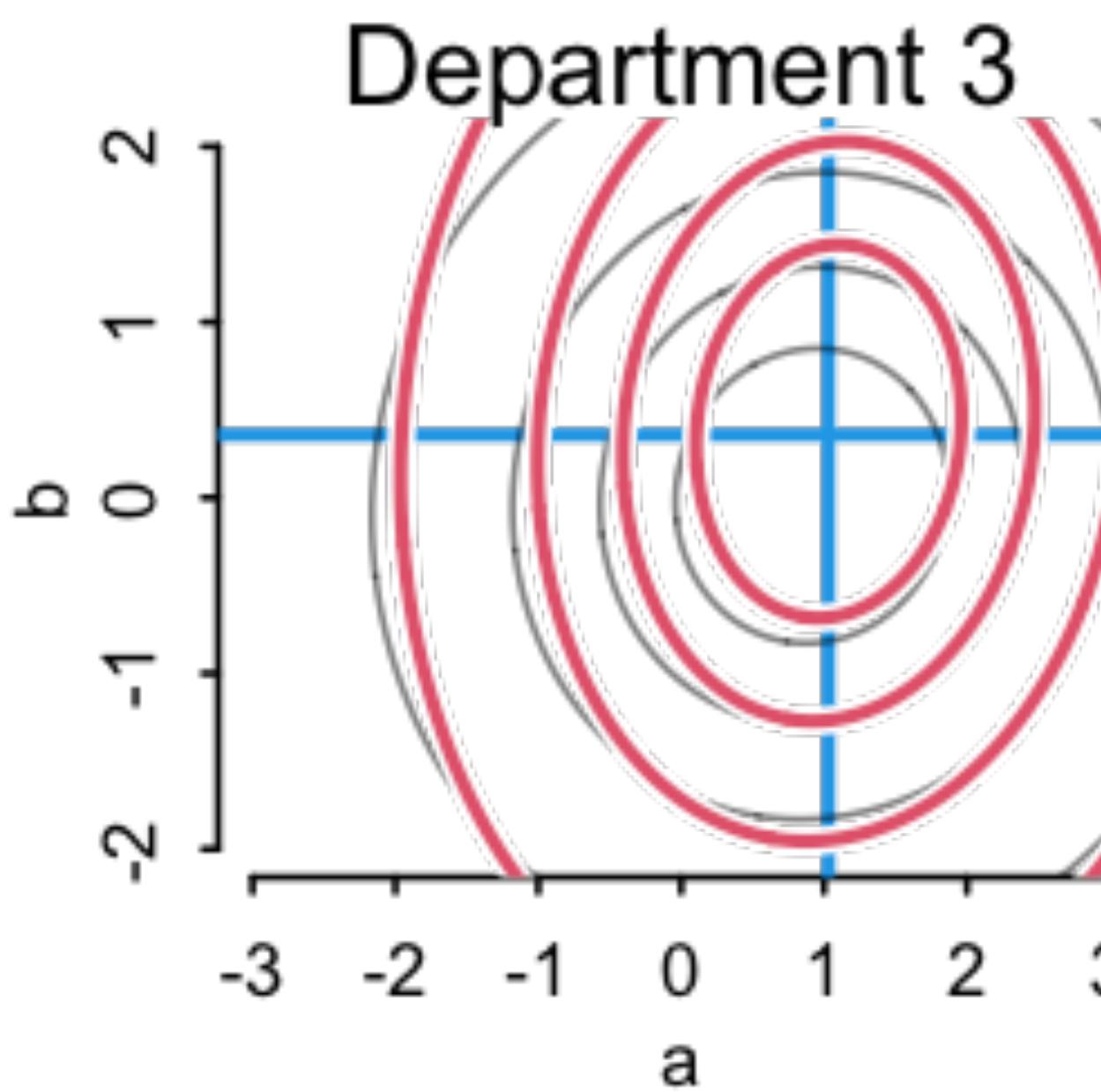
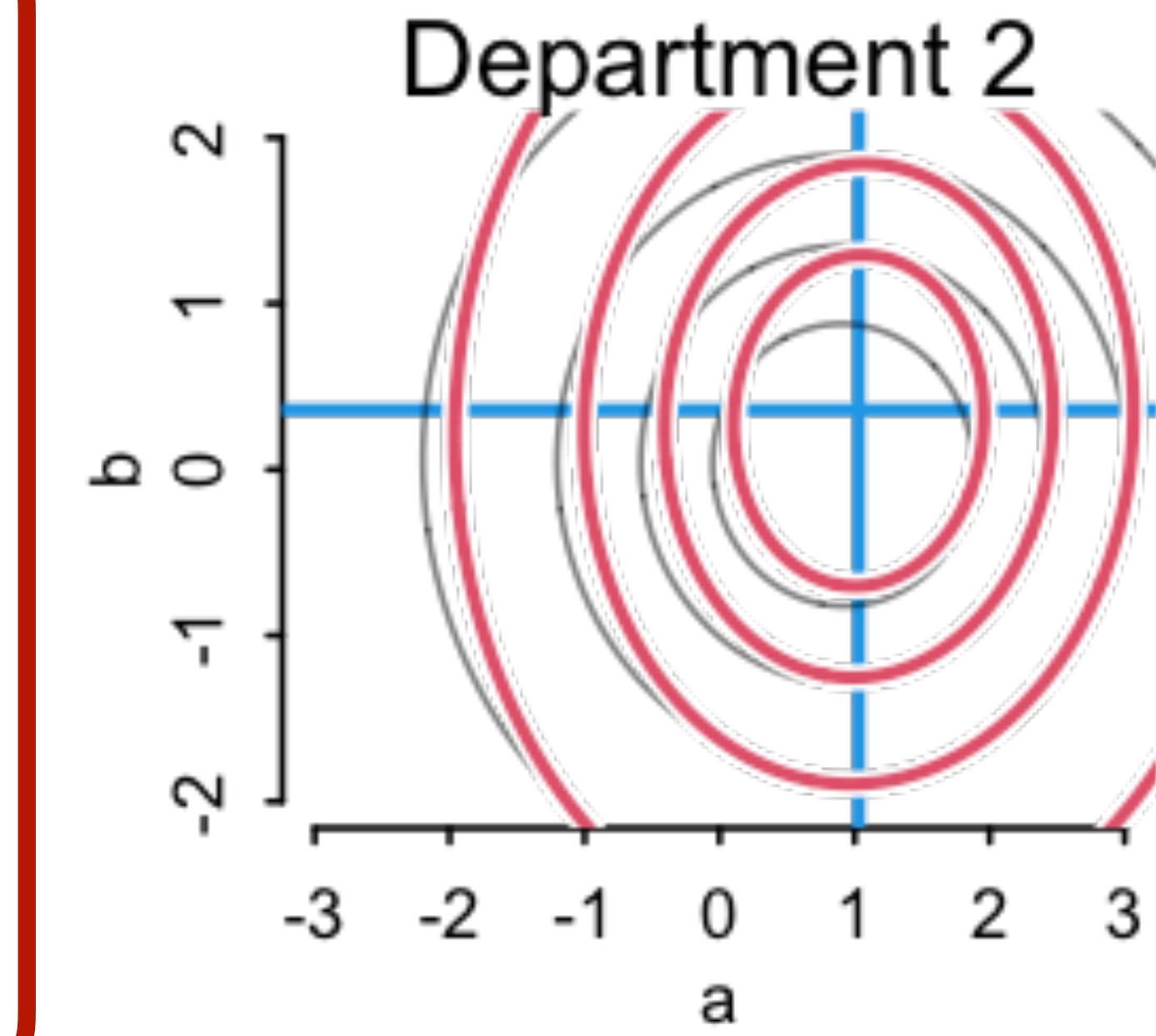
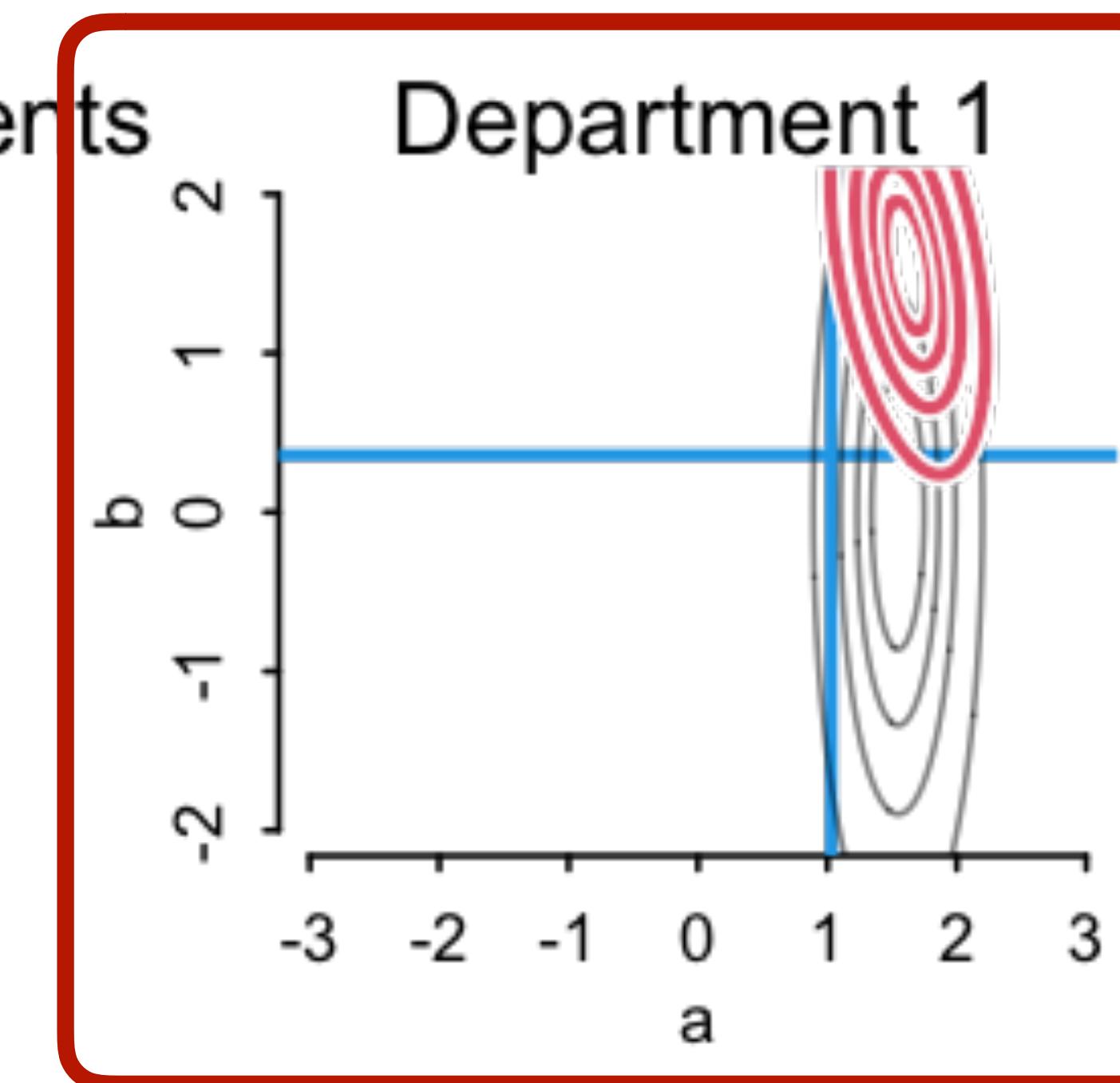
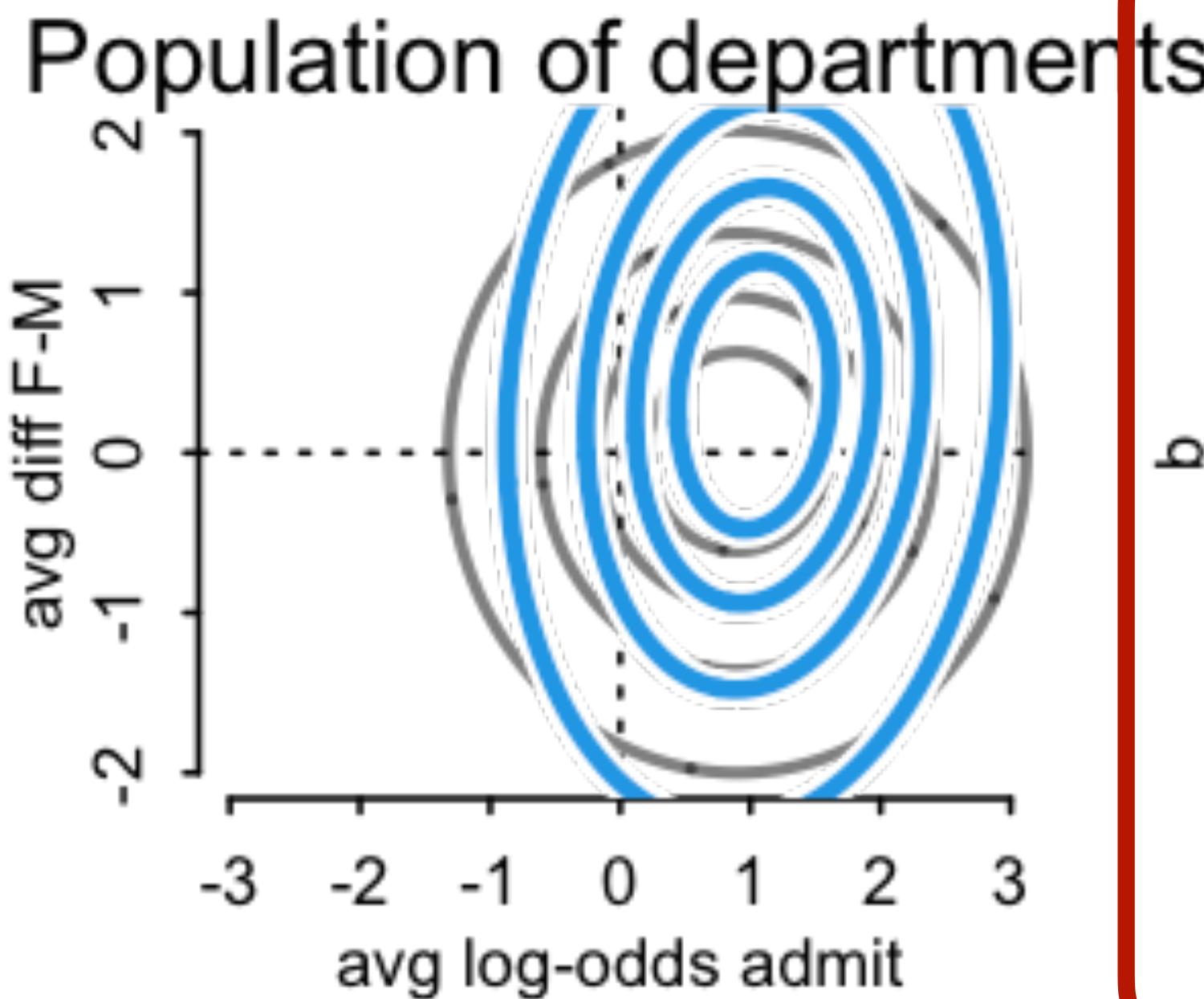
Population of departments

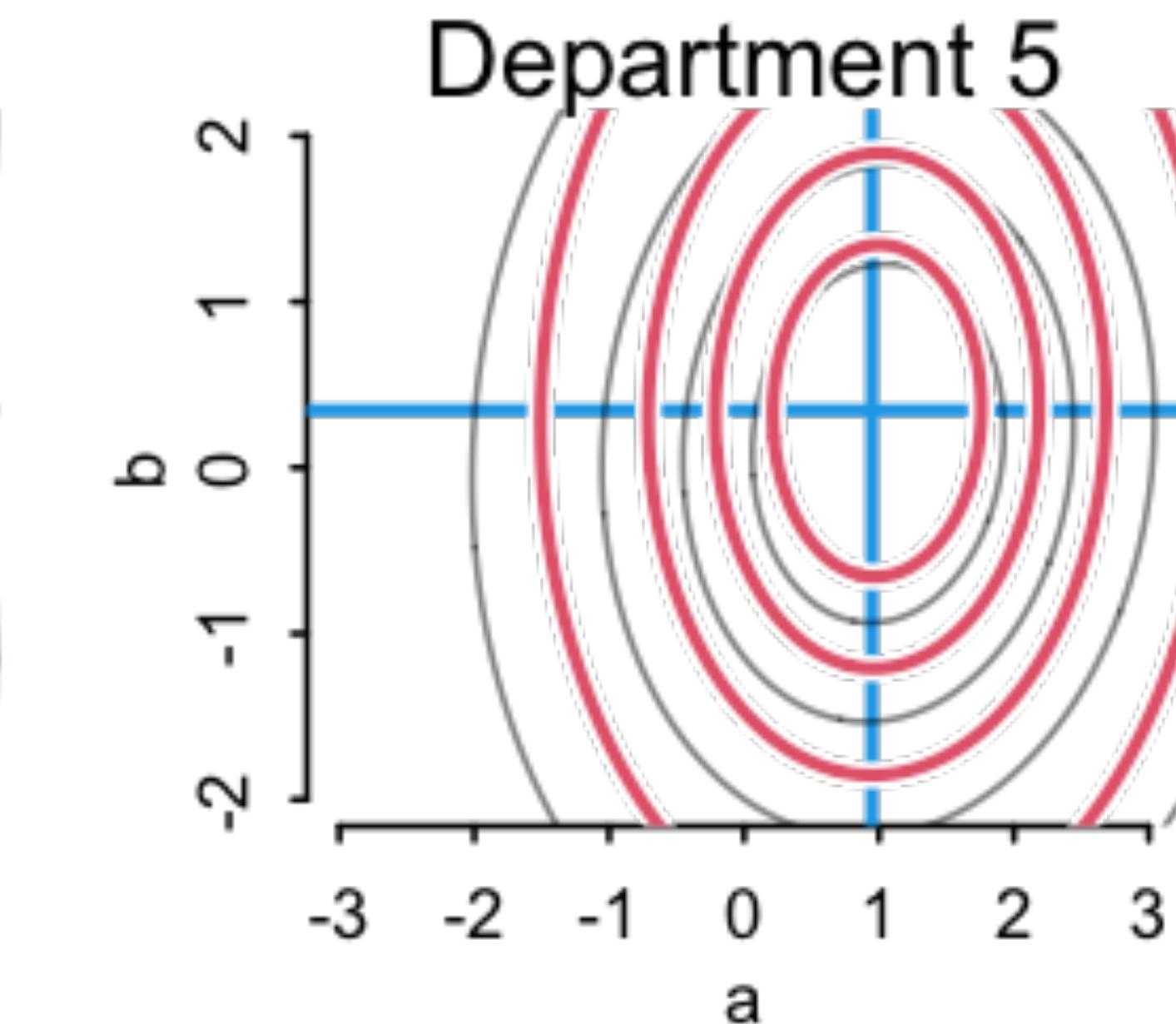
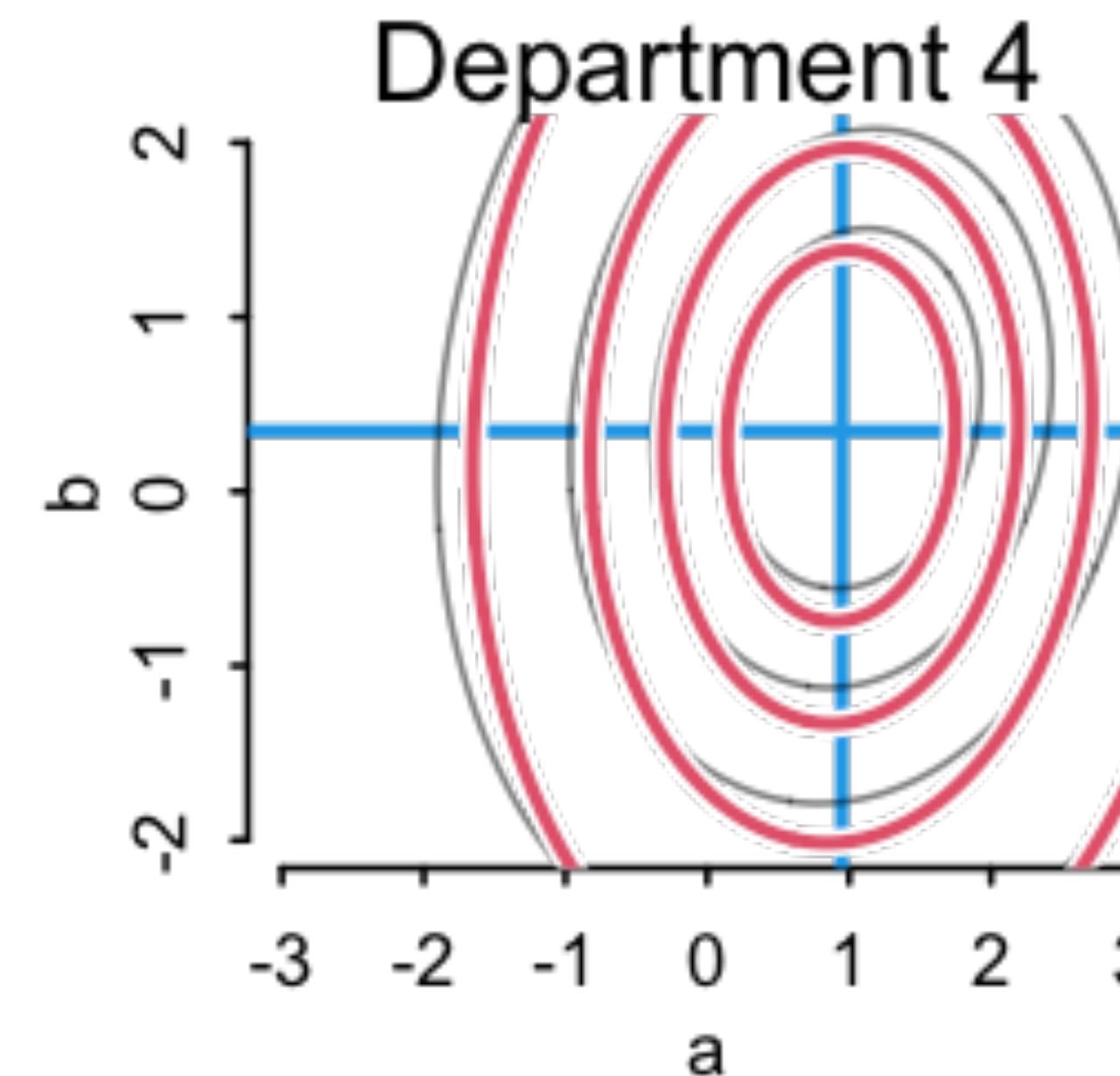
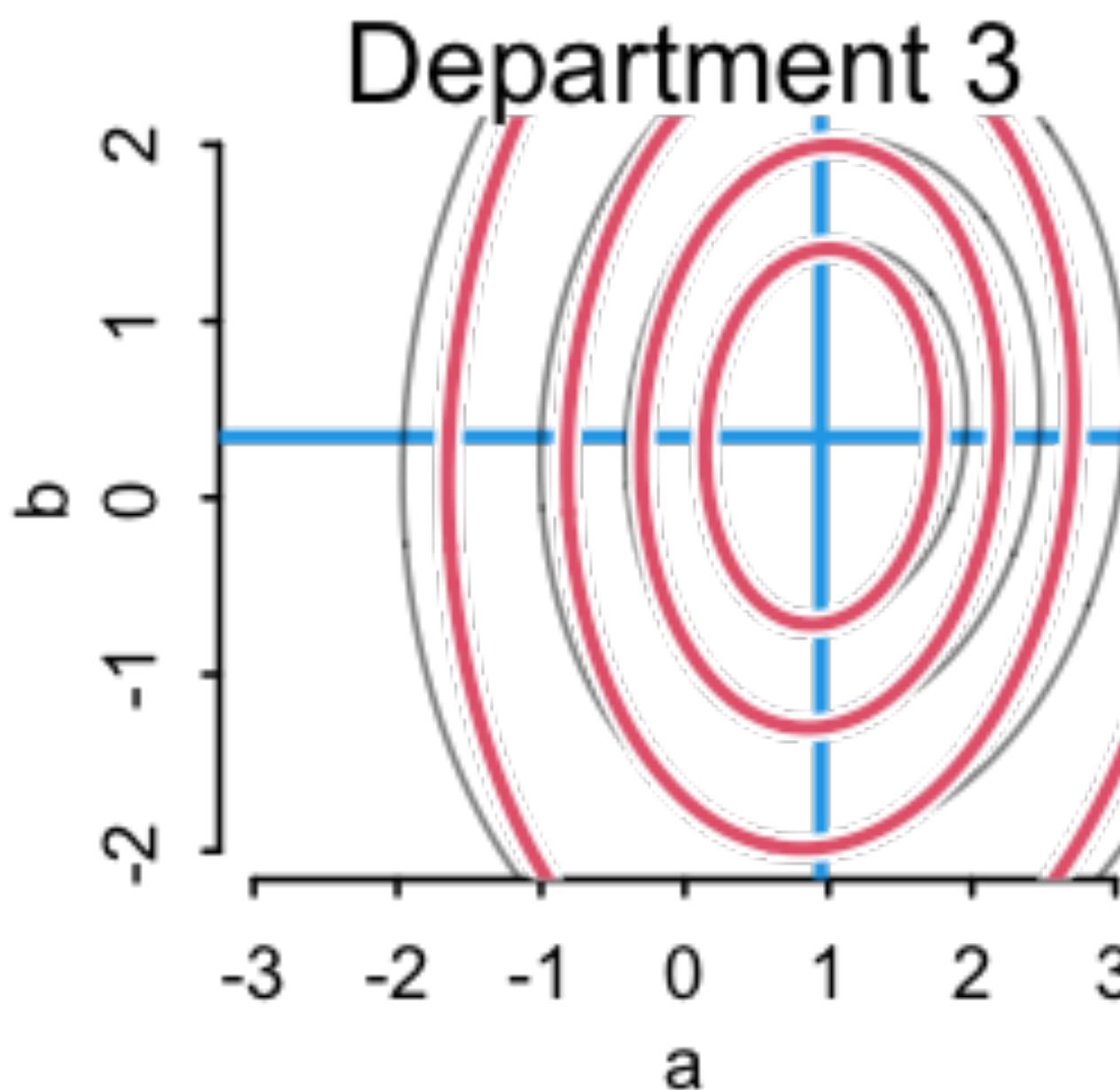
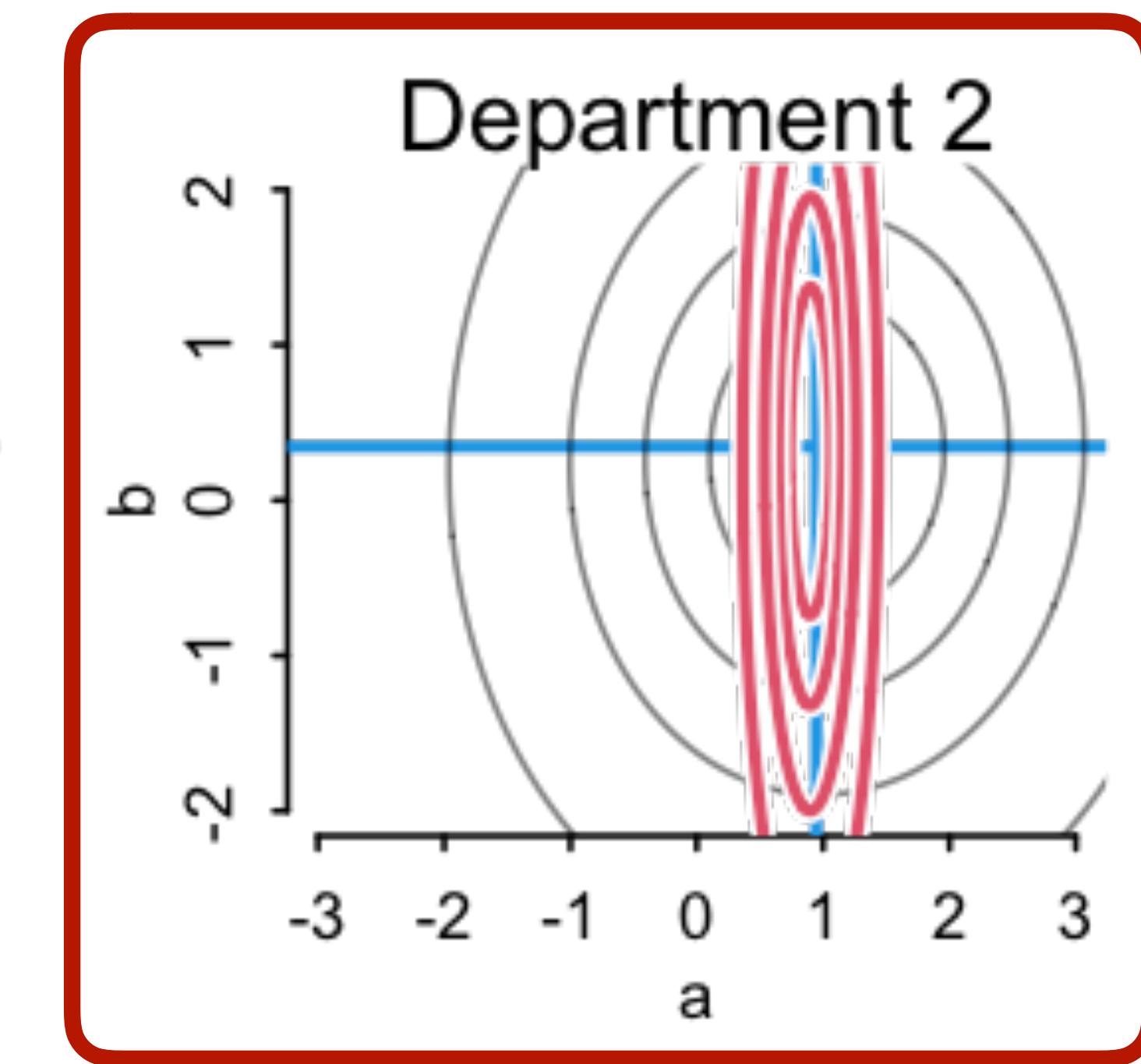
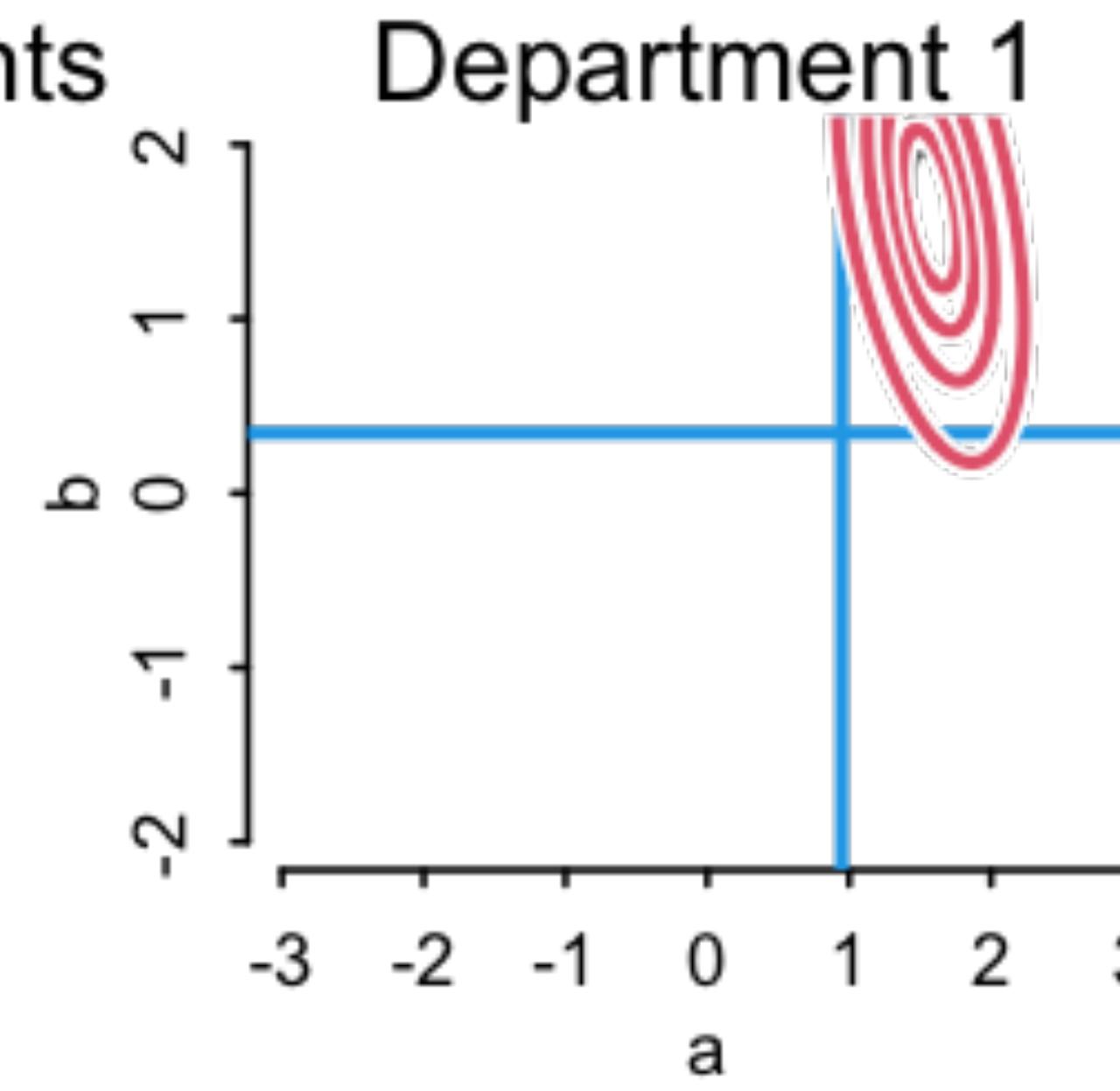
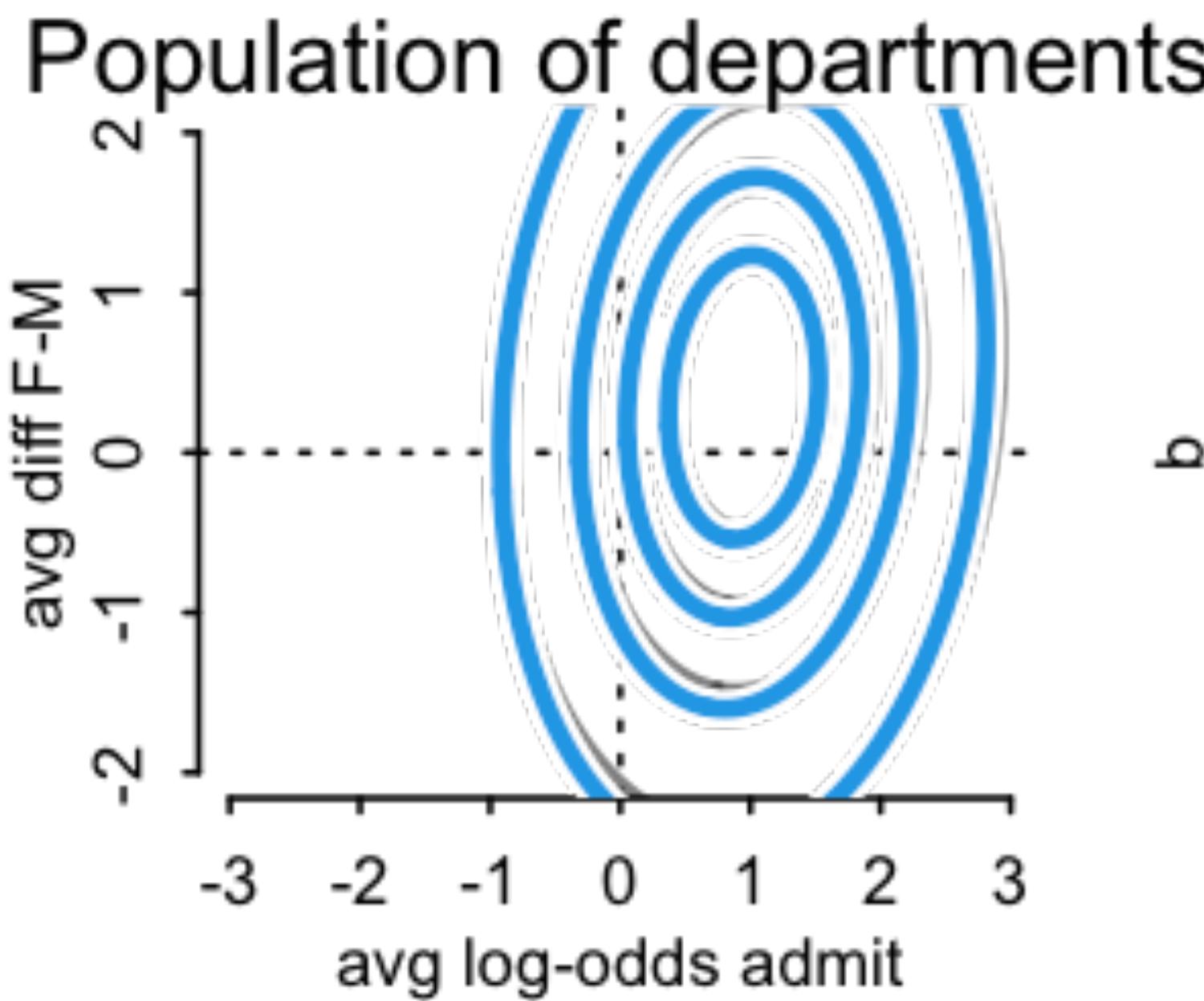


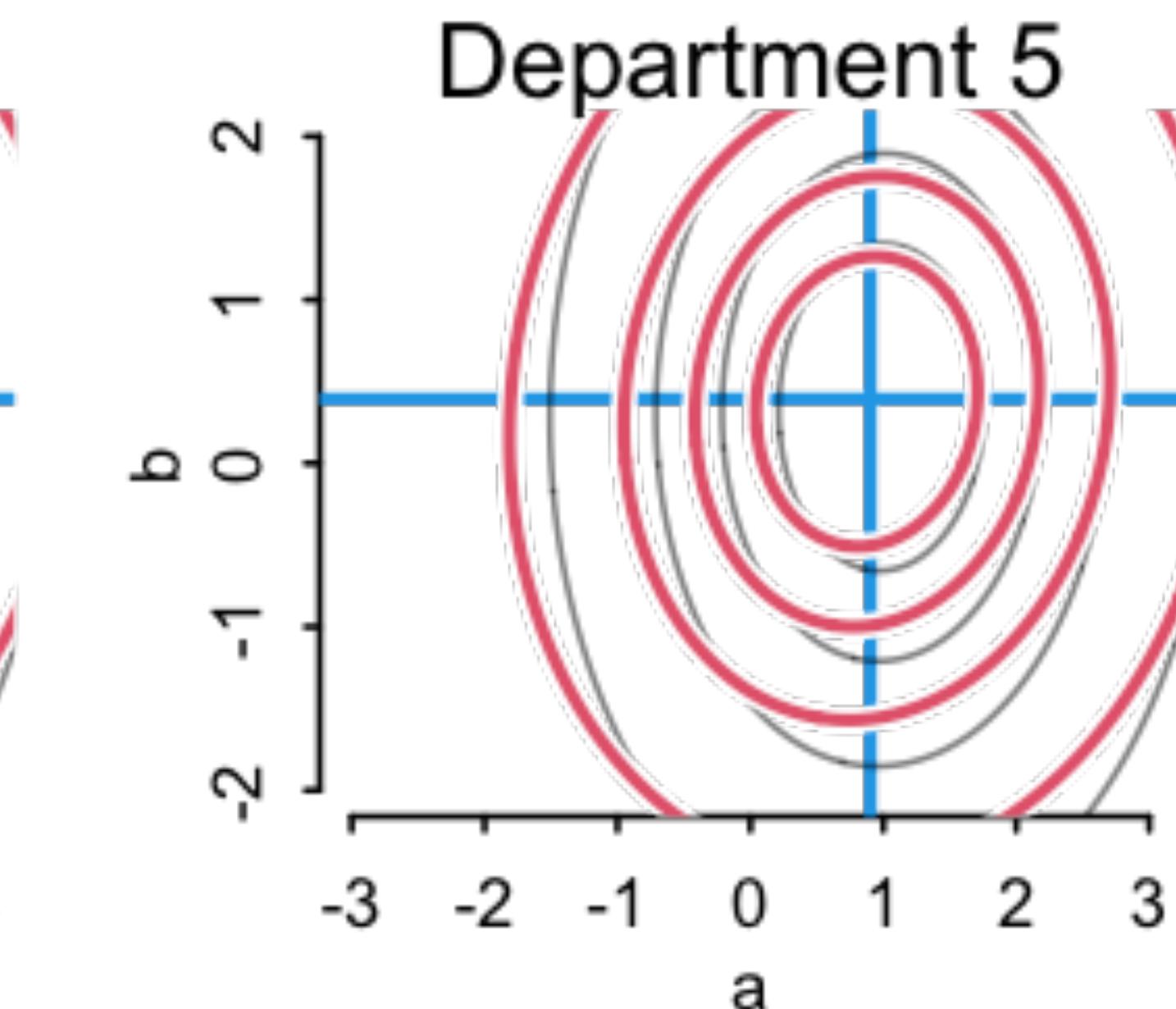
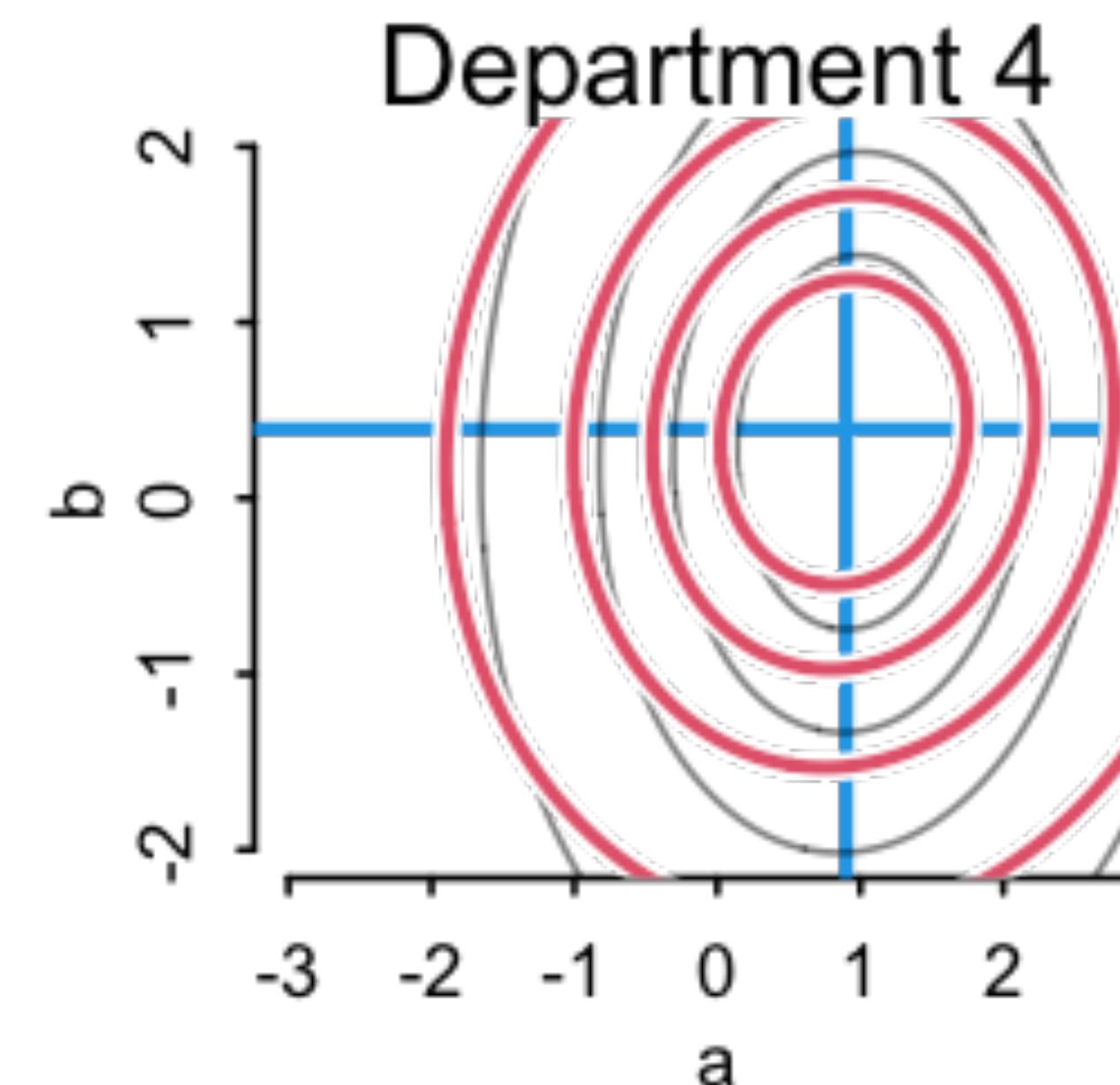
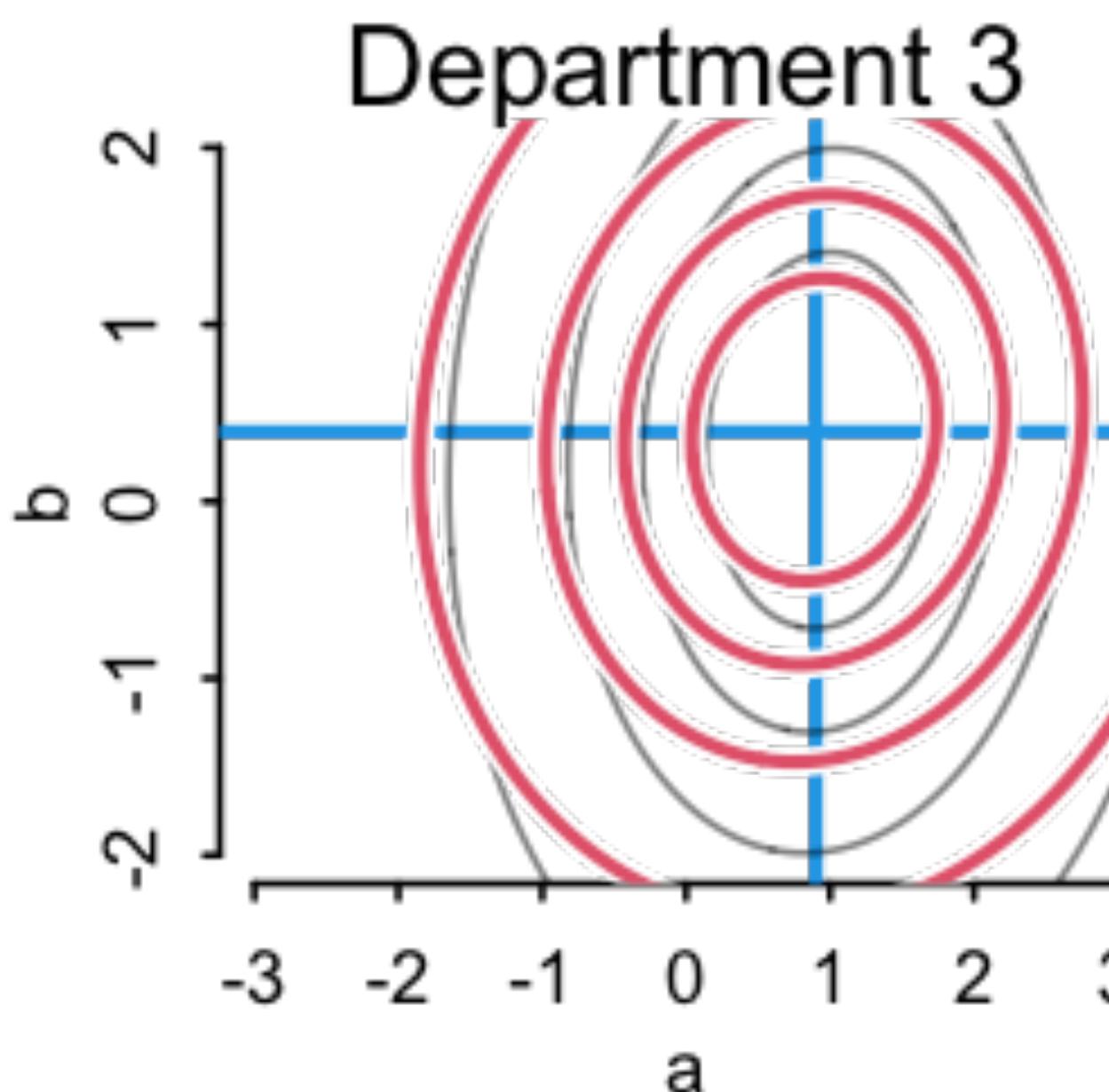
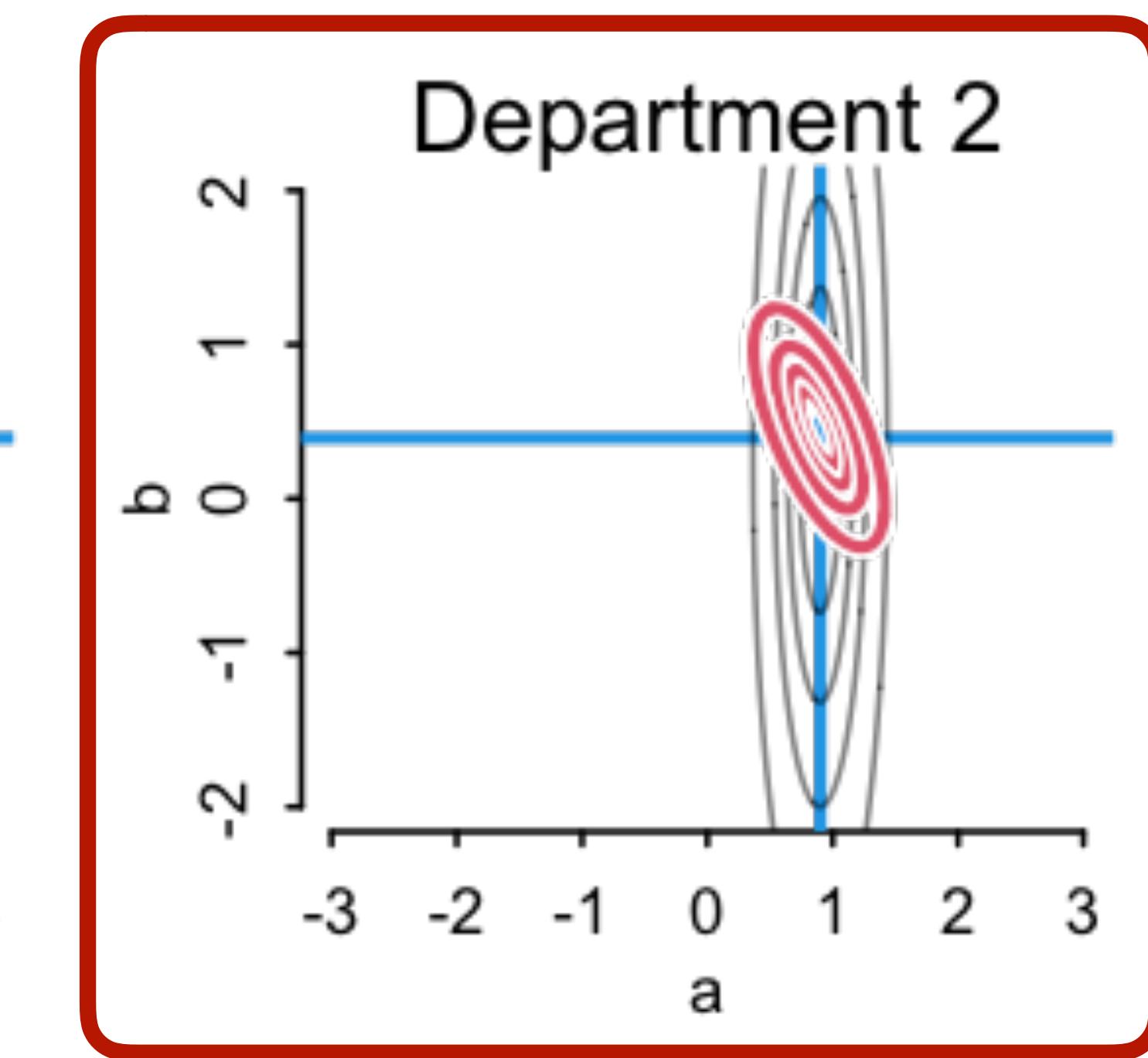
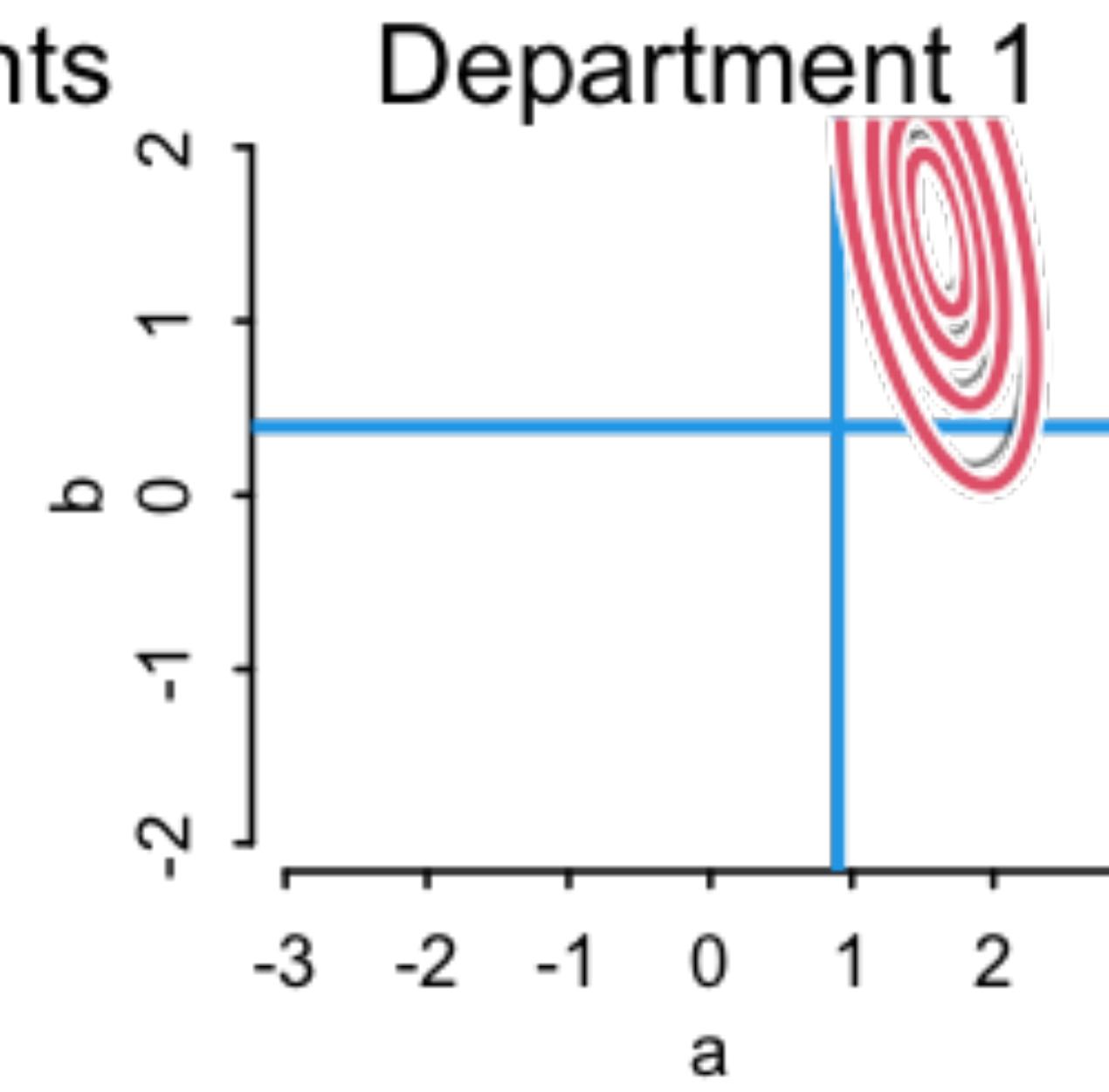
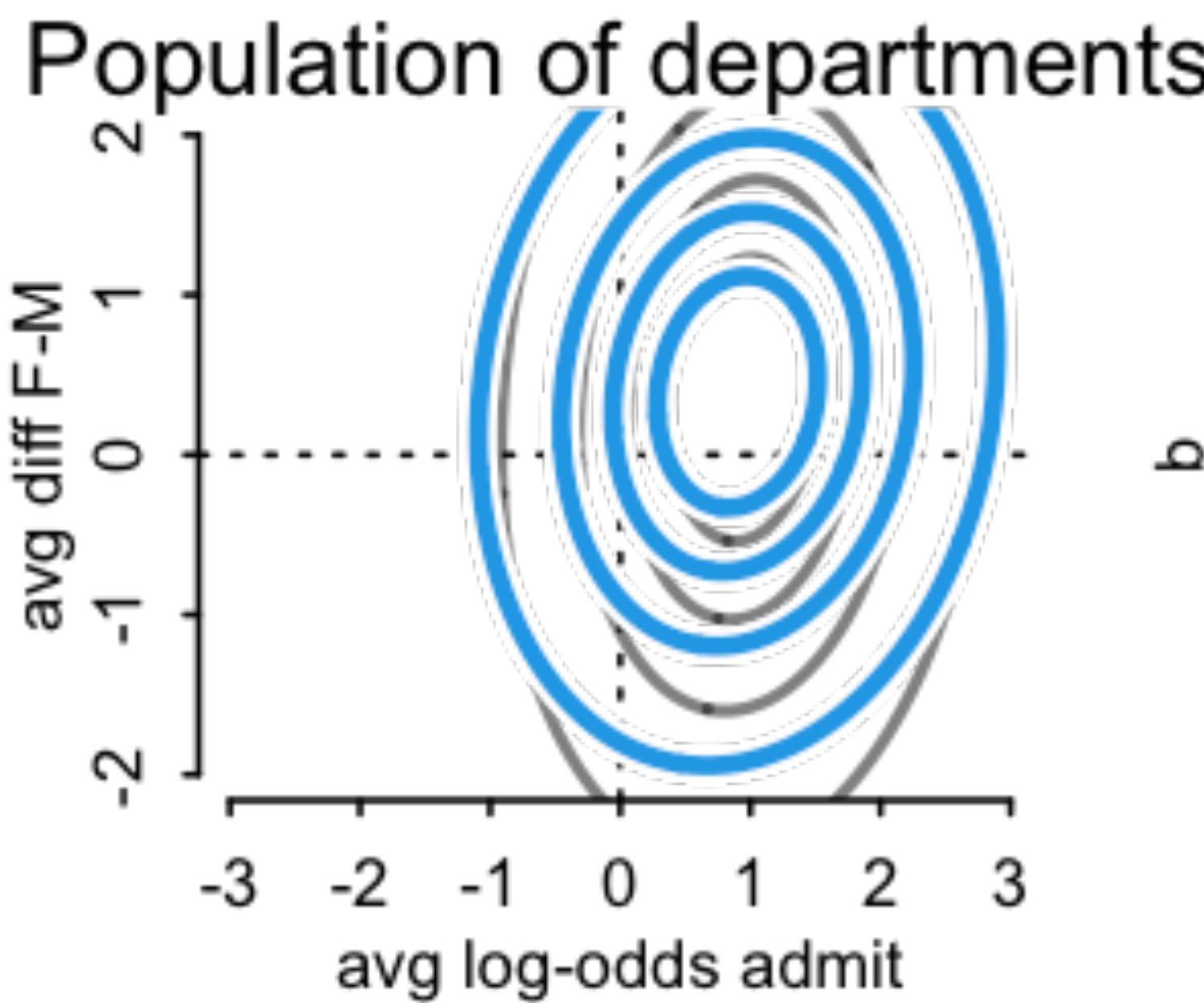


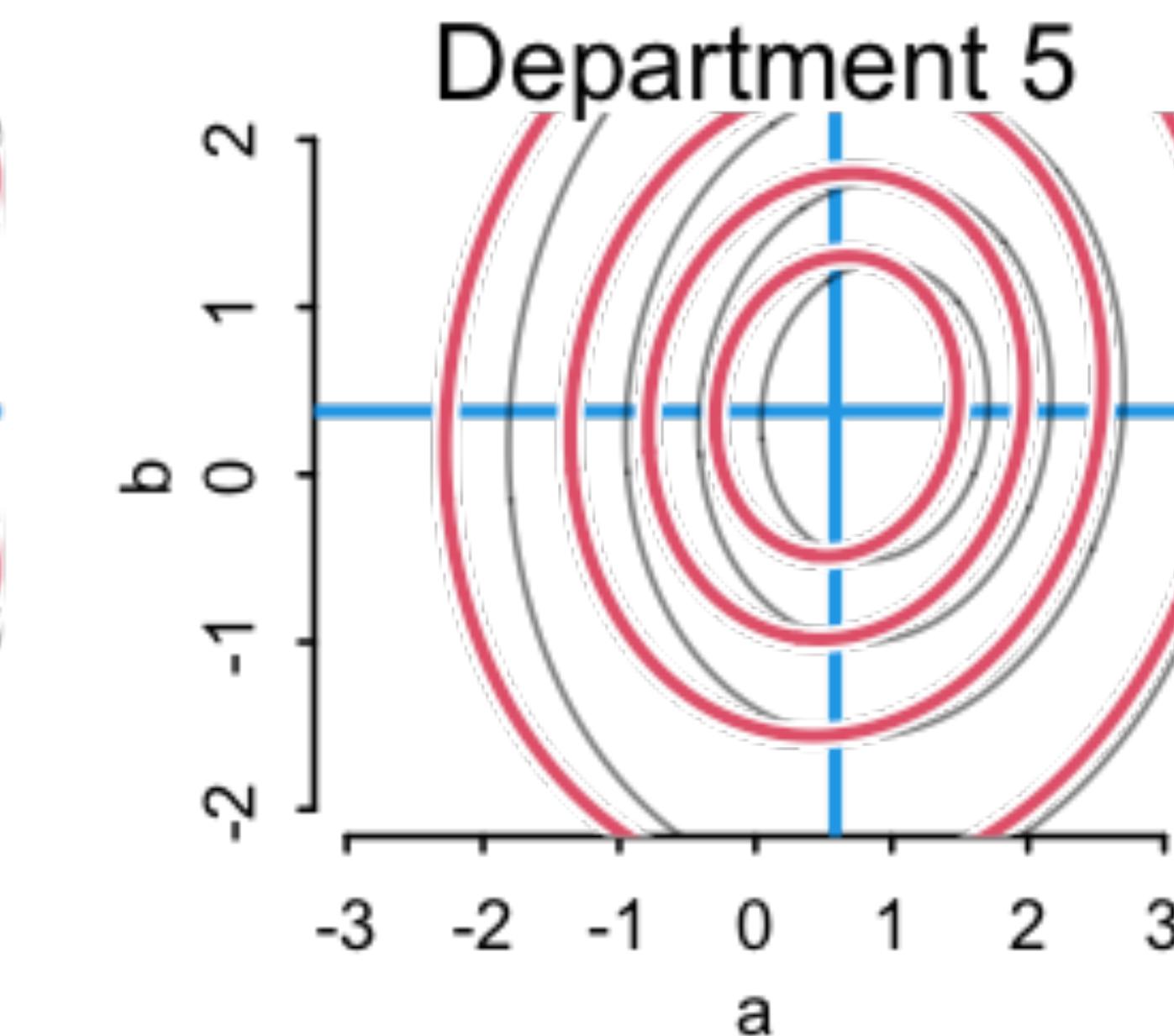
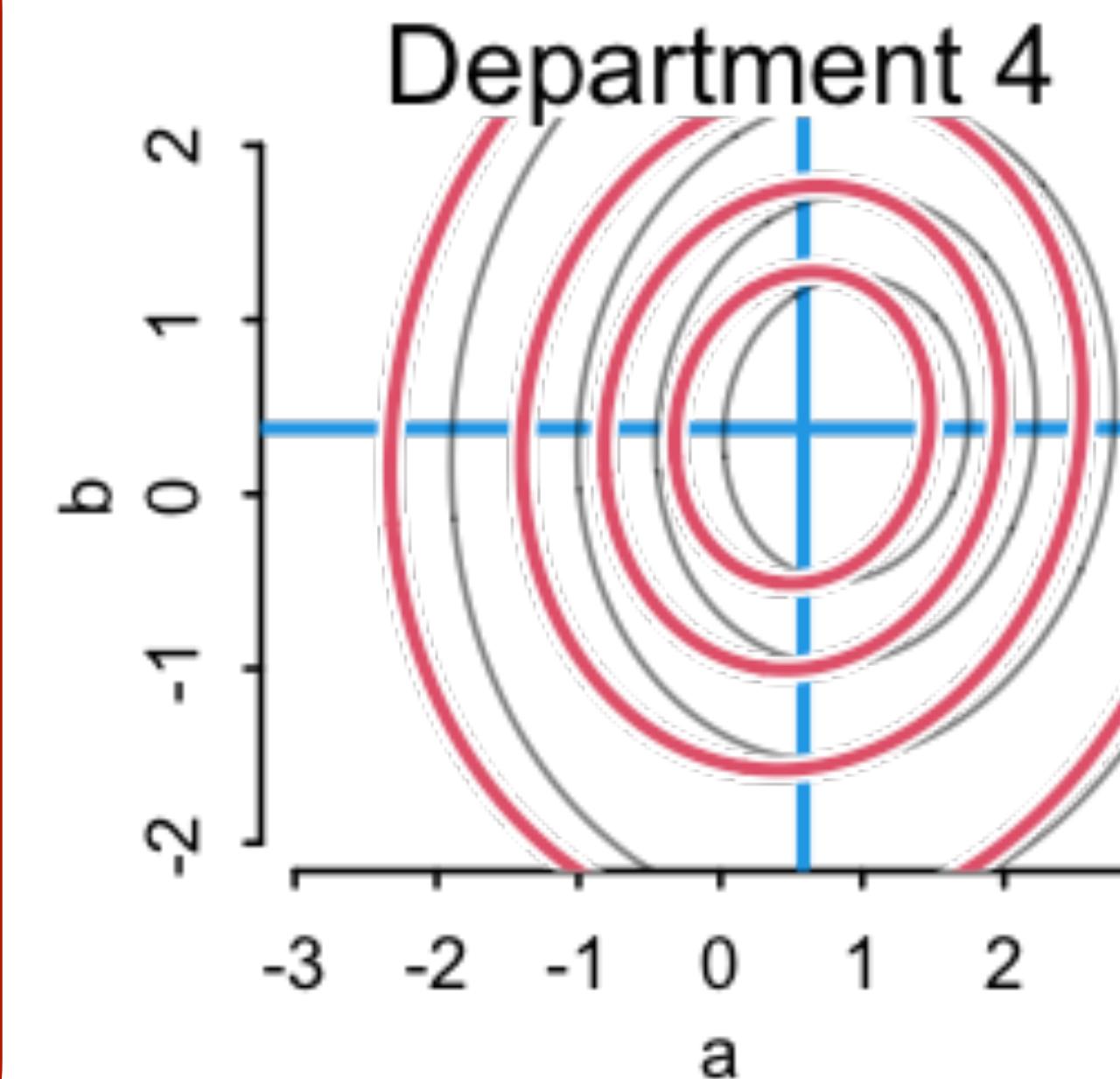
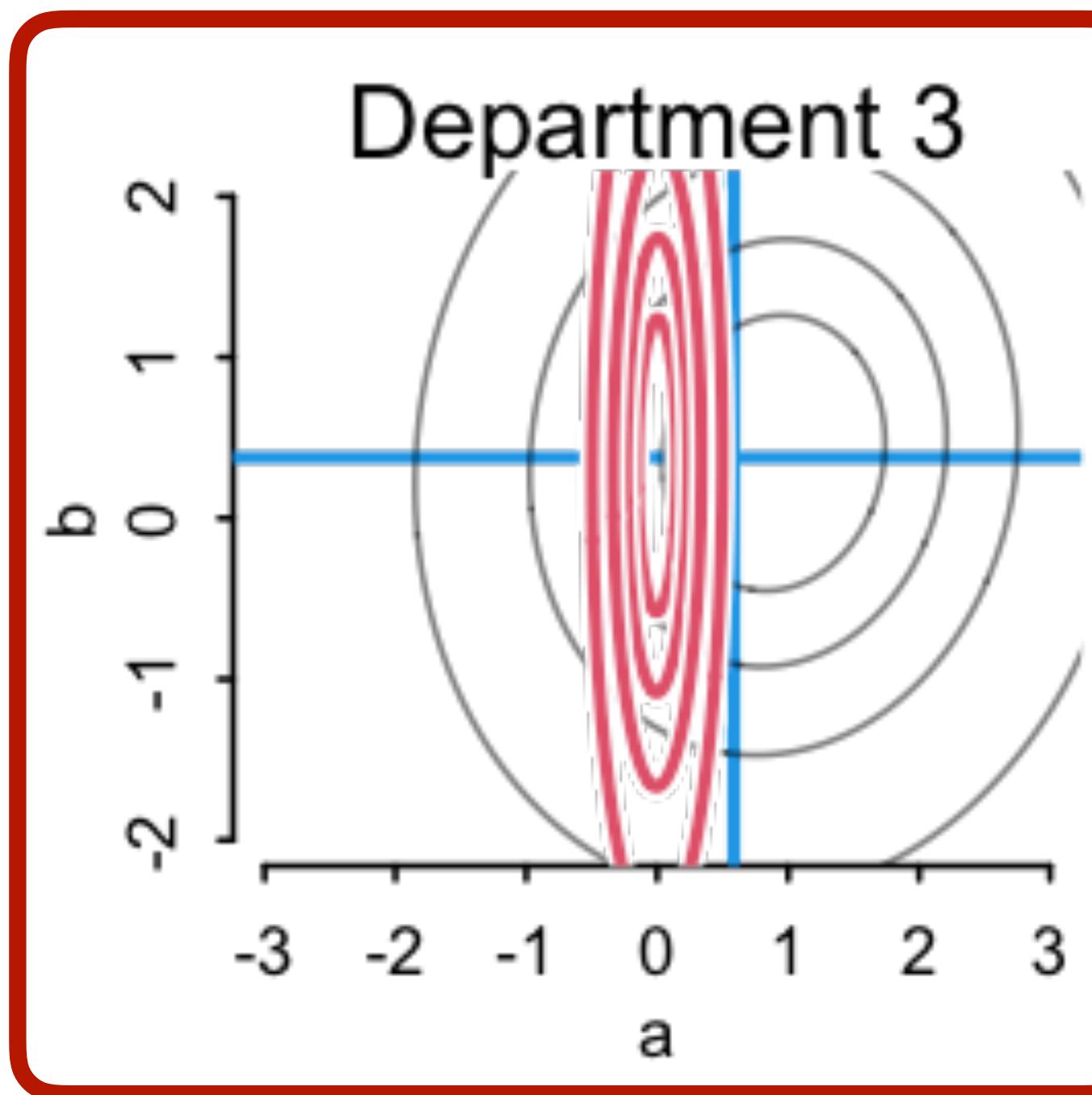
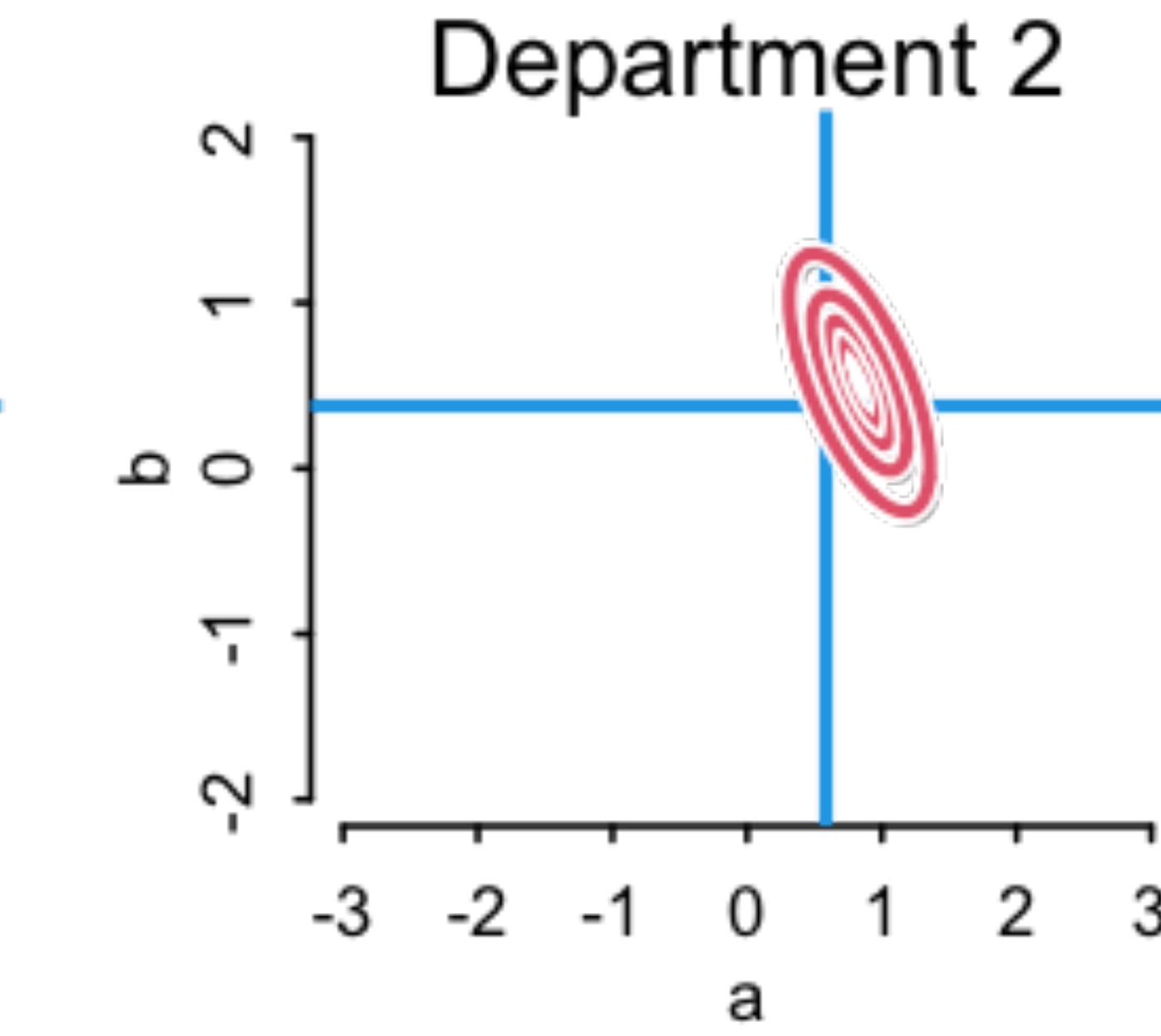
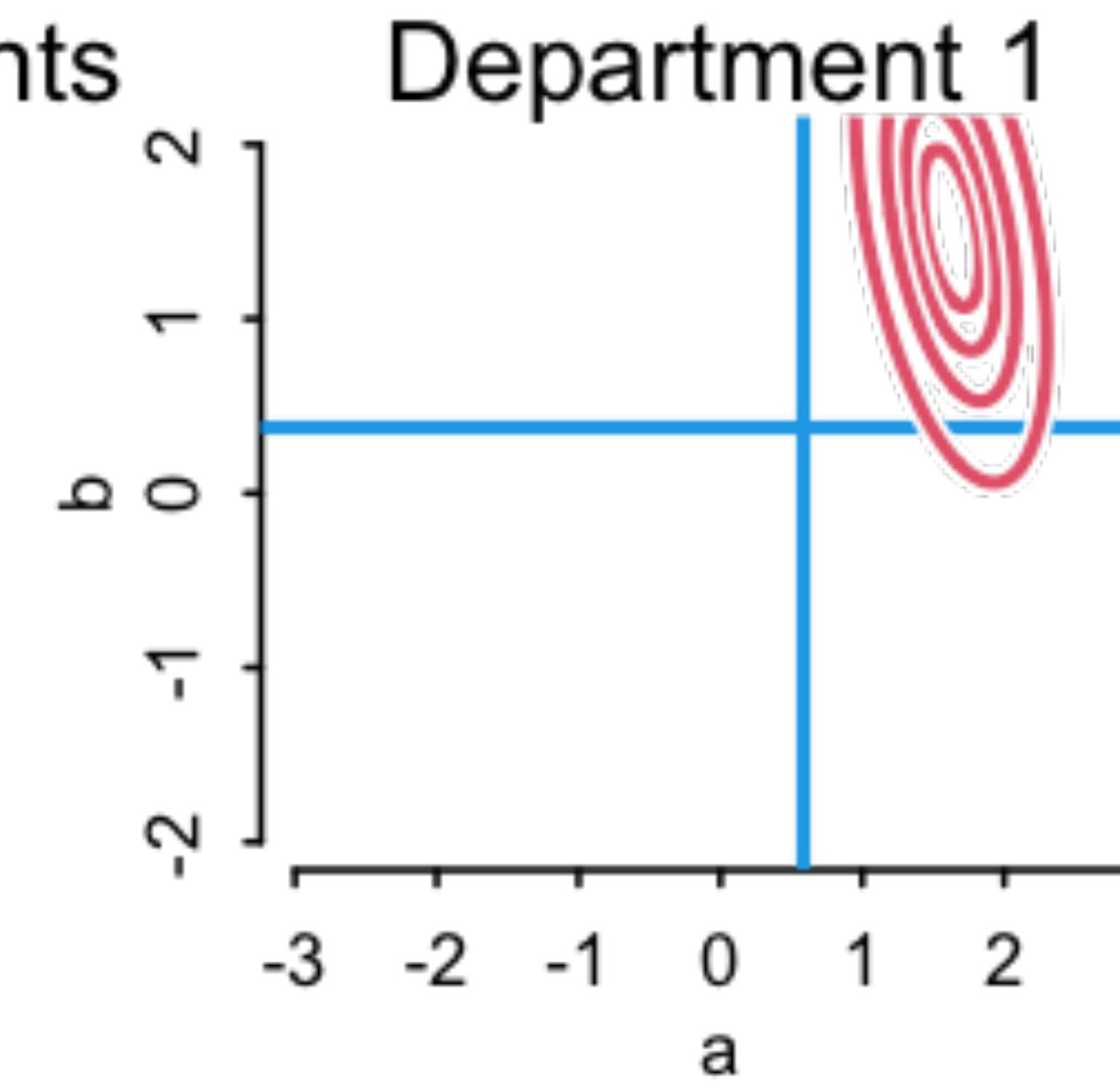
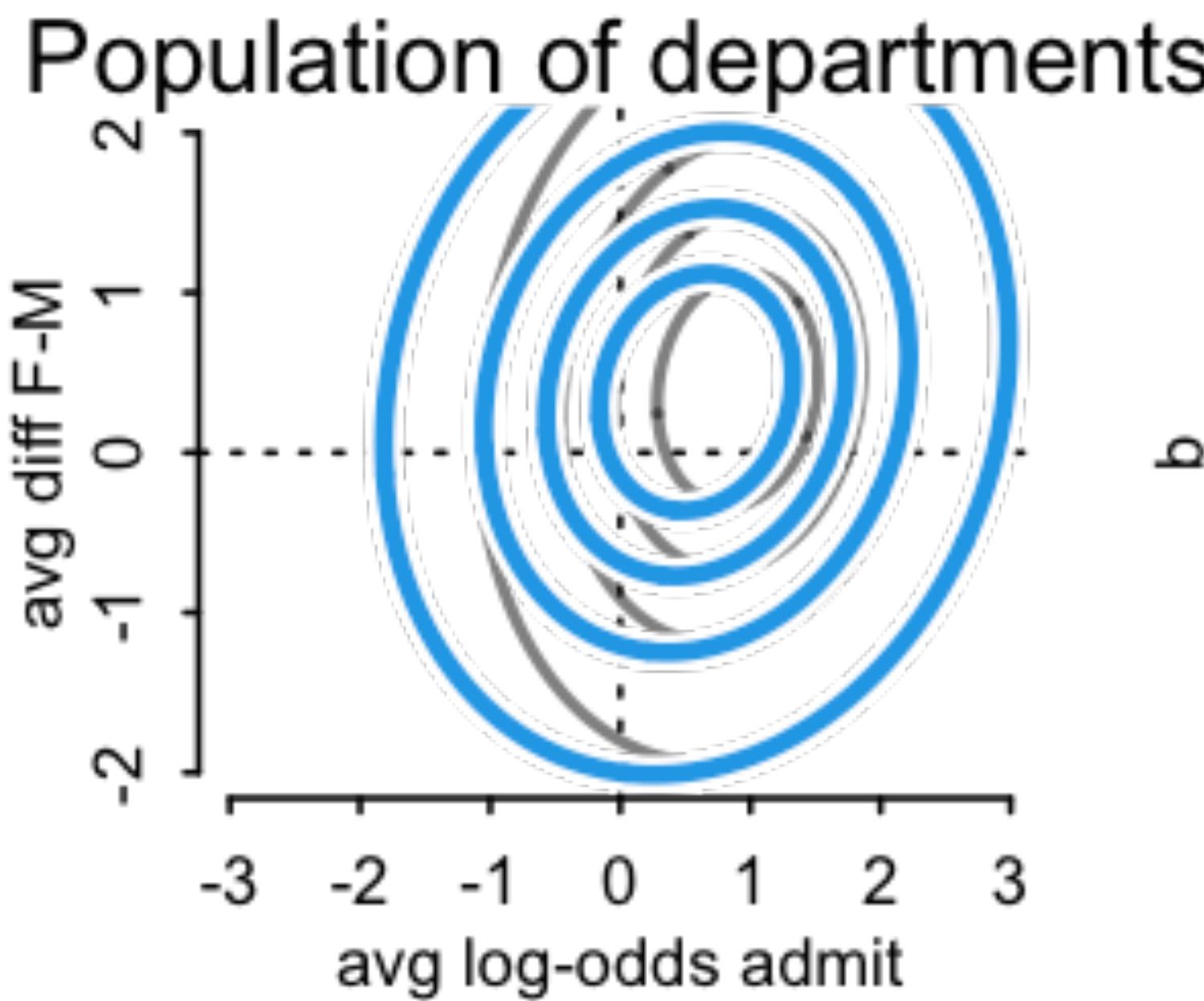




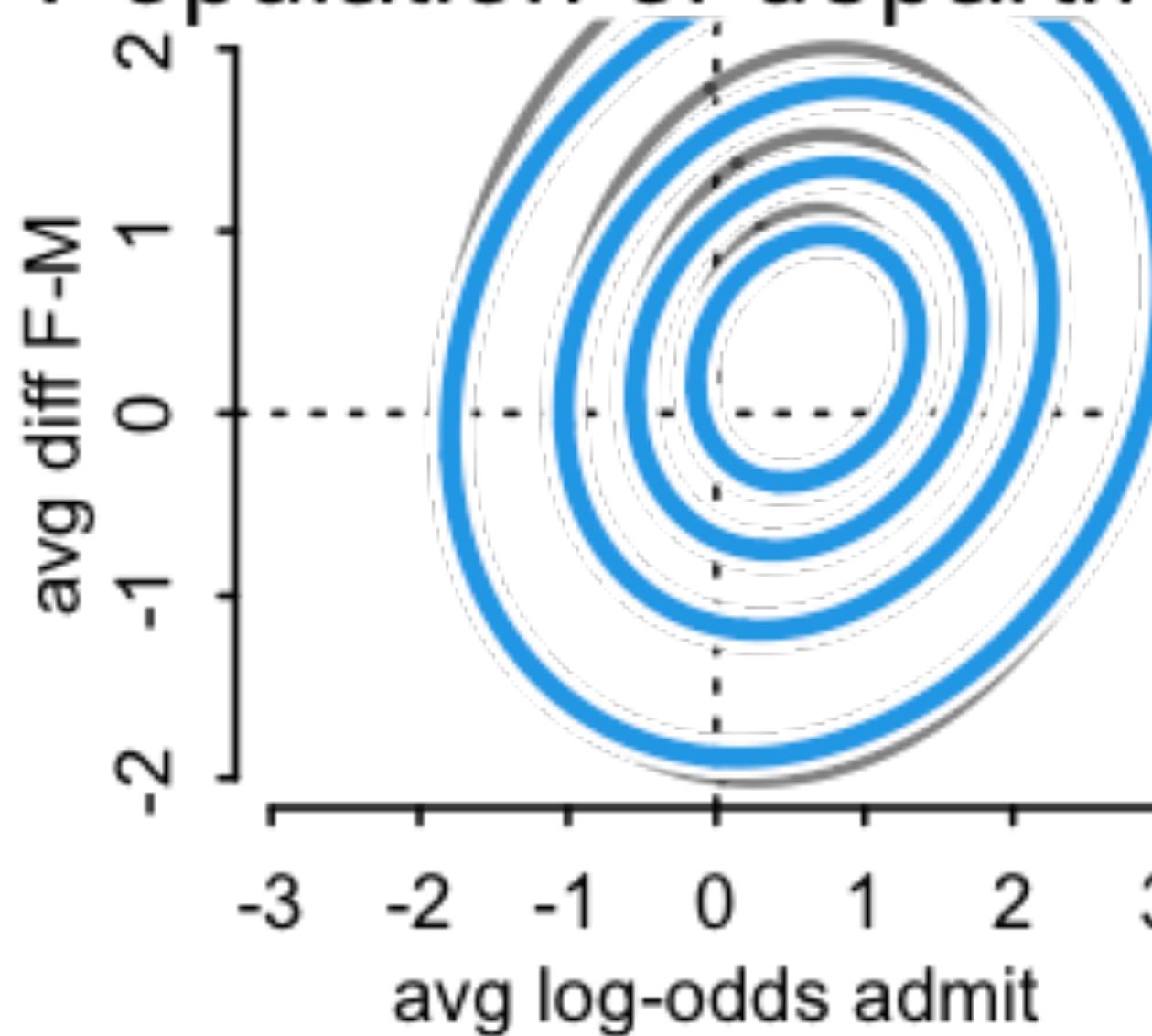




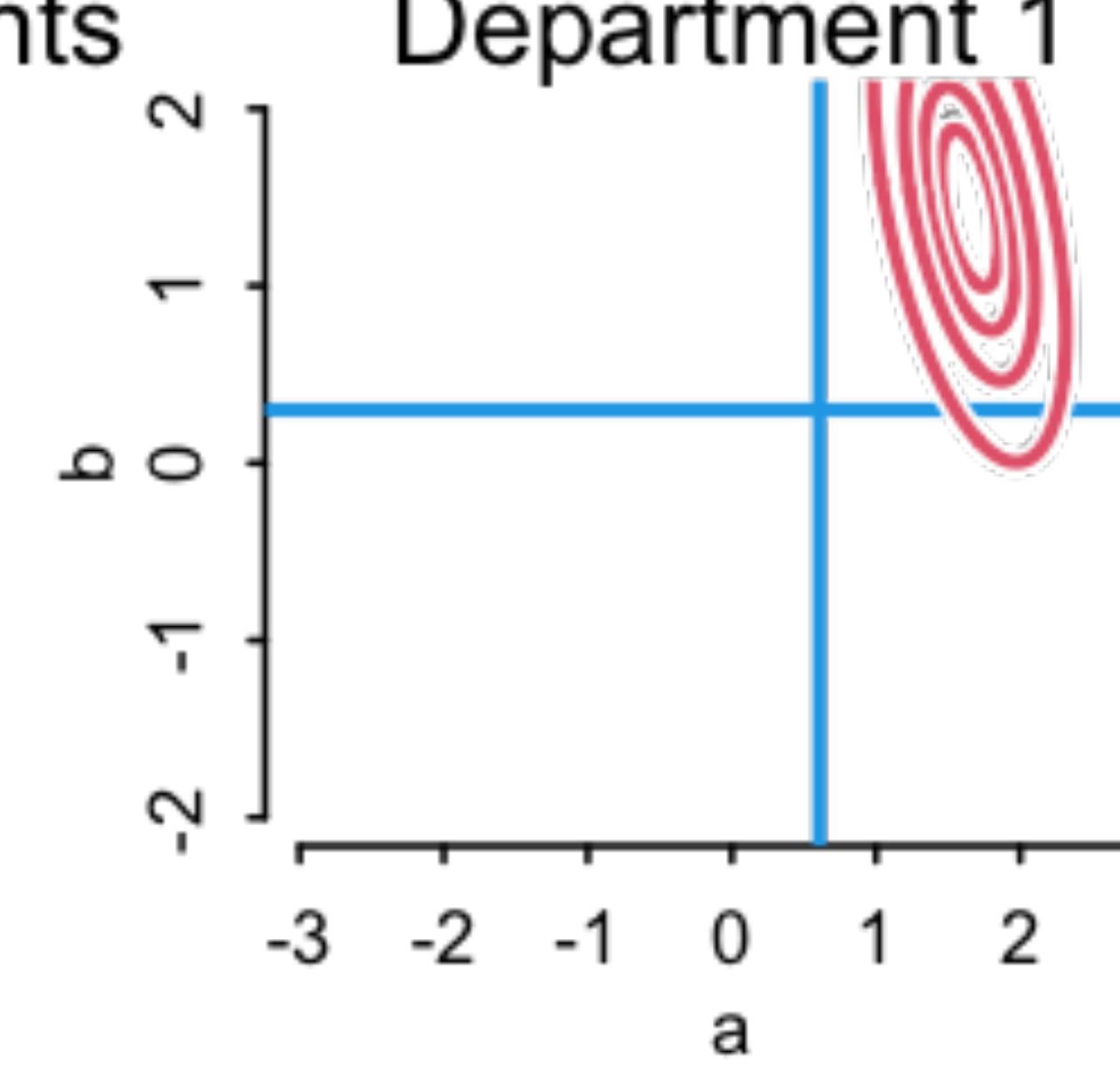




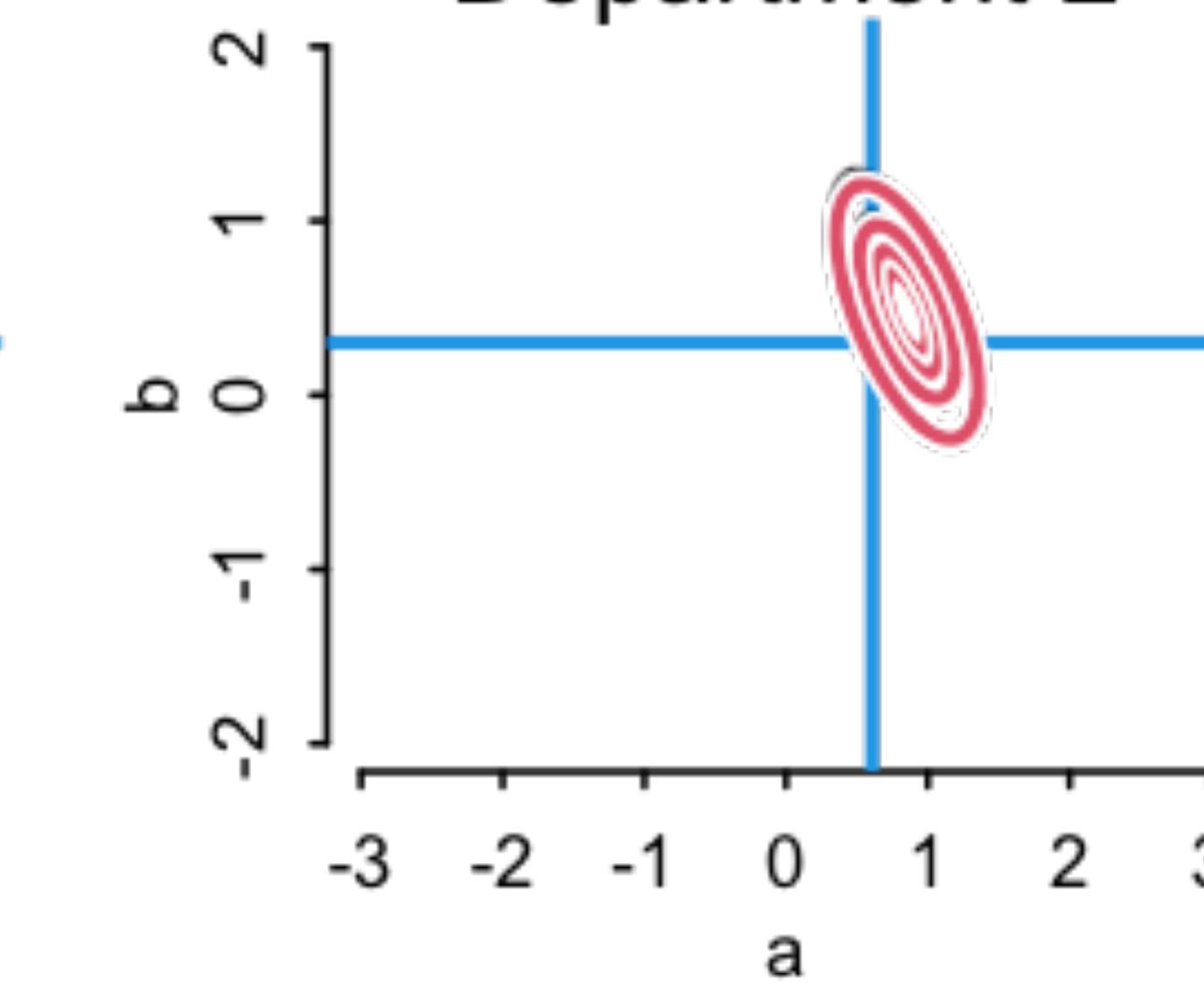
Population of departments



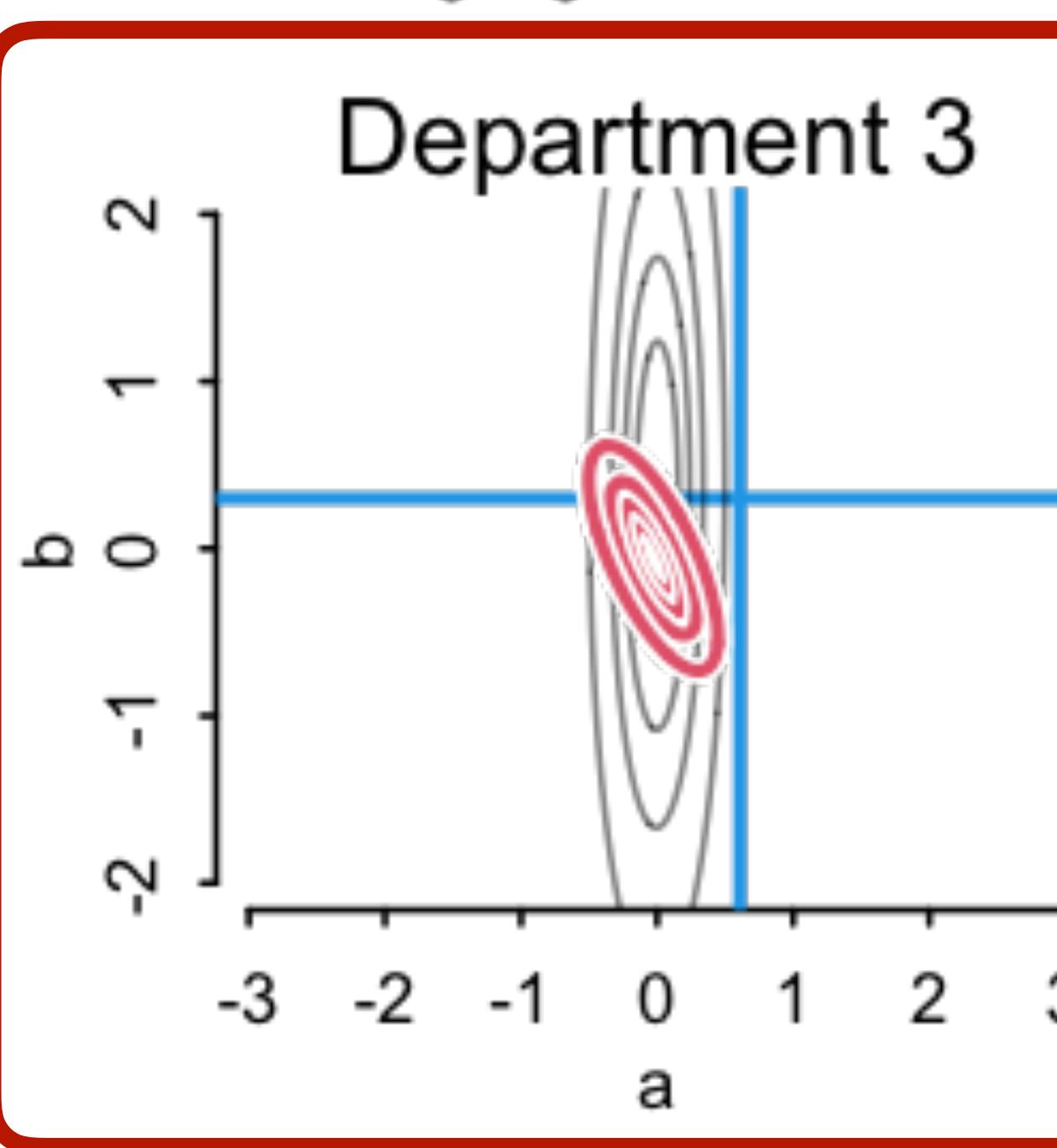
Department 1



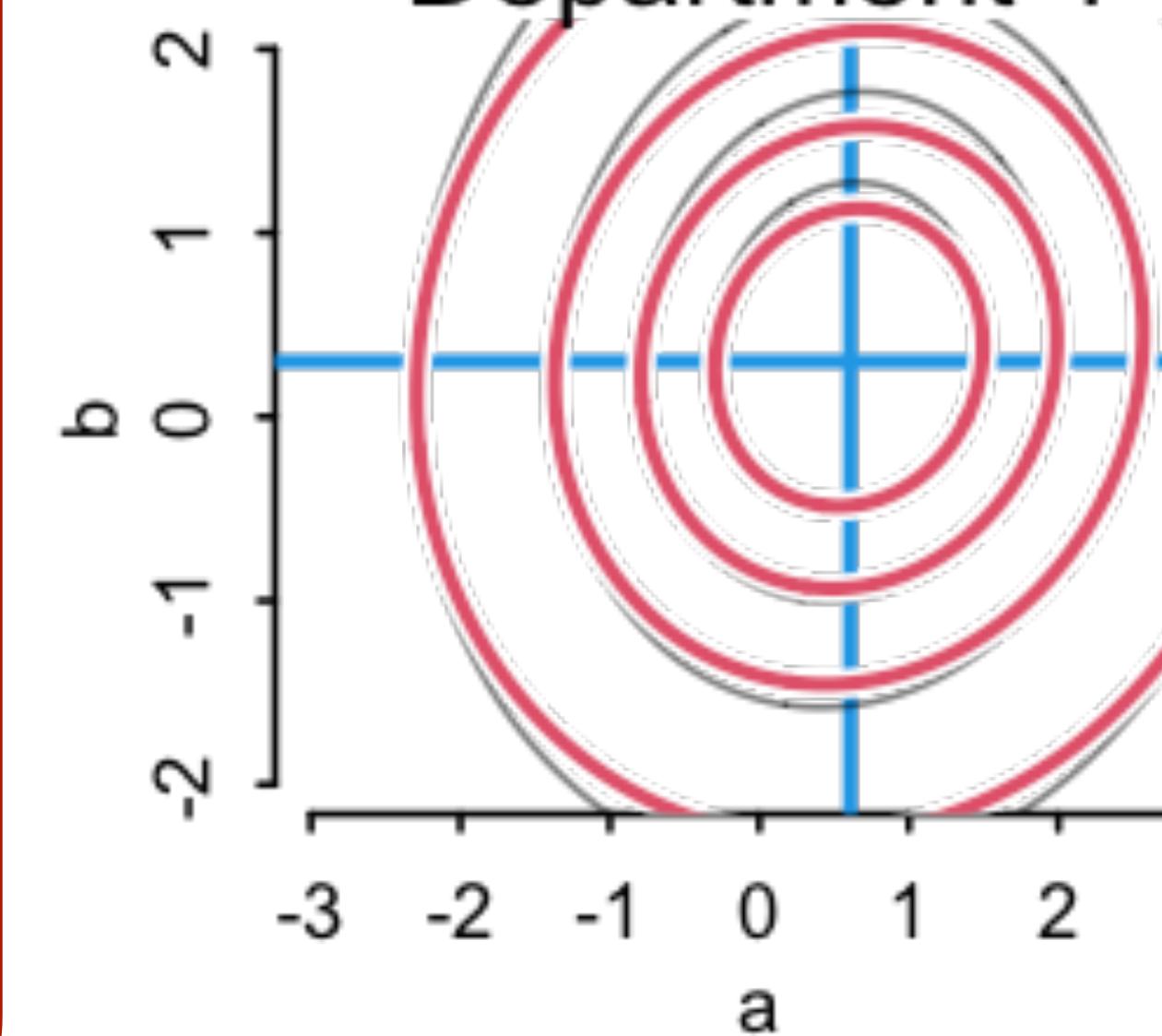
Department 2



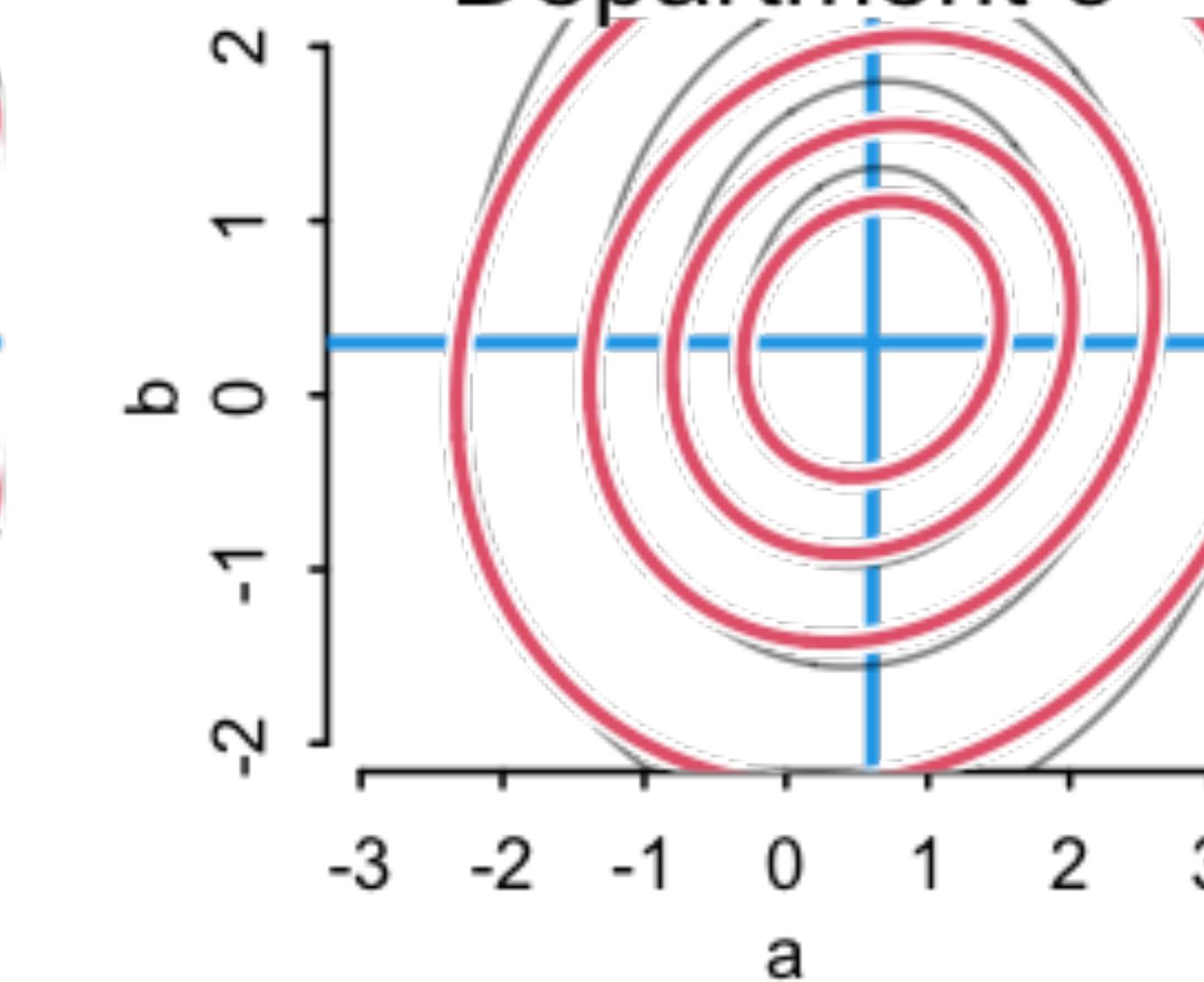
Department 3

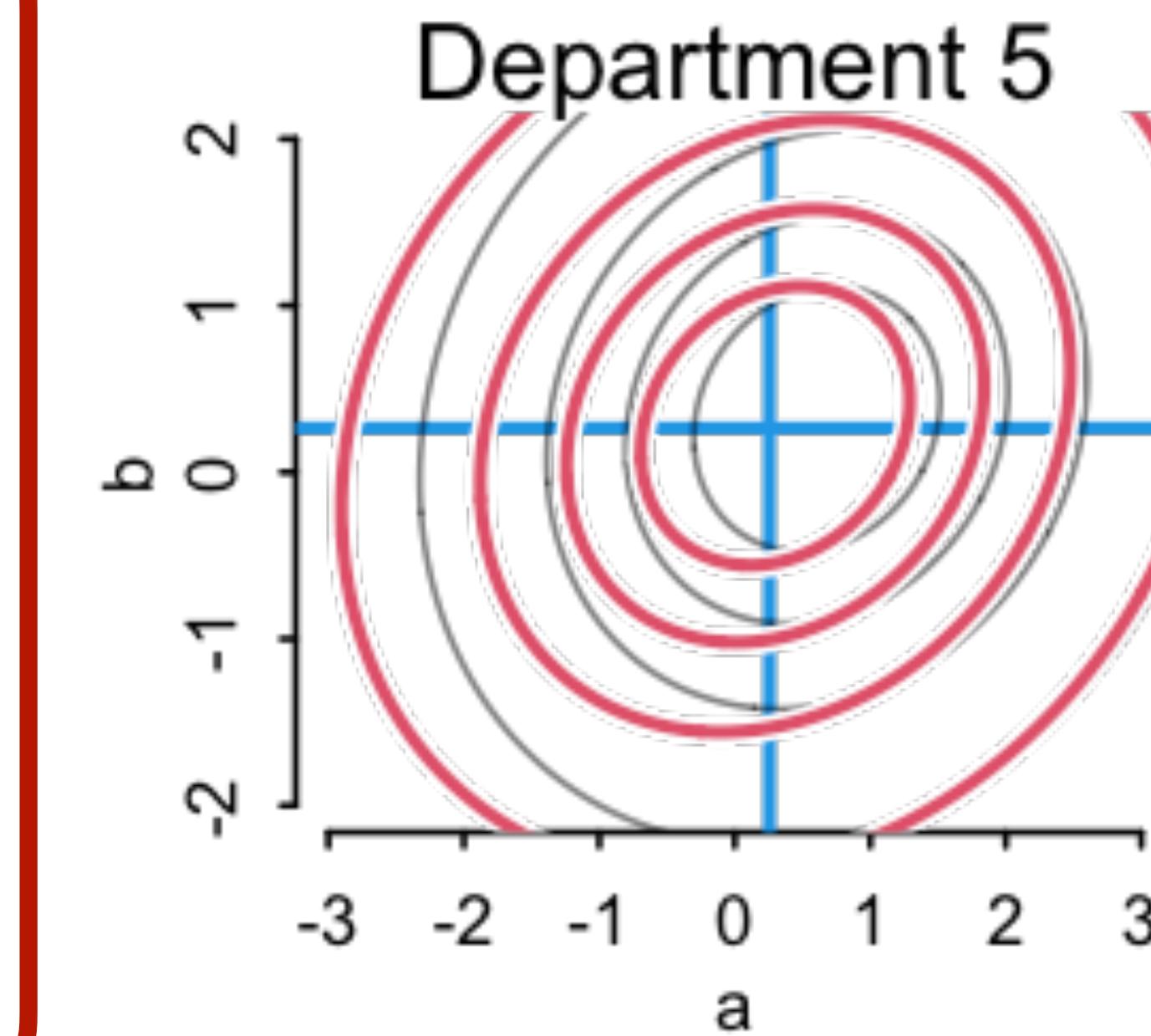
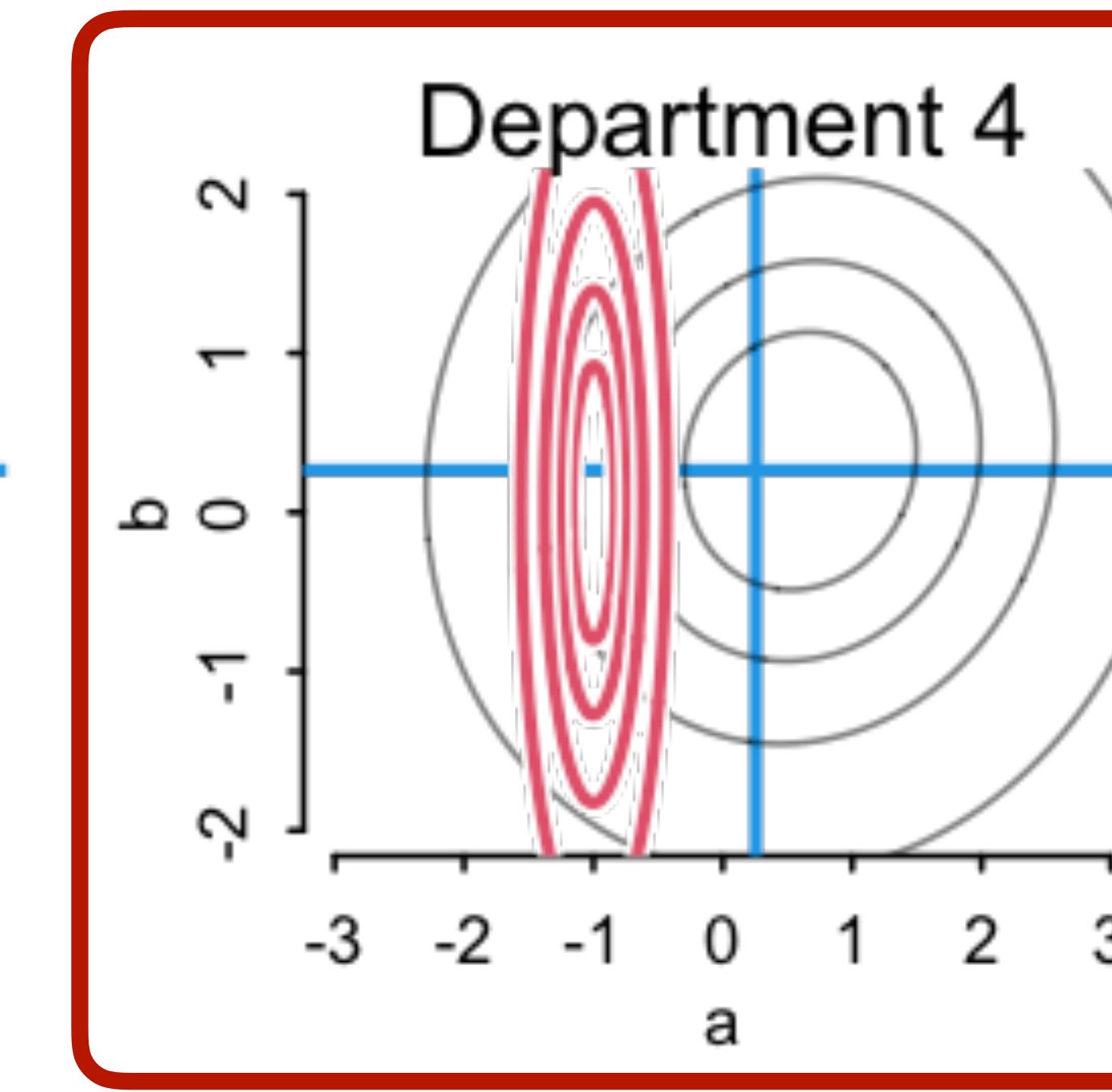
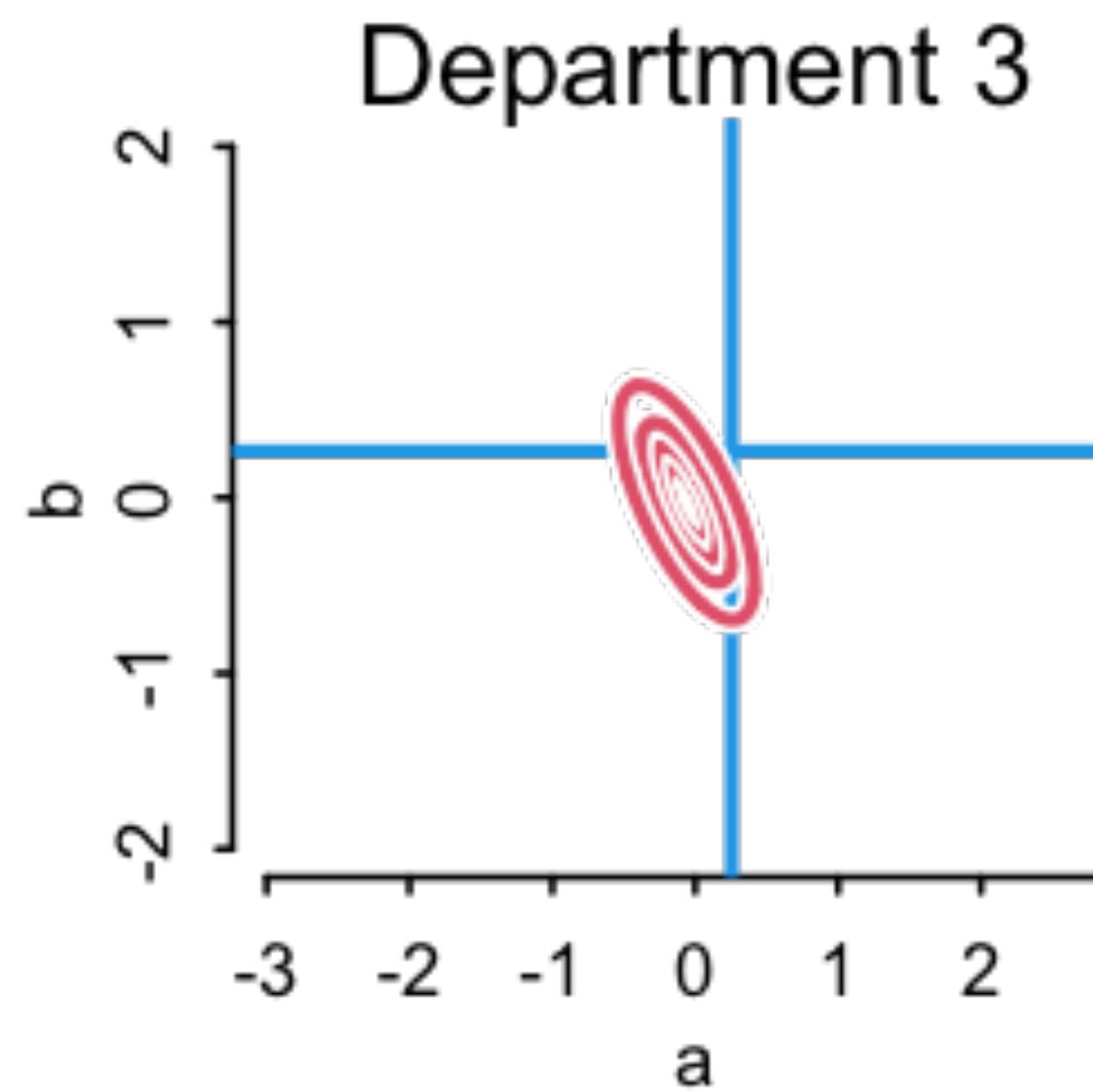
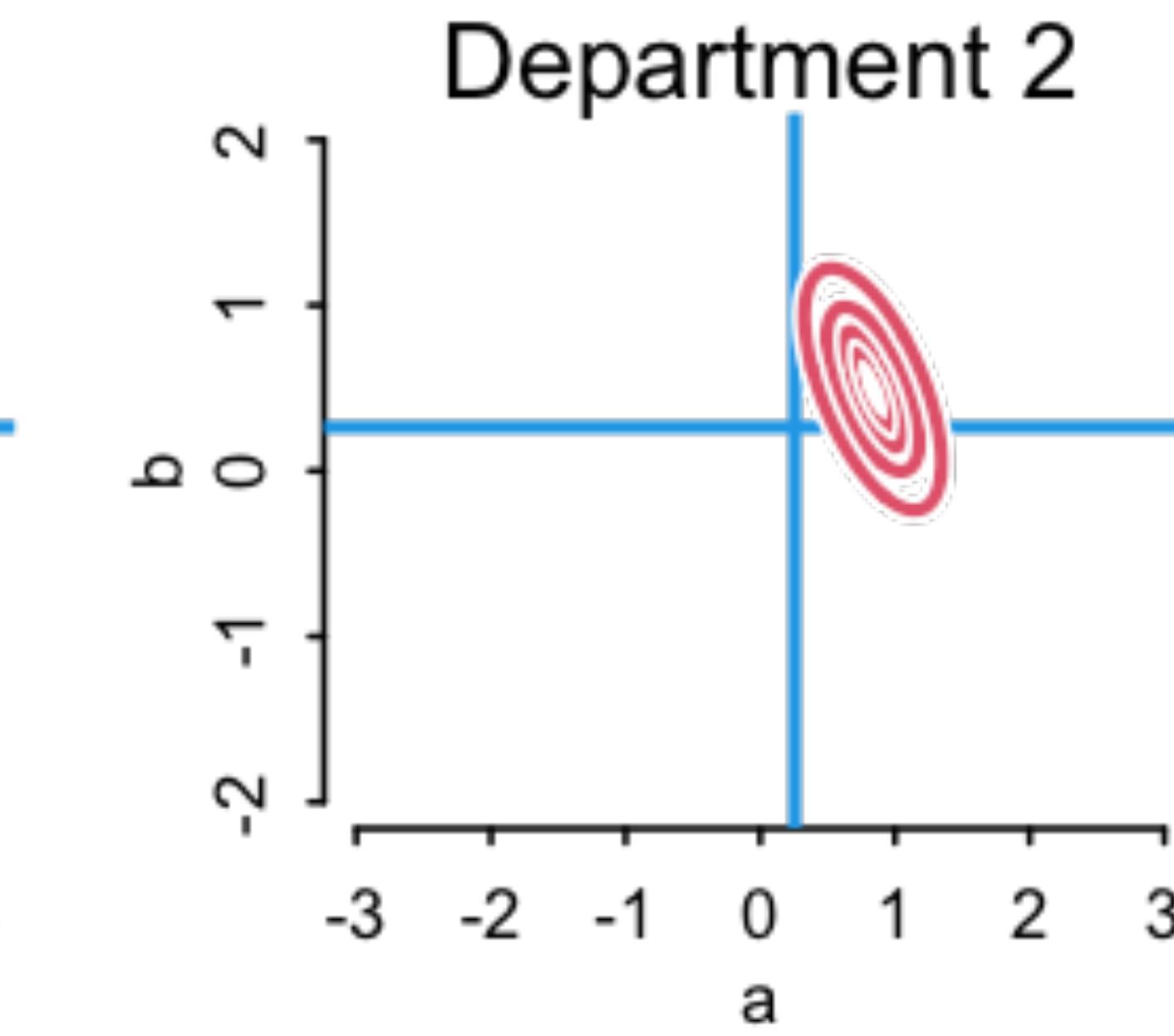
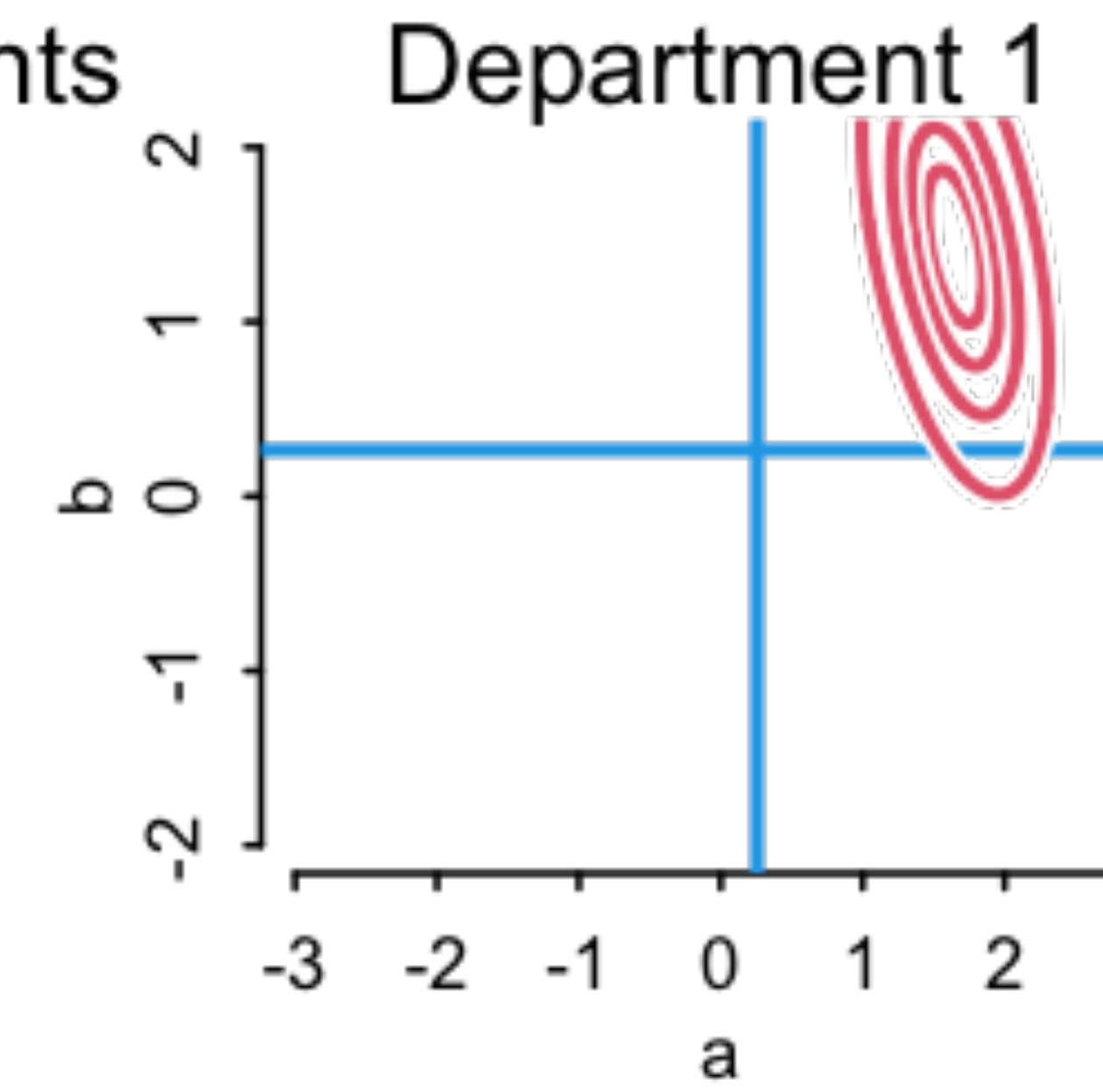
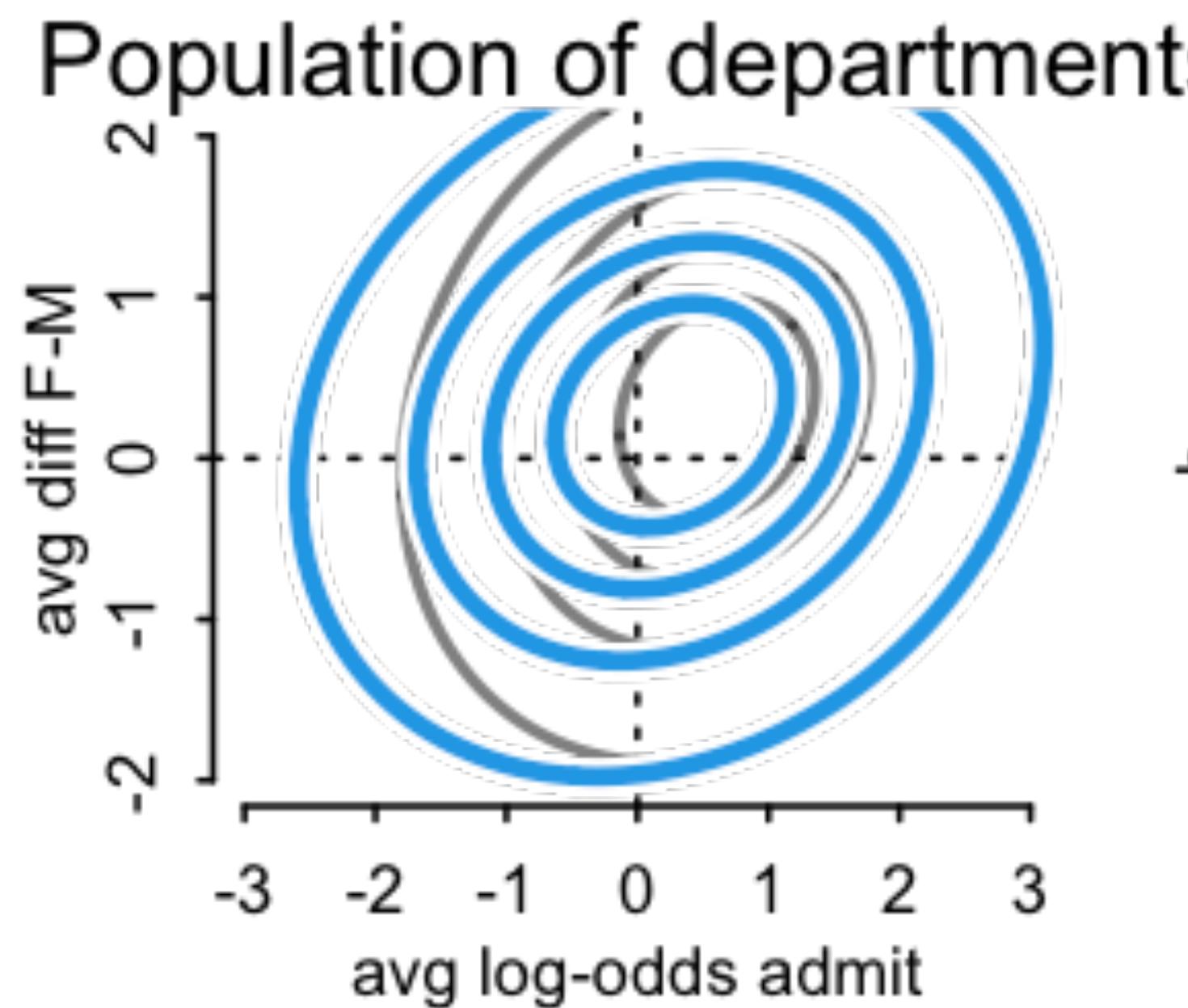


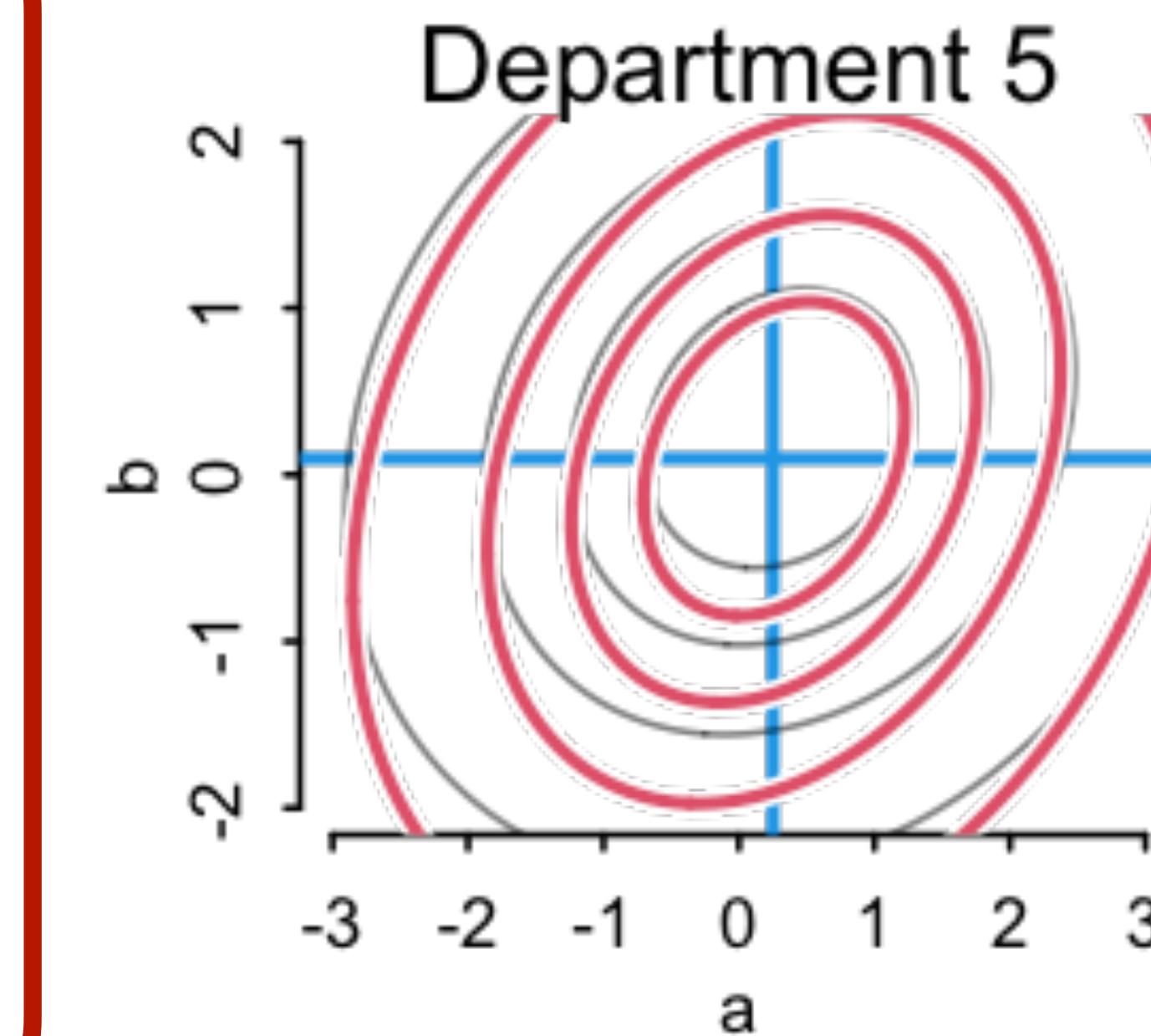
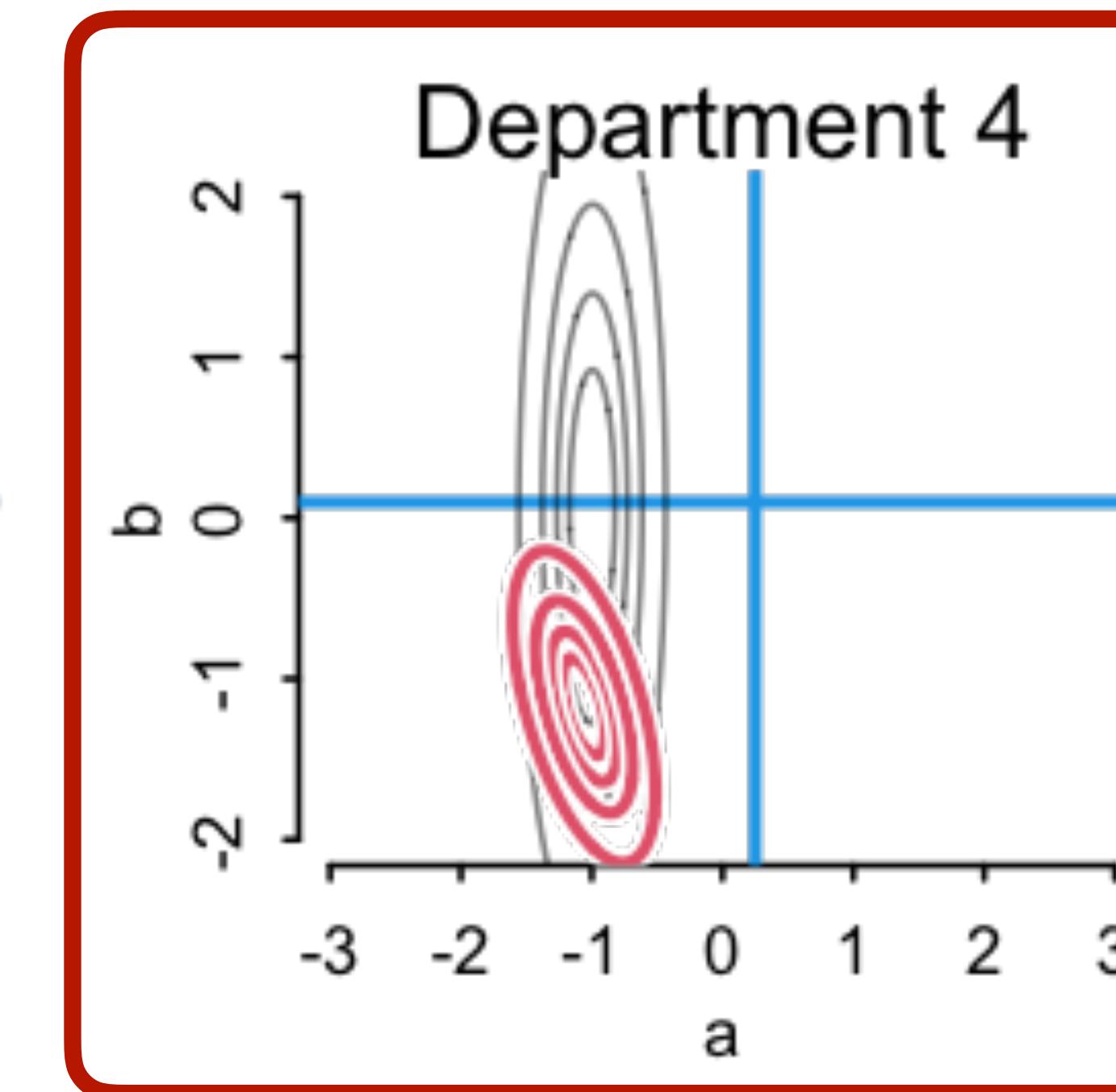
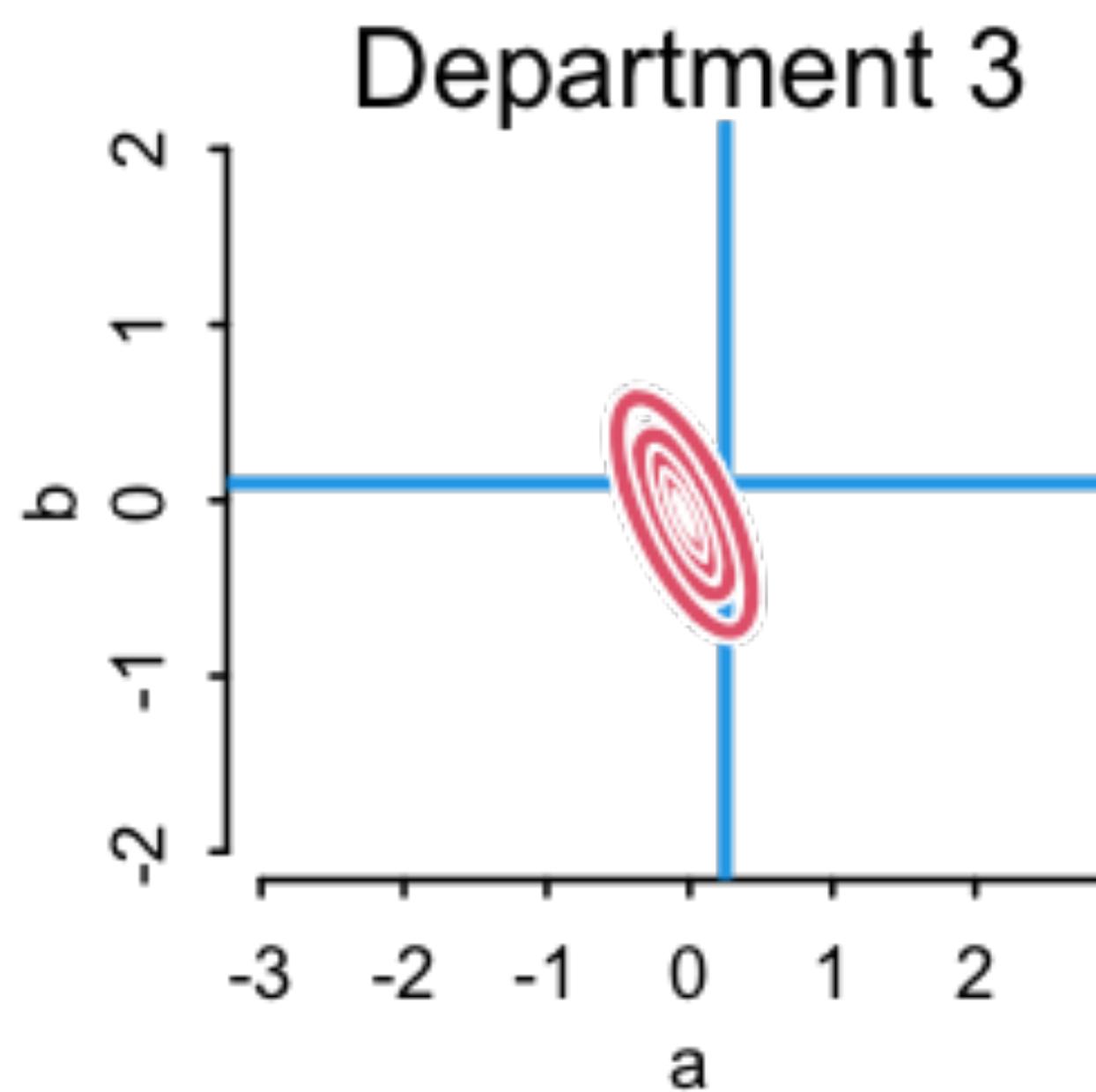
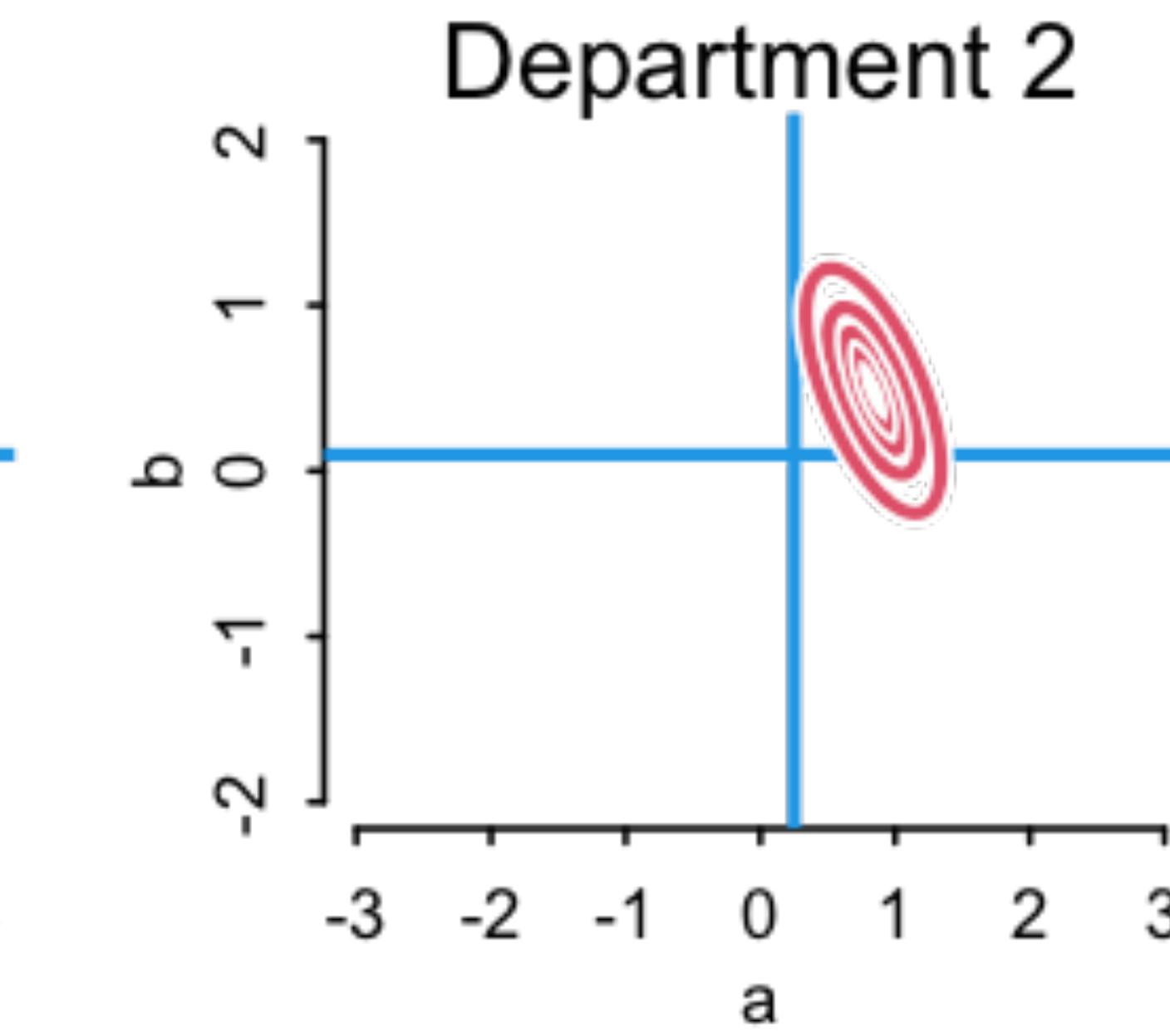
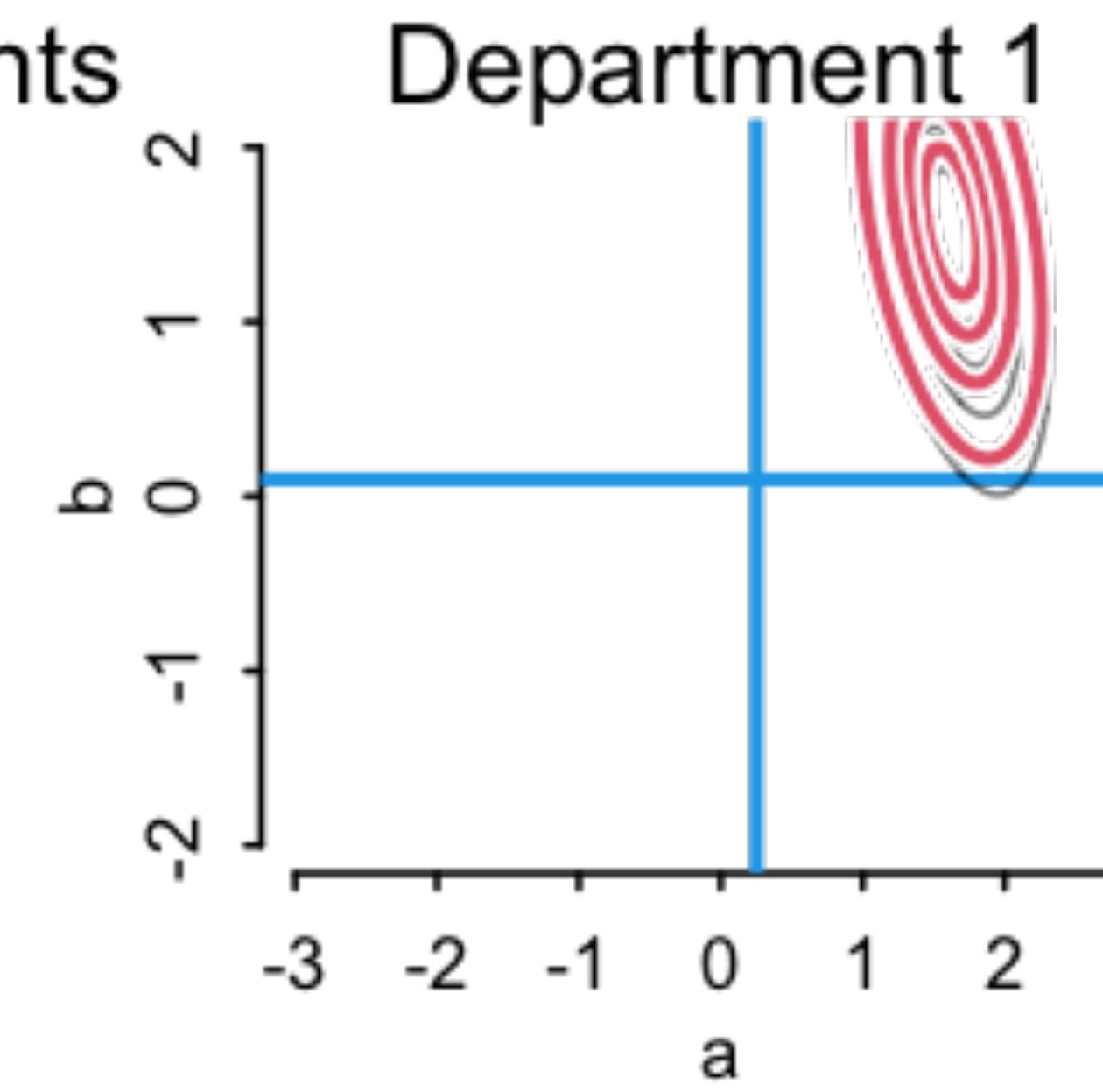
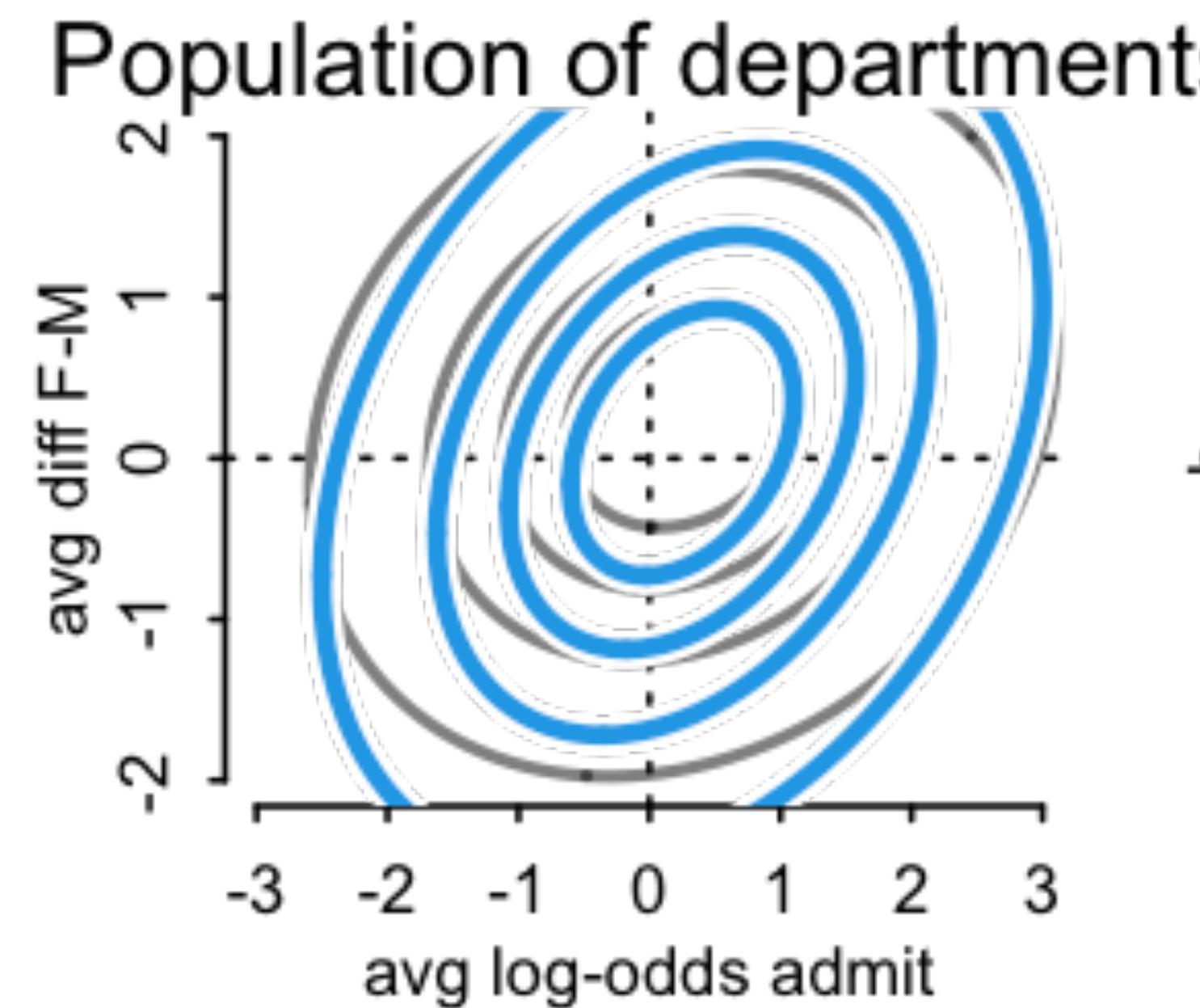
Department 4

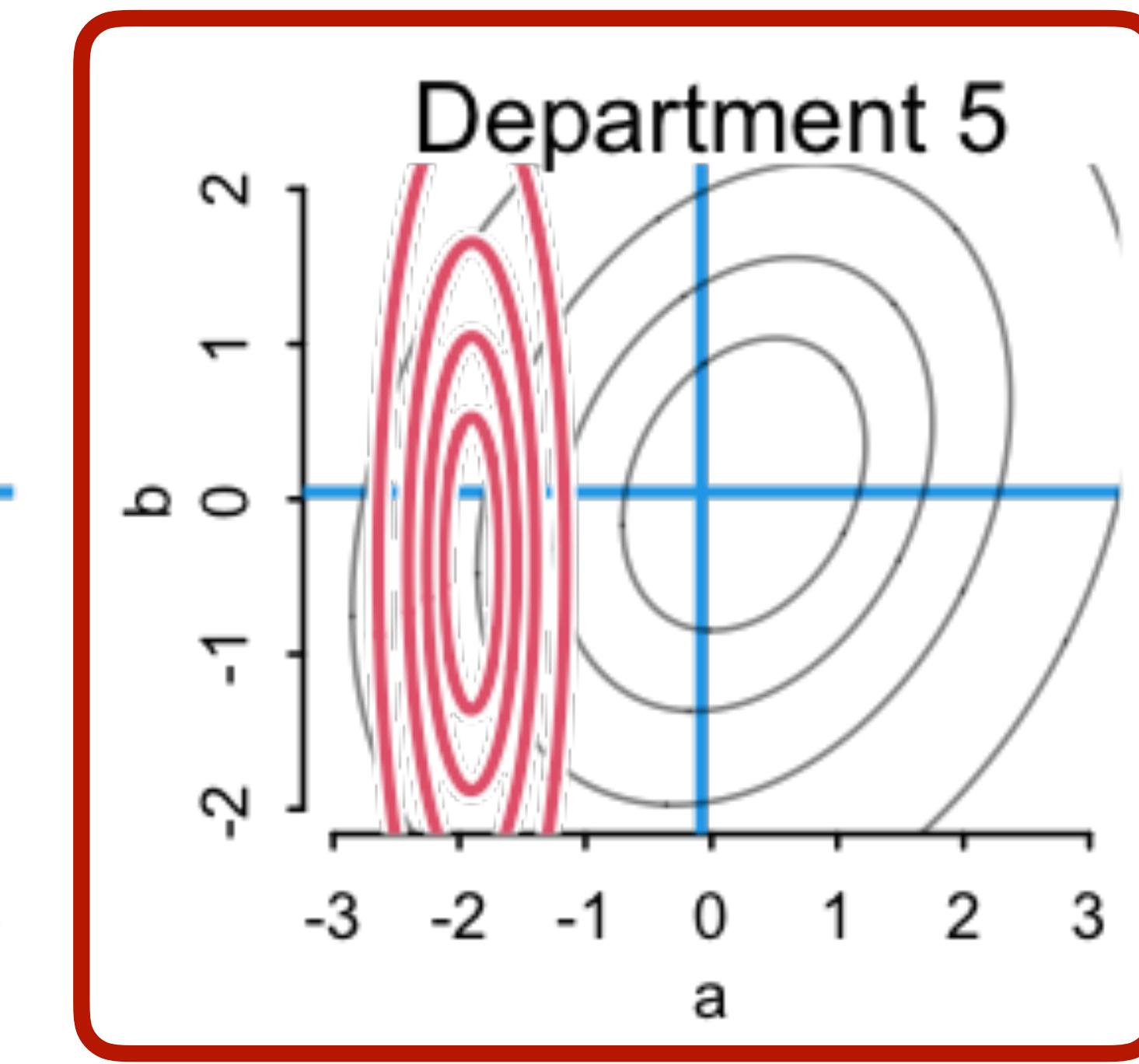
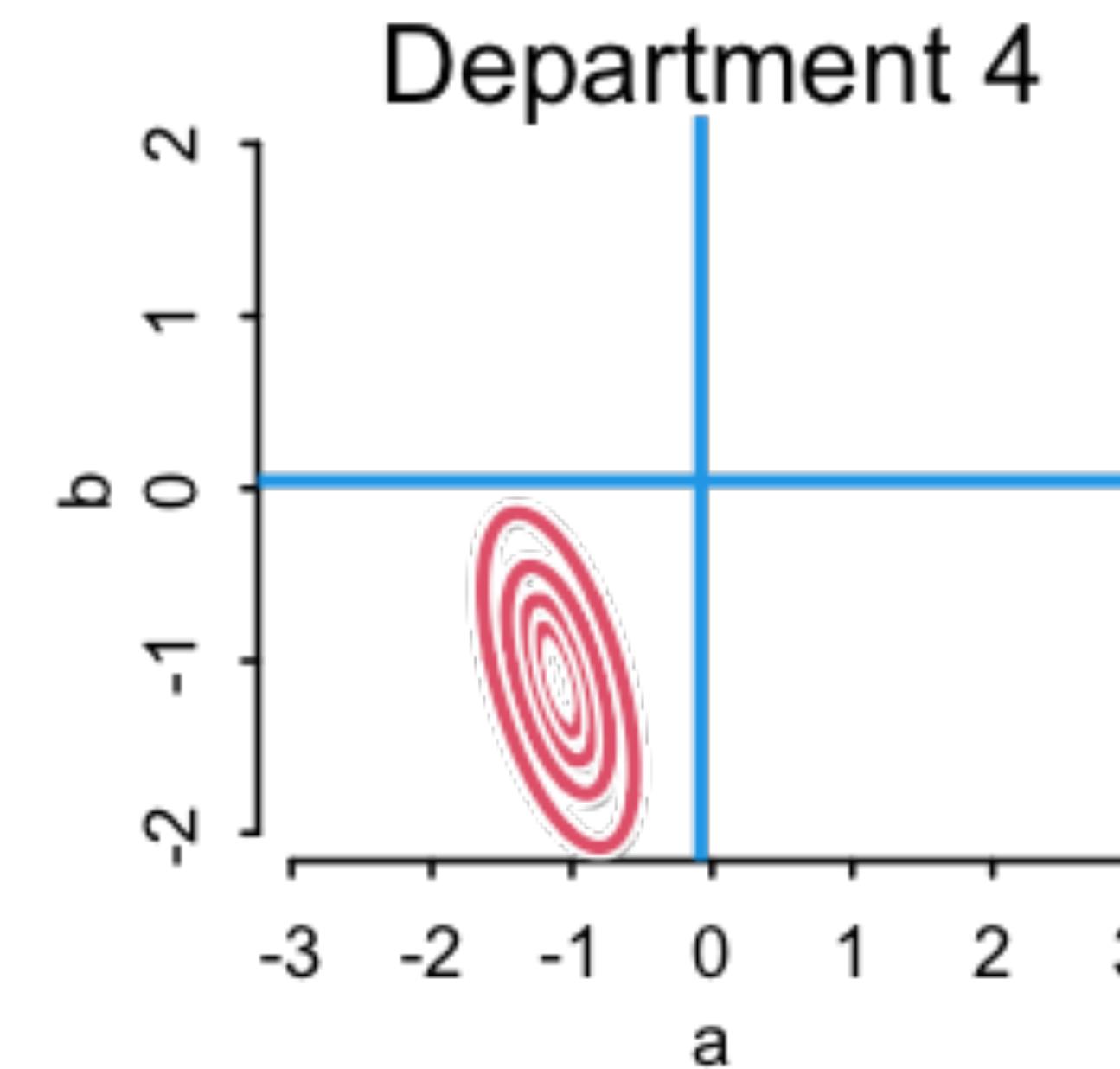
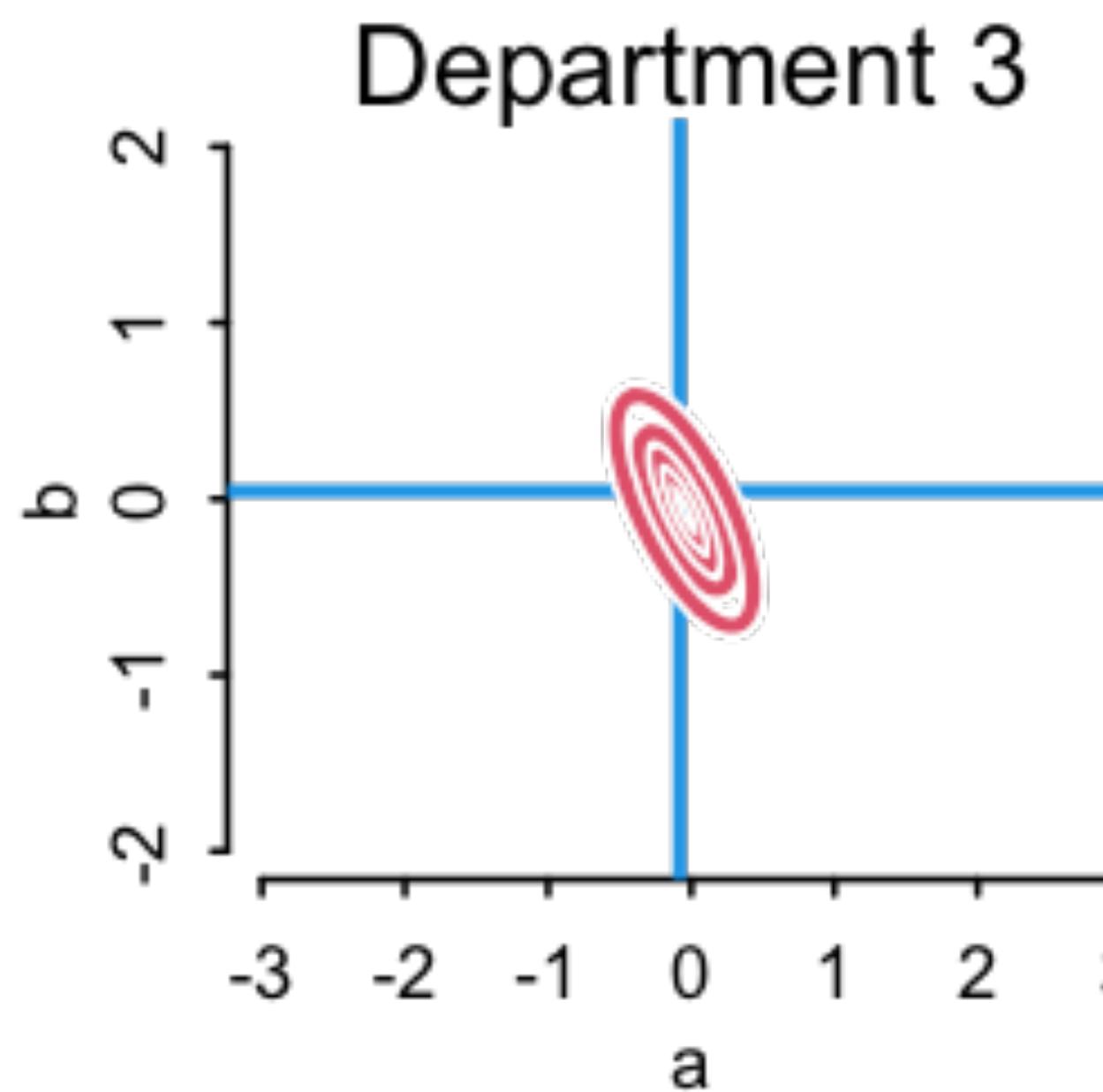
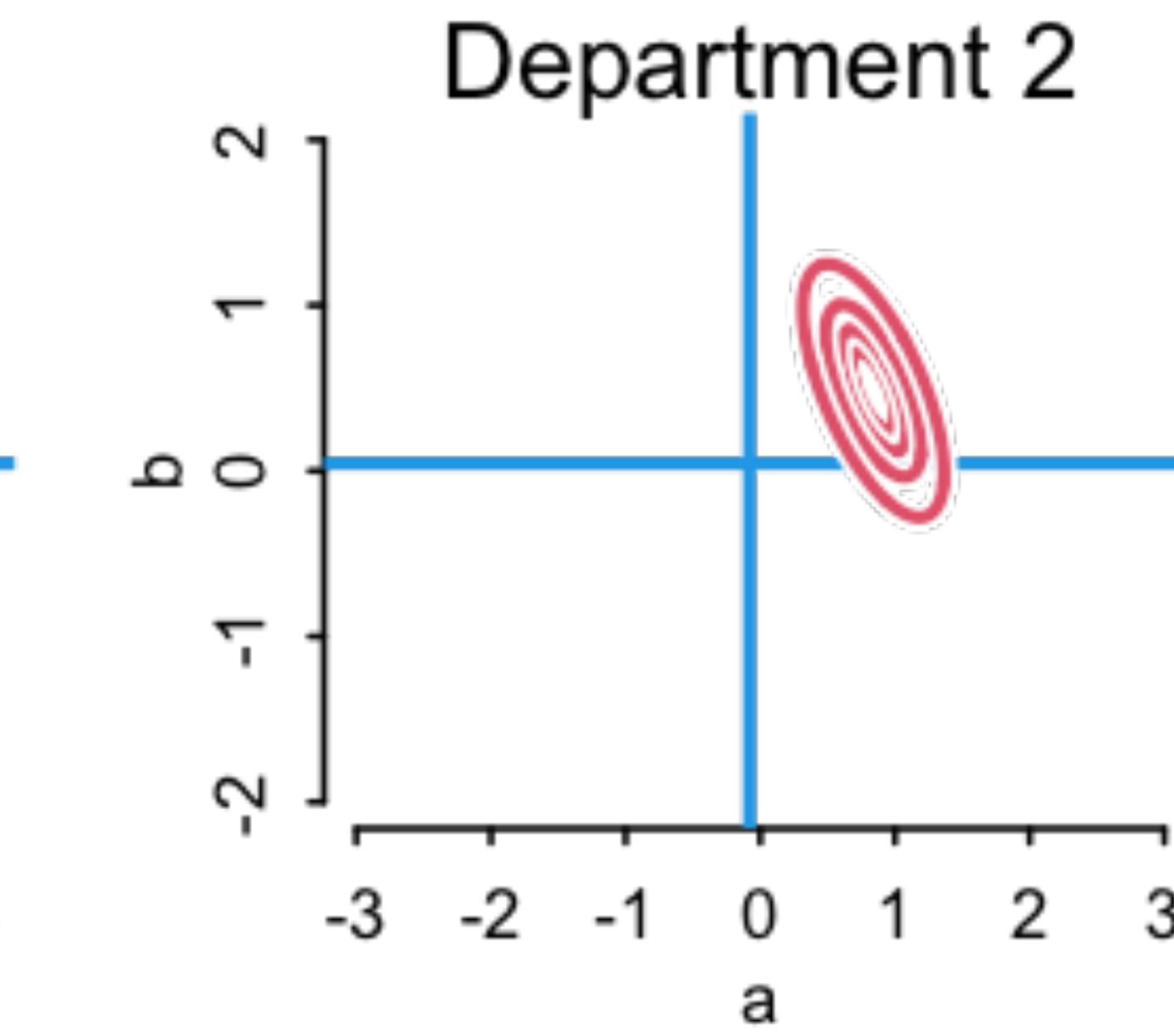
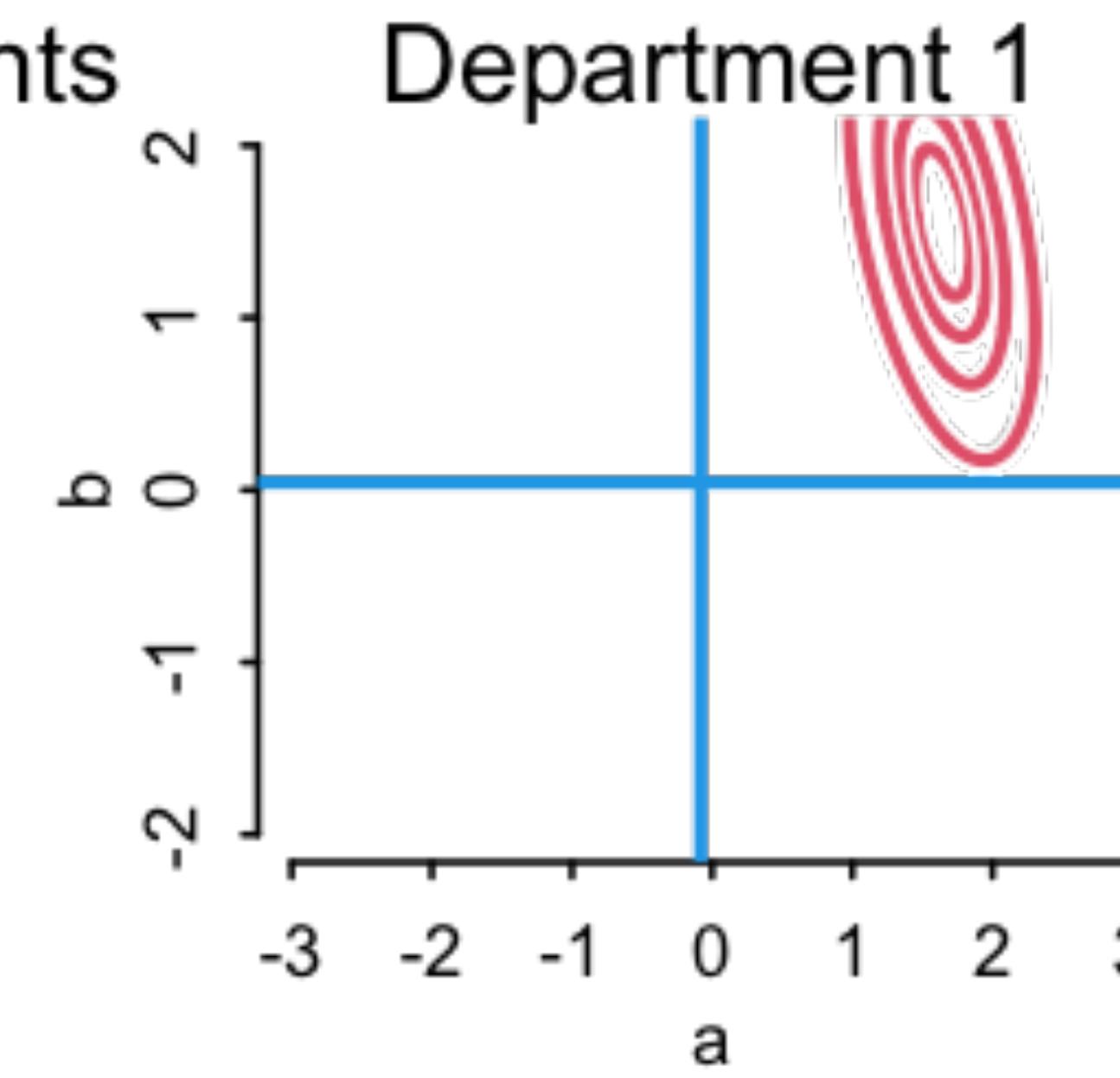
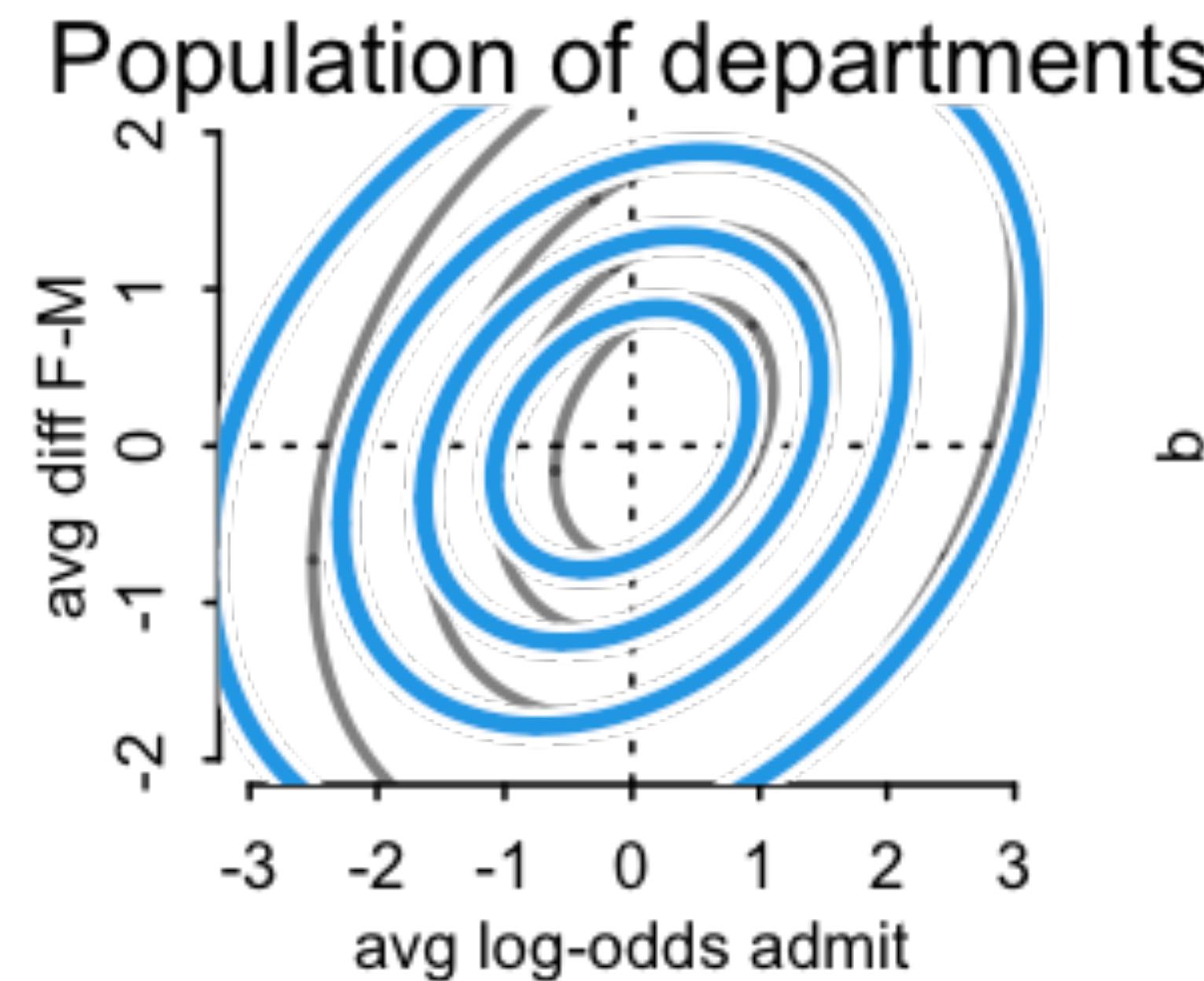


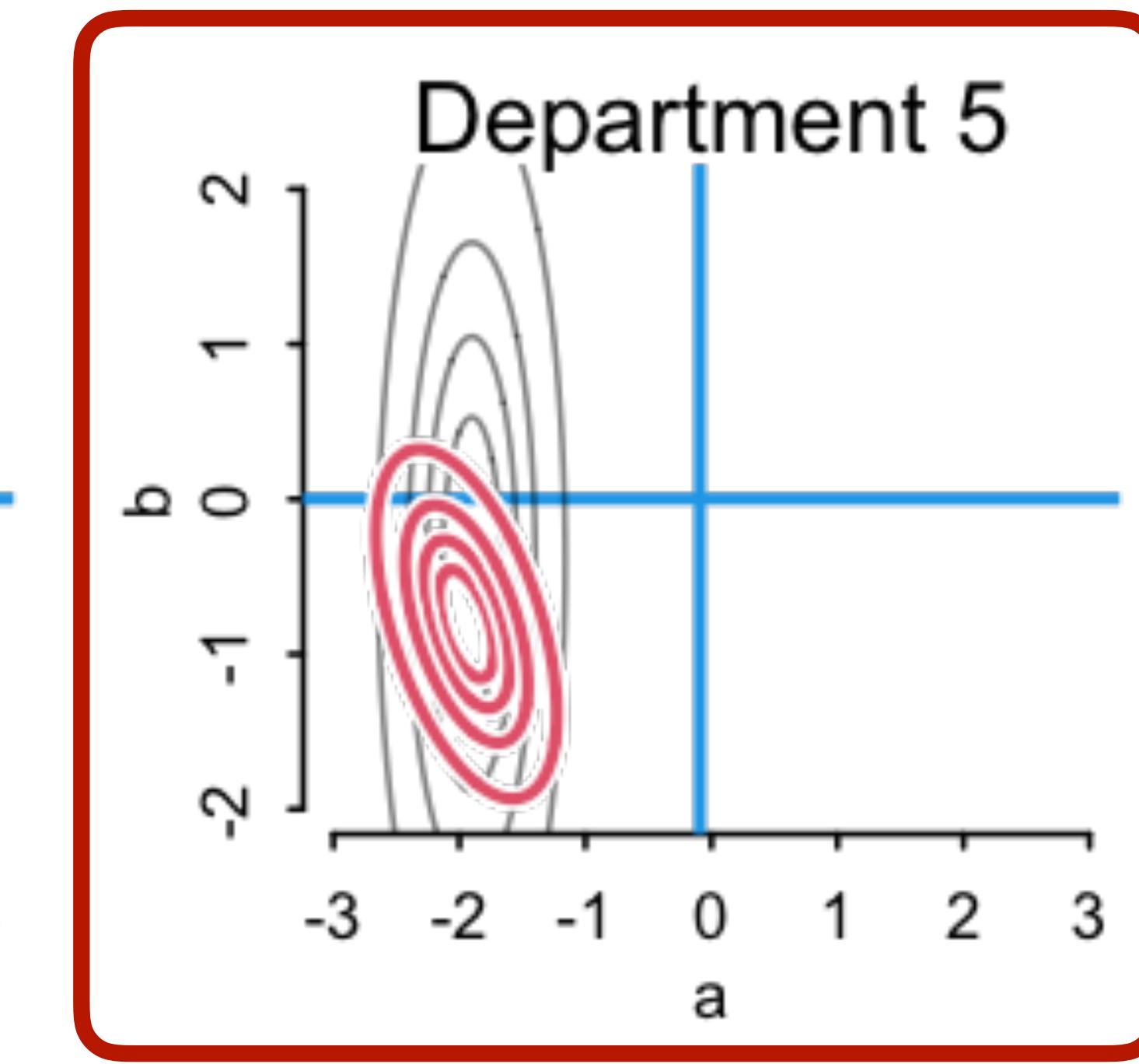
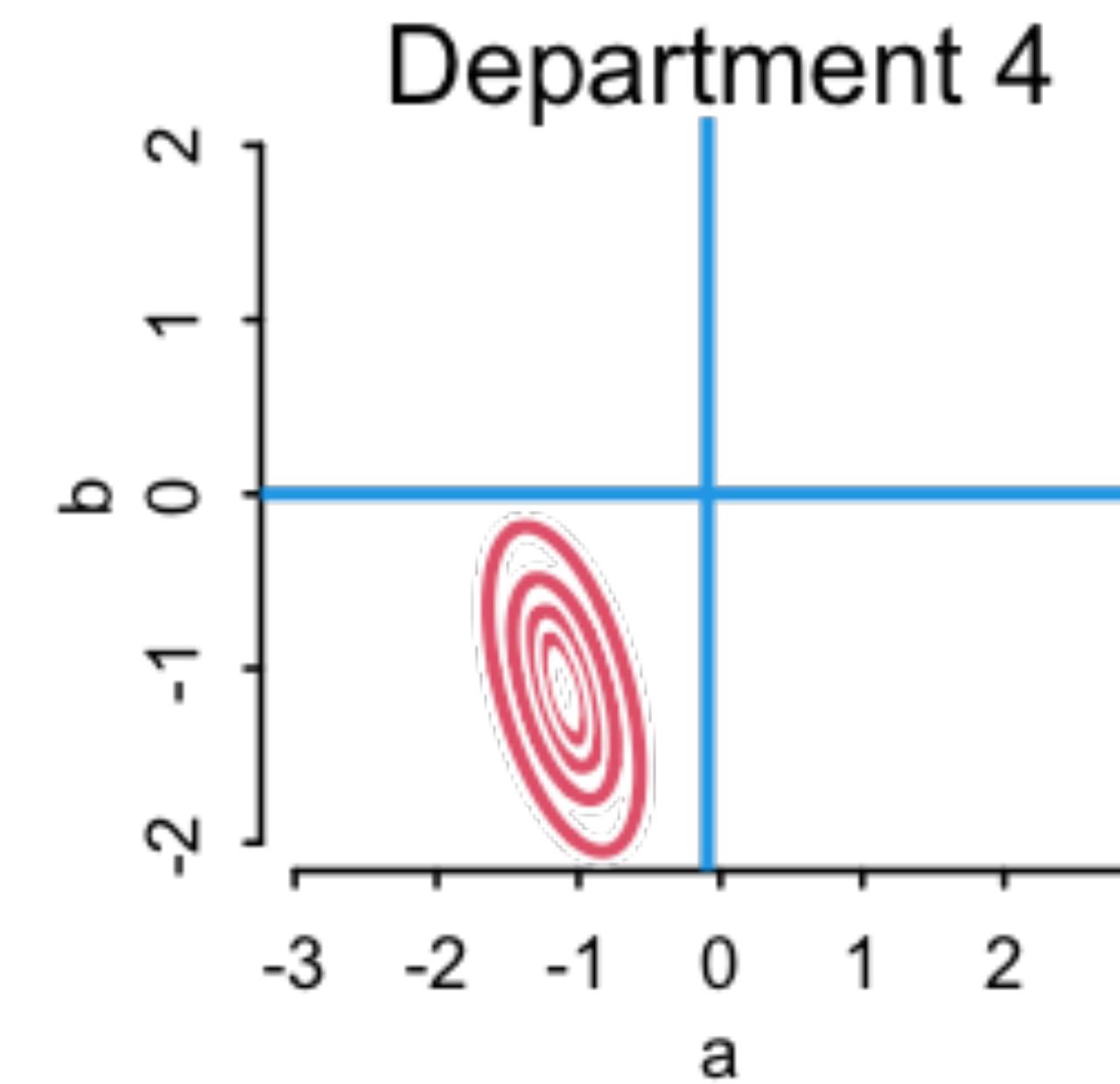
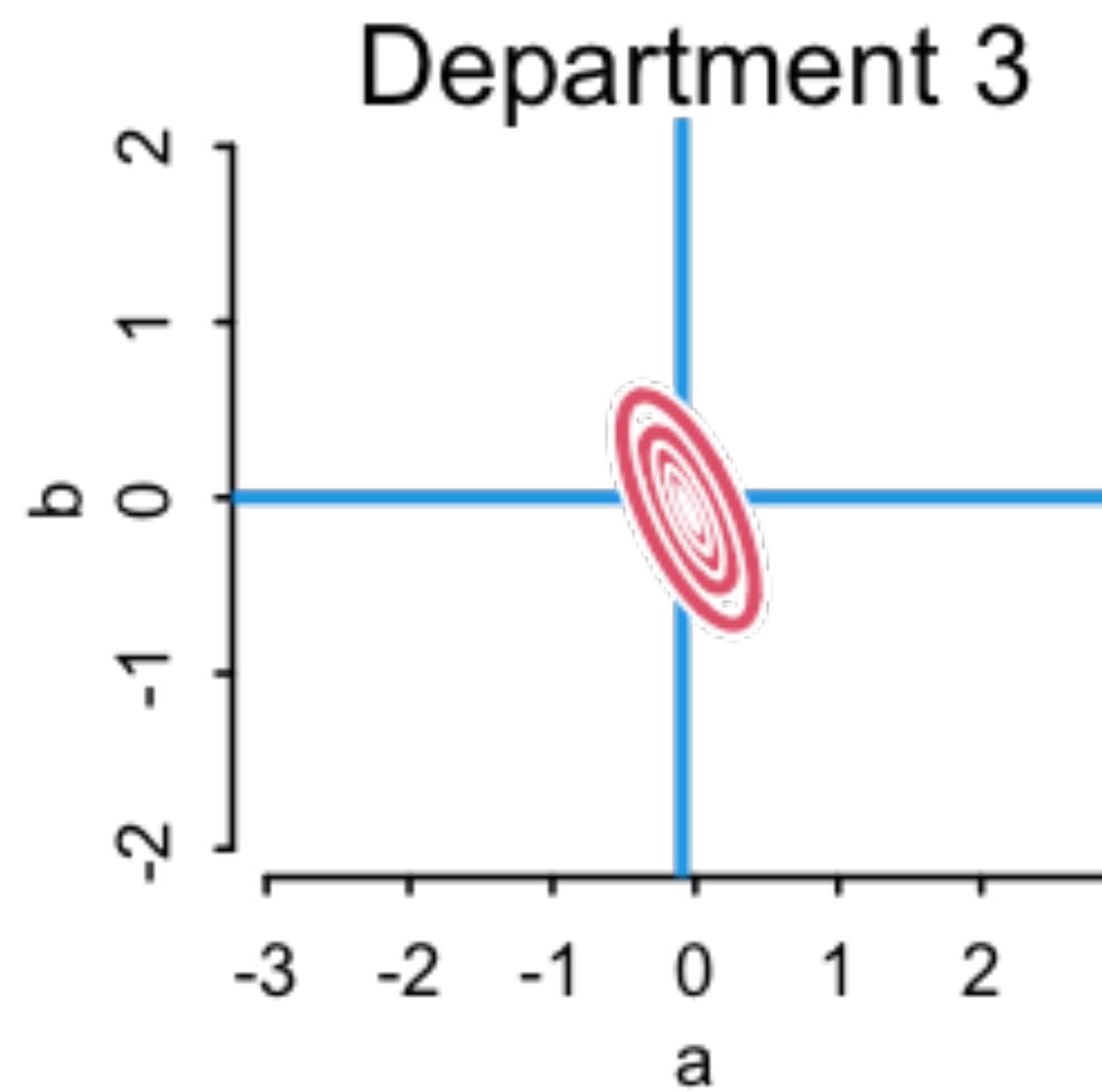
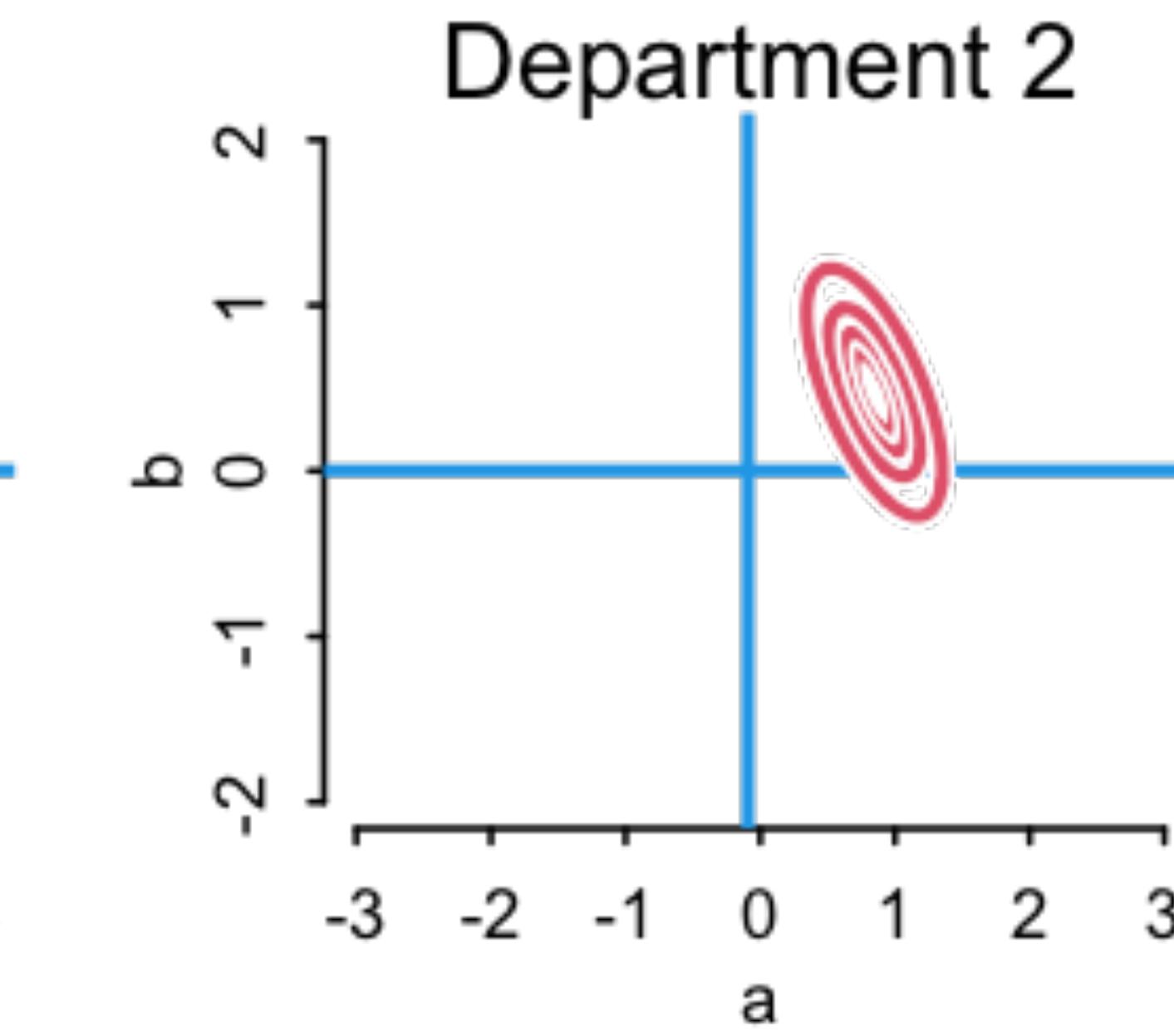
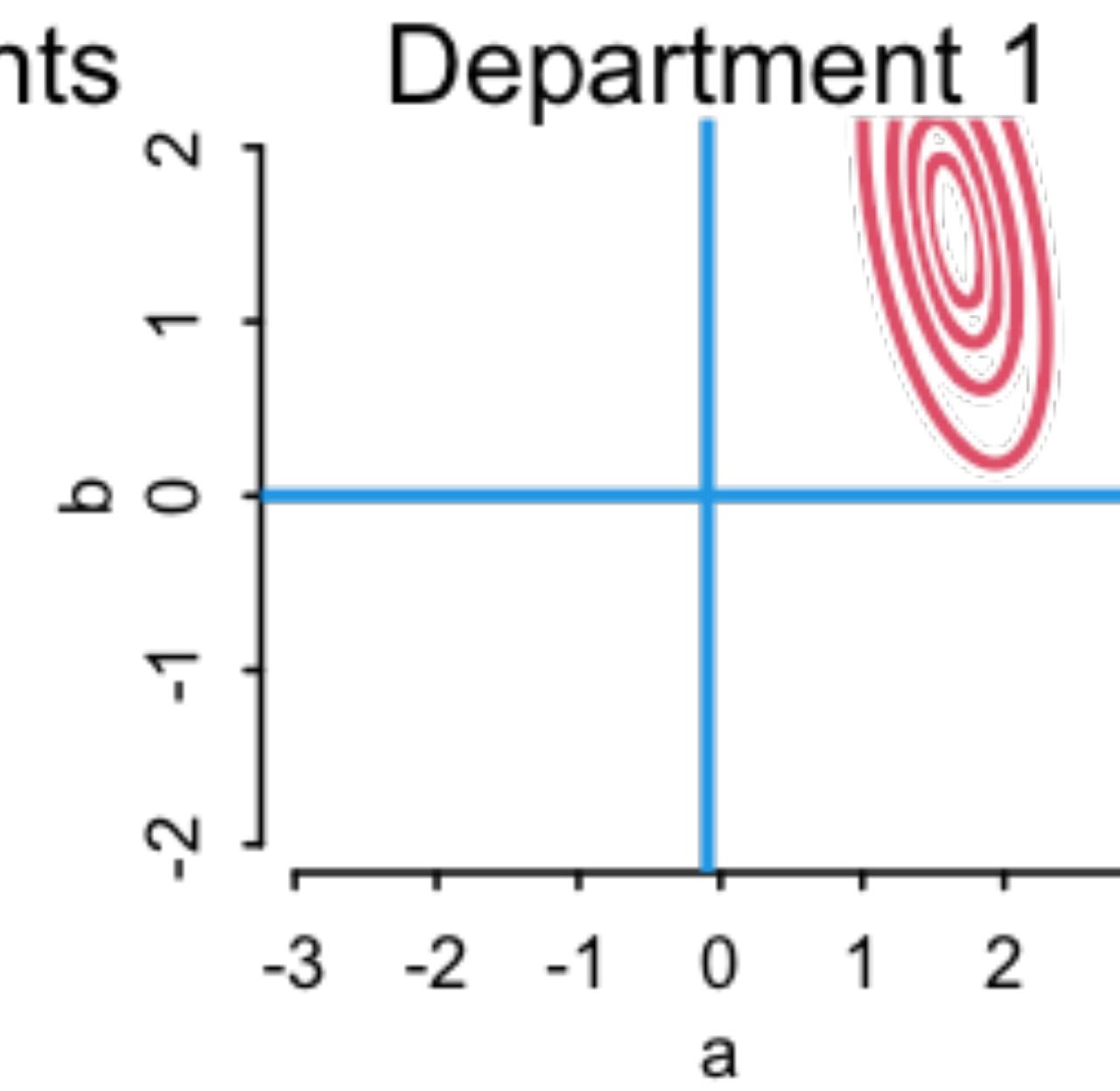
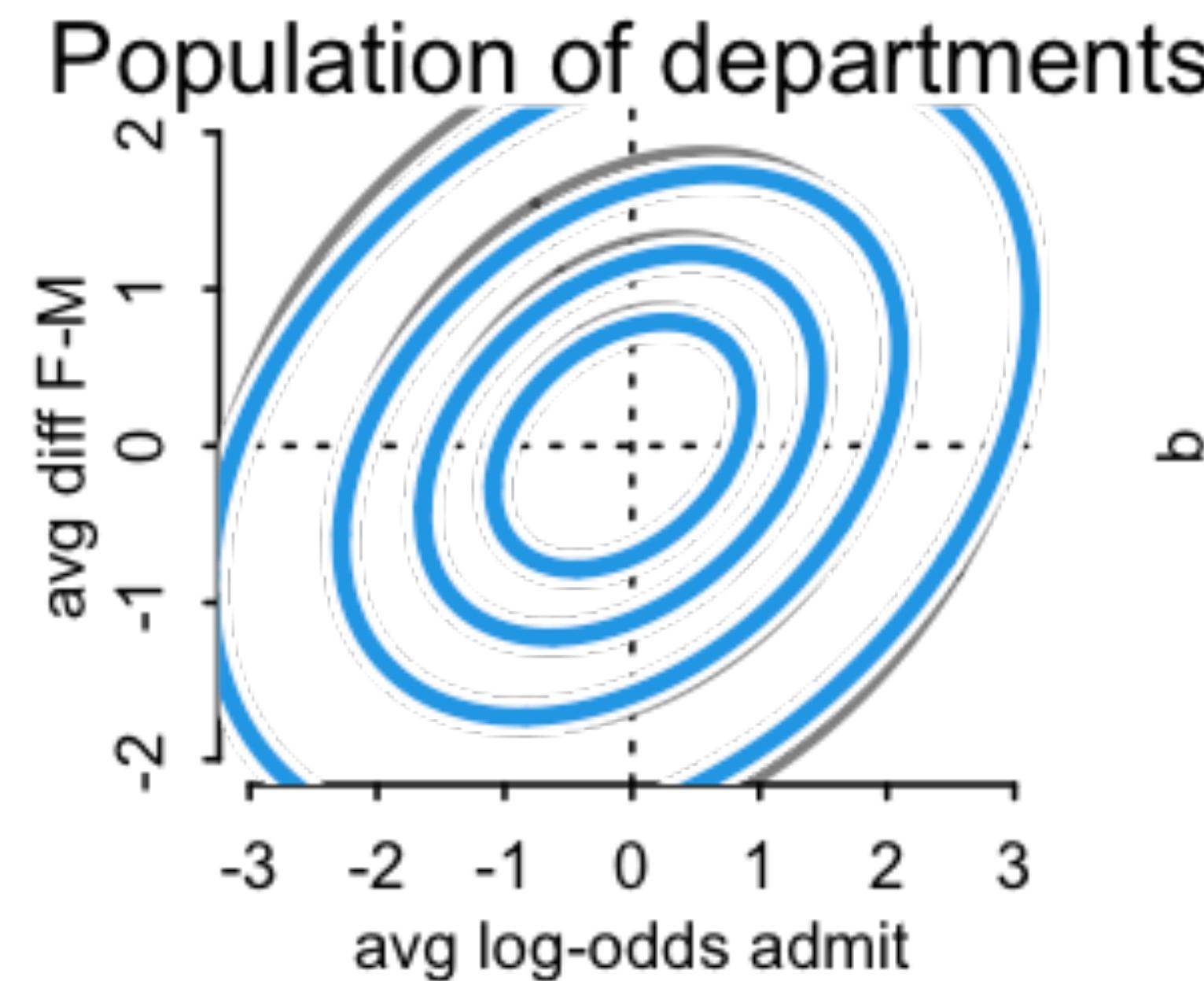
Department 5











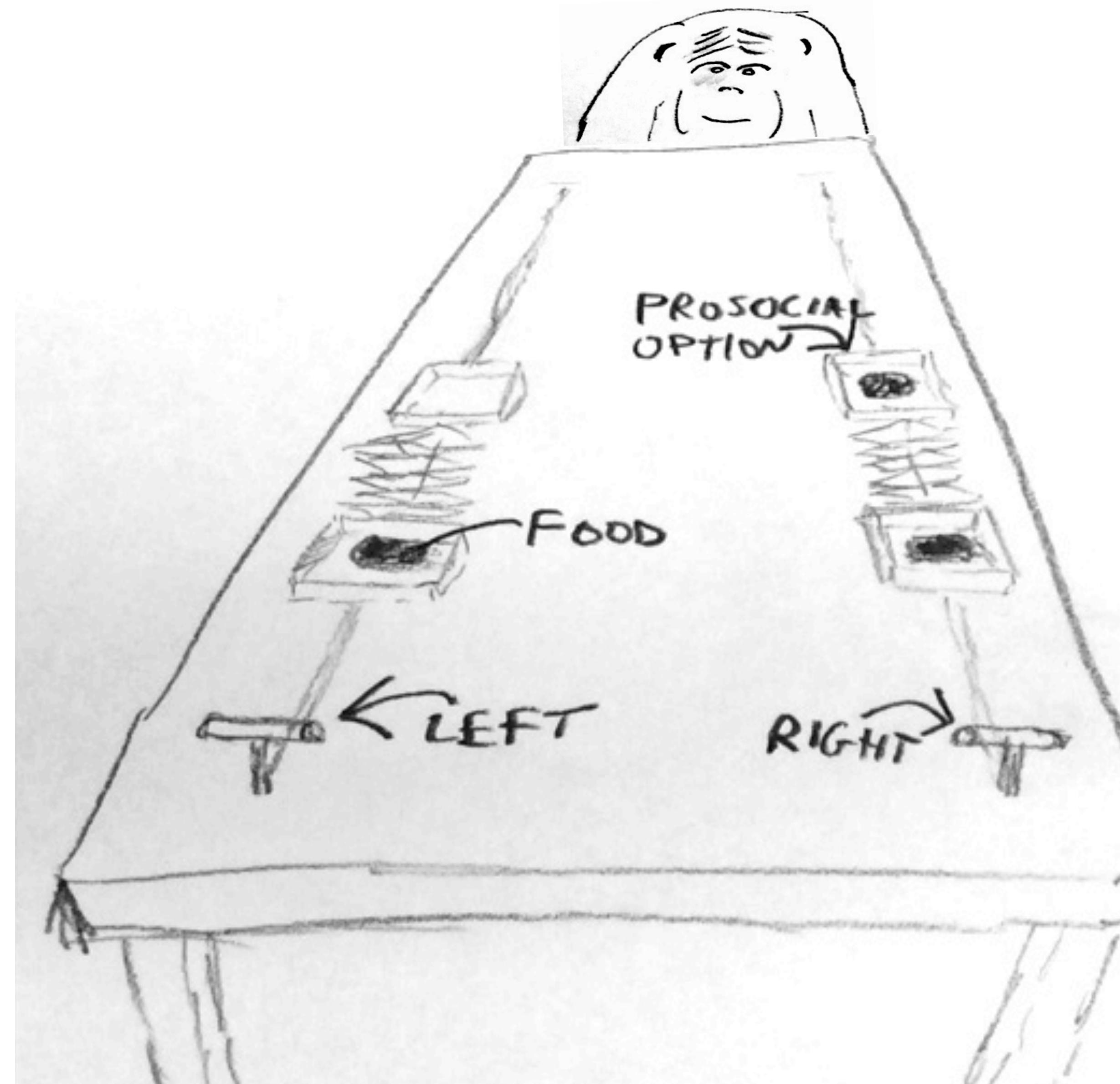
Prosocial chimpanzees

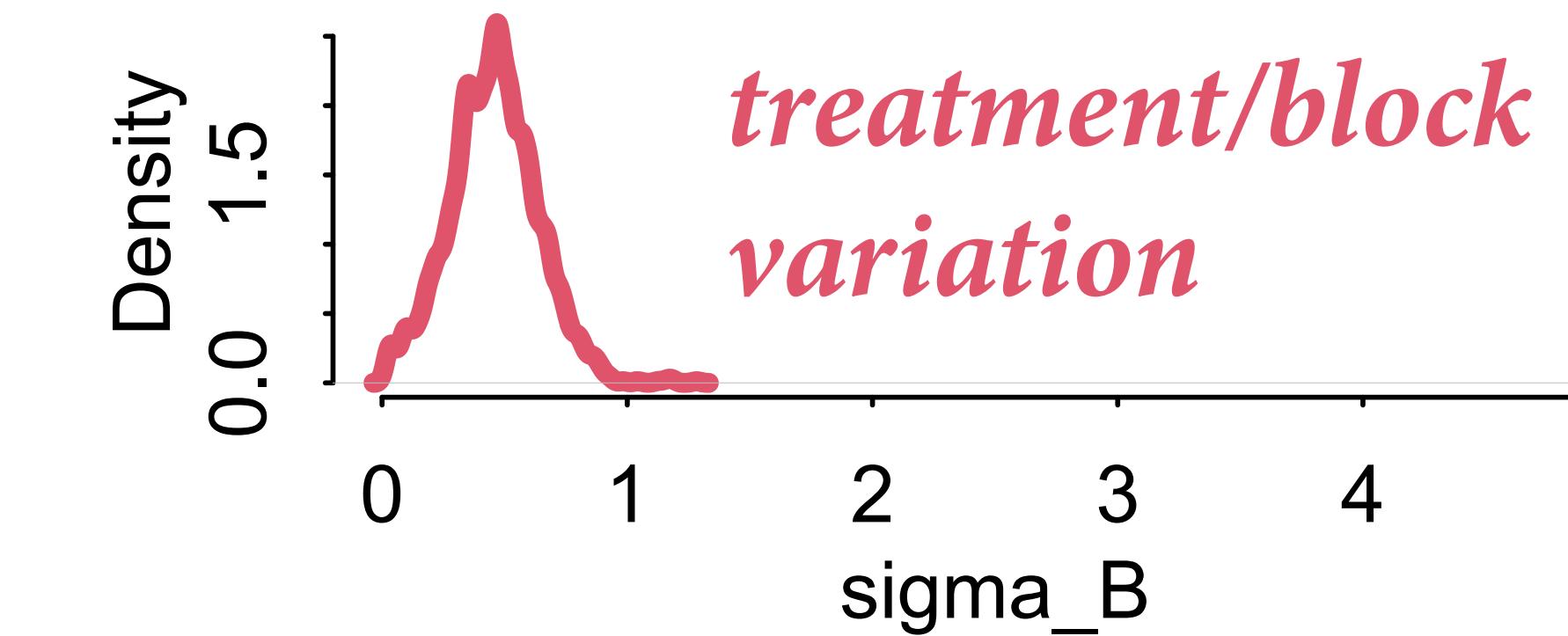
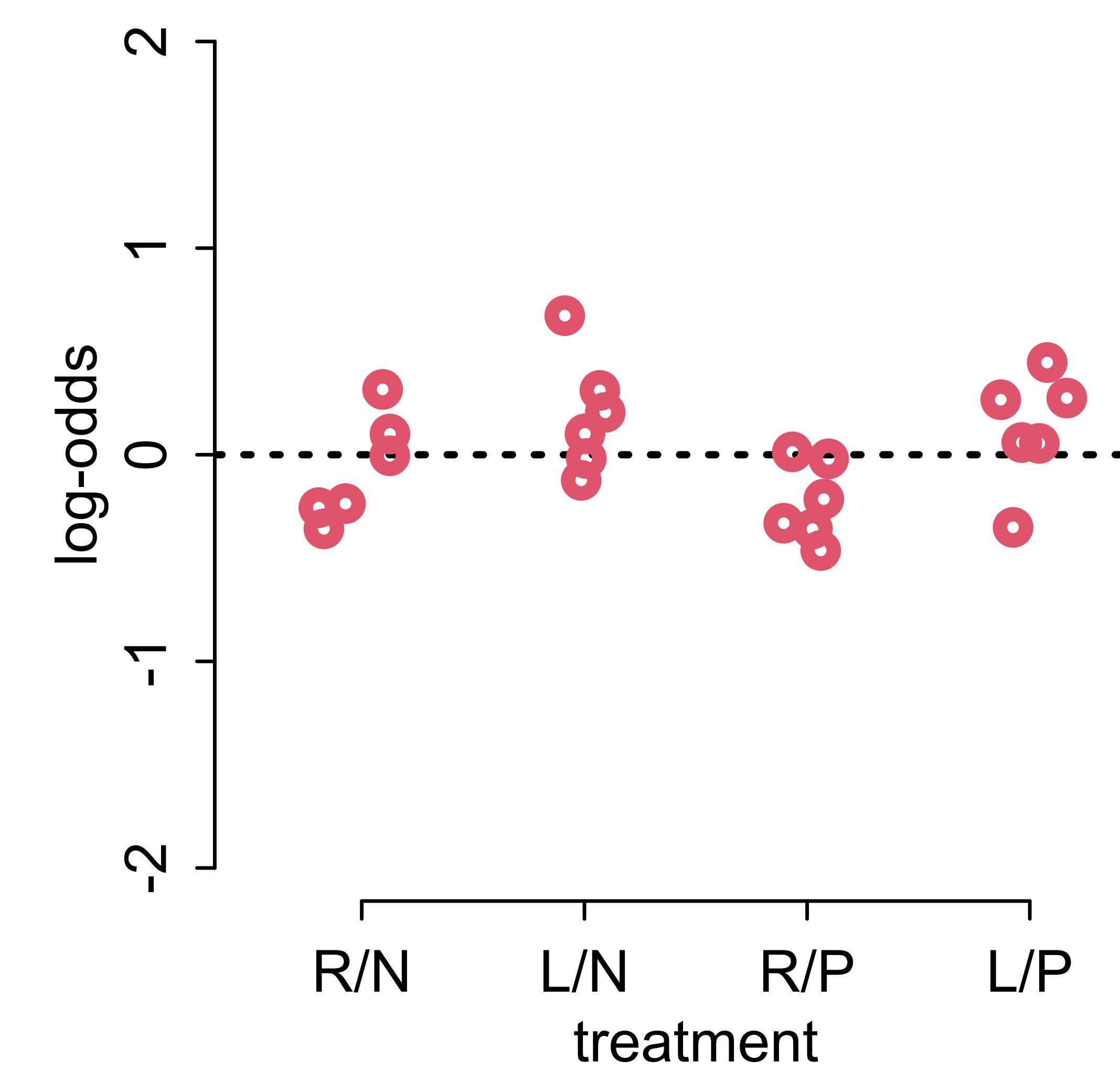
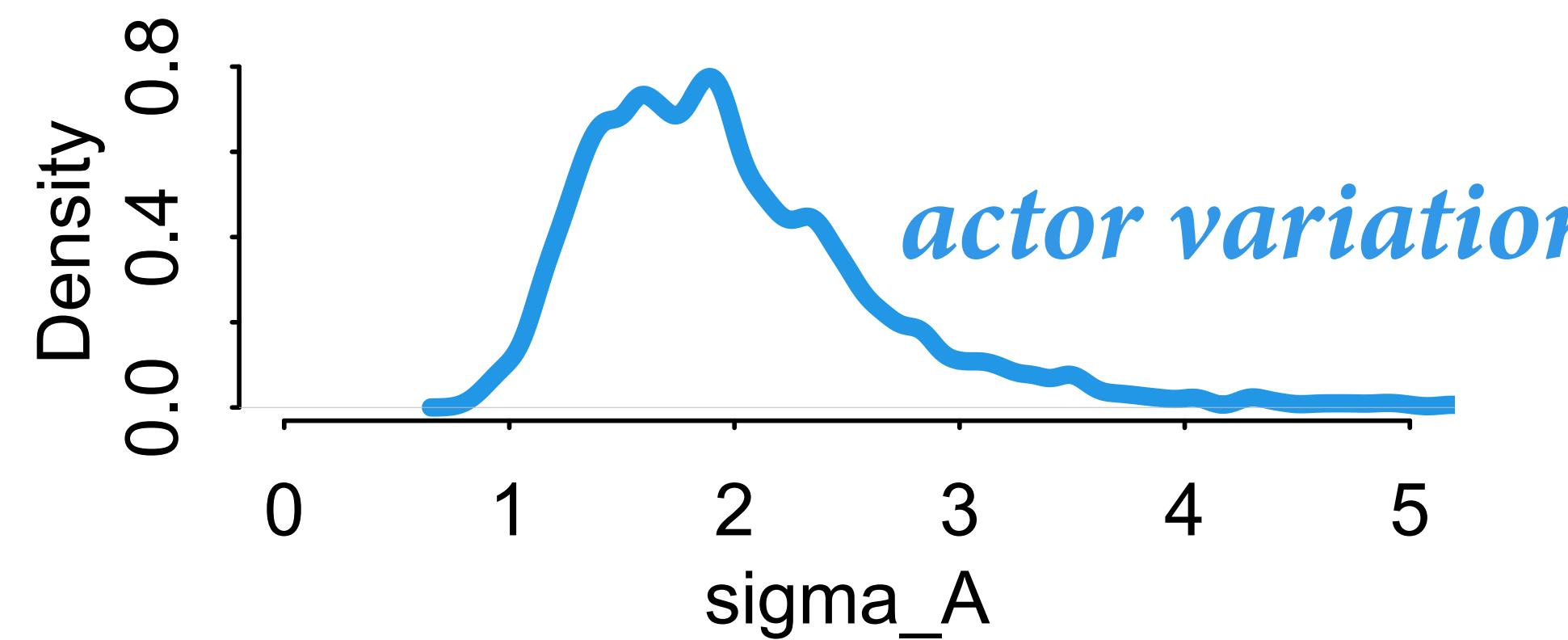
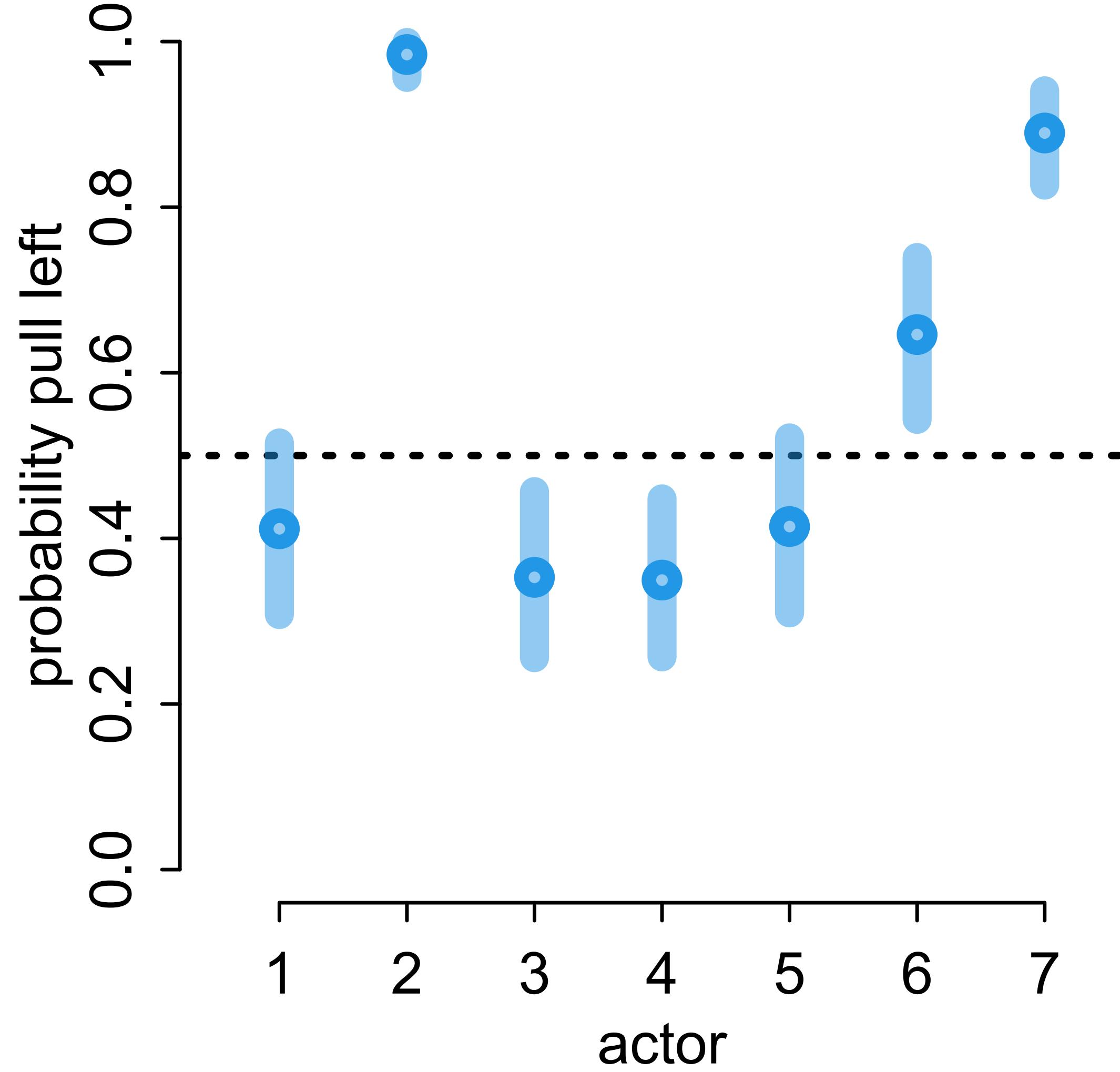
data(chimpanzees)

504 trials, 7 actors, 6 blocks

4 treatments:

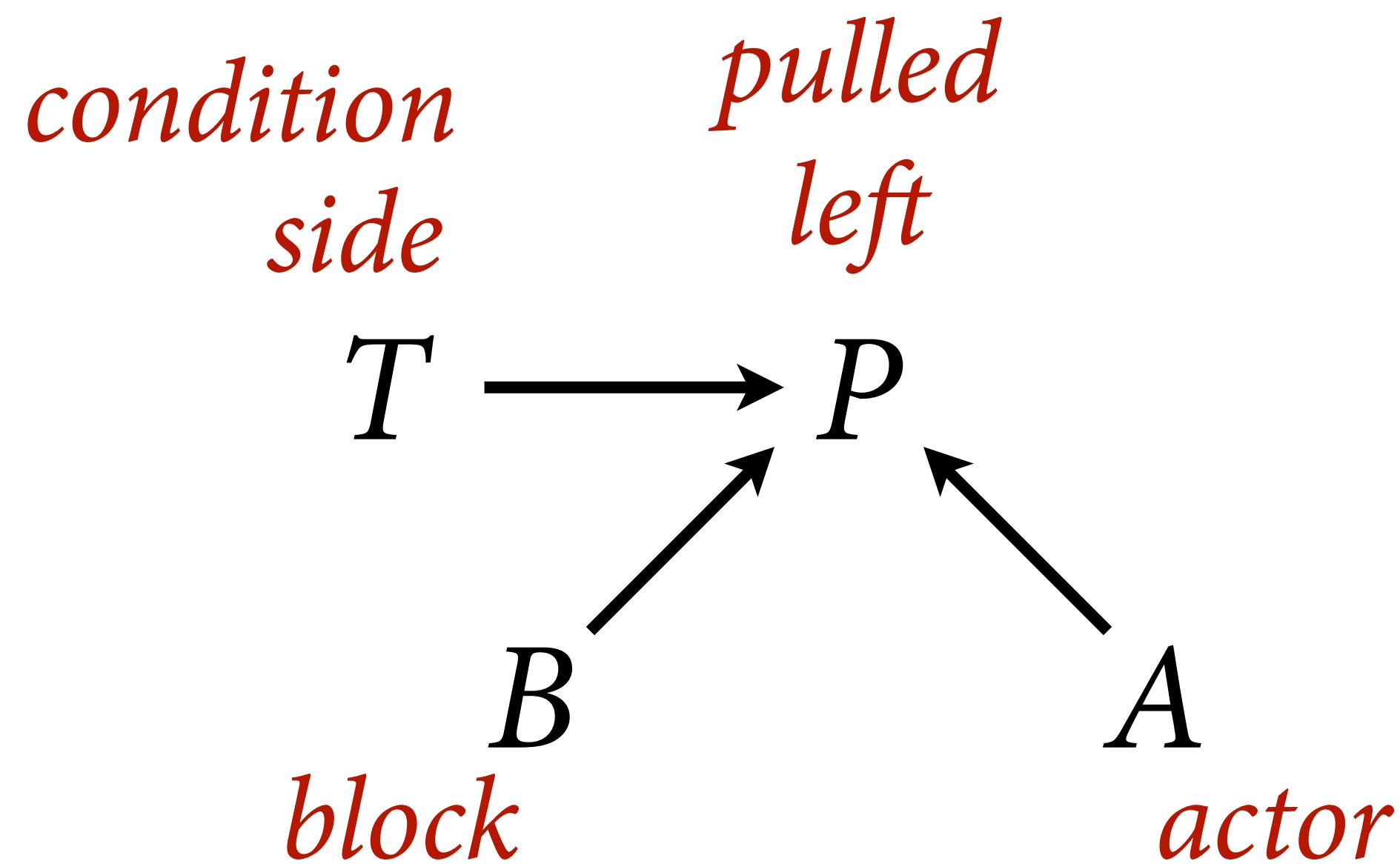
- (1) right, no partner
- (2) left, no partner
- (3) right, partner
- (4) left, partner





$$P_i \sim \text{Bernoulli}(p_i)$$

$$\text{logit}(p_i) = \bar{\alpha}_{A[i]} + \alpha_{A[i], T[i]} + \bar{\beta}_{B[i]} + \beta_{B[i], T[i]} \quad \text{mean} + \text{Actor-treatment} + \text{Block-treatment}$$



$$P_i \sim \text{Bernoulli}(p_i)$$

$$\text{logit}(p_i) = \bar{\alpha}_{A[i]} + \alpha_{A[i], T[i]} + \bar{\beta}_{B[i]} + \beta_{B[i], T[i]}$$

*mean for
each actor* *actor offset
for each
treatment*

*mean for
each block* *block offset
for each
treatment*

$$P_i \sim \text{Bernoulli}(p_i)$$

$$\text{logit}(p_i) = \bar{\alpha}_{A[i]} + \alpha_{A[i], T[i]} + \bar{\beta}_{B[i]} + \beta_{B[i], T[i]}$$

mean + Actor-treatment + Block-treatment

$$\begin{aligned} \alpha_j &\sim \text{MVNormal}([0, 0, 0, 0], \mathbf{R}_A, \mathbf{S}_A) \\ \text{for } j &\in 1..7 \end{aligned}$$

*prior for covarying actor-treatment effects
a vector of 4 parameters for each actor j*

$$P_i \sim \text{Bernoulli}(p_i)$$

$$\text{logit}(p_i) = \bar{\alpha}_{A[i]} + \alpha_{A[i],T[i]} + \bar{\beta}_{B[i]} + \beta_{B[i],T[i]}$$

mean + Actor-treatment + Block-treatment

$$\begin{aligned} \alpha_j &\sim \text{MVNormal}([0,0,0,0], \mathbf{R}_A, \mathbf{S}_A) \\ \text{for } j &\in 1..7 \end{aligned}$$

*prior for covarying actor-treatment effects
a vector of 4 parameters for each actor j*

$$\begin{aligned} \beta_k &\sim \text{MVNormal}([0,0,0,0], \mathbf{R}_B, \mathbf{S}_B) \\ \text{for } k &\in 1..6 \end{aligned}$$

*prior for covarying block-treatment effects
a vector of 4 parameters for each block k*

$$P_i \sim \text{Bernoulli}(p_i)$$

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$$\begin{aligned} \alpha_j &\sim \text{MVNormal}([0,0,0,0], \mathbf{R}_A, \mathbf{S}_A) \\ \text{for } j &\in 1..7 \end{aligned}$$

$$\begin{aligned} \beta_k &\sim \text{MVNormal}([0,0,0,0], \mathbf{R}_B, \mathbf{S}_B) \\ \text{for } k &\in 1..6 \end{aligned}$$

$$\begin{aligned} \bar{\alpha}_j &\sim \text{Normal}(0, \tau_A) \\ \bar{\beta}_k &\sim \text{Normal}(0, \tau_B) \end{aligned}$$

$$\begin{aligned} S_{A,j}, S_{B,j}, \tau_A, \tau_B &\sim \text{Exponential}(1) \\ \text{for } j &\in 1..4 \end{aligned}$$

$$\mathbf{R}_A, \mathbf{R}_B \sim \text{LKJcorr}(4)$$

mean + Actor-treatment + Block-treatment

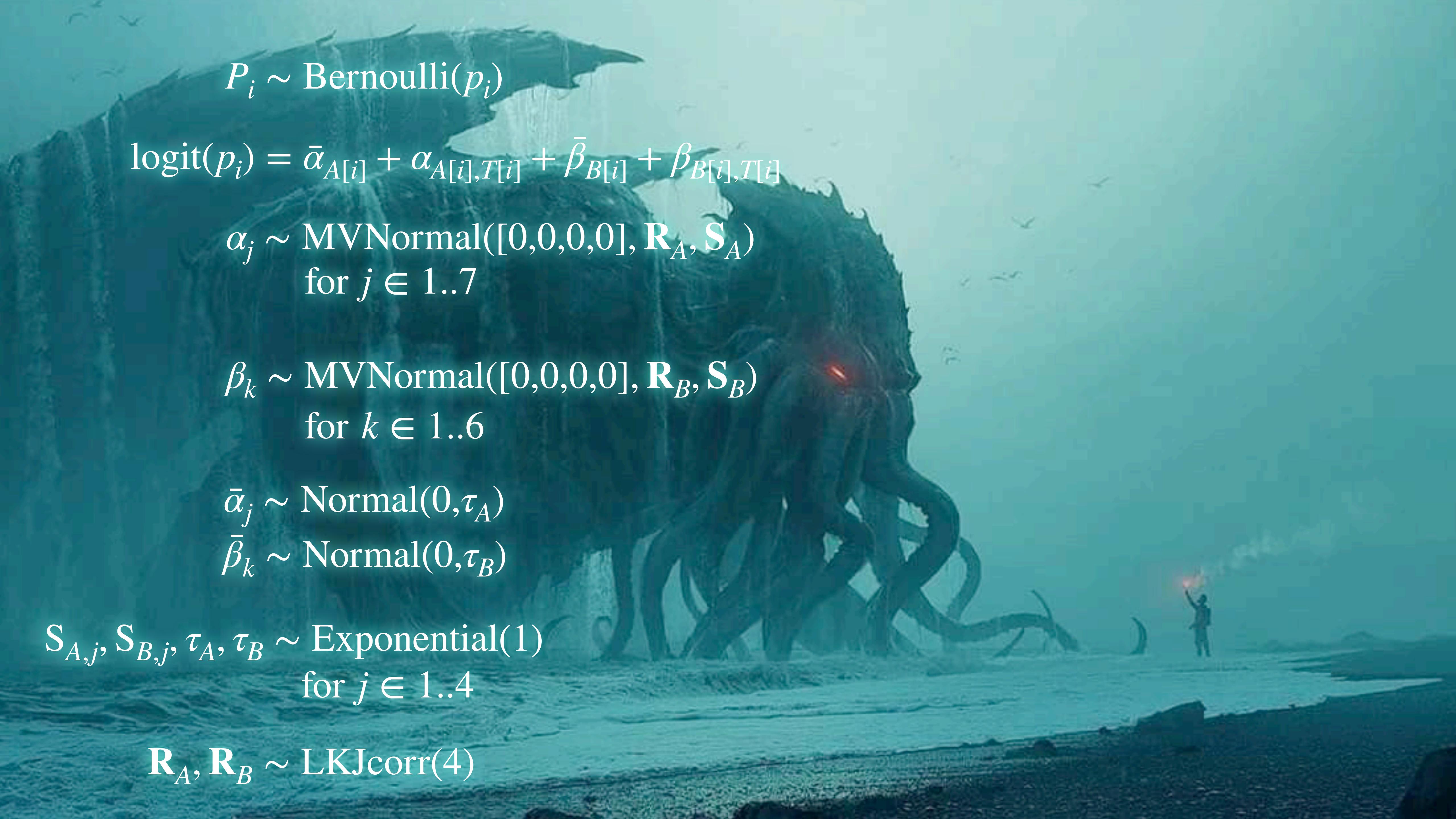
*prior for covarying actor-treatment effects
a vector of 4 parameters for each actor j*

*prior for covarying block-treatment effects
a vector of 4 parameters for each block k*

priors for actor and treatment means

*each standard deviation gets same prior
one standard deviation for each treatment*

correlation matrix prior


$$P_i \sim \text{Bernoulli}(p_i)$$

$$\text{logit}(p_i) = \bar{\alpha}_{A[i]} + \alpha_{A[i],T[i]} + \bar{\beta}_{B[i]} + \beta_{B[i],T[i]}$$

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```

data(chimpanzees)
d <- chimpanzees
dat <- list(
  P = d$pulled_left,
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  B = as.integer(d$block),
  T = 1L + d$prosoc_left + 2L*d$condition)

m14.2 <- ulam(
alist(
  P ~ bernoulli(p),
  logit(p) <- abar[A] + a[A,T] + bbar[B] + b[B,T] ,
  # adaptive priors
  vector[4]:a[A] ~ multi_normal(0,Rho_A,sigma_A),
  vector[4]:b[B] ~ multi_normal(0,Rho_B,sigma_B),
  abar[A] ~ normal(0,tau_A),
  bbar[B] ~ normal(0,tau_B),
  # fixed priors
  c(tau_A,tau_B) ~ exponential(1),
  sigma_A ~ exponential(1),
  Rho_A ~ dlkjcorr(4),
  sigma_B ~ exponential(1),
  Rho_B ~ dlkjcorr(4)
) , data=dat , chains=4 , cores=4 )

```

$$P_i \sim \text{Bernoulli}(p_i)$$

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    c(tau_A,tau_B) ~ exponential(1),
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$$\mathbf{R}_A, \mathbf{R}_B \sim \text{LKJcorr}(4)$$

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  Rho_A ~ dlkjcorr(4),
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```

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$$\mathbf{S}_{A,j}, \mathbf{S}_{B,j}, \tau_A, \tau_B \sim \text{Exponential}(1)$$

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alist(
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  logit(p) <- abar[A] + a[A,T] + bbar[B] + b[B,T] ,
  # adaptive priors
  vector[4]:a[A] ~ multi_normal(0,Rho_A,sigma_A),
  vector[4]:b[B] ~ multi_normal(0,Rho_B,sigma_B),
  abar[A] ~ normal(0,tau_A),
  bbar[B] ~ normal(0,tau_B),
  # fixed priors
  c(tau_A,tau_B) ~ exponential(1),
  sigma_A ~ exponential(1),
  Rho_A ~ dlkjcorr(4),
  sigma_B ~ exponential(1),
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```

$$P_i \sim \text{Bernoulli}(p_i)$$

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$$\alpha_j \sim \text{MVNormal}(0, \mathbf{R}_A, \mathbf{S}_A)$$

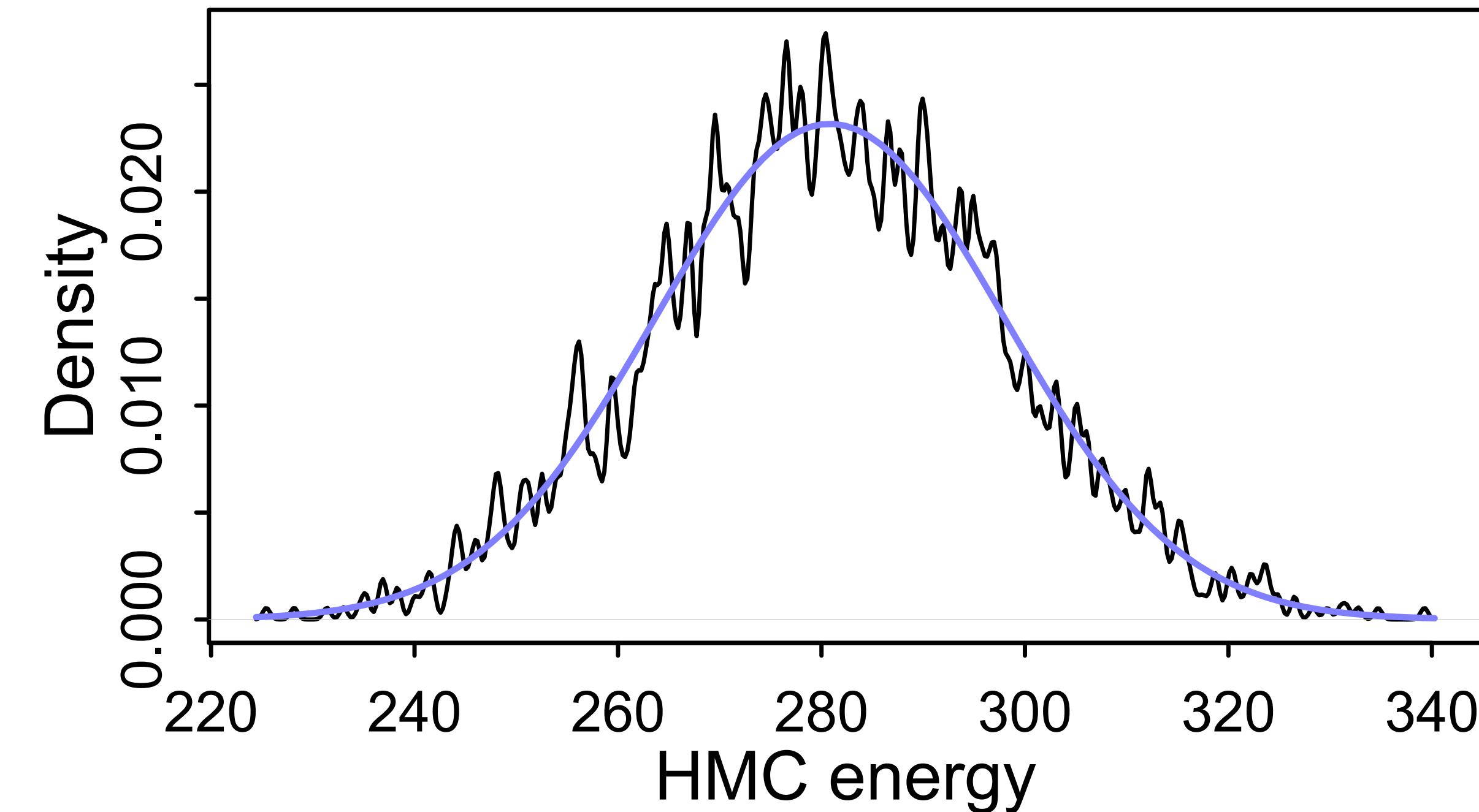
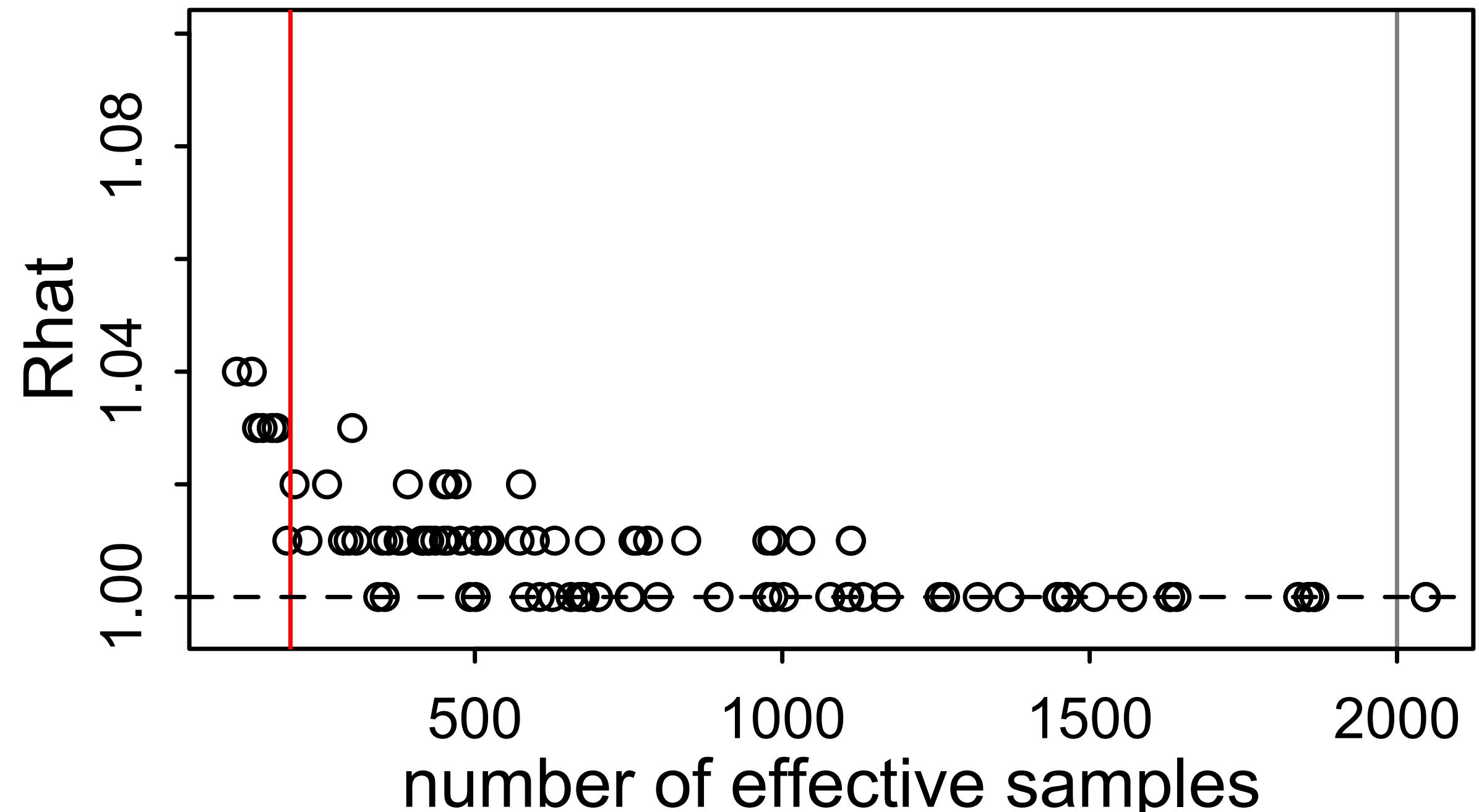
$$\beta_k \sim \text{MVNormal}(0, \mathbf{R}_B, \mathbf{S}_B)$$

$$\bar{\alpha}_j \sim \text{Normal}(0, \tau_A)$$

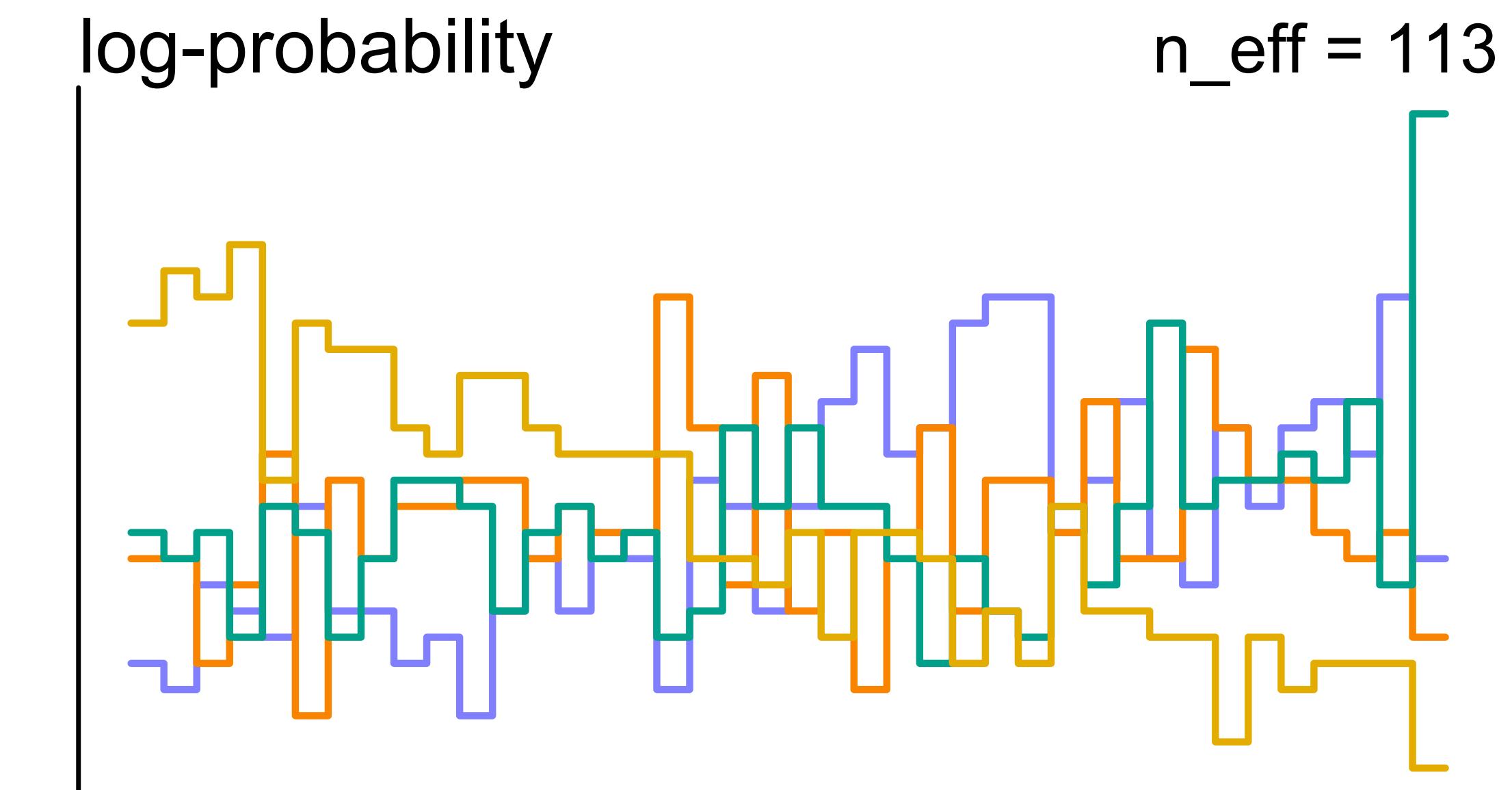
$$\bar{\beta}_k \sim \text{Normal}(0, \tau_B)$$

$$\mathbf{S}_{A,j}, \mathbf{S}_{B,j}, \tau_A, \tau_B \sim \text{Exponential}(1)$$

$$\mathbf{R}_A, \mathbf{R}_B \sim \text{LKJcorr}(4)$$



37
Divergent transitions
Check yourself before
you wreck yourself

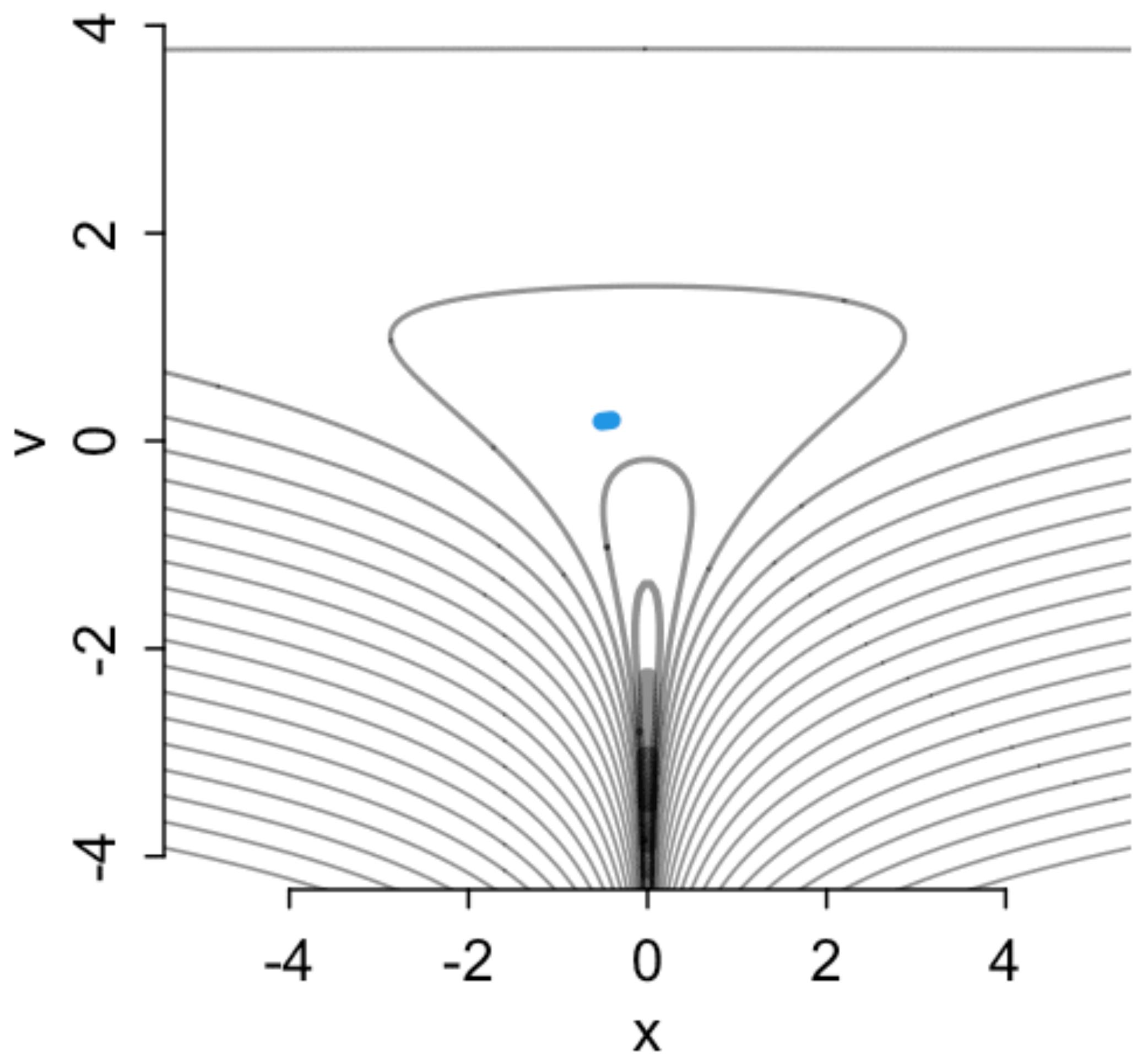


PAUSE

“Centered”

$$\nu \sim \text{Normal}(0, 3)$$

$$x \sim \text{Normal}(0, \exp(\nu))$$

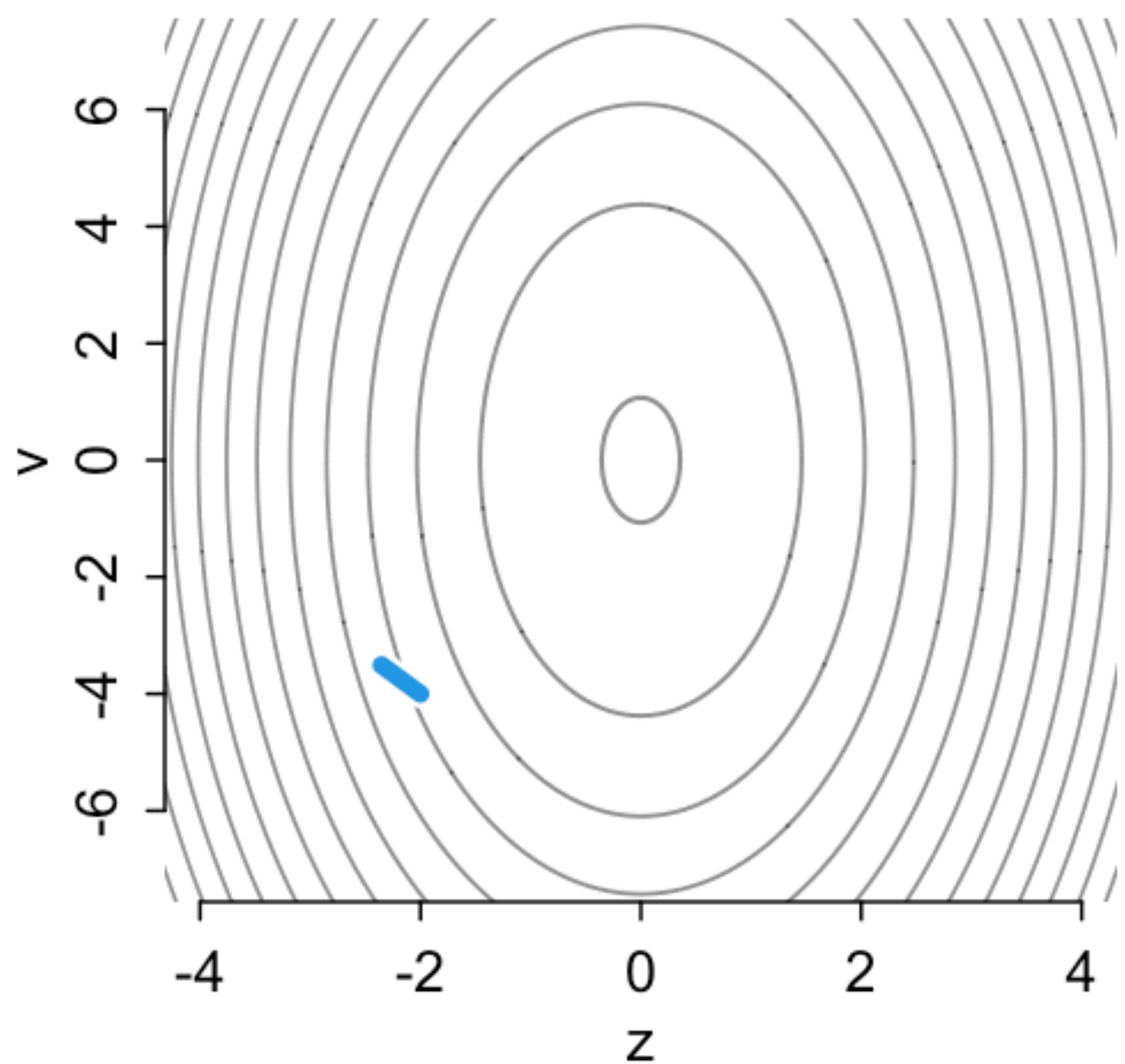


“Non-centered”

$$\nu \sim \text{Normal}(0, 3)$$

$$z \sim \text{Normal}(0, 1)$$

$$x = z \exp(\nu)$$



Centered

$$P_i \sim \text{Bernoulli}(p_i)$$

$$\text{logit}(p_i) = \beta_{T[i], B[i]} + \alpha_{A[i]}$$

$$\alpha_j \sim \text{Normal}(\bar{\alpha}, \sigma_A)$$

$$\beta_{j,k} \sim \text{Normal}(0, \sigma_B)$$

$$\sigma_A, \sigma_B \sim \text{Exponential}(1)$$

$$\bar{\alpha} \sim \text{Normal}(0, 1.5)$$

Centered

$$P_i \sim \text{Bernoulli}(p_i)$$

$$\text{logit}(p_i) = \beta_{T[i],B[i]} + \alpha_{A[i]}$$

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$$\bar{\alpha} \sim \text{Normal}(0, 1.5)$$

Non-centered

$$P_i \sim \text{Bernoulli}(p_i)$$

$$\text{logit}(p_i) = \bar{\alpha} + (z_{\alpha,A[i]})\sigma_A + (z_{\beta,T[i],B[i]})\sigma_B$$

$$z_{\alpha,j} \sim \text{Normal}(0, 1)$$

$$z_{\beta,j} \sim \text{Normal}(0, 1)$$

$$\sigma_A, \sigma_B \sim \text{Exponential}(1)$$

$$\bar{\alpha} \sim \text{Normal}(0, 1.5)$$

Centered

$$P_i \sim \text{Bernoulli}(p_i)$$

$$\text{logit}(p_i) = \beta_{T[i],B[i]} + \alpha_{A[i]}$$

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Non-centered

$$P_i \sim \text{Bernoulli}(p_i)$$

$$\text{logit}(p_i) = \bar{\alpha} + \boxed{(z_{\alpha,A[i]})\sigma_A + (z_{\beta,T[i],B[i]})\sigma_B}$$

$$z_{\alpha,j} \sim \text{Normal}(0,1)$$

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Centered

$$P_i \sim \text{Bernoulli}(p_i)$$

$$\text{logit}(p_i) = \bar{\alpha}_{A[i]} + \alpha_{A[i], T[i]} + \bar{\beta}_{B[i]} + \beta_{B[i], T[i]}$$

$$\alpha_j \sim \text{MVNormal}([0,0,0,0], \mathbf{R}_A, \mathbf{S}_A)$$

$$\beta_k \sim \text{MVNormal}([0,0,0,0], \mathbf{R}_B, \mathbf{S}_B)$$

$$\bar{\alpha}_j \sim \text{Normal}(0, \tau_A)$$

$$\bar{\beta}_k \sim \text{Normal}(0, \tau_B)$$

$$\mathbf{S}_{A,j}, \mathbf{S}_{B,j}, \tau_A, \tau_B \sim \text{Exponential}(1)$$

$$\mathbf{R}_A, \mathbf{R}_B \sim \text{LKJcorr}(4)$$

How can we factor R and S out of the priors?



$$P_i \sim \text{Bernoulli}(p_i)$$

$$\text{logit}(p_i) = \bar{\alpha}_{A[i]} + \alpha_{A[i], T[i]} + \bar{\beta}_{B[i]} + \beta_{B[i], T[i]}$$

$$\alpha = \left(\begin{bmatrix} S_{A,1} & 0 & 0 & 0 \\ 0 & S_{A,2} & 0 & 0 \\ 0 & 0 & S_{A,3} & 0 \\ 0 & 0 & 0 & S_{A,4} \end{bmatrix} \right)^T$$

a 7-by-4 matrix

diagonal matrix of standard deviations

Cholesky factor of correlation matrix across treatments

transpose!
flips rows and columns

matrix of treatment-actor z-scores

$$P_i \sim \text{Bernoulli}(p_i)$$

$$\text{logit}(p_i) = \bar{\alpha}_{A[i]} + \alpha_{A[i], T[i]} + \bar{\beta}_{B[i]} + \beta_{B[i], T[i]}$$

$$\alpha = \left(\begin{bmatrix} S_{A,1} & 0 & 0 & 0 \\ 0 & S_{A,2} & 0 & 0 \\ 0 & 0 & S_{A,3} & 0 \\ 0 & 0 & 0 & S_{A,4} \end{bmatrix} \mathbf{L}_A \mathbf{Z}_{T,A} \right)^T$$

$$\alpha = (\text{diag}(\mathbf{S}_A) \mathbf{L}_A \mathbf{Z}_{T,A})^T$$

*Cholesky factor of
correlation matrix
across treatments*

I. — NOTICES SCIENTIFIQUES

Commandant BENOIT¹.

NOTE SUR UNE MÉTHODE DE RÉSOLUTION DES ÉQUATIONS NORMALES PROVENANT DE L'APPLICATION DE LA MÉTHODE DES MOINDRES CARRÉS A UN SYSTÈME D'ÉQUATIONS LINÉAIRES EN NOMBRE INFÉRIEUR A CELUI DES INCONNUES. — APPLICATION DE LA MÉTHODE A LA RÉSOLUTION D'UN SYSTÈME défini D'ÉQUATIONS LINÉAIRES.

(Procédé du Commandant CHOLESKY².)

Le Commandant d'Artillerie Cholesky, du Service géographique de l'Armée, tué pendant la grande guerre, a imaginé, au cours de recherches sur la compensation des réseaux géodésiques, un procédé très ingénieux de résolution des équations dites *normales*, obtenues par application de la méthode des moindres carrés à des équations linéaires en nombre inférieur à celui des inconnues. Il en a conclu une méthode générale de résolution des équations linéaires.

Nous suivrons, pour la démonstration de cette méthode, la progression même qui a servi au Commandant Cholesky pour l'imaginer.



André-Louis Cholesky (1875–1918)

I. — NOTICES SCIENTIFIQUES

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(Procédé du Commandant CHOLESKY².)

The artillery commander Cholesky, of the Geographical Service of the army, killed during the Great War, imagined, during research on the compensation of the geodesic networks, a very ingenious process of solving the equations known as normal, obtained by application of the method of least squares to linear equations in lower number than that of the unknowns.

résolution des équations linéaires.



André-Louis Cholesky (1875–1918)

ques, un procédé très ingénieux de résolution des équations dites *normales*, obtenues par application de la méthode des

```
# define 2D Gaussian with correlation 0.6
N <- 1e4
sigma1 <- 2
sigma2 <- 0.5
rho <- 0.6

# independent z-scores
z1 <- rnorm( N )
z2 <- rnorm( N )

# use Cholesky to blend in correlation
a1 <- z1 * sigma1
a2 <- ( rho*z1 + sqrt( 1-rho^2 )*z2 )*sigma2
```

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a1 <- z1 * sigma1
a2 <- ( rho*z1 + sqrt( 1-rho^2 )*z2 )*sigma2
```

```
> cor(z1,z2)
[1] -0.0005542644
> cor(a1,a2)
[1] 0.5999334
> sd(a1)
[1] 1.997036
> sd(a2)
[1] 0.4989456
```

$$\alpha = (\text{diag}(\mathbf{S}_A)\mathbf{L}_A\mathbf{Z}_{T,A})^\top$$

$$P_i \sim \text{Bernoulli}(p_i)$$

$$\text{logit}(p_i) = \bar{\alpha}_{A[i]} + \alpha_{A[i], T[i]} + \bar{\beta}_{B[i]} + \beta_{B[i], T[i]} \quad \textcolor{red}{mean + Actor-treatment + Block-treatment}$$

$$\alpha = (\text{diag}(\mathbf{S}_A)\mathbf{L}_A\mathbf{Z}_{T,A})^\top$$

compute alpha from non-centered pieces

$$\beta = (\text{diag}(\mathbf{S}_B)\mathbf{L}_B\mathbf{Z}_{T,B})^\top$$

compute beta from non-centered pieces

$$P_i \sim \text{Bernoulli}(p_i)$$

$$\text{logit}(p_i) = \bar{\alpha}_{A[i]} + \alpha_{A[i],T[i]} + \bar{\beta}_{B[i]} + \beta_{B[i],T[i]} \quad \textcolor{red}{mean + Actor-treatment + Block-treatment}$$

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$$\beta = (\text{diag}(\mathbf{S}_B)\mathbf{L}_B\mathbf{Z}_{T,B})^\top \quad \textcolor{red}{compute beta from non-centered pieces}$$

$$\mathbf{Z}_{T,A} \sim \text{Normal}(0,1) \quad \textcolor{red}{matrix of treatment-actor z-scores}$$

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$$\alpha = (\text{diag}(\mathbf{S}_A)\mathbf{L}_A\mathbf{Z}_{T,A})^\top \quad \textcolor{red}{compute alpha from non-centered pieces}$$

$$\beta = (\text{diag}(\mathbf{S}_B)\mathbf{L}_B\mathbf{Z}_{T,B})^\top \quad \textcolor{red}{compute beta from non-centered pieces}$$

$$\mathbf{Z}_{T,A} \sim \text{Normal}(0,1) \quad \textcolor{red}{matrix of treatment-actor z-scores}$$

$$\mathbf{Z}_{T,B} \sim \text{Normal}(0,1) \quad \textcolor{red}{matrix of treatment-block z-scores}$$

$$z_{\bar{A},j}, z_{\bar{B},k} \sim \text{Normal}(0,1) \quad \textcolor{red}{mean actor and block z-scores}$$

$$\bar{\alpha} = z_{\bar{A}}\tau_A, \bar{\beta} = z_{\bar{B}}\tau_B \quad \textcolor{red}{compute mean effects}$$

$$P_i \sim \text{Bernoulli}(p_i)$$

$$\text{logit}(p_i) = \bar{\alpha}_{A[i]} + \alpha_{A[i],T[i]} + \bar{\beta}_{B[i]} + \beta_{B[i],T[i]} \quad \textcolor{red}{mean + Actor-treatment + Block-treatment}$$

$$\alpha = (\text{diag}(\mathbf{S}_A)\mathbf{L}_A\mathbf{Z}_{T,A})^\top \quad \textcolor{red}{compute alpha from non-centered pieces}$$

$$\beta = (\text{diag}(\mathbf{S}_B)\mathbf{L}_B\mathbf{Z}_{T,B})^\top \quad \textcolor{red}{compute beta from non-centered pieces}$$

$$\mathbf{Z}_{T,A} \sim \text{Normal}(0,1) \quad \textcolor{red}{matrix of treatment-actor z-scores}$$

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$$\mathbf{S}_{A,j}, \mathbf{S}_{B,j}, \tau_A, \tau_B \sim \text{Exponential}(1) \quad \textcolor{red}{each standard deviation gets same prior}$$

$$\mathbf{R}_A, \mathbf{R}_B \sim \text{LKJcorr}(4) \quad \textcolor{red}{correlation matrix prior}$$

```

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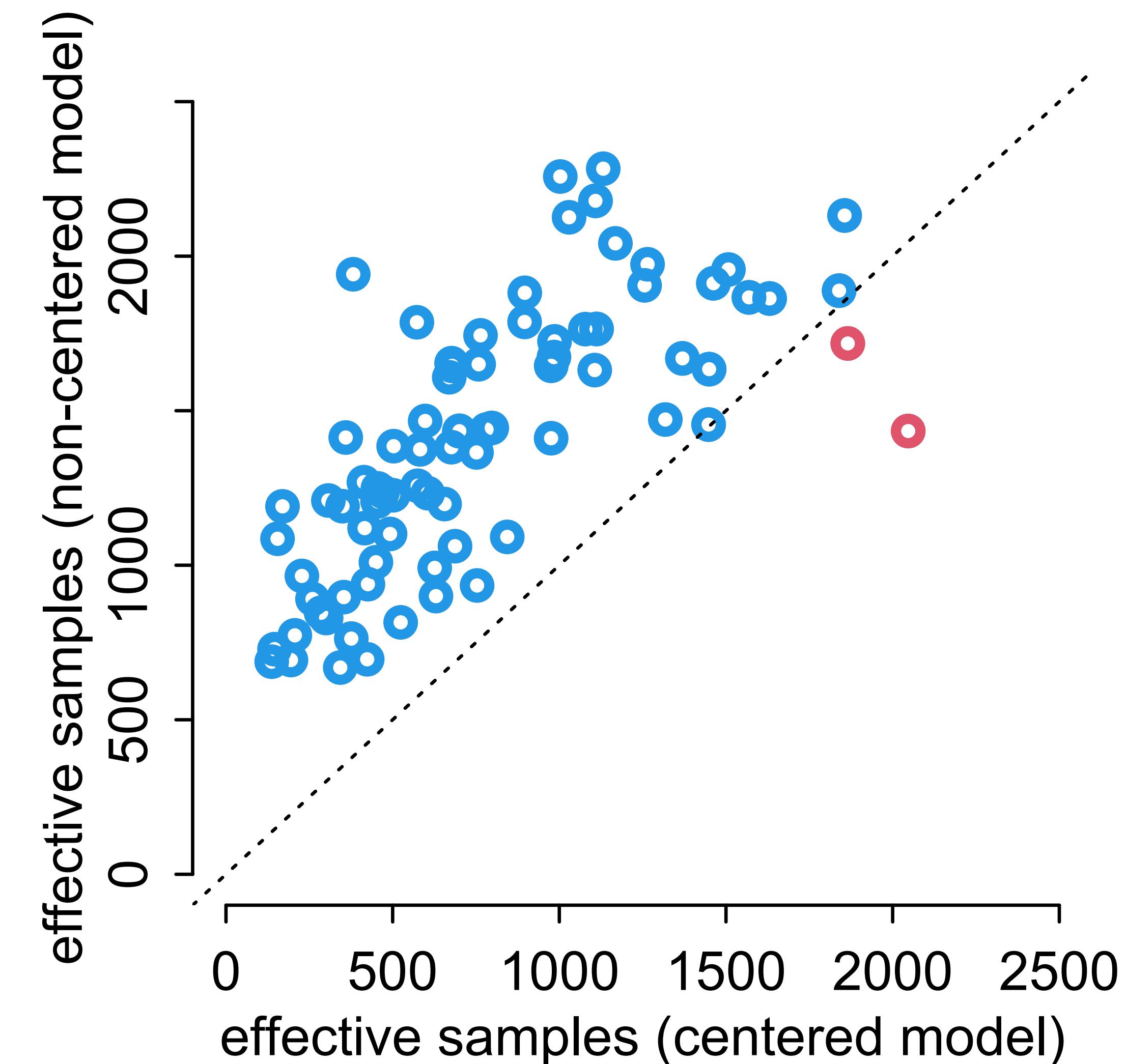
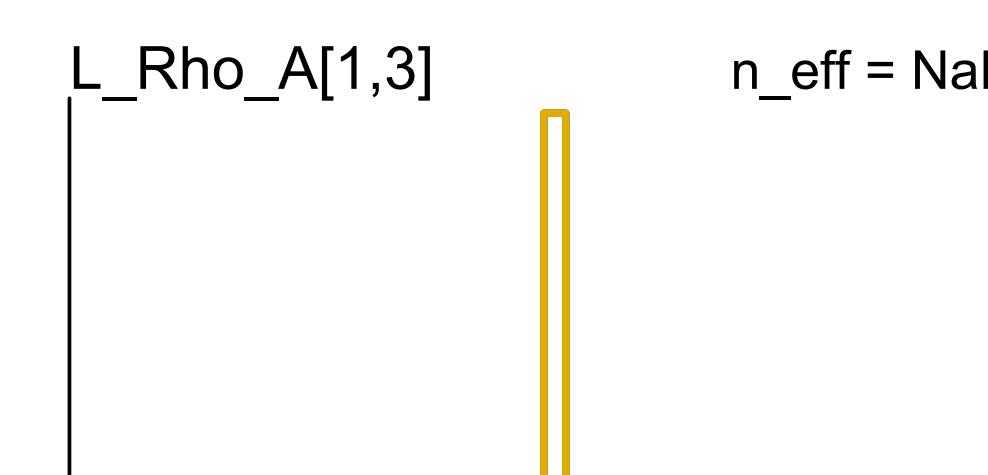
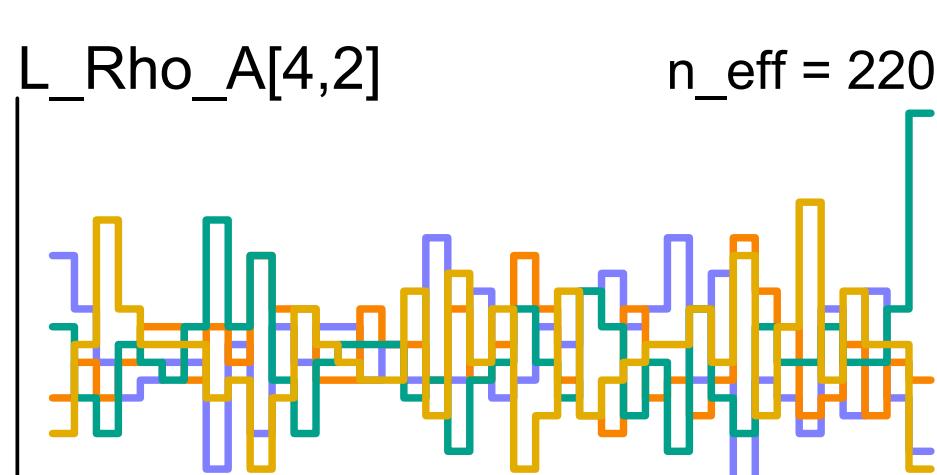
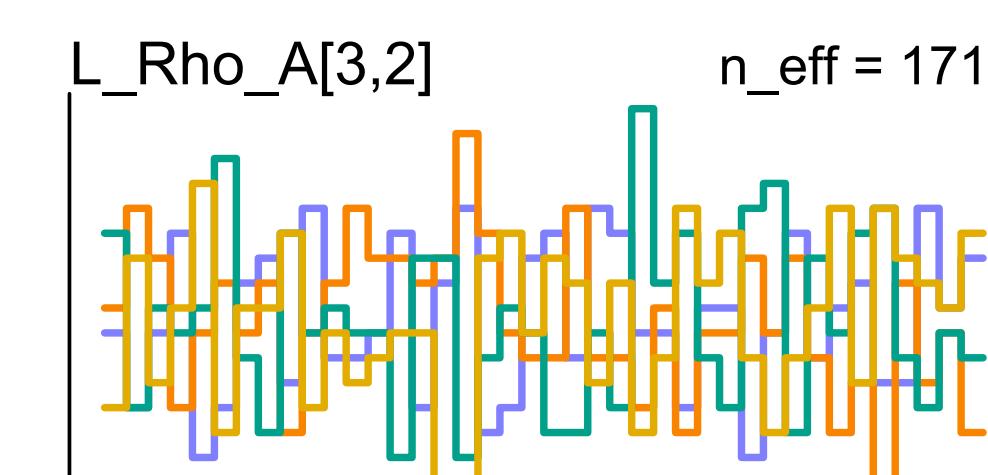
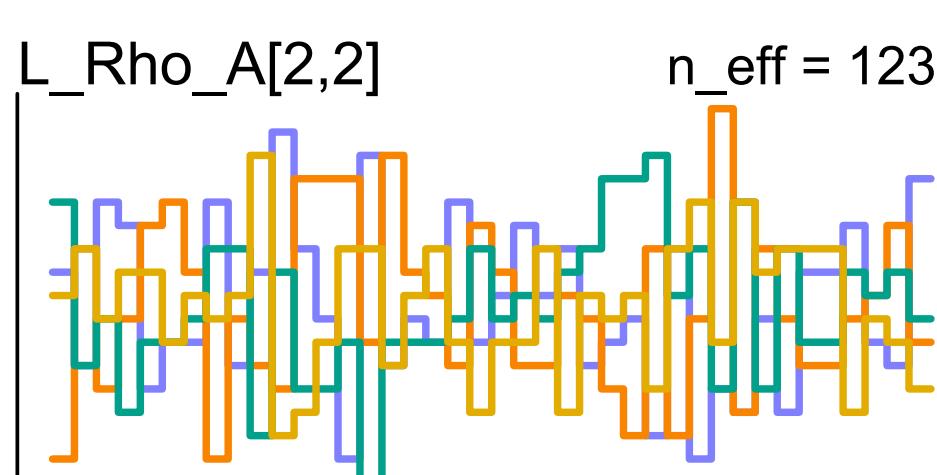
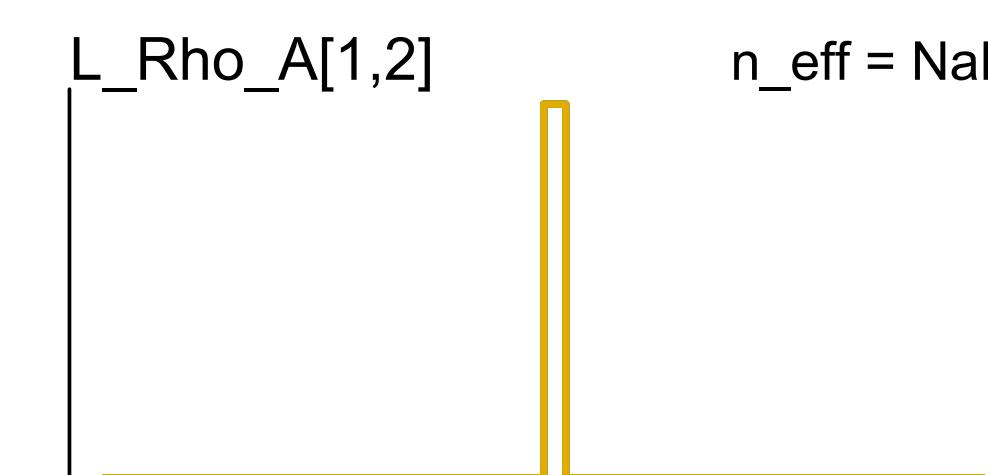
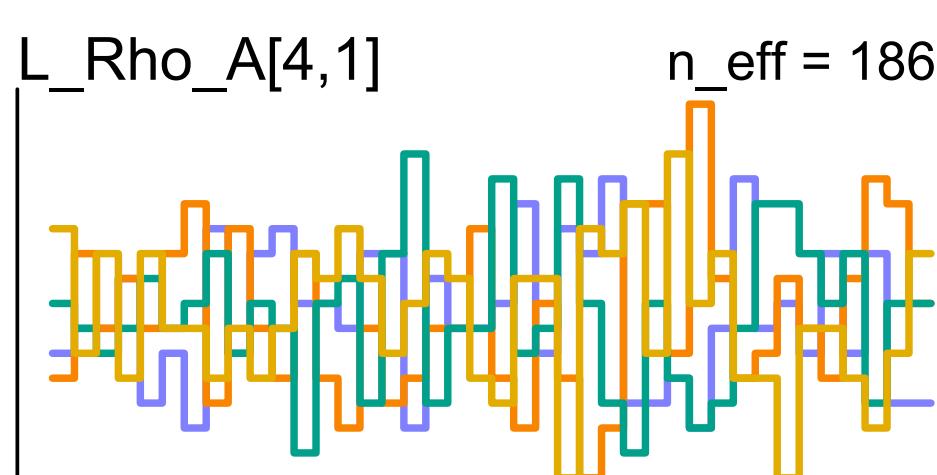
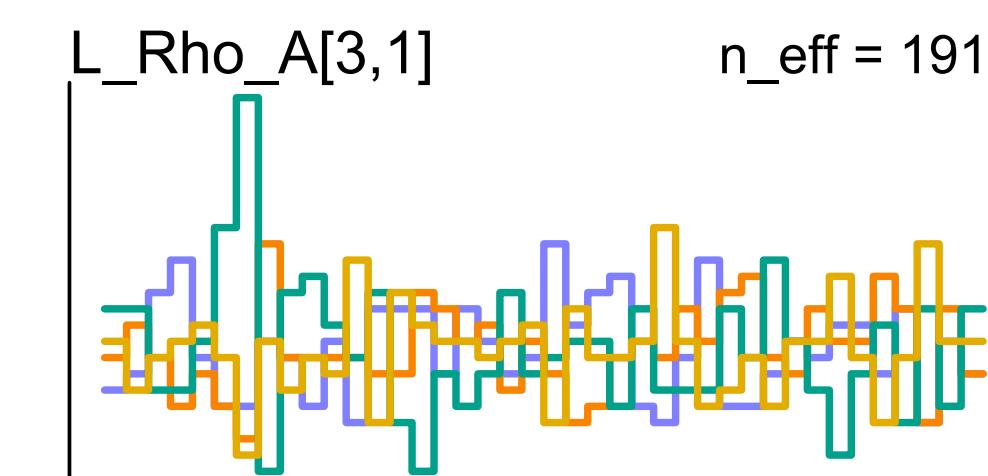
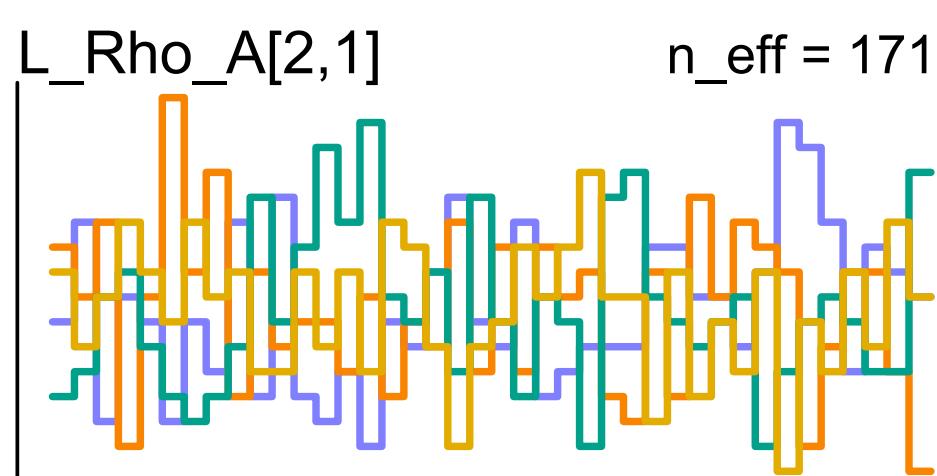
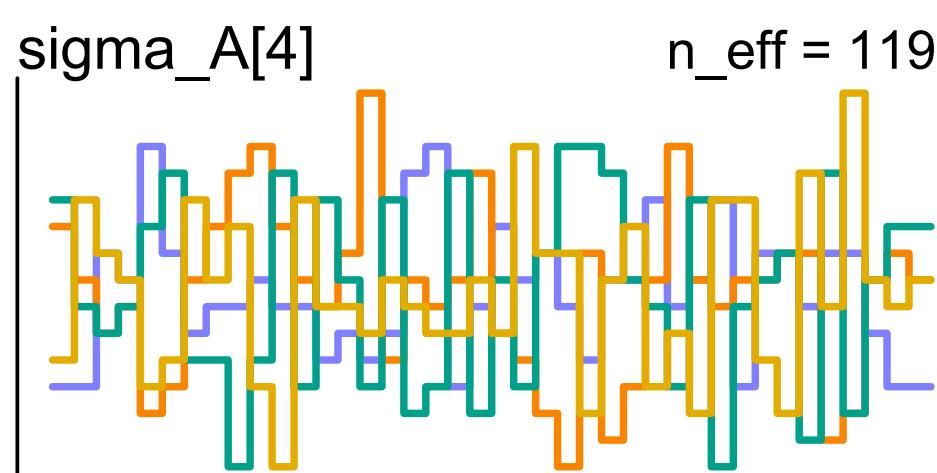
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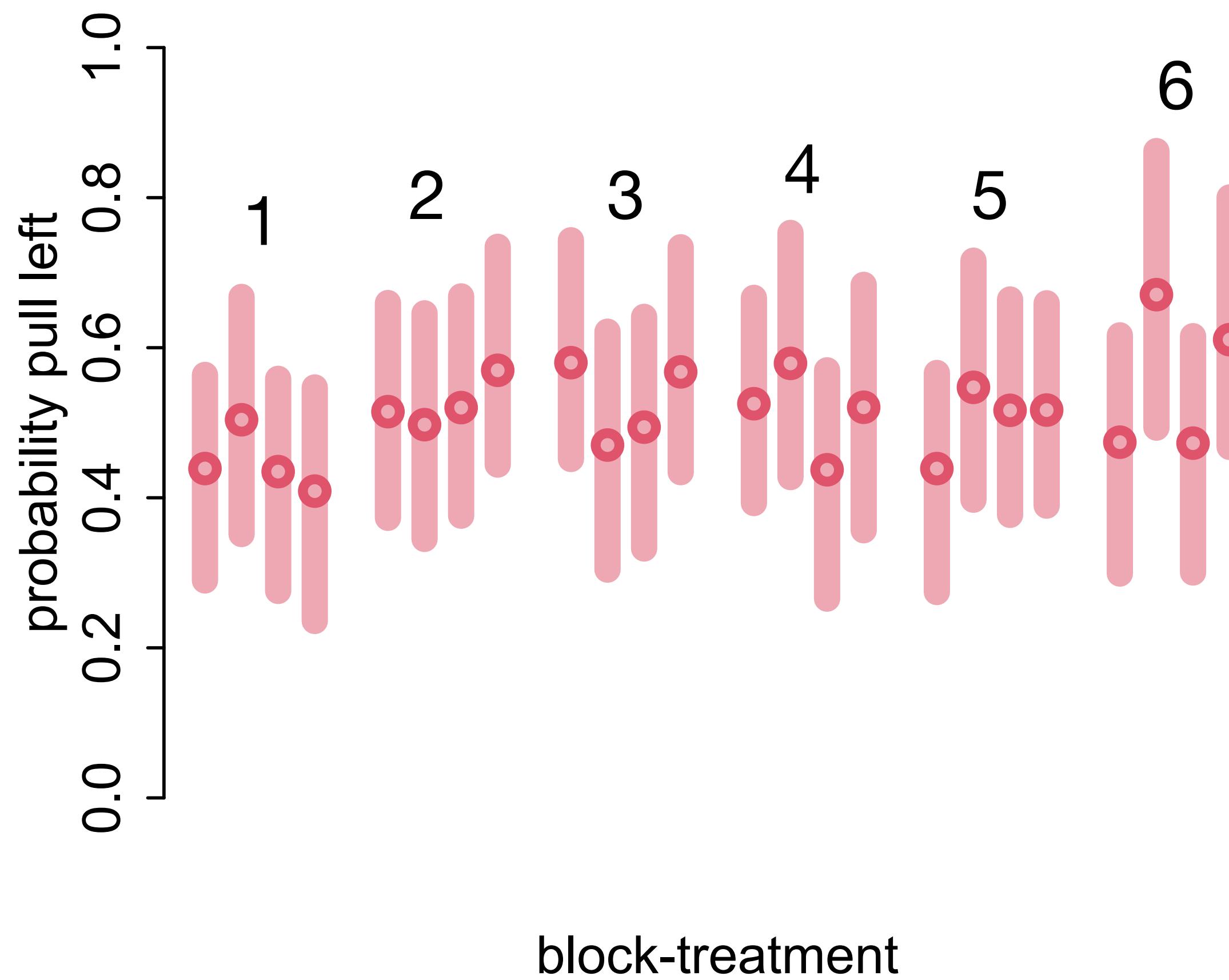
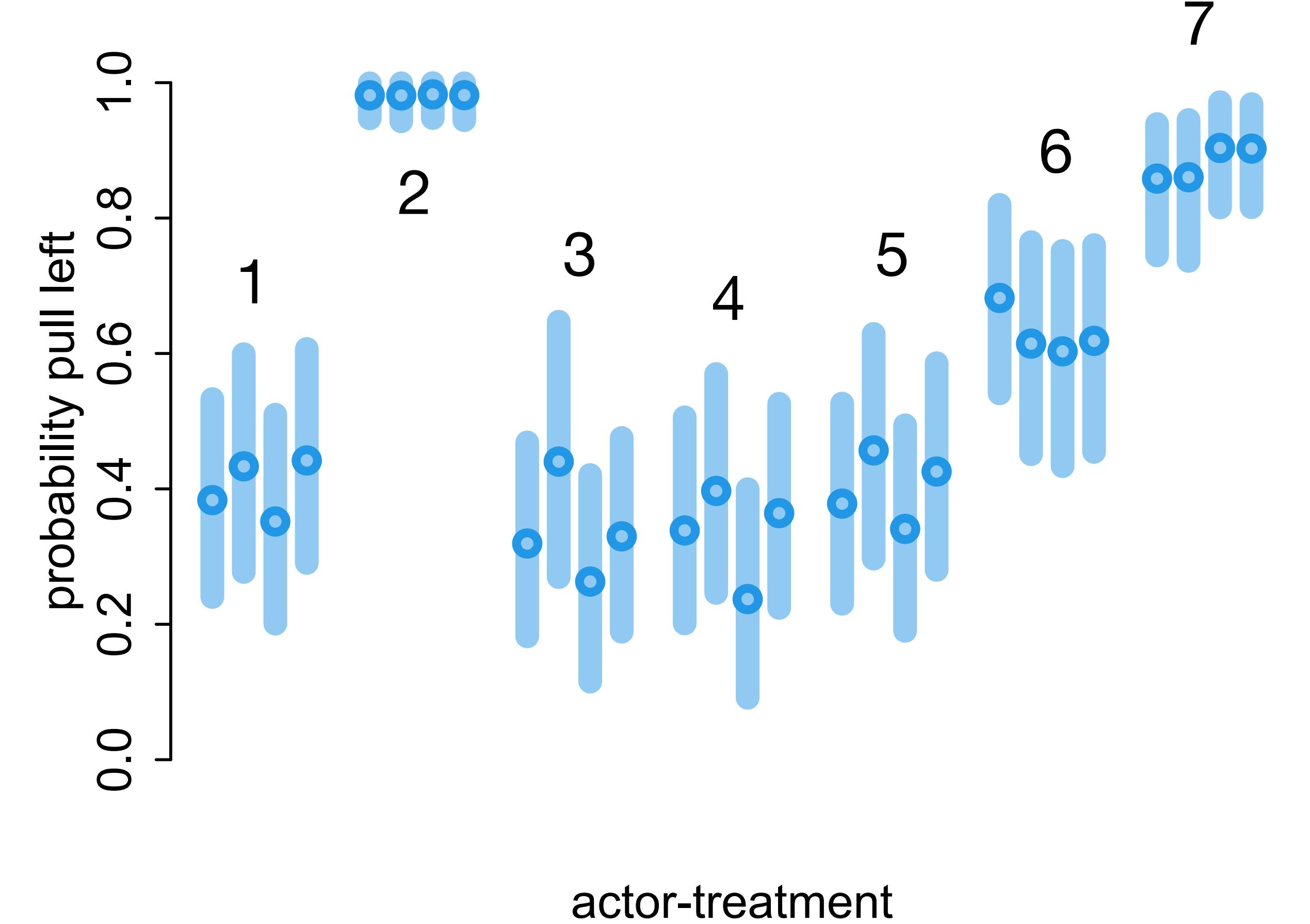
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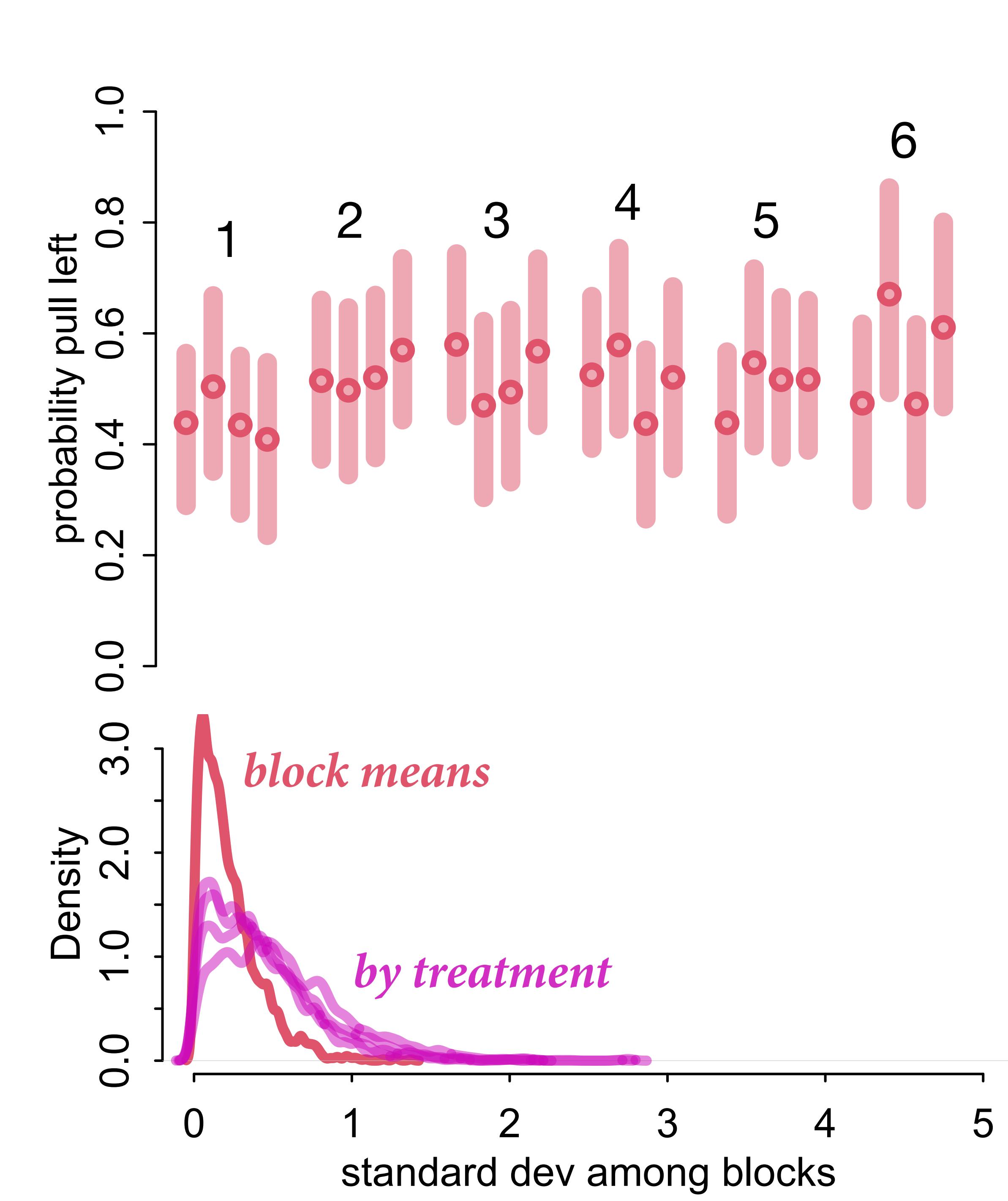
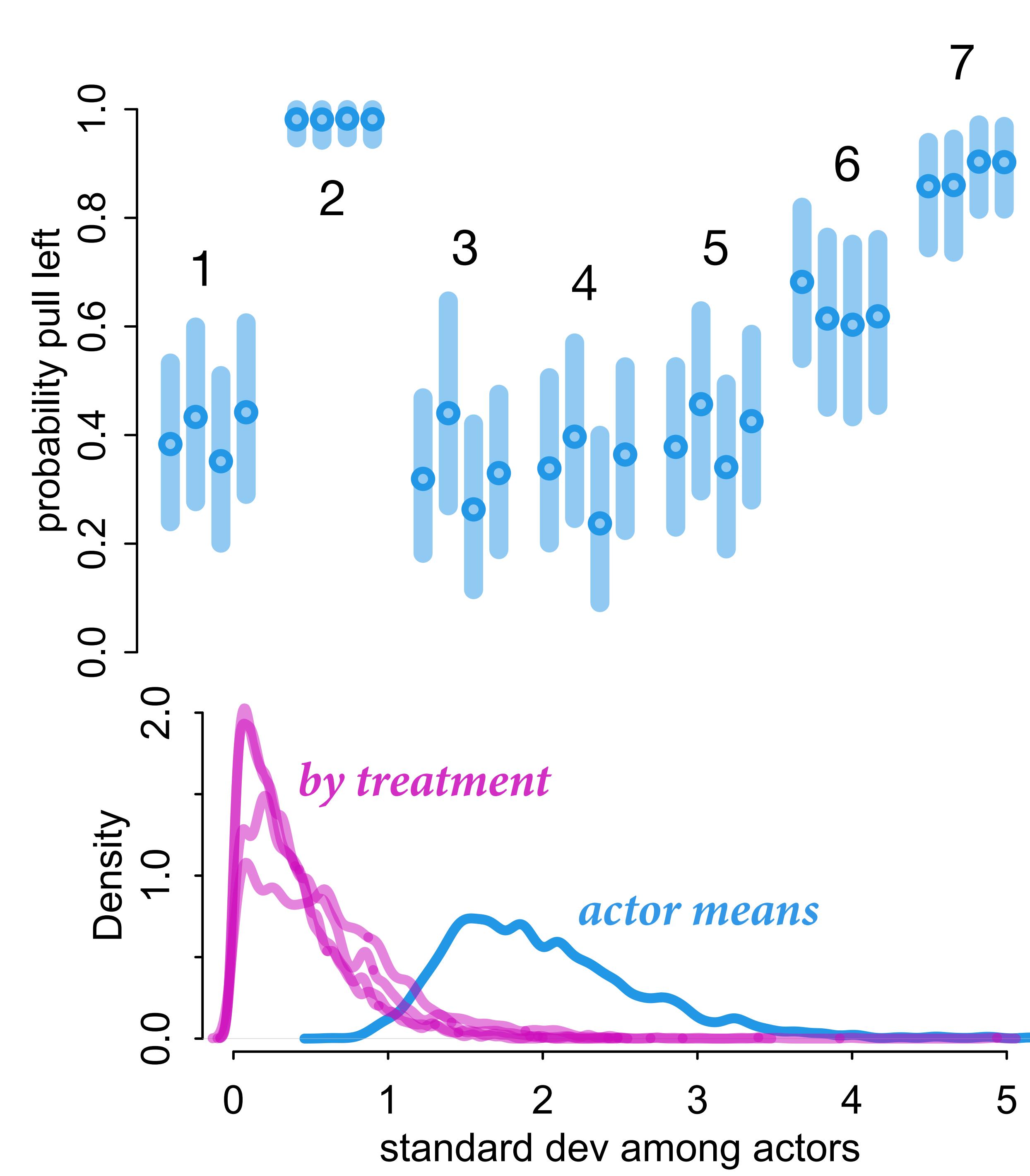
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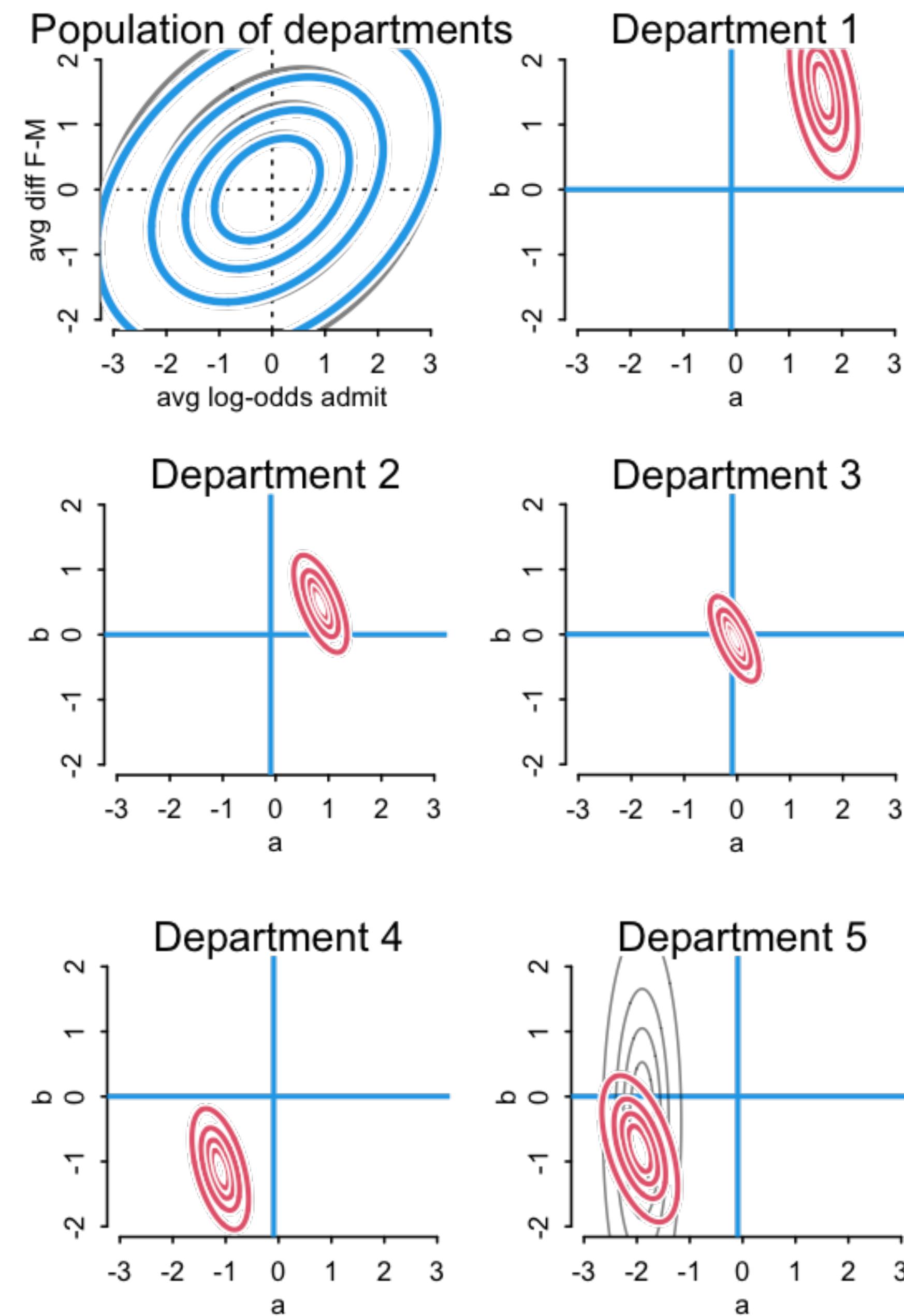
Correlated Varying Effects

Priors that **learn correlation structure**:

- (1) partial pooling across features
- (2) exploit correlations for prediction & causal inference

Varying effects can be correlated even if the prior doesn't learn the correlations!

Ethical obligation to do our best



Course Schedule

Week 1	Bayesian inference	Chapters 1, 2, 3
Week 2	Linear models & Causal Inference	Chapter 4
Week 3	Causes, Confounds & Colliders	Chapters 5 & 6
Week 4	Overfitting / MCMC	Chapters 7, 8, 9
Week 5	Generalized Linear Models	Chapters 10, 11
Week 6	Ordered categories & Multilevel models	Chapters 12 & 13
Week 7	More Multilevel models	Chapters 13 & 14
Week 8	Multilevel Tactics & Gaussian Processes	Chapter 14
Week 9	Measurement & Missingness	Chapter 15
Week 10	Generalized Linear Madness	Chapter 16

https://github.com/rmcelreath/stat_rethinking_2022

