# Assignment 4 COL380

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#### 1 BSR Data Structure

I read and store a sparse matrix in BSR format (block size  $k \times k$ ) using the following structure:

Listing 1: BSRMatrix struct definition

Here,  $row_ptr[i]..row_ptr[i+1]-1$  lists the block-columns of block-row i. This compact format enables dense  $k \times k$  micro-kernels on GPUs.

## 2 Matrix Reading and BSR Conversion

Each input file lists height, width, num\_blocks folloId by (r,c) block coordinates and up to  $k^2$  values. I:

- 1. **mmap** the file, then fast-parse integers and 64-bit values.
- 2. Collect (block-row, block-col, values) tuples in a CPU array.
- 3. Sort by (block-row, block-col) in  $O(\text{nnz} \log \text{nnz})$ . where nnz is the no. of non-zero blocks
- 4. Fill row\_ptr, col\_idx, and contiguous values arrays.

This one-pass conversion costs under 200ms for 10k blocks on a modern CPU.

## 3 Local Multiply: CUDA Kernel

I fuse numeric block-multiplication into a single CUDA kernel, after two key precomputations on the CPU:

Symbolic assembly (OpenMP) Build C.row\_ptr and C.col\_idx in two OpenMP-parallel passes (count + fill), marking which output blocks will be nonzero.

Pair list creation (OpenMP) For each output block b, count all  $(a_i, b_j)$  block-pairs that contribute to b. Prefix-sum these counts into blkPairPtr[0..B], then fill flat arrays blkPairA and blkPairB in parallel.

#### Kernel launch:

blocks = 
$$C.\text{num.blocks}$$
, threadsPerBlock =  $\min(1024, k^2)$ .

Each CUDA block handles exactly one output block b.

#### What each block does:

- Reads its own index b = blockIdx.x.
- Loads blkPairPtr[b] and blkPairPtr[b+1] to find its list of contributing pairs.
- Writes its computed  $k \times k$  tile into the global output buffer Cval[b].

#### What each thread does:

- Let t = threadIdx.x. If  $t \ge k^2$ , exit.
- Compute within-block coordinates:

$$i_0 = |t/k|, \quad j_0 = t \bmod k.$$

• Loop over pairs  $p \in [blkPairPtr[b], blkPairPtr[b+1])$ :

$$sum + = A_p[i_0, *] \times B_p[*, j_0].$$

• Write sum to  $\text{Cval}[b \times k^2 + t]$ .

#### Postprocessing:

- 1. cudaMemcpy of all  $k^2 \times C$ .num\_blocks values back to host.
- 2. Scan/filter to rebuild BSR row\_ptr, col\_idx, and compact values.

I have also included CUDA-CHECK after every cuda api calls for error detection. For calculting the product of all matrices in a node I am iterating over the matricis and calculating a running product.

### 4 Distributed Reduction: MPI

With P ranks, after local multiplication each rank holds one partial BSR product. I perform a binary-tree reduction:

- Step doubling: at step s, ranks with rank%2s==0 receive from rank+s, others send and exit.
- Each receiver multiplies the incoming matrix into its local accumulator using the same CUDA pipeline.

This yields  $O(\log P)$  communication and compute balance.

#### 5 Performance Results

Experiments on a GPU-equipped cluster (one GPU + 4 CPU cores per node and 4 nodes), multiplying 100 test matrices with around  $\sim$ 700k blocks:

- Read time (per node):  $\approx 1500-3500$ ms via parallel mmap + fast-parse.
- Local multiply: one GPU kernel takes 28–35 sec for k = 32.
- Reduction: The reduction of product to node 0 takes around 15-18 sec
- Writing the Output: Since the output file for this case is quite large (around 1.3GB) it takes around 10 sec to write output. So overall it takes around 55-65 sec to completely multiply.

### • MPI scaling:

- Doubling node count from 2→4→8 gives 2−3× total speedup (local+comm) due to concurrent I/O and GPU use.
- Increasing CPU cores per node  $(4\rightarrow 8\rightarrow 16)$  speeds up file parsing and symbolic phases.

## 6 Conclusions

By combining:

- Fast memory-mapped input & BSR conversion,
- OpenMP-parallel symbolic assembly,
- A fused, atomic-free CUDA kernel,
- An MPI pairwise reduction tree,

I achieve a high-throughput distributed BSR multiply with excellent strong and Iak scaling. Future work may explore adaptive block sizes and out-of-core strategies for extremely large sparse problems.