Please read this document carefully before using this product. The guarantee will be invalidated if the device is damaged by not following instructions detailed in the manual. The company shall not be responsible for any damage or losses however caused, which may be experienced as a result of the installation or use of this product.

# **ENDA EU SERIES PID UNIVERSAL CONTROLLER**

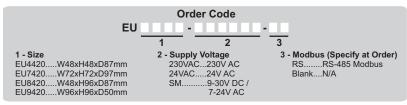
Thank you for choosing ENDA EU Series Universal Controller Devices.

- Dual setpoint value can be selected.
- ▶ PT100 ,J, K, L, T, S, R sensor (thermocouple) types can be selected.
- ▶ 0-20mA, 4-20mA, 0-10V,2-10V, 0-25mV and 0-50mV input selections.
- Auto calculation for PID parameters (SELF TUNE).



Self tune for automatic PID calculation or manually enter PID parameters if known.

- ▶ Three different feature can be assigned to digital input.
- ▶ Three different feature can be assigned to F function key.
- Soft-Start feature.
- Analogue, SSR or Relay Control Output selection.
- ▶ 0-20mA and 4-20mA analogue Control selection.
- ▶ A1 Relay output programmable as first Alarm or Cooling control output.
- C/A2 Relay output can be used as second Alarm or Temperature Control output.
- ► Heating/Cooling control.
- > Zero point input shift.
- In case of sensor failure, periodically, auto-periodically running or relay state can be selected.
- ▶ RS485 Modbus RTU communication protocol feature. (Specify at order).
- CE marked according to European Norms.











# R<sub>®</sub>HS Compliant

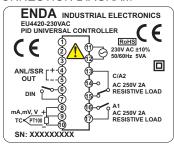


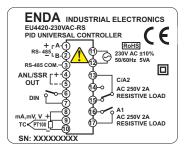
#### **TECHNICAL SPECIFICATIONS**

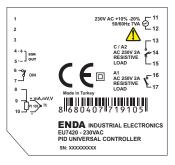
Input Type	Scale Range			Accuracy			
PT100 Resistance Thermometer	EN 60751	-199.9600.0°C		± 0,2% (for full scale) ± 1 digit			
PT100 Resistance Thermometer	EN 60751	-200600°C		± 0,2% (for full scale) ± 1 digit			
J (Fe-CuNi) Thermocouple	EN 60584	-30.0600.0°C		± 0,5% (for full scale) ± 1 digit			
J (Fe-CuNi) Thermocouple	EN 60584	-30600°C		± 0,5% (for full scale) ± 1 digit			
K (NiCr-Ni) Thermocouple K (NiCr-Ni) Thermocouple	EN 60584 EN 60584	-30.0999.9°C		± 0,5% (for full scale) ± 1 digit ± 0,5% (for full scale) ± 1 digit			
L (Fe-CuNi) Thermocouple	DIN 43710	-30.0600.0°C		± 0,5% (for full scale) ± 1 digit			
L (Fe-CuNi) Thermocouple	DIN 43710	-30600°C		± 0,5% (for full scale) ± 1 digit			
T (Cu-CuNi) Thermocouple	EN 60584	-30.0400.0°C		± 0,5% (for full scale) ± 1 digit			
T (Cu-CuNi) Thermocouple	EN 60584	-30400°C		±0,5% (for full scale) ± 1 digit			
S (Pt10Rh-Pt) Thermocouple	EN 60584	-401700°C		±0,5% (for full scale) ± 1 digit			
R (Pt13Rh-Pt) Thermocouple	EN 60584	-401700°C		±0,5% (for full scale) ± 1 digit			
0-20mA i		-1999+9999 (max.		± 0,2% (for full scale) ± 1 digit			
4-20mA i		-1999+9999 (max.		± 0,2% (for full scale) ± 1 digit			
0-10V inp		-1999+9999 (max.		± 0,2% (for full scale) ± 1 digit			
2-10V inp		-1999+9999 (max.		± 0,2% (for full scale) ± 1 digit			
0-25mV ii 0-50mV ii		-1999+9999 (max. -1999+9999 (max.		±0,2% (for full scale) ± 1 digit ±0,2% (for full scale) ± 1 digit			
ENVIRONMENTAL CONDITI	•	-1999+9999 (IIIax.	Scale range 10000)	± 0,2% (for full scale) ± 1 digit			
Ambient/storage temperature	0 +50°C/-2	25 +70°C					
Max. Relative humidity			tures up to 31°C decreasing	linearly to 50% relative humidity at 40°C.			
Rated pollution degree	According to			r panel : IP20			
Height	Max. 2000m	, 110		· pantar : 11 =0			
Keep out of flammable, co		and chemicals at a	ıll times.				
ELECTRICAL CHARACTER							
Supply		50/60Hz or 24\/ A	C +%10 50/60Hz or 0 30	0VDC / 7-24VAC ±%10 SMPS			
Power consumption	90-250V AC, Max. 5VA	JU/JUITZ UI Z4V A	O ± /0 10, JU/00□Z 01 9-30	ANDO I I-ZANAO I/0 IO SIVIFO			
Wiring		-terminal connection	ns: 2.5mm²', Signal screw-to	erminal connections: 1,5mm².			
Line resistance							
Data retention							
EMC	EN 61326-1:	2013 (Performance	criterion B satisfied for EN	61000-4-3 standard).			
Safety requirements	EN 61010-1:	2010 (Pollution deg	ree 2, overvoltage category	y II)			
OUTPUTS							
C/A2 Output			e load), NO+NC (Control or				
A1 Output	Relay: 250V AC, 2A (for resistive load), NO (Alarm1 and Cooling Control Output selection).						
ANL/SSR Output	Max. SSR Output; 0-20mA, 4-20mA, 24V 20mA. Max. load resistance; 600 Ohm (12 bit 0.2% accuracy).						
Life expectancy for relay	Without load 30.000.000 switching; 250V AC, 2A (resistive load) 300.000 switching.						
CONTROL							
Control type	Single Setpo	int and Alarm Contr	ol.				
Control algorithm		, PD, PID (selection	1).				
A/D converter	14 bit.						
Sampling time	Min. 100ms.						
Proportional band			<u>`</u>	ON-OFF control is selected.			
Control period	,	ted between 1 and					
Hysteresis		Can be adjusted between 1 and 50°C/F.  Setpoint value ratio can be adjusted between %0 and %100.					
Output power	Setpoint valu	e ratio can be adjus	sieu petween %0 and %100	J .			
HOUSING	0 11 11 6 6		l' / DIN 40 700				
ousing type Suitable for flush-panel mounting according to DIN 43 700.							
N							
Dimensions			A 64 1 - 1				
Dimensions Neight Enclosure material		(250g for EU4400)	After packing.				

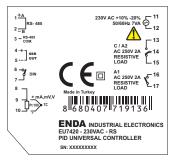
#### ENDA EUXXX SERIES PROGRAMMING DIAGRAM If no key is pressed within 20 seconds during "Programming Mode", the data is stored automatically and the "Running mode" is entered. SET Alternatively, the same function occurs first pressing key is pressing "Programming Mode" is entered. Then key is pressed while holding key, the "Programming Mode" is entered. C/A SET C/A SET are pressing together, data is recorded and "Running mode" is entered C/A SET [on.o. Lonf SECU. AL LO. 5.600 桱 For SSR output devices, if co.5£ parameter is different from £-82, this menu is nP.L. = Type of input selection. £.5.L a.= A1 Output Control setpoint value inP.E. R 15.L = Alarm1 set value lower limit. PED = PT100 decimal. 5.E. u. 5. Self tune control parameter. 5.Lod = Security menu access 5.C o d. lower limit. - 30 Adjustable between 0 and 8 15.H PŁ. = PT100 Non-decima If $\bigoplus_{\triangle}^{\text{SET}} \bigoplus_{\triangle}^{\triangle}$ keys are pressed together, the Adjustable between 0 and £.5.H i. J.D It should be 442. = J Type decimal, narameter value device returns to the main screen and if = J Type Non-decimal, 825! = Alarm2 set value lower limit [.5.H] [.5.H] = A1 Output Control setpoint = K Type decimal, the temperature is not high, P id.E. If in 5.Cod = 0 position, first held Adjustable between 0 and R2.5.H R 15H 8 15H= Alarm1 set value upper limit. = K Type Non-decimal, value upper limit. parameter value. message flashes on display and self tune down key then pressed = L Type decimal, Adjustable between £.5.L o. and Upper Adjustable between and upper scale value. Adjustable between 8 15L parameter value ∠ = L Type Non-decimal, process starts automatically. If the initial key for 4 seconds dEFP message scale value. = T Type decimal, temperature is higher to self-tune. E.b. . R25H R25H= Alarm2 set value upper limit. is displayed and return to the = T Type, message appears and the device waits factory settings. $\mathcal{L}$ . Pb = A1 Output Proportional band = S Type. Adjustable between 82.5.L parameter 600 until the temperature goes down. Then RIHY RIHY= Hysteresis of the Alarm1 output. = R Type, thermocouple selection. ıd.E. value. value and upper scale value Adjustable between 1 and 50°C. 0-20 = Type of 0-20 mA input selection, 4-20 = Type of 4-20 mA input selection, 0-10 = Type of 0-10 V input selection, P id.E. message appears and Adjustable between %0.0 and %100.0 $\overline{\phantom{a}}$ If $\mathcal{L}$ . Pb = %0.0. ON-OFF control is automatically self tune procedure is Lobc. =Parameter of Lon.o. menu R2HY R2HY= Hysteresis of the Alarm2 2-10 = Type of 2-10 V input selection, 0-25 = Type of 0-25 mV input selection selected starts. After the self tune procedure, security level. [.HY5] [.HY5 = A1 Output Hysteresis value. PSES nonE = Menu invisible. RIEP RIEP = Type of Alarm1. 0-50 = Type of 0-50 mV input selection If this parameter changed E.Pb. E E, E. dE and E. EE. values are Adjustable between 0 and 50°C. Adjustable between 1 and 50 °C. PYF5 = Modification can be done P. no = Only visible. some parameters are changed. Six kinds of functions can be selected. recorded in the memory, then the device If $\mathcal{L}$ . Pb = 0, this parameter is activated. ındE. ind €.= Independent alarm returns to "Running mode". After the 0[= °C. 0F= °F OL) R. 15c. = Parameter of RL 1.o. dε. = Deviation alarm R2EP R2EP = Type of Alarm2. A If this parameter changed successful self tune completion. ວະບຸດ $\mathcal{L}$ . $\mathcal{L}_{i}$ = A1 Output Integral value. bBod = Band alarm (Band)menu security level. Four kinds of functions can be some parameters are changed. P.YES Adjustable between 0 and 100.0 minutes. ındE. menu is removed automatically. In order $bRo_{ij}$ = Band with inhibition nonE = Menu invisible. selected. FLEr. = Digital filter coefficient. E = 0.0, integral impact is disable. , o. € o.= A1 output independent cooling to re-tune, 5.5.5c. parameter should be PYES = Modification can be done. ındE.= Independent alarm Adjustable between 1 and 200. ⚠ If *L. Pb* parameter is different from $d\mathcal{E}$ = Deviation alarm P. no = Only visible set to P.YE5 in 5ECU menu. if this parameters is 1, digital filter gives the $r \in \mathcal{L}_0 = A1$ output relative cooling control '0.0", this parameter is activated. bRnd = Band alarm fastest answer, if this parameters is 200. 8.2.5c. = Parameter of 81.2.0. digital filter gives the slow answer.If static in [. Ed] [. Ed = A1 Output Derivative value. $h8c_{i}$ = Band with inhibition menu security level. P.YES nonE = Menu invisible. 月 じと = Alarm1 output situation. environment, the value of parameter should STOPPING SELF TUNE R 1.5 E. Asjustable between 0.00 and 25.00 be incesed L.o.5£ = Control output selection I.DD Asjustab minutes. If Alarm1 output = A1 output is above the P. no = Only visible. PYF's = Modification can be done H 1. Alarm1 set value : on R25E. #2.5E. = Alarm2 output situation. [-R2 = C/A2 (Relay) output selection $\mathcal{L}$ . $\mathcal{L}d = 0.0$ , derivative time is disabled. Lo=A1 output is above the Alarm1 set If self tune process wanted to be 55 = SSR output selection 5.Eun. If A2 output H /=A1 outputs is above [n.5] [n.5] = Parameter of [onF ♠ If L. Pb parameter is different value: off U - 2 U = 0-20 mA analogue output selection terminated for any reason, A LEP parameter, in Co. or r E.Co.is the Alarm2 set value: on from"0.0", this parameter is activated 4-20 mA analogue output selection menu security level. selected; this parameter is not seen. $\triangle$ "Programming Mode" entered and P.YES nonE = Menu invisible. $I \cap = A2$ output is above the set value: oFF5 oFF5 = Offset value. [ ] [ E. E. = A1 Output Period time. off 5. Eun menu opened with and R LE c. = Alarm1 probe failure situation Offset value is added to the measuring value. PSE5 = Modification can be done. Adjustable between 1 and 125 second. on= A1 output probe failure; on. This feature which is the point of measurement due to its distance measurement probe, is used to eliminate errors that might occur. keys, 5.E.u b parameter selected 82.Er. = Alarm2 probe failure ⚠ If *C. Pb* parameter is different oFF = A1 output probe failure; off. R2Ec situation. with key, and keys 5.E.5c. = Parameter of 5.Eun. from "0.0", this parameter is activated. on = A2 output probe failure; on. Adjustable between -99 and 99°C, decimal values A LEP parameter, In.Co. or rE.Co. is menu security level can be adjusted between -10.0 and 10°C pressed together in order to stop self [.P.5] [.P.5] E.P.5E = A1 Output power at A1 setpoint selected, this parameter is not seen. oFF = A2 output probe failure:off. ann E = Invisibletune process and turn to main Adjustable between 0% and 100%. 0 dRdr. = Device address for RS485 connection. P.Y.E.5 = Modification can be done R LPb = A1 output, value of proportional 48dc If *LPb* parameter is different from 0.0, this parameter is activated. R IPh display Adjustable between 1 and 247. band. Adjustable between 0% and 100%. This parameter is active devices with CSET R IPb= 0%, On-Off control is selected Rs485 communications option. E.E.c.E = Faulty sensor control type. A IEP parameter, InCo. or rE.Co. is If $\mathcal{L}.\mathcal{E}.\mathcal{E}.\mathcal{E}.\mathcal{E} = \mathcal{E}.\mathcal{P}.\mathcal{S}$ , in case of probe failure according to $\mathcal{L}.\mathcal{E}.\mathcal{P}.\mathcal{S}$ , proportional value of bRud bRud = ModBus baud rate for RS485 connection Selectable as; off, 2.4, 4.8, 9.6, 19.20 ve 38.40 . 8 15 / = A1 output integral value. This parameter is active devices with RS485 400 the parameter control is performed. If $\vec{L}.\vec{E}.\vec{c}.\vec{L} = \vec{R}_{ij} \vec{L}_{ij}$ , in case of probe Adjustable between 0.0 and 100.0 minute mmunications option. failure, the fault found and recorded before the last setpoint control with the control $8 iF_{i} = 0.0$ effect of integral disable A R LEP, parameter, InCo. or r E.Co. is d. in.E. = Digital input setting parameter. d. 10.E. percentage is performed. nonE = Digital input is closed. selected and if 8 LPb different from "0". Λ If Γ.Pb parameter is different from 0.0. nonE [258= if digital input is activated, 2nd set value is this parameter is activated. F.o.L.o. = Retransmission output lower scale value $R \not \vdash d = A1$ output derivative value. Adjustable between lower scale and F.o.H . [EP5] [E.E.P5. = In the case of probe failure, A1 Adjustable between 0.00 and 25.00 minute $\triangle$ $\Gamma . \xi \cdot r \cdot b$ , parameter 0 - 20 or 4 - 20 and $R \perp L d = 0.00$ effect of derivative disable. are active and and rational output generated according output percentage adjustable between %0 0 to period value in E.E.b paremeter and percentage E.o.5 E. parameter is selected; apd %100. A I.E.P. parameter in.E.o. or r.E.E.o. is If E.E.c.t = E.P.b. or E.P.b = 0.0 is value in ā5E£ parameter. [ -R2 this parameter is seen. selected and if 8 IPb different from "0". selected, this parameter is activated. this parameter is activated. d5Po = If the digital input is activated; temperature In case of failure, if E, Pb = DD (ON/OFF F.o.Ho. = Retransmission output lower scala indicator mode can be exceed. Adjustable between 1 and 250sec. value. Adjustable beetween LoLo and lower Control) and E.E.P.5 = 0 output will be F.F.E.C. = Function key setting parameter. A LEP parameter in Co. or r E.Co. is scala. OFF, if different from "0" value, output will nonE = Function key is closed. に 「たっち parameter 0 - 20 or 4 - 20 and $\triangle$ $\triangle$ selected and if # !Pb different from "0", this parameter is activated. |nonE| he ON £2.5.8.= The function key is used with the 2nd set value. C.o.5 E. parameter C - R2 selected: ந்திறு. = Manual mode can be exceed by using the function key. this parameter is seen. R IP5 =At A1 Set value, A1 output percent d5Po = Temperature indicator mode can be exceed by using dP.5E = mA inputs, desimal point adjusment. of power. ちちとち = Soft Start timer set value function key. Adjustable between 0% and 100%. Adjustable between 0 and 0.000. in P.L. parameter mV, mA or V input is selected; This parameter indicates the time to R.o.L o. Ro.Lo. = Analog output minimum output A ILP parameter in La or r E.Ca is $\triangle$ reach set point value when the device is percentage. Adjustable between 0 and Ro.H . this parameter is seen. selected and if 8 IPb different from "0", ⚠ C.o.5E. parameter, 0 - 20 or 4 - 20 is selected; first energised. this narameter is activated Adjustable between 0 and 250 minutes. $\triangle$ this parameter is seen. u.5.L a. = mA inputs, lower scala value R IEP = At A1 Set value, A1 output percent If 0 is selected, soft start feature will be R.o.H , Ro.H . = Analog output maksimum output Adjustable between -1999 and ( u.5H i - 10 ). of power. -1999 enable and the device reaches set point in Pt. parameter mV, mA or V input is selected; Adjustable between 0%-100%. percentage. Adjustable between RoLo and 100 100 value quickly. £.o.5E. parameter, 0-20 or 4-20 is selected; $\triangle$ this parameter is seen. 25H; = mA inputs lower scala value. Adjustable A IEP parameter in Eq. or cEEq. is this parameter is seen. selected, this parameter is activated. 0.5.H r. between ( u 5 L o + 10 ) and 9999 $f. E \circ 5$ . = the retransmission output control parameter nonE = the retransmission is off. noPt. parameter mV. mA or V input is selected: E.E SP. = Control output type this patameter is seen. nonEl Ū-2Ū = Analog output 0-20mA the retransmission $\triangle$ ELYP = HERE means heating control. output Ч − 2 Ū = Analog output 4-20mA retransmission Š CESP = Cool means cooling control. 2/7 £.o.5 £. parameter, £ - 82 is selected; this parameter is seen.

#### CONNECTION DIAGRAM



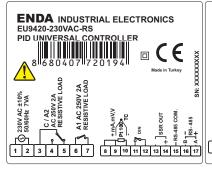


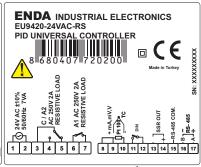






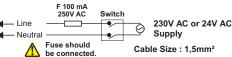










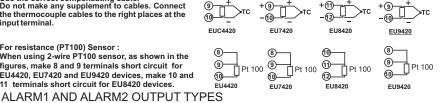




#### SENSOR INPUT:

For J - K - T- S and R Thermocouples : Use the correct compensating cable. Do not make any supplement to cables. Connect the thermocouple cables to the right places at the input terminal.

For resistance (PT100) Sensor : When using 2-wire PT100 sensor, as shown in the figures, make 8 and 9 terminals short circuit for EU4420, EU7420 and EU9420 devices, make 10 and 11 terminals short circuit for EU8420 devices.



+11

+(9)

Equipment is protected throughout by DOUBLE INSULATION.

Logic output of the instrument is not electrically insulated from the internal circuits. Therefore, when using a grounding thermocouple, do not connect the logic output terminals to the ground.

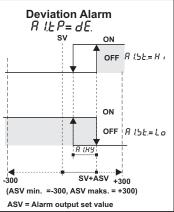
#### Note:

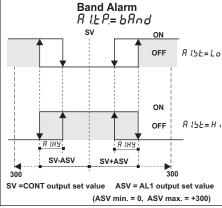
1) Mains supply cords shall meet the requirements of IEC 60227 or IEC 60245.

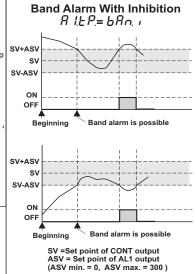
2) In accordance with the safety regulations, the power supply switch shall bring the identification of the relevant instrument and it should be easily accessible by the operator.

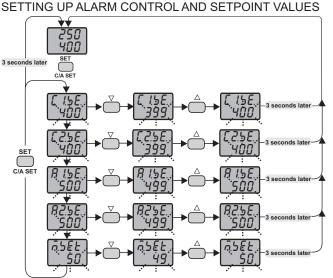
# **Independent Alarm** R LEP = IndE ON OFF ON OFF R IHY











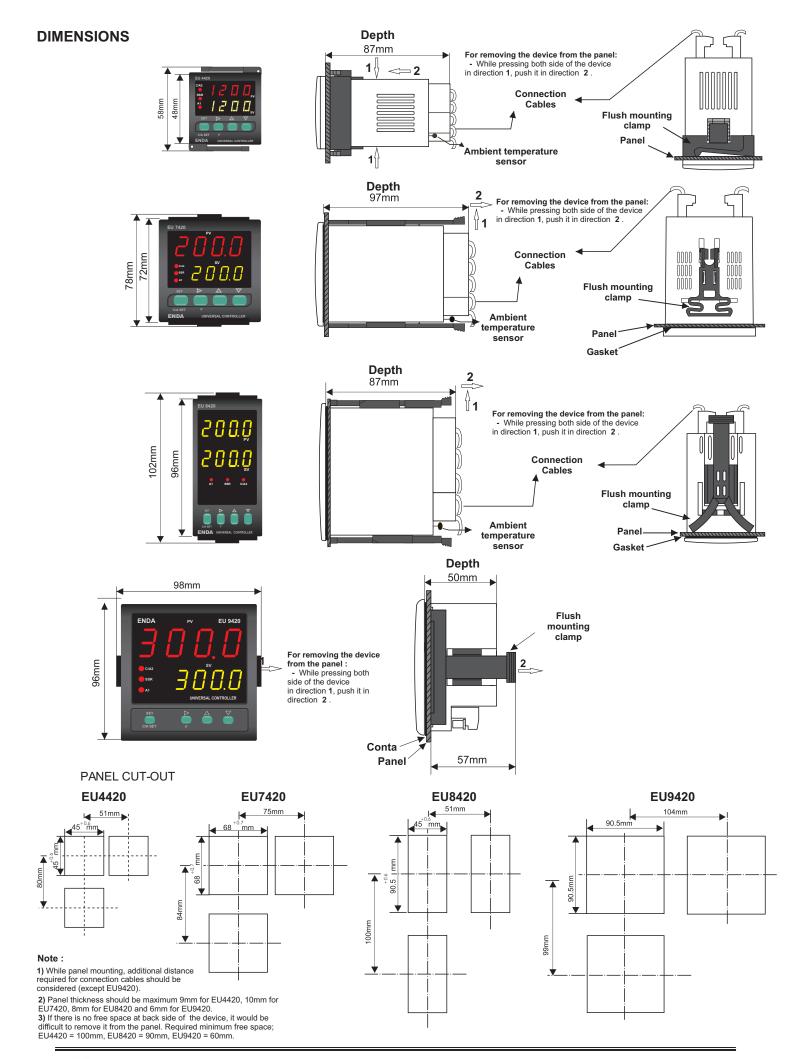
If one of the d. in.c. or F.F.E.c. parameters are set to the  $\mathcal{L}25\mathcal{B}$  value, this parameter is seen.

If the  $\ell.o.5E$  parameter is set to SSR out, this parameter is seen.

If one of the *d. i.o.c.* or *F.F.E.c.* parameters are set to the  $\bar{o}Rou$ , value and if  $\mathcal{L}$ . Pb is different from 0, this parameter is seen.

## **ERROR MESSAGES** Temperature sensor is broken. 400 Temperature value is higher than the scale. 400 Temperature value is broken or over temperature.









# **ENDA EU SERISI PID SICAKLIK KONTROL CİHAZI** MODBUS PROTOKOLÜ ADRES HARİTASI

	Parameter Number	Holding F Addre Desimal	sses	Data Type	Data Content	Read / Write Permission	Factory Defauls
	Н0	0000d (	(0000h)	Word	Control output, temperature setpoint value	Read / Write	400
ဟ	H1	0001d (	(0001h)	Word	Control output, 2nd temperature setpoint value	Read / Write	400
ter	H2	0002d (	(0002h)	Word	Control output, minimum setpoint value	Read / Write	0
Control Output Parameters	Н3	0003d (	(0003h)	Word	Control output, maximum setpoint value	Read / Write	600
arg	H4	0004d (	(0004h)	Word	Control output, proportional band setpoint value (Adjustable between %0.0 and %100.0)	Read / Write	4
T E	Н5	0005d (	(0005h)	Word	Control output, hysteresis value (Adjustable between 1 and 50 °C or °F)	Read / Write	2
utp	Н6	0006d (	(0006h)	Word	Control output, integral time (Adjustable between 0.1 and 100.0 minute)	Read / Write	40
0	H7	0007d (	(0007h)	Word	Control output, derivative time (Adjustable between 0.01 and 10.00 minute)	Read / Write	100
ltro	H8	0008d (	(0008h)	Word	Control output, time period setpoint value (Adjustable between 1 and 125 second)	Read / Write	20
S	Н9	0009d (	(0009h)	Word	Control output, set value power ratio (Adjustable between %0 and %100)	Read / Write	0
	H10	0010d (	(000Ah)	Word	Control output, set value power ratio in case of sensor failure (Adjustable between %0 and %100)	Read / Write	0
	H11	0011d (	(000Bh)	Word	Control output, soft start value	Read / Write	0
	H12	0012d (	(000Ch)	Word	Alarm1 output temperature setpoint value	Read / Write	500
	H13	0013d	(000Dh)	Word	Alarm1 output minimum setpoint value limit	Read / Write	0
ပ	H14	0014d (	(000Eh)	Word	Alarm1 output maximum setpoint value limit	Read / Write	600
ete		0015d (	(000Fh)	Word	Alarm1 output proportional band set value (Adjustable between %0.0 and %100.0)	Read / Write	0
Parameters		0016d (	(0010h)	Word	Alarm1 output hysteresis value (Adjustable between 1 and 50 °C or °F)	Read / Write	2
are	H17	0017d (	` ′	Word	Alarm1 output, integral time (Adjustable between 0.1 and 100.0 minute)	Read / Write	0
		0018d (	` ′	Word	Alarm1 output, derivative time (Adjustable between 0.01 and 10.00 minute)	Read / Write	0
Output		0019d (	` ′	Word	Alarm1 output, time period setpoint value (Adjustable between 1 and 125 second)	Read / Write	20
O		0020d (	` ′	Word	Alarm1 output, set value power ratio (Adjustable between %0 and %100)	Read / Write	0
A	H21	0020d (	` /	Word	Alarm1 output, set value power ratio in case of sensor failure (Adjustable between %0 and %100)	Read / Write	0
	H22	0021d (	` /	Word	Alarm1 output type selection (Values can be given from 0 to 4) (0 = Independent alarm, 1 = Deviation alarm, 2 = Band alarm, 3 = Active alarm after in band time, 4 = Alarm1 output, cooling control selection)	Read / Write	0
2	H23	0023d (	(0017h)	Word	Alarm2 output, temperature setpoint value	Read / Write	500
utput Parameters	H24	0024d (	(0018h)	Word	Alarm2 output minimum setpoint value limit	Read / Write	0
Paral	H25	0025d (	(0019h)	Word	Alarm2 output maximum setpoint value limit	Read / Write	600
tput	H26	0026d (	(001Ah)	Word	Alarm2 output, hysteresis value (Adjustable between 1 and 50 °C or °F)	Read / Write	2
A2 Out	H27	0027d (	(001Bh)	Word	Alarm2 output type selection (Values can be given from 0 to 3) (0 = Independent alarm,	Read / Write	0
A	H28	0028d (	(001Ch)	Word	1 = Deviation alarm, 2 = Band alarm, 3 = Active alarm after in band time)  Input selection number (0 = PT100 Decimal, 1 = Pt100 Non-decimal, 2 = J Decimal, 3 = J Non-decimal, 4 = K Decimal, 5 = K Non-decimal, 6 = L Decimal, 7 = L Non-decimal, 8 = T Decimal, 9 = T Non-decimal, 10= S Non-decimal, 11 = R Non-decimal.	Read / Write	5
SIS	H29	0029d (	(001Dh)	Word	ModBus device address (Adjustable between 1 and 247)	Read / Write	1
nete	H30	0030d (	001Eh)	Word	Modbus communication speed (Baudrate) (0 = Modbus cancel, 1 = 2400 bps, 2 = 4800 bps, 3 = 9600 bps, 4 = 19200 bps, 5 = 38400 bps)	Read / Write	3
Parameters		0031d (	001Fh)	Word	Digital filter coefficient (Adjustable between 1 and 200, 1 = filter is disable)		10
	H32	0032d (	0020h)	Word	Control output, selection value (0 = C/A2 Control output selection, 1 = SSR Output )  ATTENTION !! If this parameter is set to a 0 value is H42:0		0
tio		0033d (		Word	Analog output minimum out percentage		0
ura	H34	0034d	` ′		Analog output maximum out percentage	Read / Write	100
fig	H35	0035d	(0023h)	Word	Offset value	Read / Write	0
Configuration	H36	0036d	(0024h)	Word	Function control parameter. ( 23040d ( 5A00h ) self tune stops when this value is entered ) ( 23041d ( 5A01h ) self tune starts when this value is entered ) ( 23042d ( 5A02h ) returns to factory defaults when this value is entered)	Read / Write	0
	H37	0037d	(0025h)	Word	Reserved	Read / Write	XX
	H38	0038d (	(0026h)		Reserved	Read / Write	XX
	H39	0039d	(0027h)	Word	Manual control output percentage (Adjustable between %0 and %100)	Read / Write	50





# 1.1 Memory Map for Holding Registers (continue)

	Parameter Number	Holding I Addre Desimal	sses	Data Type	Data Content	Read / Write Permission	Factory Defauls
	H40	0040d	(0028h)	Word	Digital input control parameter ( 0 = Digital input off, 1 = 2nd set value is selected with digital input, 2 = Manual mode is entered via digital input, 3 = Digital input is passed to display mode	Read / Write	0
	H41	0041d	(0029h)	Word	Function key control parameter (0 = Function key off, 1 = 2nd Set value is selected with function key, 2 = Manual mode is entered via function key, 3 = With the function key display mode is entered)	Read / Write	0
ters	H42	0042d	(002Ah)	Word	Retransmission output control parameter: If this parameter is 0, Retransmission output; off If this parameter is 1, Analog output; 0-20mA Retransmission output If this parameter is 2, Analog output; 4-20mA Retransmission output ATTENTION!! To set this parameter must be H32 = 0	Okunabilir / Yazılabilir	0
ramete	H43	0043d	(002Bh)	Word	Retransmission output lower scala value.	Okunabilir / Yazılabilir	0
	H44	0044d	(002Ch)	Word	Retransmission output upper scala value.	Okunabilir / Yazılabilir	600
Ра	H45	0045d	(002Dh)	Word	Decimal point adjustment for mA and V input	Okunabilir / Yazılabilir	0
o u	H46	0046d	(002Eh)	Word	Users upper scale value for 2-20mA, 4-20mA, 0-10V and 2-10Vamper input selecting	Okunabilir / Yazılabilir	0
atic	H47	0047d	(002Fh)	Word	Users lower scale value for 2-20mA, 4-20mA, 0-10V and 2-10V amper input selecting	Okunabilir / Yazılabilir	9999
onfiguration	H48	0048d	(0030h)	Word	Control output menu, security parameter ( 0 = Menu invisible, 1 = Menu programmable, 2 = Menu only visible )	Read / Write	1
	H49	0049d	(0031h)	Word	Alarm1 output menu security parameter ( 0 = Menu invisible, 1 = Menu programmable, 2 = Menu only visible )	Read / Write	1
S	H50	0050d	(0032h)	Word	Alarm2 output menu, security parameter ( 0 = Menu invisible, 1 = Menu programmable, 2 = Menu only visible )	Read / Write	1
	H51	0051d	(0033h)	Word	Configuration menu, security parameter ( 0 = Menu invisible, 1 = Menu programmable, 2 = Menu only visible )	Read / Write	1
	H52	0052d	(0034h)	Word	Self tune menu, security parameter ( 0 = Menu invisible, 1 = Self tune can be done)	Read / Write	1

# 1.2 Memory Map for Coils

Parameter Number	Coil Addresses	Data Type	Data Content	Read / Write Permission	Factory Defauls
C0	(0000)h	Bit	Alarm2 Status (0 = Active Low ,1 = Active High)	Read / Write	1
C1	(0001)h	Bit	Alarm2 output position in case of Prob failure (0 = Off , 1 = On )	Read / Write	0
C2	(0002)h	Bit	Alarm1 Status (0 = Active Low ,1 = Active High)	Read / Write	1
C3	(0003)h	Bit	Alarm1 output position in case of Prob failure (0 = Off , 1 = On )	Read / Write	0
C4	(0004)h	Bit	Control output configuration (0 = Heat; 1 = Cool)	Read / Write	0
C5	(0005)h	Bit	Temperature unit (0 = °C; 1 = °F)	Read / Write	0
C6	(0006)h	Bit	Control outputs active (0 = Control outputs active, 1 = Only display mode)	Read / Write	0
<b>C</b> 7	(0007)h	Bit	Controlling according to 2nd temperature setpoint (If C7 = 0 is H0, if C7 = 1 is H1)	Read / Write	0
C8	(0008)h	Bit	Auto/Manual selection (0 = Automatic "Running mode", 1 = Manual "Running mode". In this mode, output generated according to H39 parameter.)	Read / Write	0
C9	(0009)h	Bit	Control format in case of probe failure (0 = H10 proportional control according to percentage value, 1 = Error found before the setpoint control is done with the value of the proportional control	Read / Write	0

## 1.3 Memory Map for Input Registers

Parameter Number	Input Register Addresses Desimal (Hex)	Data Type	Data Content	Read / Write Permission
10	0000d (0000h)	Word	Measured temperature	Read Only
11	0001d (0001h)	Word	Percentage of analog output	Read Only
12	0002d (0002h)	Word	Measurement error codes  0 = No error, 1 = Sensor disconnected or broken, 2 = Lower scale error,  3 = Upper scale error, 4 = PT100 short circuit or temperature too low, 5 = Wrong input selection	Read Only
13	0003d (0003h)	Word	Self tune condition codes  0 = No error, 1 = Initial temperature is higher than 60% setpoint value,  2 = Calculating PID parameters, 3 = Calculating power set parameters	Read Only
14	0004d (0004h)	Word	Current (active) temperature setpoint.	Read Only
15	0005d (0005h)	Word	Reserved	Read Only
16	0006d (0006h)	Word	Current (active) decimal point value (0 = No decimal point, 1 = 0.0 Decimal point is tenths	Read Only

# 1.4 Memory Map for Software Revision Input Registers

Software Revision 61472d (F020h) Word	Software name and update is read in ASCII format and as 14 word.  Sample: EU4420-01 22 AUG. 2016.	Read Only
	Memory Formats :	





# ENDA ET SERIES PID TEMPERATURE CONTROLLER MODBUS ADDRESS MAP

#### 1.5 Memory Map for Discrete input

Parametre Numarası	Discrete Input Addresses	Data Type	Data Content	Read / Write Permission
D0	(0000)h	Bit	C/A2 Control output status (0 = OFF ,1 = ON)	Read Only
D1	(0001)h	Bit	A1 Output status (0 = OFF , 1 = ON )	Read Only
D2	(0002)h	Bit	SSR Output status (0 = OFF ,1 = ON)	Read Only
D3	(0003)h	Bit	Digital input status (0 = OFF ,1 = ON)	Read Only

### 2. MODBUS ERROR MESSAGES

Modbus protocol has two types error, communication error and operating error. Reason of the communication error is data corruption in transmission. Parity and CRC control should be done to prevent communication error. Receiver side checks parity and CRC of the data. If they are wrong, the message will be ignored. If format of the data is true but function doesn't perform for any reason, operating error occurs. Slave realizes error and sends error message. Most significant bit of function is changed '1' to indicate error in error message by slave. Error code is sent in data section. Master realizes error type via this message.

#### **ModBus Error Codes**

Error Code	Name	Meaning
01	ILLEGAL FUNCTION	The function code received in the query is not an allowable action for the slave. If a Poll Program Complete command was issued, this code indicates that no program function preceded it.
02	ILLEGAL DATA ADDRESS	The data address received in the query is not an allowable address for the slave.
03	ILLEGAL DATA VALUE	A value contained in the query data field is not an allowable value for the slave.

#### Message example;

Structure of command message (Byte Format)

Device Addres	(0A)h	
Function Code	е	(01)h
Beginning address	MSB	(04)h
of coils.	LSB	(A1)h
Number of coils (N)	MSB	(00)h
	LSB	(01)h
CDC DATA	LSB	(AC)h
CRC DATA	MSB	(63)h

Structure of response message (Byte Format)

Davida - Addus	(0.A)I-	
Device Addres	(0A)h	
Function Code	(81)h	
Error Code	(02)h	
CRC DATA	(B0)h	
CRC DATA	(53)h	

As you see in command message, coil information of (4A1)h = 1185 is required but there isn't any coil with 1185 address. Therefore error code with number (02) (Illegal Data Address) sends.



