

# System Design

ME 2984

“Design is a funny word. Some people think design means how it looks.  
But of course, if you dig deeper, it’s really how it works.” - Steve Jobs



# WHAT AM I TRYING TO DO?

- Design is about making choices
  - Law of Unintended Consequences
- Several different approaches
- Operates at multiple levels
- Write it down so you can come back to it later
  - What *and* why



# GET ME A DRINK!

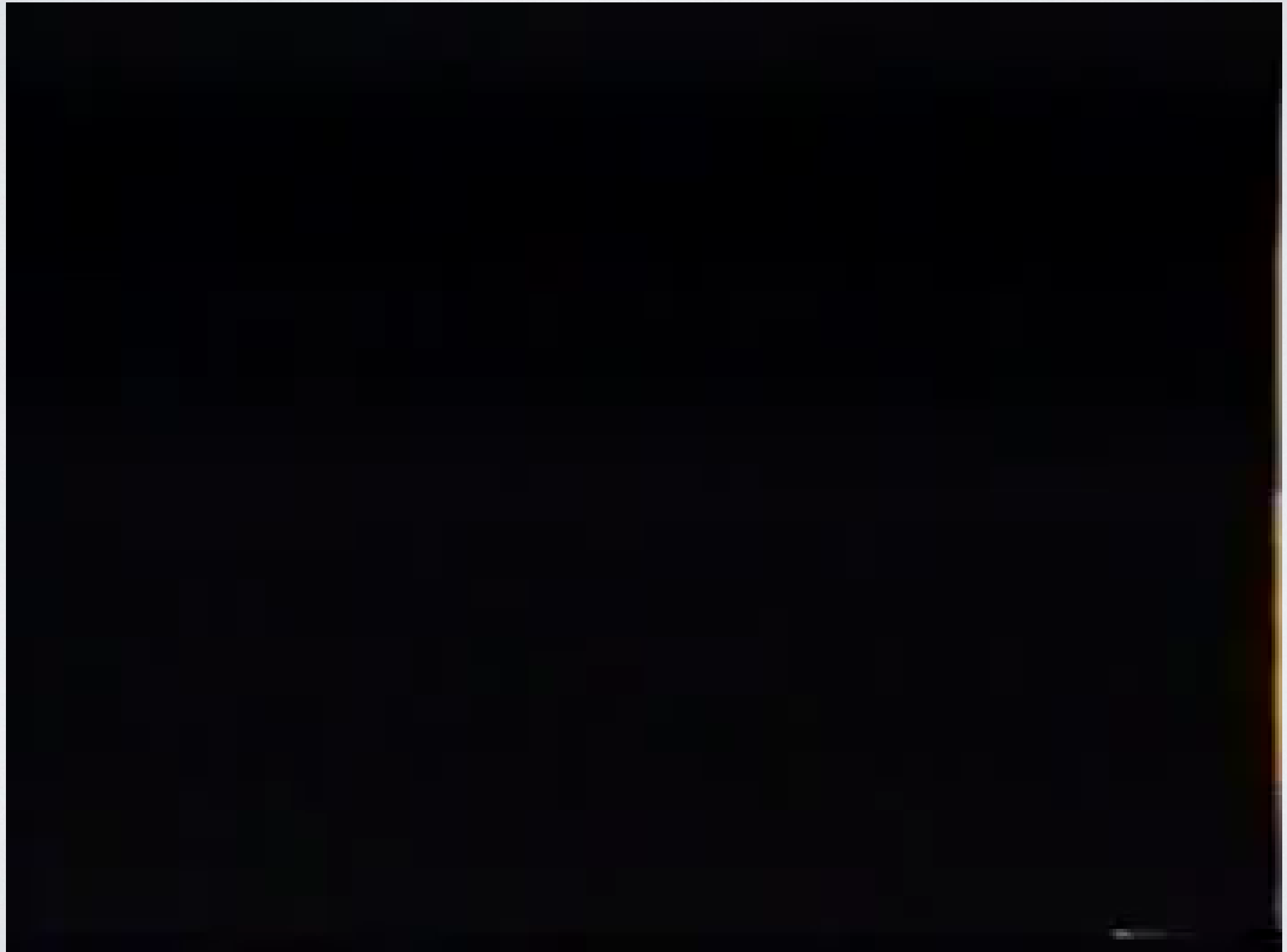
- I want soda, but don't want to leave my desk
- What does my robot butler need to do?
- How do we approach the problem?



# BRAINSTORMING TIME



# SOLUTIONS





# SOLUTIONS



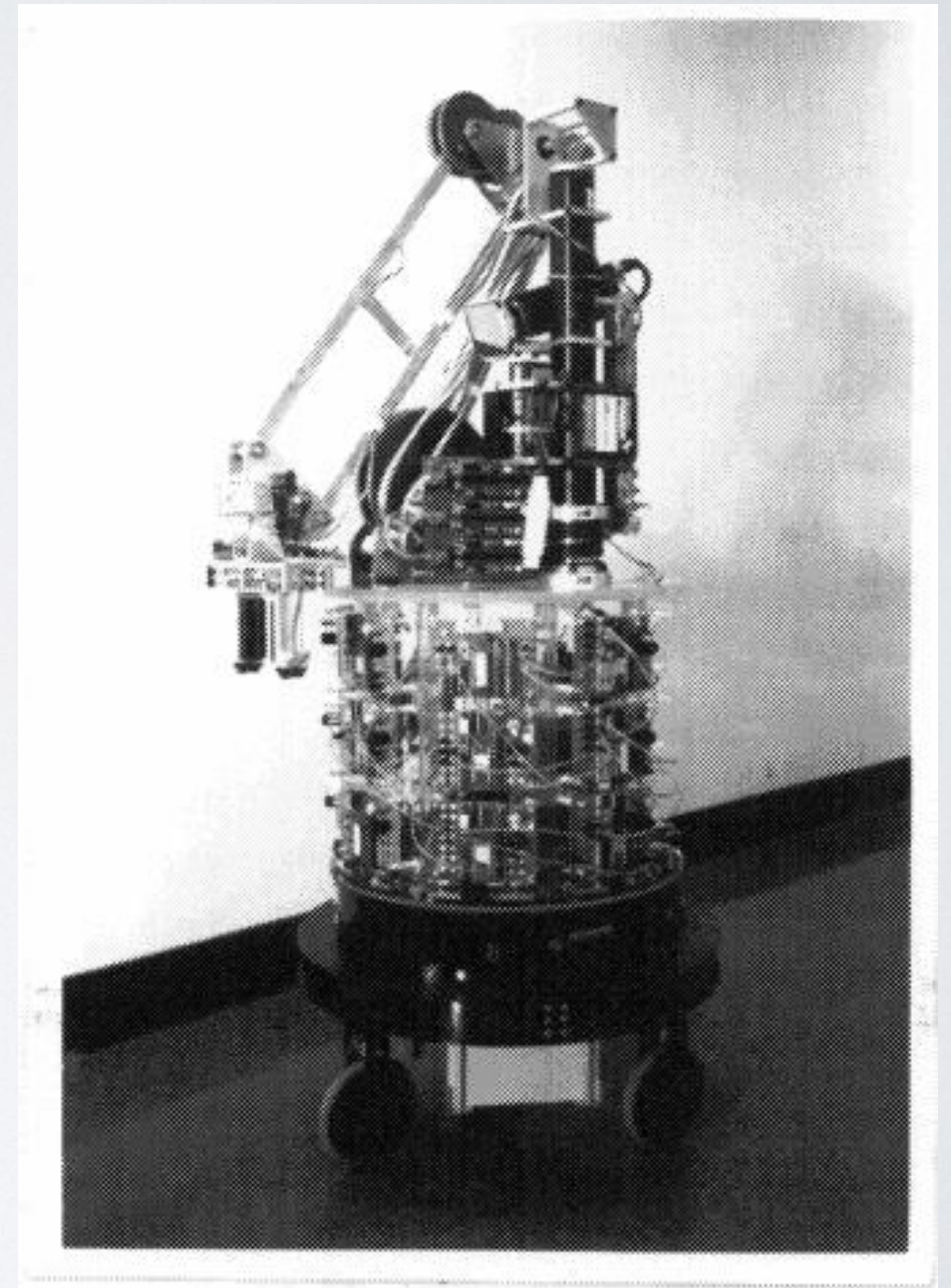
Credit: [Willow Garage](#)



WHICH IS BETTER?

# HERBERT

- 3 wheels
- Laser Sensor
- IR Sensors
- Independent, small processors



Source: Brooks *et al*





## PR2

- Kinect
- 5 MP Camera
- Stereo Camera
  - Wide and narrow
- LIDAR
  - Shoulder and base
- Accelerometers
  - Base and Hands
- Pressure Sensors
- Forearm Camera



Source: [Willow Garage](http://www.willowgarage.com)



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# REQUIREMENTS AND DESIGN

- Similar on the face
  - Mobile base
  - Manipulator
  - Task performed
- Major differences in approach





# WHICH IS BETTER?

- Herbert can achieve the goal with less sensors and technology
  - Designed with a specific goal in mind
  - Complex behavior from simple systems
- PR2 is a more general design
  - Bottom up approach
  - How do we achieve a goal with a given system?
- Better depends on metrics chosen



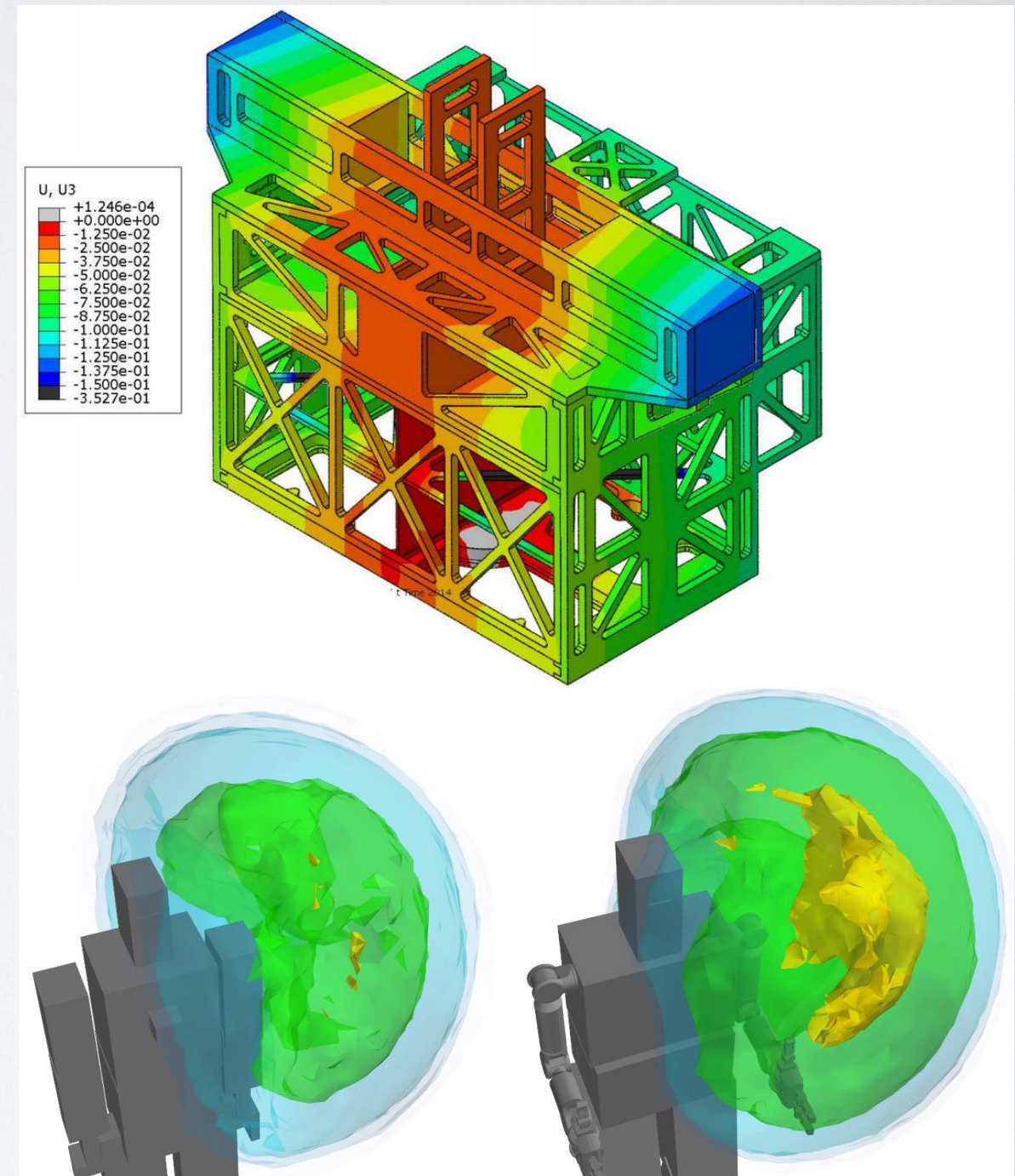


# SCALES OF DESIGN

- Design operates over many scales
  - Technical
  - System
  - Environment
  - Small Scale Interaction
  - Society

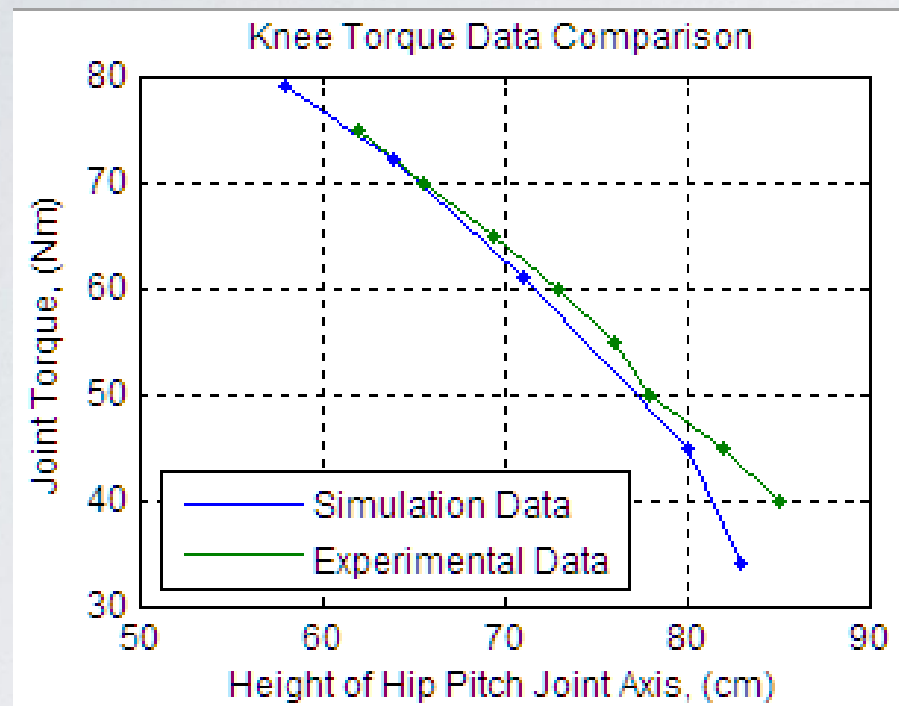
# TECHNICAL DESIGN

- Define technical requirements
  - Understand how requirements evolve
- Analysis is crucial
- Think about factors of safety
- Leave room for the future

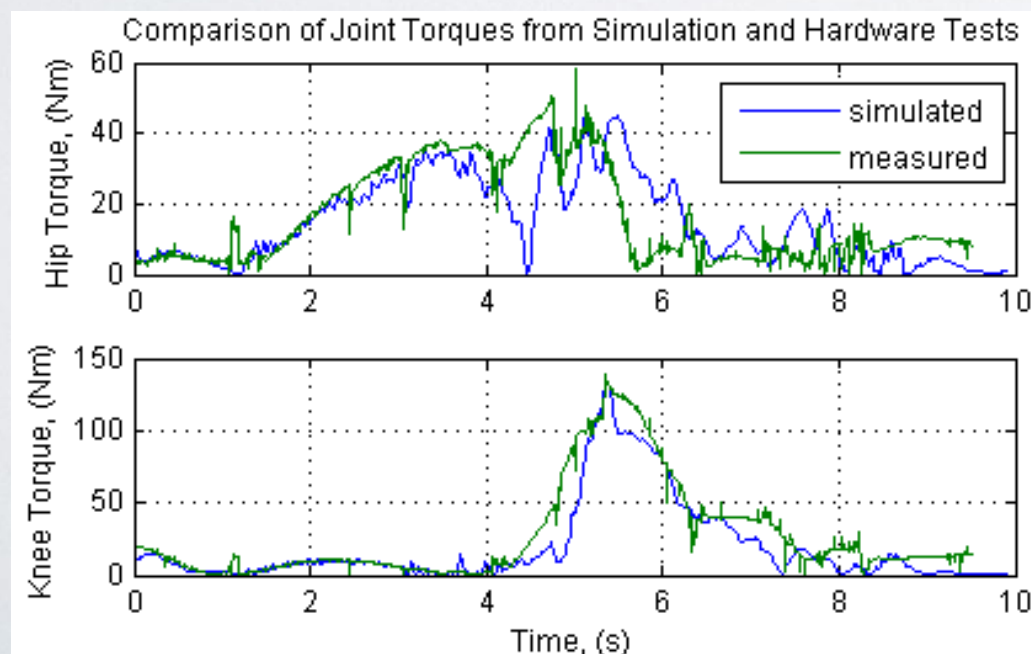




## V&V



- Validation
  - Are you building the right thing?



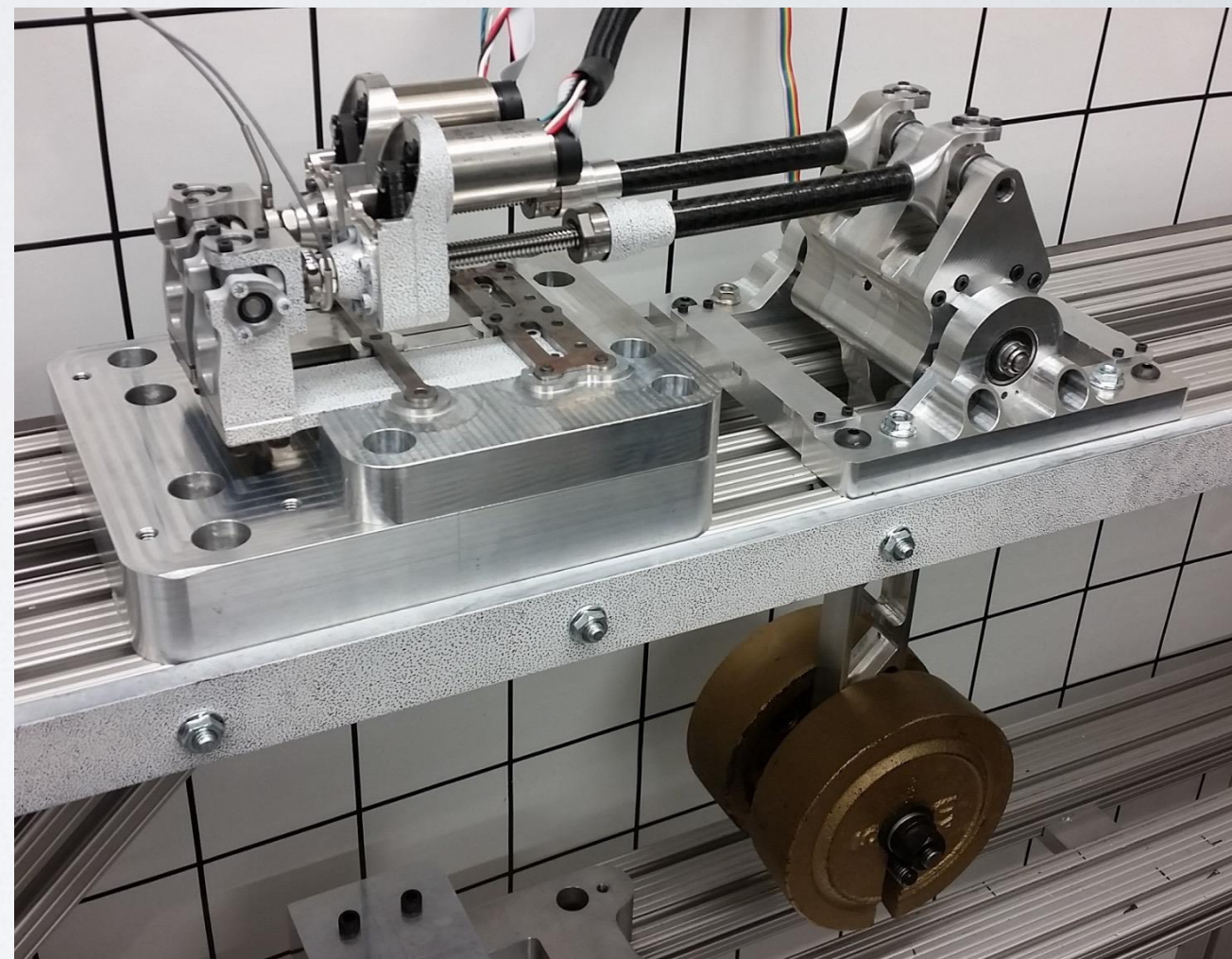
- Verification
  - Are you building it right?





# TESTING

- Test from small to large
- Have a plan
- ALWAYS record data!
- Don't just test for success, test for failure!





# TAKE IT FROM THE TOP

- Start with the big picture
- Decompose the problem
- Keep track of the puzzle pieces
- Over designing can be tempting





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# START WITH THE FIRST STEP

- Start with small, useful units of capability
- Keep adding new ones
- Eventually build up to higher levels of capability
- Emergent Behaviors





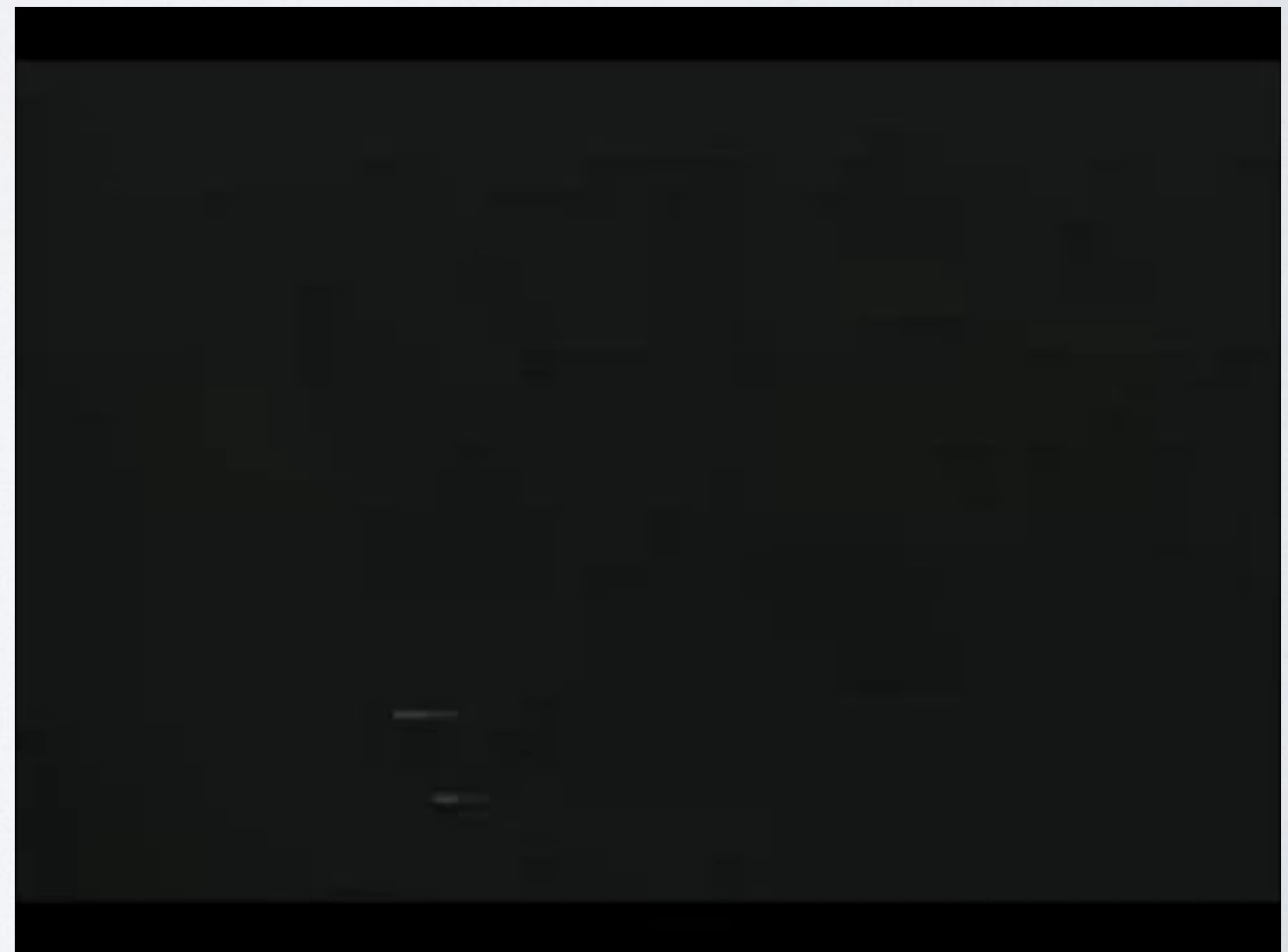
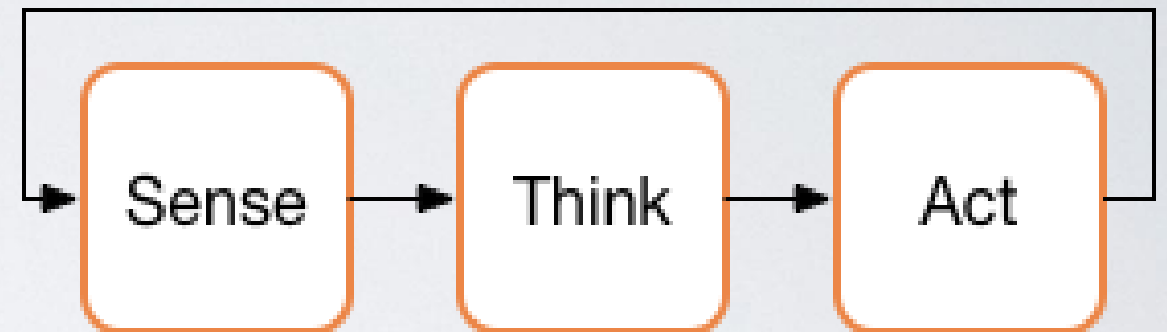
# MEET IN THE MIDDLE

- Hybrid both approaches
- Minimize over-design
  - Encode useful concepts in the design
- Typically an iterative process
- Sometimes uses a voting scheme
- Needs care to reach a local minima



# DELIBERATIVE SYSTEMS

- System uses data to plan for the future\*
- Useful for encoding expert information into system
- Require much more structure





# REACTIVE SYSTEMS

- Sensing directly leads to action
- Faster reactions, no lookahead





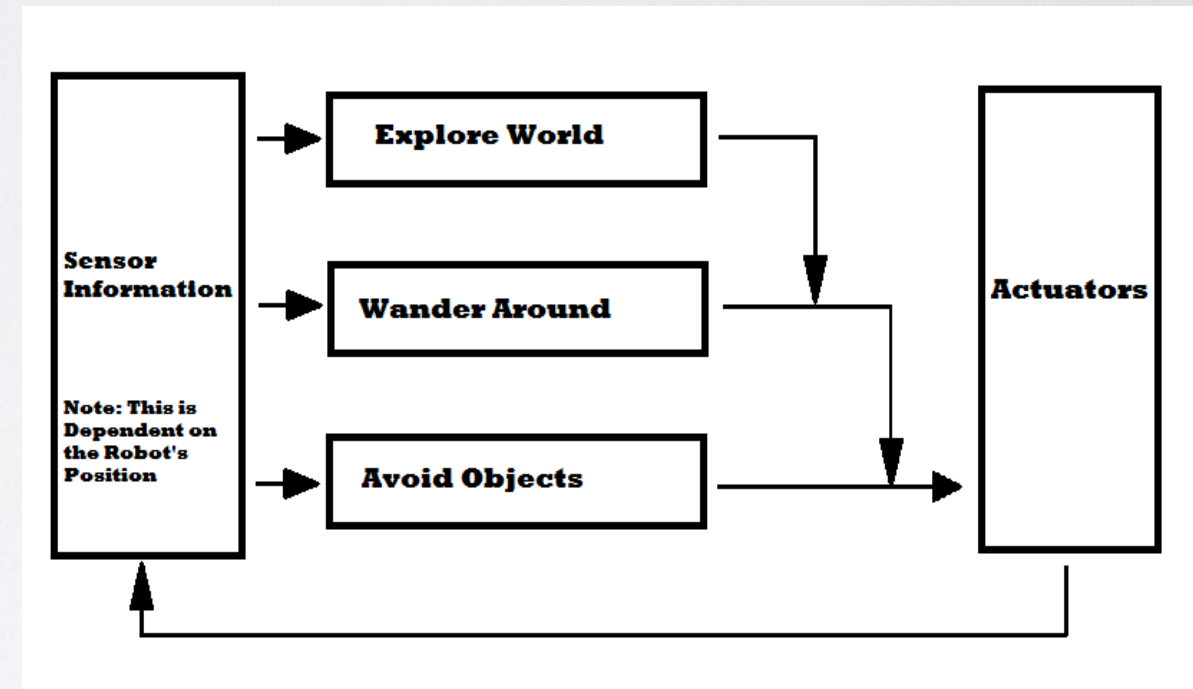


# HYBRID SYSTEMS

- Try to capture best of both worlds
- Hard to transition between styles
- Sometimes referred to as Behavioral Robotics
  - Plan sequence of behaviors

# SUBSUMPTIVE ARCHITECTURE

- Developed by Rodney Brooks at MIT
- Independent sub-behaviors
- Bottom Up Layering



Source: [Wikipedia](https://en.wikipedia.org/wiki/Subsumption_architecture)





# PROBLEMS IN CONTEXT

- Context drives how a problem is formulated
  - And how people think about a problem
- Problem definition can fundamentally alter the approach (and difficulty) of a project
- The inverse situation is true as well



# INTERACTING WITH PEOPLE

- Robots interact with people in a variety of roles
- As roboticists, we can design the robot for interactions
- People are strange (and we can't design them)
- Covers a massive range of issues





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# INTERACTING WITH PEOPLE

# SOCIETAL DESIGN

- Role of robots in society?
  - Tool
  - Assistant
  - Cultural Participant



Credit: [Construction Robotics](#)





# SOCIETAL DESIGN

- Role of robots in society?
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Credit: [Google](#)

# SOCIETAL DESIGN

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Credit: [Sony](https://www.sony.com/robotics/)



# WHY BUILD A HUMANOID?

- Navy wanted to fight fires
- Previous Experience
- Advancing Technology
- Analyzing Risk



Source: [Logan Wallace](#)



# SUGGESTED WORK

- ROS Tutorials will be very helpful
  - 1, 2, 5-8 are likely useful already
  - 3, 4, 12, 13, 17 will be useful soon





# PROJECT PROPOSAL

- Cover required topics
- Start forming teams
- Teams can propose a budget of \$20/member for the class to purchase to loan for projects
  - Subject to approval
- Using outside resources to acquire hardware is fine within reason