X-Ray Experiment

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Abstract—The experiment aims to calculate the Planck Constant h. To calculate the Planck Constant, we have scattered X-Rays from NaCl crystal which are emitted from Molybdenum (Mo42). We have used the characteristic radiations of Mo42 to calibrate our data and we have used Bragg's Law and Duane-Hunt Law to calculate the Planck Constant. We have found the Planck Constant to be $h=6.1\pm1.7\times10^{-34}JHz^{-1}$. The CODATA recommended value is $6.62607015\times10^{-34}JHz^{-1}$ [1]. We are 0.31σ away from the recommended value with %7.9 relative error.

I. THEORY

When an accelerated electron hits an atom whose atomic number is sufficiently big, X-rays are produced. The dominant X-Ray emissions are Bremsstrahlung and de-excitation. [2] "Bremsstrahlung" word is originated from German and it can be translated as "The Breaking Radiation". As the name suggests, the de-acceleration of electron beam creates the Bremsstrahlung. Since the energetic electron beam can lose its energy up to its maximum energy depending on its position and its energy, the produced X-Rays has a continuous spectra. On the other hand, the de-excitation creates a discrete spectra, this discrete spectra depends on excitation energy of the atom. So, it is a Characteristic Radiation. In this experiment, we will use the characteristic radiation to calibrate the data and we will use Bremsstrahlung to calculate the Planck Constant.

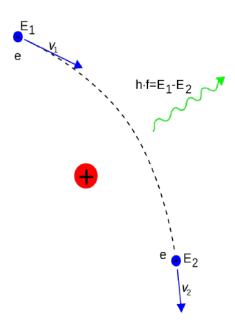


Fig. 1. Bremsstrahlung [3]

We will test the following Theory:

Duane–Hunt law:
$$h\nu_{max} = qV_{acc} \tag{1}$$

where, h is the Planck Constant, $\nu_{max} \mbox{ is the maximum frequency of X-Ray,} \\ \mbox{q is the electron charge,} \\ V_{acc} \mbox{ is the accelerating voltage.}$

Speed of Light:
$$c = \lambda \nu \tag{2}$$

where, c is the speed of light and λ is the wavelength

Using Eq.1 and Eq.2
$$h = \frac{q\lambda_{min}V_{acc}}{c} \tag{3}$$

We know the electron charge, the speed of light and the accelerating frequency, so, if we can obtain the minimum wavelength of the X-Ray, we can obtain the Planck Constant. To obtain minimum wavelength, one can scatter the emitted X-Rays from a crystal. The scattered X-Rays obeys the Bragg's Law:

Bragg's Law:
$$2dsin(\theta) = m\lambda \tag{4}$$

where, d is the spacing between crystal layers, θ is the incident angle, λ is wavelength, and m is the diffraction order.

With the Bragg's Law, we have obtained the wavelengths.

Using Bragg's Law and Eq.3:
$$h = \frac{2dqsin(\theta)V_{acc}}{mc} \tag{5}$$

With the equation 5, we know every parameter at the right-hand side, so we have obtained a reasonable theory to extract the Planck Constant.

II. METHOD

To extract the Planck Constant, we will use the scattering method mentioned in the theory. We have used the Mo42 as the

X-Ray source and NaCl to scatter the emitted X-Rays. We have used the characteristic X-Ray radiations of Mo42 to calibrate our data and used the Duane-Hunt Law and Bragg's Law to extract the Planck Constant.

- 1) Electron beams are created with heating the filament.
- 2) Created electron beams are accelerated with various high voltages. (15kV, 18kV, 21kV, 24kV, 27kV, 30kV, 35kV)
- 3) The emitted X-Rays are gathered with a diaphragm tube.
- 4) The gathered X-Rays from Mo42 are scattered from NaCl.
- The succesive scatterings are counted with Geiger-Muller Counter Tube.
- 6) The collected data is calibrated according to the characteristic X-Rays of Mo42. For calibration, we have used 35kV.
- 7) Using Eq.5, the Planck Constant is extracted.

III. THE EXPERIMENTAL SETUP

- Mo42 atom as the X-Ray source.
- Diaphragm Tube for gathering X-Rays.
- NaCl Crystal for scattering.
- Geiger-Muller Counter Tube.
- Goniometer for angle measurement.
- Computer for getting data.

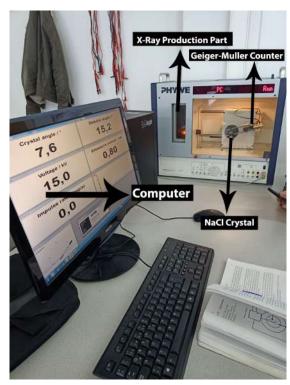


Fig. 2. Apparatus.

IV. THE DATA

The error on angles is 0.1 Deg and on Counts are $\sqrt{N/5}$.

TABLE I: 15kV

| 3.0 25.0 3.1 29.0 3.2 20.0 3.3 11.0 3.4 9.0 3.5 7.0 3.6 2.0 3.7 2.0 3.8 0.0 3.9 1.0 4.0 1.0 4.1 1.0 4.2 1.0 4.3 1.0 4.4 0.0 4.5 0.0 4.6 2.0 4.7 0.0 4.8 2.0 4.9 1.0 5.0 1.0 5.1 1.0 5.2 1.0 5.3 1.0 5.4 0.0 5.5 2.0 5.6 0.0 5.7 1.0 5.8 1.0 5.9 1.0 6.0 0.0 6.1 0.0 6.2 0.0 6.3 1.0 6.5 0.0 6.6 < | Angle(Deg) | Count per Second |
|---|------------|------------------|
| 3.2 20.0 3.3 11.0 3.4 9.0 3.5 7.0 3.6 2.0 3.7 2.0 3.8 0.0 3.9 1.0 4.0 1.0 4.1 1.0 4.2 1.0 4.3 1.0 4.4 0.0 4.5 0.0 4.6 2.0 4.7 0.0 4.8 2.0 4.9 1.0 5.0 1.0 5.1 1.0 5.2 1.0 5.3 1.0 5.4 0.0 5.5 2.0 5.6 0.0 5.7 1.0 5.8 1.0 5.9 1.0 6.0 0.0 6.1 0.0 6.2 0.0 6.3 1.0 6.5 0.0 6.6 1.0 6.7 0.0 | 3.0 | 25.0 |
| 3.3 11.0 3.4 9.0 3.5 7.0 3.6 2.0 3.7 2.0 3.8 0.0 3.9 1.0 4.0 1.0 4.1 1.0 4.2 1.0 4.3 1.0 4.4 0.0 4.5 0.0 4.6 2.0 4.7 0.0 4.8 2.0 4.9 1.0 5.0 1.0 5.1 1.0 5.2 1.0 5.3 1.0 5.4 0.0 5.5 2.0 5.6 0.0 5.7 1.0 5.8 1.0 5.9 1.0 6.0 0.0 6.1 0.0 6.2 0.0 6.3 1.0 6.5 0.0 6.6 1.0 6.7 0.0 | 3.1 | 29.0 |
| 3.4 9.0 3.5 7.0 3.6 2.0 3.7 2.0 3.8 0.0 3.9 1.0 4.0 1.0 4.1 1.0 4.2 1.0 4.3 1.0 4.4 0.0 4.5 0.0 4.6 2.0 4.7 0.0 4.8 2.0 4.9 1.0 5.0 1.0 5.1 1.0 5.2 1.0 5.3 1.0 5.4 0.0 5.5 2.0 5.6 0.0 5.7 1.0 5.8 1.0 5.9 1.0 6.0 0.0 6.1 0.0 6.2 0.0 6.3 1.0 6.5 0.0 6.6 1.0 6.7 0.0 | 3.2 | 20.0 |
| 3.5 7.0 3.6 2.0 3.7 2.0 3.8 0.0 3.9 1.0 4.0 1.0 4.1 1.0 4.2 1.0 4.3 1.0 4.4 0.0 4.5 0.0 4.6 2.0 4.7 0.0 4.8 2.0 4.9 1.0 5.0 1.0 5.1 1.0 5.2 1.0 5.3 1.0 5.4 0.0 5.5 2.0 5.6 0.0 5.7 1.0 5.8 1.0 5.9 1.0 6.0 0.0 6.1 0.0 6.2 0.0 6.3 1.0 6.5 0.0 6.6 1.0 6.7 0.0 | 3.3 | 11.0 |
| 3.6 2.0 3.7 2.0 3.8 0.0 3.9 1.0 4.0 1.0 4.1 1.0 4.2 1.0 4.3 1.0 4.4 0.0 4.5 0.0 4.6 2.0 4.7 0.0 4.8 2.0 4.9 1.0 5.0 1.0 5.1 1.0 5.2 1.0 5.3 1.0 5.4 0.0 5.5 2.0 5.6 0.0 5.7 1.0 5.8 1.0 5.9 1.0 6.0 0.0 6.1 0.0 6.2 0.0 6.3 1.0 6.5 0.0 6.6 1.0 6.7 0.0 | 3.4 | 9.0 |
| 3.7 2.0 3.8 0.0 3.9 1.0 4.0 1.0 4.1 1.0 4.2 1.0 4.3 1.0 4.4 0.0 4.5 0.0 4.6 2.0 4.7 0.0 4.8 2.0 4.9 1.0 5.0 1.0 5.1 1.0 5.2 1.0 5.3 1.0 5.4 0.0 5.5 2.0 5.6 0.0 5.7 1.0 5.8 1.0 5.9 1.0 6.0 0.0 6.1 0.0 6.2 0.0 6.3 1.0 6.4 1.0 6.5 0.0 6.6 1.0 6.7 0.0 | 3.5 | 7.0 |
| 3.8 0.0 3.9 1.0 4.0 1.0 4.1 1.0 4.2 1.0 4.3 1.0 4.4 0.0 4.5 0.0 4.6 2.0 4.7 0.0 4.8 2.0 4.9 1.0 5.0 1.0 5.1 1.0 5.2 1.0 5.3 1.0 5.4 0.0 5.5 2.0 5.6 0.0 5.7 1.0 5.8 1.0 5.9 1.0 6.0 0.0 6.1 0.0 6.2 0.0 6.3 1.0 6.4 1.0 6.5 0.0 6.6 1.0 6.7 0.0 | 3.6 | 2.0 |
| 3.9 1.0 4.0 1.0 4.1 1.0 4.2 1.0 4.3 1.0 4.4 0.0 4.5 0.0 4.6 2.0 4.7 0.0 4.8 2.0 4.9 1.0 5.0 1.0 5.1 1.0 5.2 1.0 5.3 1.0 5.4 0.0 5.5 2.0 5.6 0.0 5.7 1.0 5.8 1.0 5.9 1.0 6.0 0.0 6.1 0.0 6.2 0.0 6.3 1.0 6.4 1.0 6.5 0.0 6.6 1.0 6.7 0.0 | 3.7 | 2.0 |
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| 4.1 1.0 4.2 1.0 4.3 1.0 4.4 0.0 4.5 0.0 4.6 2.0 4.7 0.0 4.8 2.0 4.9 1.0 5.0 1.0 5.1 1.0 5.2 1.0 5.3 1.0 5.4 0.0 5.5 2.0 5.6 0.0 5.7 1.0 5.8 1.0 5.9 1.0 6.0 0.0 6.1 0.0 6.2 0.0 6.3 1.0 6.5 0.0 6.6 1.0 6.7 0.0 | 3.9 | 1.0 |
| 4.2 1.0 4.3 1.0 4.4 0.0 4.5 0.0 4.6 2.0 4.7 0.0 4.8 2.0 4.9 1.0 5.0 1.0 5.1 1.0 5.2 1.0 5.3 1.0 5.4 0.0 5.5 2.0 5.6 0.0 5.7 1.0 5.8 1.0 5.9 1.0 6.0 0.0 6.1 0.0 6.2 0.0 6.3 1.0 6.4 1.0 6.5 0.0 6.6 1.0 6.7 0.0 | 4.0 | 1.0 |
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| 4.4 0.0 4.5 0.0 4.6 2.0 4.7 0.0 4.8 2.0 4.9 1.0 5.0 1.0 5.1 1.0 5.2 1.0 5.3 1.0 5.4 0.0 5.5 2.0 5.6 0.0 5.7 1.0 5.8 1.0 5.9 1.0 6.0 0.0 6.1 0.0 6.2 0.0 6.3 1.0 6.4 1.0 6.5 0.0 6.6 1.0 6.7 0.0 | 4.2 | 1.0 |
| 4.5 0.0 4.6 2.0 4.7 0.0 4.8 2.0 4.9 1.0 5.0 1.0 5.1 1.0 5.2 1.0 5.3 1.0 5.4 0.0 5.5 2.0 5.6 0.0 5.7 1.0 5.8 1.0 5.9 1.0 6.0 0.0 6.1 0.0 6.2 0.0 6.3 1.0 6.4 1.0 6.5 0.0 6.6 1.0 6.7 0.0 | 4.3 | 1.0 |
| 4.6 2.0 4.7 0.0 4.8 2.0 4.9 1.0 5.0 1.0 5.1 1.0 5.2 1.0 5.3 1.0 5.4 0.0 5.5 2.0 5.6 0.0 5.7 1.0 5.8 1.0 5.9 1.0 6.0 0.0 6.1 0.0 6.2 0.0 6.3 1.0 6.4 1.0 6.5 0.0 6.6 1.0 6.7 0.0 | 4.4 | 0.0 |
| 4.7 0.0 4.8 2.0 4.9 1.0 5.0 1.0 5.1 1.0 5.2 1.0 5.3 1.0 5.4 0.0 5.5 2.0 5.6 0.0 5.7 1.0 5.8 1.0 5.9 1.0 6.0 0.0 6.1 0.0 6.2 0.0 6.3 1.0 6.4 1.0 6.5 0.0 6.6 1.0 6.7 0.0 | 4.5 | 0.0 |
| 4.8 2.0 4.9 1.0 5.0 1.0 5.1 1.0 5.2 1.0 5.3 1.0 5.4 0.0 5.5 2.0 5.6 0.0 5.7 1.0 5.8 1.0 5.9 1.0 6.0 0.0 6.1 0.0 6.2 0.0 6.3 1.0 6.4 1.0 6.5 0.0 6.6 1.0 6.7 0.0 | 4.6 | 2.0 |
| 4.9 1.0 5.0 1.0 5.1 1.0 5.2 1.0 5.3 1.0 5.4 0.0 5.5 2.0 5.6 0.0 5.7 1.0 5.8 1.0 5.9 1.0 6.0 0.0 6.1 0.0 6.2 0.0 6.3 1.0 6.4 1.0 6.5 0.0 6.6 1.0 6.7 0.0 | 4.7 | 0.0 |
| 5.0 1.0 5.1 1.0 5.2 1.0 5.3 1.0 5.4 0.0 5.5 2.0 5.6 0.0 5.7 1.0 5.8 1.0 5.9 1.0 6.0 0.0 6.1 0.0 6.2 0.0 6.3 1.0 6.4 1.0 6.5 0.0 6.6 1.0 6.7 0.0 | 4.8 | 2.0 |
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| 5.2 1.0 5.3 1.0 5.4 0.0 5.5 2.0 5.6 0.0 5.7 1.0 5.8 1.0 5.9 1.0 6.0 0.0 6.1 0.0 6.2 0.0 6.3 1.0 6.4 1.0 6.5 0.0 6.6 1.0 6.7 0.0 | 5.0 | 1.0 |
| 5.3 1.0 5.4 0.0 5.5 2.0 5.6 0.0 5.7 1.0 5.8 1.0 5.9 1.0 6.0 0.0 6.1 0.0 6.2 0.0 6.3 1.0 6.4 1.0 6.5 0.0 6.6 1.0 6.7 0.0 | 5.1 | 1.0 |
| 5.4 0.0 5.5 2.0 5.6 0.0 5.7 1.0 5.8 1.0 5.9 1.0 6.0 0.0 6.1 0.0 6.2 0.0 6.3 1.0 6.4 1.0 6.5 0.0 6.6 1.0 6.7 0.0 | 5.2 | 1.0 |
| 5.5 2.0 5.6 0.0 5.7 1.0 5.8 1.0 5.9 1.0 6.0 0.0 6.1 0.0 6.2 0.0 6.3 1.0 6.4 1.0 6.5 0.0 6.6 1.0 6.7 0.0 | 5.3 | 1.0 |
| 5.6 0.0 5.7 1.0 5.8 1.0 5.9 1.0 6.0 0.0 6.1 0.0 6.2 0.0 6.3 1.0 6.4 1.0 6.5 0.0 6.6 1.0 6.7 0.0 | 5.4 | 0.0 |
| 5.7 1.0 5.8 1.0 5.9 1.0 6.0 0.0 6.1 0.0 6.2 0.0 6.3 1.0 6.4 1.0 6.5 0.0 6.6 1.0 6.7 0.0 | 5.5 | 2.0 |
| 5.8 1.0 5.9 1.0 6.0 0.0 6.1 0.0 6.2 0.0 6.3 1.0 6.4 1.0 6.5 0.0 6.6 1.0 6.7 0.0 | 5.6 | 0.0 |
| 5.9 1.0 6.0 0.0 6.1 0.0 6.2 0.0 6.3 1.0 6.4 1.0 6.5 0.0 6.6 1.0 6.7 0.0 | 5.7 | 1.0 |
| 6.0 0.0 6.1 0.0 6.2 0.0 6.3 1.0 6.4 1.0 6.5 0.0 6.6 1.0 6.7 0.0 | 5.8 | 1.0 |
| 6.1 0.0 6.2 0.0 6.3 1.0 6.4 1.0 6.5 0.0 6.6 1.0 6.7 0.0 | 5.9 | 1.0 |
| 6.2 0.0 6.3 1.0 6.4 1.0 6.5 0.0 6.6 1.0 6.7 0.0 | 6.0 | 0.0 |
| 6.3 1.0 6.4 1.0 6.5 0.0 6.6 1.0 6.7 0.0 | 6.1 | 0.0 |
| 6.4 1.0 6.5 0.0 6.6 1.0 6.7 0.0 | 6.2 | 0.0 |
| 6.5 0.0 6.6 1.0 6.7 0.0 | 6.3 | 1.0 |
| 6.6 1.0 6.7 0.0 | 6.4 | 1.0 |
| 6.7 0.0 | 6.5 | 0.0 |
| | 6.6 | 1.0 |
| 6.8 0.0 | 6.7 | 0.0 |
| | 6.8 | 0.0 |

TABLE I: 15kV (Continued)

| Angle(Deg) | Count per Second |
|------------|------------------|
| 6.9 | 0.0 |
| 7.0 | 1.0 |
| 7.1 | 1.0 |
| 7.2 | 0.0 |
| 7.3 | 0.0 |
| 7.4 | 0.0 |
| 7.5 | 0.0 |
| 7.6 | 0.0 |
| 7.7 | 0.0 |
| 7.8 | 1.0 |
| 7.9 | 1.0 |
| 8.0 | 0.0 |
| 8.1 | 0.0 |
| 8.2 | 0.0 |
| 8.3 | 1.0 |
| 8.4 | 1.0 |
| 8.5 | 1.0 |
| 8.6 | 2.0 |
| 8.7 | 2.0 |
| 8.8 | 5.0 |
| 8.9 | 6.0 |
| 9.0 | 9.0 |
| 9.1 | 11.0 |
| 9.2 | 14.0 |
| 9.3 | 16.0 |
| 9.4 | 20.0 |
| 9.5 | 18.0 |
| 9.6 | 25.0 |
| 9.7 | 27.0 |
| 9.8 | 21.0 |
| 9.9 | 22.0 |
| 10.0 | 26.0 |
| 10.1 | 23.0 |
| 10.2 | 25.0 |
| 10.3 | 21.0 |
| 10.4 | 25.0 |
| 10.5 | 27.0 |
| 10.6 | 27.0 |
| 10.7 | 27.0 |

TABLE I: 15kV (Continued)

| Angle(Deg) | Count per Second |
|------------|------------------|
| 10.8 | 27.0 |
| 10.9 | 30.0 |
| 11.0 | 24.0 |
| 11.1 | 30.0 |
| 11.2 | 28.0 |
| 11.3 | 26.0 |
| 11.4 | 28.0 |
| 11.5 | 26.0 |
| 11.6 | 25.0 |
| 11.7 | 27.0 |
| 11.8 | 26.0 |
| 11.9 | 29.0 |
| 12.0 | 25.0 |
| 12.1 | 24.0 |
| 12.2 | 29.0 |
| 12.3 | 25.0 |
| 12.4 | 21.0 |
| | |

TABLE II: 18kV

| Angle(Deg) | Count per Second |
|------------|------------------|
| 3.0 | 57.0 |
| 3.1 | 59.0 |
| 3.2 | 42.0 |
| 3.3 | 26.0 |
| 3.4 | 21.0 |
| 3.5 | 16.0 |
| 3.6 | 8.0 |
| 3.7 | 4.0 |
| 3.8 | 3.0 |
| 3.9 | 2.0 |
| 4.0 | 3.0 |
| 4.1 | 2.0 |
| 4.2 | 3.0 |
| 4.3 | 3.0 |
| 4.4 | 2.0 |
| 4.5 | 2.0 |
| 4.6 | 2.0 |
| 4.7 | 2.0 |
| | |

TABLE II: 18kV (Continued)

| Angle(Deg) | Count per Second |
|------------|------------------|
| 4.8 | 2.0 |
| 4.9 | 2.0 |
| 5.0 | 1.0 |
| 5.1 | 2.0 |
| 5.2 | 2.0 |
| 5.3 | 2.0 |
| 5.4 | 3.0 |
| 5.5 | 2.0 |
| 5.6 | 1.0 |
| 5.7 | 2.0 |
| 5.8 | 2.0 |
| 5.9 | 1.0 |
| 6.0 | 1.0 |
| 6.1 | 2.0 |
| 6.2 | 0.0 |
| 6.3 | 1.0 |
| 6.4 | 1.0 |
| 6.5 | 2.0 |
| 6.6 | 2.0 |
| 6.7 | 1.0 |
| 6.8 | 0.0 |
| 6.9 | 3.0 |
| 7.0 | 2.0 |
| 7.1 | 4.0 |
| 7.2 | 4.0 |
| 7.3 | 5.0 |
| 7.4 | 6.0 |
| 7.5 | 10.0 |
| 7.6 | 15.0 |
| 7.7 | 15.0 |
| 7.8 | 20.0 |
| 7.9 | 29.0 |
| 8.0 | 27.0 |
| 8.1 | 26.0 |
| 8.2 | 32.0 |
| 8.3 | 32.0 |
| 8.4 | 40.0 |
| 8.5 | 41.0 |
| 8.6 | 45.0 |

TABLE II: 18kV (Continued)

| Angle(Deg) | Count per Second |
|------------|------------------|
| 8.7 | 44.0 |
| 8.8 | 46.0 |
| 8.9 | 50.0 |
| 9.0 | 48.0 |
| 9.1 | 57.0 |
| 9.2 | 56.0 |
| 9.3 | 54.0 |
| 9.4 | 54.0 |
| 9.5 | 57.0 |
| 9.6 | 56.0 |
| 9.7 | 60.0 |
| 9.8 | 54.0 |
| 9.9 | 50.0 |
| 10.0 | 44.0 |
| 10.1 | 57.0 |
| 10.2 | 48.0 |
| 10.3 | 48.0 |
| 10.4 | 48.0 |
| 10.5 | 52.0 |
| 10.6 | 44.0 |
| 10.7 | 50.0 |
| 10.8 | 54.0 |
| 10.9 | 50.0 |
| 11.0 | 41.0 |
| 11.1 | 48.0 |
| 11.2 | 51.0 |
| 11.3 | 43.0 |
| 11.4 | 50.0 |
| | |

TABLE III: 21kV

| Angle(Deg) | Count per Second |
|------------|------------------|
| 3.0 | 122.0 |
| 3.1 | 106.0 |
| 3.2 | 86.0 |
| 3.3 | 61.0 |
| 3.4 | 41.0 |
| 3.5 | 25.0 |
| 3.6 | 15.0 |

| TABLE III: | 21kV (| (Continued) |
|------------|--------|-------------|
|------------|--------|-------------|

| Angle(Deg) | Count per Second |
|------------|------------------|
| 3.7 | 6.0 |
| 3.8 | 4.0 |
| 3.9 | 5.0 |
| 4.0 | 5.0 |
| 4.1 | 4.0 |
| 4.2 | 5.0 |
| 4.3 | 6.0 |
| 4.4 | 4.0 |
| 4.5 | 2.0 |
| 4.6 | 4.0 |
| 4.7 | 3.0 |
| 4.8 | 4.0 |
| 4.9 | 5.0 |
| 5.0 | 4.0 |
| 5.1 | 4.0 |
| 5.2 | 4.0 |
| 5.3 | 2.0 |
| 5.4 | 2.0 |
| 5.5 | 3.0 |
| 5.6 | 3.0 |
| 5.7 | 2.0 |
| 5.8 | 1.0 |
| 5.9 | 2.0 |
| 6.0 | 2.0 |
| 6.1 | 5.0 |
| 6.2 | 5.0 |
| 6.3 | 6.0 |
| 6.4 | 9.0 |
| 6.5 | 12.0 |
| 6.6 | 21.0 |
| 6.7 | 21.0 |
| 6.8 | 28.0 |
| 6.9 | 32.0 |
| 7.0 | 34.0 |
| 7.1 | 33.0 |
| 7.2 | 41.0 |
| 7.3 | 38.0 |
| 7.4 | 50.0 |
| 7.5 | 48.0 |

TABLE III: 21kV (Continued)

| Angle(Deg) | Count per Second |
|------------|------------------|
| 7.6 | 57.0 |
| 7.7 | 64.0 |
| 7.8 | 64.0 |
| 7.9 | 68.0 |
| 8.0 | 63.0 |
| 8.1 | 66.0 |
| 8.2 | 72.0 |
| 8.3 | 75.0 |
| 8.4 | 81.0 |
| 8.5 | 79.0 |
| 8.6 | 80.0 |
| 8.7 | 85.0 |
| 8.8 | 78.0 |
| 8.9 | 86.0 |
| 9.0 | 83.0 |
| 9.1 | 84.0 |
| 9.2 | 83.0 |
| 9.3 | 82.0 |
| 9.4 | 82.0 |
| 9.5 | 81.0 |
| 9.6 | 89.0 |
| 9.7 | 91.0 |
| 9.8 | 84.0 |
| 9.9 | 82.0 |
| 10.0 | 78.0 |
| 10.1 | 78.0 |
| 10.2 | 65.0 |
| 10.3 | 79.0 |
| | |

TABLE IV: 24kV

| Angle(Deg) | Count per Second |
|------------|------------------|
| 3.0 | 188.0 |
| 3.1 | 179.0 |
| 3.2 | 121.0 |
| 3.3 | 114.0 |
| 3.4 | 70.0 |
| 3.5 | 44.0 |
| 3.6 | 25.0 |

| TABI | E IV | 24kV | (Continued) |
|------|------|-------|-------------|
| IADL | LIV. | 27K V | (Commucu) |

| 3.7 15.0 3.8 12.0 3.9 12.0 4.0 0.0 4.1 10.0 4.2 9.0 4.3 8.0 4.4 8.0 4.5 8.0 4.6 8.0 4.7 8.0 4.8 7.0 4.9 5.0 5.0 6.0 5.1 7.0 5.2 5.0 5.3 10.0 5.4 8.0 5.5 9.0 5.6 9.0 5.7 11.0 5.8 17.0 5.9 22.0 6.0 22.0 6.1 29.0 6.2 27.0 6.3 39.0 6.4 47.0 6.5 49.0 6.6 42.0 6.7 50.0 6.8 60.0 6.9 62.0 7.0 62.0 7.1 80.0 | Angle(Deg) | Count per Second |
|---|------------|------------------|
| 3.9 12.0 4.0 0.0 4.1 10.0 4.2 9.0 4.3 8.0 4.4 8.0 4.5 8.0 4.6 8.0 4.7 8.0 4.8 7.0 4.9 5.0 5.0 6.0 5.1 7.0 5.2 5.0 5.3 10.0 5.4 8.0 5.5 9.0 5.6 9.0 5.7 11.0 5.8 17.0 5.9 22.0 6.1 29.0 6.2 27.0 6.3 39.0 6.4 47.0 6.5 49.0 6.6 42.0 6.7 50.0 6.8 60.0 6.9 62.0 7.0 62.0 7.1 80.0 7.2 95.0 | 3.7 | 15.0 |
| 4.0 0.0 4.1 10.0 4.2 9.0 4.3 8.0 4.4 8.0 4.5 8.0 4.6 8.0 4.7 8.0 4.8 7.0 5.0 6.0 5.1 7.0 5.2 5.0 5.3 10.0 5.4 8.0 5.5 9.0 5.6 9.0 5.7 11.0 5.8 17.0 5.9 22.0 6.0 22.0 6.1 29.0 6.2 27.0 6.3 39.0 6.4 47.0 6.5 49.0 6.6 42.0 6.7 50.0 6.8 60.0 6.9 62.0 7.0 62.0 7.1 80.0 7.2 95.0 | 3.8 | 12.0 |
| 4.1 10.0 4.2 9.0 4.3 8.0 4.4 8.0 4.5 8.0 4.6 8.0 4.7 8.0 4.8 7.0 4.9 5.0 5.0 6.0 5.1 7.0 5.2 5.0 5.3 10.0 5.4 8.0 5.5 9.0 5.6 9.0 5.7 11.0 5.8 17.0 5.9 22.0 6.1 29.0 6.2 27.0 6.3 39.0 6.4 47.0 6.5 49.0 6.6 42.0 6.7 50.0 6.8 60.0 6.9 62.0 7.0 62.0 7.1 80.0 7.2 95.0 | 3.9 | 12.0 |
| 4.2 9.0 4.3 8.0 4.4 8.0 4.5 8.0 4.6 8.0 4.7 8.0 4.8 7.0 5.0 6.0 5.1 7.0 5.2 5.0 5.3 10.0 5.4 8.0 5.5 9.0 5.6 9.0 5.7 11.0 5.8 17.0 5.9 22.0 6.0 22.0 6.1 29.0 6.2 27.0 6.3 39.0 6.4 47.0 6.5 49.0 6.6 42.0 6.7 50.0 6.8 60.0 6.9 62.0 7.0 62.0 7.1 80.0 7.2 95.0 | 4.0 | 0.0 |
| 4.3 8.0 4.4 8.0 4.5 8.0 4.6 8.0 4.7 8.0 4.8 7.0 4.9 5.0 5.0 6.0 5.1 7.0 5.2 5.0 5.3 10.0 5.4 8.0 5.5 9.0 5.6 9.0 5.7 11.0 5.8 17.0 5.9 22.0 6.0 22.0 6.1 29.0 6.2 27.0 6.3 39.0 6.4 47.0 6.5 49.0 6.6 42.0 6.7 50.0 6.8 60.0 7.0 62.0 7.1 80.0 7.2 95.0 | 4.1 | 10.0 |
| 4.4 8.0 4.5 8.0 4.6 8.0 4.7 8.0 4.8 7.0 4.9 5.0 5.0 6.0 5.1 7.0 5.2 5.0 5.3 10.0 5.4 8.0 5.5 9.0 5.6 9.0 5.7 11.0 5.8 17.0 5.9 22.0 6.1 29.0 6.2 27.0 6.3 39.0 6.4 47.0 6.5 49.0 6.6 42.0 6.7 50.0 6.8 60.0 6.9 62.0 7.0 62.0 7.1 80.0 7.2 95.0 | 4.2 | 9.0 |
| 4.5 8.0 4.6 8.0 4.7 8.0 4.8 7.0 4.9 5.0 5.0 6.0 5.1 7.0 5.2 5.0 5.3 10.0 5.4 8.0 5.5 9.0 5.6 9.0 5.7 11.0 5.8 17.0 5.9 22.0 6.0 22.0 6.1 29.0 6.2 27.0 6.3 39.0 6.4 47.0 6.5 49.0 6.6 42.0 6.7 50.0 6.8 60.0 7.0 62.0 7.1 80.0 7.2 95.0 | 4.3 | 8.0 |
| 4.6 8.0 4.7 8.0 4.8 7.0 4.9 5.0 5.0 6.0 5.1 7.0 5.2 5.0 5.3 10.0 5.4 8.0 5.5 9.0 5.6 9.0 5.7 11.0 5.8 17.0 5.9 22.0 6.0 22.0 6.1 29.0 6.2 27.0 6.3 39.0 6.4 47.0 6.5 49.0 6.6 42.0 6.7 50.0 6.8 60.0 6.9 62.0 7.0 62.0 7.1 80.0 7.2 95.0 | 4.4 | 8.0 |
| 4.7 8.0 4.8 7.0 4.9 5.0 5.0 6.0 5.1 7.0 5.2 5.0 5.3 10.0 5.4 8.0 5.5 9.0 5.6 9.0 5.7 11.0 5.8 17.0 5.9 22.0 6.0 22.0 6.1 29.0 6.2 27.0 6.3 39.0 6.4 47.0 6.5 49.0 6.6 42.0 6.7 50.0 6.8 60.0 6.9 62.0 7.0 62.0 7.1 80.0 7.2 95.0 | 4.5 | 8.0 |
| 4.8 7.0 4.9 5.0 5.0 6.0 5.1 7.0 5.2 5.0 5.3 10.0 5.4 8.0 5.5 9.0 5.6 9.0 5.7 11.0 5.8 17.0 5.9 22.0 6.0 22.0 6.1 29.0 6.2 27.0 6.3 39.0 6.4 47.0 6.5 49.0 6.6 42.0 6.7 50.0 6.8 60.0 6.9 62.0 7.0 62.0 7.1 80.0 7.2 95.0 | 4.6 | 8.0 |
| 4.9 5.0 5.0 6.0 5.1 7.0 5.2 5.0 5.3 10.0 5.4 8.0 5.5 9.0 5.6 9.0 5.7 11.0 5.8 17.0 5.9 22.0 6.0 22.0 6.1 29.0 6.2 27.0 6.3 39.0 6.4 47.0 6.5 49.0 6.6 42.0 6.7 50.0 6.8 60.0 6.9 62.0 7.0 62.0 7.1 80.0 7.2 95.0 | 4.7 | 8.0 |
| 5.0 6.0 5.1 7.0 5.2 5.0 5.3 10.0 5.4 8.0 5.5 9.0 5.6 9.0 5.7 11.0 5.8 17.0 5.9 22.0 6.0 22.0 6.1 29.0 6.2 27.0 6.3 39.0 6.4 47.0 6.5 49.0 6.6 42.0 6.7 50.0 6.8 60.0 6.9 62.0 7.0 62.0 7.1 80.0 7.2 95.0 | 4.8 | 7.0 |
| 5.1 7.0 5.2 5.0 5.3 10.0 5.4 8.0 5.5 9.0 5.6 9.0 5.7 11.0 5.8 17.0 5.9 22.0 6.0 22.0 6.1 29.0 6.2 27.0 6.3 39.0 6.4 47.0 6.5 49.0 6.6 42.0 6.7 50.0 6.8 60.0 6.9 62.0 7.0 62.0 7.1 80.0 7.2 95.0 | 4.9 | 5.0 |
| 5.2 5.0 5.3 10.0 5.4 8.0 5.5 9.0 5.6 9.0 5.7 11.0 5.8 17.0 5.9 22.0 6.0 22.0 6.1 29.0 6.2 27.0 6.3 39.0 6.4 47.0 6.5 49.0 6.6 42.0 6.7 50.0 6.8 60.0 6.9 62.0 7.0 62.0 7.1 80.0 7.2 95.0 | 5.0 | 6.0 |
| 5.3 10.0 5.4 8.0 5.5 9.0 5.6 9.0 5.7 11.0 5.8 17.0 5.9 22.0 6.0 22.0 6.1 29.0 6.2 27.0 6.3 39.0 6.4 47.0 6.5 49.0 6.6 42.0 6.7 50.0 6.8 60.0 6.9 62.0 7.0 62.0 7.1 80.0 7.2 95.0 | 5.1 | 7.0 |
| 5.4 8.0 5.5 9.0 5.6 9.0 5.7 11.0 5.8 17.0 5.9 22.0 6.0 22.0 6.1 29.0 6.2 27.0 6.3 39.0 6.4 47.0 6.5 49.0 6.6 42.0 6.7 50.0 6.8 60.0 6.9 62.0 7.0 62.0 7.1 80.0 7.2 95.0 | 5.2 | 5.0 |
| 5.5 9.0 5.6 9.0 5.7 11.0 5.8 17.0 5.9 22.0 6.0 22.0 6.1 29.0 6.2 27.0 6.3 39.0 6.4 47.0 6.5 49.0 6.6 42.0 6.7 50.0 6.8 60.0 6.9 62.0 7.0 62.0 7.1 80.0 7.2 95.0 | 5.3 | 10.0 |
| 5.6 9.0 5.7 11.0 5.8 17.0 5.9 22.0 6.0 22.0 6.1 29.0 6.2 27.0 6.3 39.0 6.4 47.0 6.5 49.0 6.6 42.0 6.7 50.0 6.8 60.0 6.9 62.0 7.0 62.0 7.1 80.0 7.2 95.0 | 5.4 | 8.0 |
| 5.7 11.0 5.8 17.0 5.9 22.0 6.0 22.0 6.1 29.0 6.2 27.0 6.3 39.0 6.4 47.0 6.5 49.0 6.6 42.0 6.7 50.0 6.8 60.0 6.9 62.0 7.0 62.0 7.1 80.0 7.2 95.0 | 5.5 | 9.0 |
| 5.8 17.0 5.9 22.0 6.0 22.0 6.1 29.0 6.2 27.0 6.3 39.0 6.4 47.0 6.5 49.0 6.6 42.0 6.7 50.0 6.8 60.0 6.9 62.0 7.0 62.0 7.1 80.0 7.2 95.0 | 5.6 | 9.0 |
| 5.9 22.0 6.0 22.0 6.1 29.0 6.2 27.0 6.3 39.0 6.4 47.0 6.5 49.0 6.6 42.0 6.7 50.0 6.8 60.0 6.9 62.0 7.0 62.0 7.1 80.0 7.2 95.0 | 5.7 | 11.0 |
| 6.0 22.0 6.1 29.0 6.2 27.0 6.3 39.0 6.4 47.0 6.5 49.0 6.6 42.0 6.7 50.0 6.8 60.0 6.9 62.0 7.0 62.0 7.1 80.0 7.2 95.0 | 5.8 | 17.0 |
| 6.1 29.0 6.2 27.0 6.3 39.0 6.4 47.0 6.5 49.0 6.6 42.0 6.7 50.0 6.8 60.0 6.9 62.0 7.0 62.0 7.1 80.0 7.2 95.0 | 5.9 | 22.0 |
| 6.2 27.0 6.3 39.0 6.4 47.0 6.5 49.0 6.6 42.0 6.7 50.0 6.8 60.0 6.9 62.0 7.0 62.0 7.1 80.0 7.2 95.0 | 6.0 | 22.0 |
| 6.3 39.0 6.4 47.0 6.5 49.0 6.6 42.0 6.7 50.0 6.8 60.0 6.9 62.0 7.0 62.0 7.1 80.0 7.2 95.0 | 6.1 | 29.0 |
| 6.4 47.0 6.5 49.0 6.6 42.0 6.7 50.0 6.8 60.0 6.9 62.0 7.0 62.0 7.1 80.0 7.2 95.0 | 6.2 | 27.0 |
| 6.5 49.0 6.6 42.0 6.7 50.0 6.8 60.0 6.9 62.0 7.0 62.0 7.1 80.0 7.2 95.0 | 6.3 | 39.0 |
| 6.6 42.0 6.7 50.0 6.8 60.0 6.9 62.0 7.0 62.0 7.1 80.0 7.2 95.0 | 6.4 | 47.0 |
| 6.7 50.0 6.8 60.0 6.9 62.0 7.0 62.0 7.1 80.0 7.2 95.0 | 6.5 | 49.0 |
| 6.8 60.0 6.9 62.0 7.0 62.0 7.1 80.0 7.2 95.0 | 6.6 | 42.0 |
| 6.9 62.0 7.0 62.0 7.1 80.0 7.2 95.0 | 6.7 | 50.0 |
| 7.0 62.0 7.1 80.0 7.2 95.0 | 6.8 | 60.0 |
| 7.1 80.0 7.2 95.0 | 6.9 | 62.0 |
| 7.2 95.0 | 7.0 | 62.0 |
| | 7.1 | 80.0 |
| 7.3 109.0 | 7.2 | 95.0 |
| | 7.3 | 109.0 |
| 7.4 114.0 | 7.4 | 114.0 |
| 7.5 110.0 | 7.5 | 110.0 |

Continued on next page

TABLE IV: 24kV (Continued)

| Angle(Deg) | Count per Second |
|------------|------------------|
| 7.6 | 115.0 |
| 7.7 | 158.0 |
| 7.8 | 109.0 |
| 7.9 | 86.0 |
| 8.0 | 87.0 |
| 8.1 | 92.0 |
| 8.2 | 92.0 |
| 8.3 | 89.0 |
| 8.4 | 94.0 |
| 8.5 | 91.0 |
| 8.6 | 102.0 |
| 8.7 | 92.0 |
| 8.8 | 96.0 |
| 8.9 | 99.0 |
| 9.0 | 98.0 |
| 9.1 | 94.0 |
| 9.2 | 99.0 |
| 9.3 | 105.0 |
| 9.4 | 107.0 |
| 9.5 | 102.0 |
| 9.6 | 99.0 |
| 9.7 | 98.0 |
| 9.8 | 99.0 |
| 9.9 | 91.0 |
| 10.0 | 94.0 |
| 10.1 | 86.0 |
| 10.2 | 85.0 |
| 10.3 | 85.0 |
| 10.4 | 77.0 |
| 10.5 | 85.0 |
| 10.6 | 79.0 |
| 10.7 | 80.0 |
| 10.8 | 78.0 |
| | |

TABLE V: 27kV

| Angle(Deg) | Count per Second |
|------------|------------------|
| 3.0 | 294.0 |
| 3.1 | 273.0 |

TABLE V: 27kV (Continued)

| Angle(Deg) | Count per Second |
|------------|------------------|
| 3.2 | 188.0 |
| 3.3 | 159.0 |
| 3.4 | 106.0 |
| 3.5 | 66.0 |
| 3.6 | 42.0 |
| 3.7 | 32.0 |
| 3.8 | 19.0 |
| 3.9 | 22.0 |
| 4.0 | 21.0 |
| 4.1 | 21.0 |
| 4.2 | 15.0 |
| 4.3 | 14.0 |
| 4.4 | 14.0 |
| 4.5 | 12.0 |
| 4.6 | 15.0 |
| 4.7 | 15.0 |
| 4.8 | 15.0 |
| 4.9 | 15.0 |
| 5.0 | 22.0 |
| 5.1 | 18.0 |
| 5.2 | 26.0 |
| 5.3 | 26.0 |
| 5.4 | 30.0 |
| 5.5 | 34.0 |
| 5.6 | 39.0 |
| 5.7 | 39.0 |
| 5.8 | 48.0 |
| 5.9 | 51.0 |
| 6.0 | 52.0 |
| 6.1 | 64.0 |
| 6.2 | 66.0 |
| 6.3 | 66.0 |
| 6.4 | 76.0 |
| 6.5 | 85.0 |
| 6.6 | 89.0 |
| 6.7 | 87.0 |
| 6.8 | 95.0 |
| 6.9 | 114.0 |
| 7.0 | 115.0 |
| | |

TABLE V: 27kV (Continued)

| Angle(Deg) | Count per Second |
|------------|------------------|
| 7.1 | 142.0 |
| 7.2 | 159.0 |
| 7.3 | 194.0 |
| 7.4 | 210.0 |
| 7.5 | 218.0 |
| 7.6 | 236.0 |
| 7.7 | 304.0 |
| 7.8 | 202.0 |
| 7.9 | 114.0 |
| 8.0 | 118.0 |
| 8.1 | 121.0 |
| 8.2 | 119.0 |
| 8.3 | 123.0 |
| 8.4 | 123.0 |
| 8.5 | 120.0 |
| 8.6 | 131.0 |
| 8.7 | 130.0 |
| 8.8 | 135.0 |
| 8.9 | 122.0 |
| 9.0 | 132.0 |
| 9.1 | 126.0 |
| 9.2 | 123.0 |
| 9.3 | 121.0 |
| 9.4 | 129.0 |
| 9.5 | 135.0 |
| 9.6 | 133.0 |
| 9.7 | 127.0 |
| 9.8 | 131.0 |
| 9.9 | 121.0 |
| 10.0 | 117.0 |
| 10.1 | 116.0 |
| 10.2 | 109.0 |
| 10.3 | 117.0 |
| 10.4 | 114.0 |
| 10.5 | 108.0 |
| 10.6 | 110.0 |
| 10.7 | 114.0 |
| 10.8 | 119.0 |
| 10.9 | 119.0 |
| | . 1 |

TABLE V: 27kV (Continued)

| Angle(Deg) | Count per Second |
|------------|------------------|
| 11.0 | 117.0 |
| 11.1 | 109.0 |
| 11.2 | 110.0 |
| 11.3 | 116.0 |
| 11.4 | 110.0 |
| 11.5 | 98.0 |
| 11.6 | 103.0 |
| 11.7 | 108.0 |

TABLE VI: 30kV

| A 1 (D) | |
|------------|------------------|
| Angle(Deg) | Count per Second |
| 3.0 | 403.0 |
| 3.1 | 386.0 |
| 3.2 | 272.0 |
| 3.3 | 196.0 |
| 3.4 | 144.0 |
| 3.5 | 103.0 |
| 3.6 | 69.0 |
| 3.7 | 55.0 |
| 3.8 | 40.0 |
| 3.9 | 39.0 |
| 4.0 | 37.0 |
| 4.1 | 33.0 |
| 4.2 | 29.0 |
| 4.3 | 29.0 |
| 4.4 | 29.0 |
| 4.5 | 34.0 |
| 4.6 | 31.0 |
| 4.7 | 35.0 |
| 4.8 | 34.0 |
| 4.9 | 44.0 |
| 5.0 | 48.0 |
| 5.1 | 0.0 |
| 5.2 | 61.0 |
| 5.3 | 70.0 |
| 5.4 | 75.0 |
| 5.5 | 74.0 |
| 5.6 | 88.0 |
| | |

TABLE VI: 30kV (Continued)

| Angle(Deg) | Count per Second |
|------------|------------------|
| 5.7 | 83.0 |
| 5.8 | 77.0 |
| 5.9 | 85.0 |
| 6.0 | 88.0 |
| 6.1 | 86.0 |
| 6.2 | 89.0 |
| 6.3 | 111.0 |
| 6.4 | 117.0 |
| 6.5 | 129.0 |
| 6.6 | 125.0 |
| 6.7 | 130.0 |
| 6.8 | 144.0 |
| 6.9 | 166.0 |
| 7.0 | 163.0 |
| 7.1 | 218.0 |
| 7.2 | 274.0 |
| 7.3 | 297.0 |
| 7.4 | 339.0 |
| 7.5 | 311.0 |
| 7.6 | 375.0 |
| 7.7 | 499.0 |
| 7.8 | 316.0 |
| 7.9 | 147.0 |
| 8.0 | 130.0 |
| 8.1 | 141.0 |
| 8.2 | 142.0 |
| 8.3 | 146.0 |
| 8.4 | 148.0 |
| 8.5 | 152.0 |
| 8.6 | 169.0 |
| 8.7 | 151.0 |
| 8.8 | 151.0 |
| 8.9 | 152.0 |
| 9.0 | 148.0 |
| 9.1 | 169.0 |
| 9.2 | 159.0 |
| 9.3 | 161.0 |
| 9.4 | 164.0 |
| 9.5 | 161.0 |
| | |

| TABLE VI: | 30kV | (Continued) |
|-----------|------|-------------|
| | | |

| Angle(Deg) | Count per Second |
|------------|------------------|
| 9.6 | 157.0 |
| 9.7 | 168.0 |
| 9.8 | 164.0 |
| 9.9 | 152.0 |
| 10.0 | 165.0 |
| 10.1 | 152.0 |
| 10.2 | 151.0 |
| 10.3 | 145.0 |
| 10.4 | 141.0 |
| 10.5 | 153.0 |
| 10.6 | 140.0 |
| 10.7 | 146.0 |
| 10.8 | 144.0 |
| 10.9 | 144.0 |
| 11.0 | 144.0 |
| 11.1 | 150.0 |
| 11.2 | 138.0 |
| 11.3 | 137.0 |
| 11.4 | 142.0 |
| 11.5 | 135.0 |
| 11.6 | 125.0 |
| 11.7 | 133.0 |
| 11.8 | 130.0 |
| 11.9 | 133.0 |
| 12.0 | 126.0 |
| 12.1 | 122.0 |
| 12.2 | 128.0 |
| 12.3 | 113.0 |
| 12.4 | 126.0 |
| 12.5 | 123.0 |
| 12.6 | 121.0 |
| 12.7 | 123.0 |
| 12.8 | 121.0 |
| 12.9 | 121.0 |
| 13.0 | 122.0 |
| 13.1 | 133.0 |
| 13.2 | 138.0 |
| 13.3 | 178.0 |
| 13.4 | 199.0 |

TABLE VI: 30kV (Continued)

| Angle(Deg) | Count per Second |
|------------|------------------|
| 13.5 | 171.0 |
| 13.6 | 122.0 |
| 13.7 | 116.0 |
| 13.8 | 130.0 |
| 13.9 | 104.0 |
| 14.0 | 120.0 |
| 14.1 | 114.0 |
| 14.2 | 119.0 |
| 14.3 | 121.0 |
| 14.4 | 120.0 |
| 14.5 | 121.0 |
| 14.6 | 106.0 |
| 14.7 | 127.0 |
| 14.8 | 143.0 |
| 14.9 | 277.0 |
| 15.0 | 480.0 |
| | |

TABLE VII: 30kV - Calibration

| Angle(Deg) | Count per Second |
|------------|------------------|
| 3 | 923 |
| 3.1 | 768 |
| 3.2 | 489 |
| 3.3 | 343 |
| 3.4 | 257 |
| 3.5 | 187 |
| 3.6 | 135 |
| 3.7 | 124 |
| 3.8 | 117 |
| 3.9 | 105 |
| 4 | 107 |
| 4.1 | 98 |
| 4.2 | 100 |
| 4.3 | 95 |
| 4.4 | 94 |
| 4.5 | 123 |
| 4.6 | 138 |
| 4.7 | 135 |
| 4.8 | 156 |

TABLE VII: 30kV - Calibration (Continued)

| Angle(Deg) | Count per Second |
|------------|------------------|
| 4.9 | 150 |
| 5 | 165 |
| 5.1 | 154 |
| 5.2 | 157 |
| 5.3 | 162 |
| 5.4 | 159 |
| 5.5 | 142 |
| 5.6 | 155 |
| 5.7 | 144 |
| 5.8 | 144 |
| 5.9 | 133 |
| 6 | 141 |
| 6.1 | 139 |
| 6.2 | 143 |
| 6.3 | 173 |
| 6.4 | 184 |
| 6.5 | 201 |
| 6.6 | 205 |
| 6.7 | 202 |
| 6.8 | 234 |
| 6.9 | 284 |
| 7 | 269 |
| 7.1 | 355 |
| 7.2 | 428 |
| 7.3 | 494 |
| 7.4 | 600 |
| 7.5 | 596 |
| 7.6 | 712 |
| 7.7 | 930 |
| 7.8 | 631 |
| 7.9 | 217 |
| 8 | 221 |
| 8.1 | 219 |
| 8.2 | 211 |
| 8.3 | 213 |
| 8.4 | 222 |
| 8.5 | 226 |
| 8.6 | 239 |
| | |

Continued on next page

TABLE VII: 30kV - Calibration (Continued)

| Angle(Deg) | Count per Second |
|------------|----------------------|
| 8.7 | 238 |
| 8.8 | 239 |
| 8.9 | 226 |
| 9 | 239 |
| 9.1 | 229 |
| 9.2 | 239 |
| 9.3 | 248 |
| 9.4 | 237 |
| 9.5 | 236 |
| 9.6 | 244 |
| 9.7 | 240 |
| 9.8 | 236 |
| 9.9 | 243 |
| 10 | 224 |
| 10.1 | 217 |
| 10.2 | 210 |
| 10.3 | 208 |
| 10.4 | 203 |
| 10.5 | 205 |
| 10.6 | 203 |
| 10.7 | 204 |
| 10.8 | 200 |
| 10.9 | 187 |
| 11 | 197 |
| 11.1 | 199 |
| 11.2 | 192 |
| 11.3 | 187 |
| 11.4 | 182 |
| 11.5 | 184 |
| 11.6 | 182 |
| 11.7 | 192 |
| 11.8 | 186 |
| 11.9 | 173 |
| 12 | 171 |
| 12.1 | 173 |
| 12.2 | 170 |
| 12.3 | 176 |
| 12.4 | 168 |
| | ntinuad on navt nasa |

TABLE VII: 30kV - Calibration (Continued)

| Angle(Deg) | Count per Second |
|------------|------------------|
| 12.5 | 174 |
| 12.6 | 181 |
| 12.7 | 170 |
| 12.8 | 162 |
| 12.9 | 170 |
| 13 | 171 |
| 13.1 | 193 |
| 13.2 | 215 |
| 13.3 | 263 |
| 13.4 | 337 |
| 13.5 | 271 |
| 13.6 | 184 |
| 13.7 | 169 |
| 13.8 | 166 |
| 13.9 | 165 |
| 14 | 166 |
| 14.1 | 172 |
| 14.2 | 156 |
| 14.3 | 153 |
| 14.4 | 159 |
| 14.5 | 171 |
| 14.6 | 177 |
| 14.7 | 199 |
| 14.8 | 222 |
| 14.9 | 429 |
| 15 | 810 |
| 15.1 | 810 |
| 15.2 | 442 |
| 15.3 | 226 |
| 15.4 | 167 |
| 15.5 | 131 |
| 15.6 | 130 |
| 15.7 | 123 |
| 15.8 | 129 |
| 15.9 | 110 |
| 16 | 114 |
| 16.1 | 116 |
| 16.2 | 116 |
| | |

Continued on next page

TABLE VII: 30kV - Calibration (Continued)

| Angle(Deg) | Count per Second |
|------------|------------------|
| 16.3 | 105 |
| 16.4 | 112 |
| 16.5 | 102 |
| 16.6 | 103 |
| 16.7 | 108 |
| 16.8 | 107 |
| 16.9 | 89 |
| 17 | 95 |
| 17.1 | 93 |
| 17.2 | 86 |
| 17.3 | 84 |
| 17.4 | 80 |
| 17.5 | 86 |
| 17.6 | 84 |
| 17.7 | 80 |
| 17.8 | 74 |
| 17.9 | 82 |
| 18 | 72 |
| 18.1 | 78 |
| 18.2 | 75 |
| 18.3 | 74 |
| 18.4 | 74 |
| 18.5 | 77 |
| 18.6 | 75 |
| 18.7 | 75 |
| 18.8 | 69 |
| 18.9 | 68 |
| 19 | 75 |
| 19.1 | 71 |
| 19.2 | 79 |
| 19.3 | 68 |
| 19.4 | 69 |
| 19.5 | 68 |
| 19.6 | 62 |
| 19.7 | 71 |
| 19.8 | 69 |
| 19.9 | 66 |
| 20 | 92 |
| | ntinuad on nout |

TABLE VII: 30kV - Calibration (Continued)

| Angle(Deg) | Count per Second |
|------------|------------------|
| 20.1 | 96 |
| 20.2 | 67 |
| 20.3 | 65 |
| 20.4 | 54 |
| 20.5 | 53 |
| 20.6 | 52 |
| 20.7 | 47 |
| 20.8 | 49 |
| 20.9 | 48 |
| 21 | 51 |
| 21.1 | 48 |
| 21.2 | 48 |
| 21.3 | 46 |
| 21.4 | 51 |
| 21.5 | 47 |
| 21.6 | 46 |
| 21.7 | 49 |
| 21.8 | 47 |
| 21.9 | 54 |
| 22 | 50 |
| 22.1 | 57 |
| 22.2 | 58 |
| 22.3 | 56 |
| 22.4 | 64 |
| 22.5 | 125 |
| 22.6 | 191 |
| 22.7 | 190 |
| 22.8 | 151 |
| 22.9 | 73 |
| 23 | 52 |
| 23.1 | 48 |
| 23.2 | 52 |
| 23.3 | 41 |
| 23.4 | 43 |
| 23.5 | 39 |
| 23.6 | 41 |
| 23.7 | 47 |
| 23.8 | 36 |
| | |

Continued on next page

TABLE VII: 30kV - Calibration (Continued)

| Angle(Deg) | Count per Second |
|------------|------------------|
| 23.9 | 38 |
| 24 | 40 |
| 24.1 | 35 |
| 24.2 | 32 |
| 24.3 | 36 |
| 24.4 | 40 |
| 24.5 | 35 |
| 24.6 | 39 |
| 24.7 | 37 |
| 24.8 | 37 |
| 24.9 | 31 |
| 25 | 35 |
| 25.1 | 32 |
| 25.2 | 33 |
| 25.3 | 29 |
| 25.4 | 33 |
| 25.5 | 33 |
| 25.6 | 32 |
| 25.7 | 32 |
| 25.8 | 31 |
| 25.9 | 27 |
| 26 | 30 |
| 26.1 | 31 |
| 26.2 | 28 |
| 26.3 | 28 |
| 26.4 | 29 |
| 26.5 | 32 |
| 26.6 | 31 |
| 26.7 | 28 |
| 26.8 | 25 |
| 26.9 | 30 |
| 27 | 38 |
| 27.1 | 35 |
| 27.2 | 34 |
| 27.3 | 28 |
| 27.4 | 29 |
| 27.5 | 32 |
| 27.6 | 31 |
| | |

TABLE VII: 30kV - Calibration (Continued)

| Angle(Deg) | Count per Second |
|------------|------------------|
| 27.7 | 27 |
| 27.8 | 25 |
| 27.9 | 33 |
| 28 | 27 |
| 28.1 | 26 |
| 28.2 | 25 |
| 28.3 | 28 |
| 28.4 | 28 |
| 28.5 | 26 |
| 28.6 | 25 |
| 28.7 | 20 |
| 28.8 | 25 |
| 28.9 | 27 |
| 29 | 23 |
| 29.1 | 23 |
| 29.2 | 27 |
| 29.3 | 25 |
| 29.4 | 22 |
| 29.5 | 26 |
| 29.6 | 27 |
| 29.7 | 29 |
| 29.8 | 24 |
| 29.9 | 28 |
| 30 | 25 |
| 30.1 | 20 |
| 30.2 | 25 |
| 30.3 | 28 |
| 30.4 | 27 |
| 30.5 | 39 |
| 30.6 | 54 |
| 30.7 | 55 |
| 30.8 | 42 |
| 30.9 | 35 |
| 31 | 27 |
| 31.1 | 26 |
| 31.2 | 23 |
| 31.3 | 21 |
| 31.4 | 21 |

Continued on next page

TABLE VII: 30kV - Calibration (Continued)

| Angle(Deg) | Count per Second |
|------------|------------------|
| 31.5 | 23 |
| 31.6 | 18 |
| 31.7 | 19 |
| 31.8 | 20 |
| 31.9 | 22 |
| 32 | 24 |
| 32.1 | 19 |
| 32.2 | 19 |
| 32.3 | 17 |
| 32.4 | 18 |
| 32.5 | 18 |
| 32.6 | 20 |
| 32.7 | 17 |
| 32.8 | 21 |
| 32.9 | 18 |
| 33 | 15 |
| 33.1 | 18 |
| 33.2 | 15 |
| 33.3 | 19 |
| 33.4 | 17 |
| 33.5 | 17 |
| 33.6 | 17 |
| 33.7 | 16 |
| 33.8 | 20 |
| 33.9 | 18 |
| 34 | 17 |
| 34.1 | 16 |
| 34.2 | 18 |
| 34.3 | 16 |
| 34.4 | 14 |
| 34.5 | 14 |
| 34.6 | 18 |
| 34.7 | 17 |
| 34.8 | 15 |
| 34.9 | 15 |
| 35 | 19 |
| 35.1 | 17 |
| 35.2 | 13 |
| | |

TABLE VII: 30kV - Calibration (Continued)

| Angle(Deg) | Count per Second |
|------------|------------------|
| 35.3 | 13 |
| 35.4 | 17 |
| 35.5 | 13 |
| 35.6 | 13 |
| 35.7 | 13 |
| 35.8 | 12 |
| 35.9 | 17 |
| 36 | 15 |
| 36.1 | 16 |
| 36.2 | 17 |
| 36.3 | 13 |
| 36.4 | 16 |
| 36.5 | 17 |
| 36.6 | 15 |
| 36.7 | 12 |
| 36.8 | 13 |
| 36.9 | 12 |
| 37 | 12 |
| 37.1 | 13 |
| 37.2 | 16 |
| 37.3 | 16 |
| 37.4 | 14 |
| 37.5 | 14 |
| 37.6 | 13 |
| 37.7 | 14 |
| 37.8 | 13 |
| 37.9 | 15 |
| 38 | 12 |
| 38.1 | 14 |
| 38.2 | 12 |
| 38.3 | 14 |
| 38.4 | 14 |
| 38.5 | 11 |
| 38.6 | 12 |
| 38.7 | 15 |
| 38.8 | 14 |
| 38.9 | 13 |
| 39.0 | 11 |
| | |

Continued on next page

TABLE VII: 30kV - Calibration (Continued)

| Angle(Deg) | Count per Second |
|------------|------------------|
| 39.1 | 12 |
| 39.2 | 15 |
| 39.3 | 13 |
| 39.4 | 18 |
| 39.5 | 16 |
| 39.6 | 17 |
| 39.7 | 15 |
| 39.8 | 10 |
| 39.9 | 13 |
| 40.0 | 12 |
| 40.1 | 13 |
| 40.2 | 8 |
| 40.3 | 13 |
| 40.4 | 12 |
| 40.5 | 11 |
| 40.6 | 13 |
| 40.7 | 11 |
| 40.8 | 9 |
| 40.9 | 11 |
| 41.0 | 11 |
| 41.1 | 11 |
| 41.2 | 12 |
| 41.3 | 11 |
| 41.4 | 9 |
| 41.5 | 13 |
| 41.6 | 9 |
| 41.7 | 11 |
| 41.8 | 10 |
| 41.9 | 11 |
| 42.0 | 11 |
| 42.1 | 11 |
| 42.2 | 9 |
| 42.3 | 8 |
| 42.4 | 12 |
| 42.5 | 11 |
| 42.6 | 11 |
| 42.7 | 10 |
| 42.8 | 9 |
| | |

TABLE VII: 30kV - Calibration (Continued)

| Angle(Deg) | Count per Second |
|------------|------------------|
| 42.9 | 10 |
| 43.0 | 8 |
| 43.1 | 11 |
| 43.2 | 8 |
| 43.3 | 9 |
| 43.4 | 10 |
| 43.5 | 10 |
| 43.6 | 10 |
| 43.7 | 12 |
| 43.8 | 9 |
| 43.9 | 9 |
| 44.0 | 11 |
| 44.1 | 8 |
| 44.2 | 8 |
| 44.3 | 9 |
| 44.4 | 10 |
| 44.5 | 8 |
| 44.6 | 11 |
| 44.7 | 10 |
| 44.8 | 9 |
| 44.9 | 10 |
| 45.0 | 11 |
| - | |

V. THE ANALYSIS

We have used 35kV upto 45 degree to calibrate the proceeding data. As can be seen at Fig.3, we have counted very high X-Rays at the very first angles. This is due to that the Geiger-Muller Tube looks straight to the diaphragm, so the tube also counts non-scattered X-Rays. Therefore, the data at very first angles/wavelengths of figures are meaningless.

We have obtained the theoretical angles corresponds to K_{α} and K_{β} according to the Eq.5. The characteristic energies are $K_{\alpha_1}=17,479.34eV,~K_{\alpha_2}=17,374.3eV,~K_{\beta_1}=19,608.3eV$ [4]. Since the ratio of intensities of K_{α_1} and K_{α_2} is approximately 2:1, we have taken the weighted average of them to obtain K_{alpha} [5].

We have Gauss Fitted the characteristic emissions as can be seen at Fig.3. The emissions occur as a spike in the continues spectra. The first spike is the merging of K_{α} and K_{β} . Since their energy is similar for m=1, we have used the average value of K_{α} and K_{β} for the first spike.

We have taken the uncertainty on the Count as $\sqrt{N/5}$ and on the angle as 0.1.

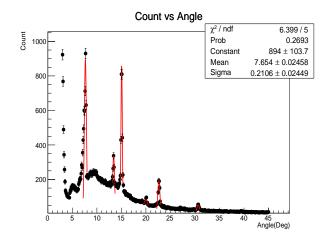


Fig. 3. Experimental Characteristic X-Rays

We have obtained the theoretical and experimental angles to calibrate the data. As can be seen from Fig.4, the calibration obeys the linear equation with Interception = 0.1594 +- 0.03085 and Slope = 0.922 +- 0.001688.

TABLE VIII
THEORETICAL AND EXPERIMENTAL ANGLES

| Spike Number | Theoretical | Experimental |
|--------------|-------------|-------------------|
| 1 | 6.83828 Deg | 7.65 +- 0.02 Deg |
| 2 | 12.9571 Deg | 13.41 +- 0.05 Deg |
| 3 | 14.598 Deg | 15.05 +- 0.05 Deg |
| 4 | 19.6536 Deg | 19.98 +- 0.06 Deg |
| 5 | 22.2132 Deg | 22.64 +- 0.03 Deg |
| 6 | 26.6438 Deg | 30.65 +- 0.04 Deg |

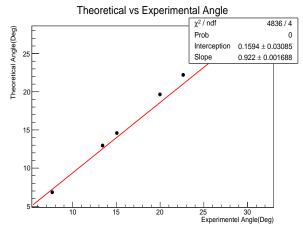


Fig. 4. Calibration - Linear Fit

The χ^2 value of Fig.4 is not close to 1 because of that there is no error on theoretical value.

We have used the uncertainties given by the Root's fit. To calculate the uncertainties of angle and wavelengths, we have used the general formula:

General Case:

$$\sigma_y^2 = \sum_{i}^{m} \left(\frac{\partial f}{\partial x_i}\right)^2 \sigma_i^2 + \sum_{j>i}^{m} \left(\frac{\partial f}{\partial x_i}\right) \left(\frac{\partial f}{\partial x_j}\right) \sigma_{ij}^2 \tag{C.14}$$

In the following special cases, it was assumed that there is no correlation between the variables, $\sigma_{ij} = 0$.

Fig. 5. Error Propogation. [2]

To calculate the calibrated angles and the uncertainties, we have used the following equation:

Calculating Calibrated Angles:

$$\theta_{calibrated} = \theta slope + intercept$$

Calculating Uncertainty of Calibrated Angle:

$$\sigma_{\theta_{calibrated}} = \sqrt{(slope)^2 \sigma_{\theta}^2 + \theta^2 \sigma_{slope}^2 + \sigma_{intercept}^2}$$

To calculate the wavelength corresponding to the angles, we have used the Bragg's Law and to calculate the uncertainty of the wavelengths, we have used the following equation:

Calculating Uncertainty of Wavelength:

$$\sigma_{\lambda} = \sqrt{(2Sin(\theta_{calibrated}))^2 \sigma_d^2 + (2dCos(\theta_{calibrated}))^2 \sigma_{\theta_{calibrated}}^2}$$

where,
$$d = 282.0 + 0.1 \text{ pm}$$

The following plots are created with the raw data and the calibration equation. As can be seen at Fig.5-10, after a certain wavelength, the accumulation rate increases. We have fitted a line to obtain the minimum wavelength.

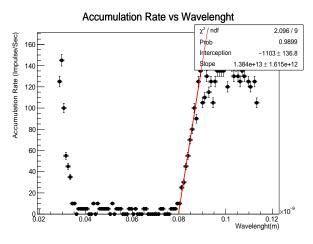


Fig. 6. 15kV

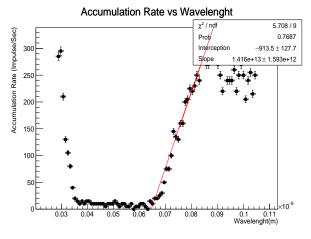


Fig. 7. 18kV

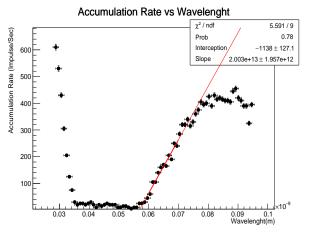


Fig. 8. 21kV

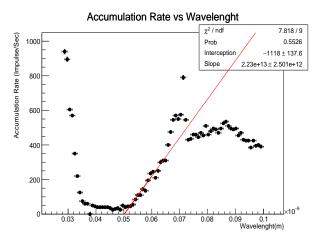


Fig. 9. 24kV

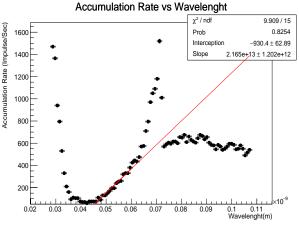
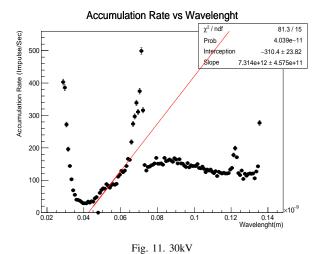


Fig. 10. 27kV



We have used the acceleration voltage to obtain the energy and the minimum wavelength to obtain the maximum frequency using Eq.2.

TABLE IX
FREQUENCY AND WAVELENGTH FOR APPLIED VOLTS

| Applied Volt | λ_{min} | ν_{max} |
|-----------------------|----------------------|-----------------------|
| $15 \pm 1 \text{ kV}$ | 8.0e-11 +- 1.4e-11 m | 3.8e+18 +- 0.6e+18 Hz |
| $18 \pm 1 \text{ kV}$ | 6.4e-11 +- 1.2e-11 m | 4.6e+18 +- 0.8e+18 Hz |
| $21 \pm 1 \text{ kV}$ | 5.7e-11 +- 0.8e-11 m | 5.3e+18 +- 0.8e+18 Hz |
| $24 \pm 1 \text{ kV}$ | 5.0e-11 +- 0.8e-11 m | 6.0e+18 +- 1.0e+18 Hz |
| $27 \pm 1 \text{ kV}$ | 4.3e-11 +- 0.4e-11 m | 7.0e+18 +- 0.6e18 Hz |
| $30 \pm 1 \text{ kV}$ | 4.2e-11 +- 0.4e-11 m | 7.1e+18 +- 0.7e+18 Hz |
| | | |

As Duane-Hunt Law states, there is a linear relation between the energy and the corresponding maximum frequency. The slope of the linear relation is exactly the Planck Constant.

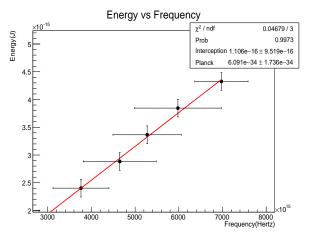


Fig. 12. Planck Constant

We have obtained the Planck Constant with the linear fit.

VI. THE RESULT

We have found the Planck Constant to be $h=6.1\pm1.7\times10^{-34}JHz^-1$. The CODATA recommended value is $6.62607015\times10^{-34}JHz^-1$ [1]. We are 0.31σ away with %7.9 relative error.

VII. THE CONCLUSION

We have found the Planck Constant to be $h=6.1\pm1.7\times10^{-34}JHz^-1$. The CODATA recommended value is $6.62607015\times10^{-34}JHz^-1$ [1]. We are 0.31σ away with %7.9 relative error. So, we have concluded that the experiment was a success. However, the uncertainty on the Planck Constant is not sufficiently small, this is due to the apparatus we have used is not adequate for calculating with a high precision.

Moreover, we have observed a high accumulation at the low wavelengths, this is because of that the Geiger-Muller counter look straight to the diaphragm, so it counts non-scattered X-Rays too. So, for a better data the diaphragm could be made smaller.

Another problem we have observed is that, the Geiger-Muller Counter counts several radiations even if we do not apply voltage. This is due to the background radiation. A better shielded environment could lead to a better calculation.

REFERENCES

- [1] CODATA Value: Planck constant. URL: https://physics.nist.gov/cgi-bin/cuu/Value?h (visited on 05/10/2023).
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- [4] Molybdenum. URL: https://xdb.lbl.gov/Section1/Periodic_ Table/Mo Web data.htm (visited on 05/10/2023).
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VIII. APPENDIX

The fit has been done with Root's built-in function (See Fig.3-11). We have used root release 6.28/00 for Ubuntu22.

Macro for Calibration:

```
TCanvas *c1 = new TCanvas();
TTree *tree = new TTree("tree", "tree");
                                                   TGraphErrors *graph = new
tree->ReadFile("XRAY_data/calibration.csv");
                                                       TGraphErrors(n, angle, count, sd_angle, sd_count);
                                                   graph->SetTitle("Count vs Angle;
float c, a;
                                                       Angle (Deg); Count");
tree->SetBranchAddress("c", &c);
tree->SetBranchAddress("a", &a);
                                                   TF1 * f1 = new TF1("f1", "gaus", 7.2, 8);
                                                   TF1 *f2 = new TF1("f2", "gaus", 13.2, 13.7);
double *count, *angle, *sd_count, *sd_angle;
                                                   TF1 *f3 = new TF1("f3", "gaus", 14.8, 15.3);
double *experimental, *sd_experimental;
                                                   TF1 *f4 = new TF1("f4", "gaus", 19.5, 20.5);
double *theoretical;
                                                   TF1 *f5 = new TF1("f5", "gaus", 22.2, 23);
int n_angle = 6;
                                                   TF1 *f6 = new TF1("f6", "gaus", 30.2, 31);
int n = tree->GetEntries();
count = new double[n];
                                                   graph->Fit(f1, "R");
angle = new double[n];
                                                   graph->Fit(f2,"R+");
sd_count = new double[n];
                                                   graph->Fit(f3,"R+");
sd_angle = new double[n];
                                                   graph->Fit(f4, "R+");
theoretical = new double[n_angle];
experimental = new double[n_angle];
                                                   graph->Fit(f5, "R+");
                                                   graph->Fit(f6, "R+");
sd_experimental = new double[n_angle];
                                                   experimental[0] = f1->GetParameter(1);
for (int i = 0; tree->LoadTree(i) >= 0; i++) {
                                                   sd_experimental[0] = f1->GetParError(1);
tree->GetEntry(i);
count[i] = c;
                                                   experimental[1] = f2->GetParameter(1);
 angle[i] = a;
                                                   sd_experimental[1] = f2->GetParError(1);
 sd_count[i] = sqrt(count[i]/5);
 sd_angle[i] = 0.1;
                                                   experimental[2] = f3->GetParameter(1);
                                                   sd_experimental[2] = f3->GetParError(1);
double h = 6.62607015e-34;
                                                   experimental[3] = f4->GetParameter(1);
                                                   sd_experimental[3] = f4->GetParError(1);
double light = 299792458.;
double d = 282.0e-12;
                                                   experimental [4] = f5 -> GetParameter(1);
double sd_d = 0.1e-12;
                                                   sd_experimental[4] = f5->GetParError(1);
double eV = 1.60217663e-19;
double K_a1 = 17479.34 * eV;
double K_a2 = 17374.3 * eV;
                                                   experimental[5] = f6->GetParameter(1);
                                                   sd_experimental[5] = f6->GetParError(1);
double K_a = (2*K_a1 + 1*K_a2)/3;
double K_b = 19608.3 * eV;
                                                   graph->SetMarkerStyle(20);
double rad2deg = 180/TMath::Pi();
                                                   graph->Draw("AP");
                                                   TCanvas *c2 = new TCanvas();
for (int m = 0; m < 4; m++) {
                                                   TGraphErrors *graph_c = new
                                                       TGraphErrors (n_angle, experimental, theoretical,
double theta_a =
   rad2deg*TMath::ASin((m+1)*h*light/(2*K_a*d)); sd_experimental,0);
                                                   TF1 *f_linear = new TF1("f_linear","[0] +
double theta_b =
                                                       [1] *x", 0, 35);
   rad2deg*TMath::ASin((m+1)*h*light/(2*K_b*d));
                                                   f_linear->SetParameters(0,1);
                                                   f_linear->SetParNames("Interception", "Slope");
if(m == 0){
                                                   graph_c->Fit("f_linear", "RE");
 theoretical[m] = (theta_a+theta_b)/2;
                                                   graph_c->SetTitle("Theoretical vs
                                                       Experimental Angle; Experimentel
else{
 if(m == 3){
                                                       Angle (Deg); Theoretical Angle (Deg)");
                                                   graph_c->SetMarkerStyle(20);
   theoretical[2*m-1] = theta_b;
                                                   graph_c->Draw("AP");
                                                   gStyle->SetOptFit(1111);
 else{
 theoretical[2*m - 1] = theta_b;
                                                   double slope = f_linear->GetParameter(1);
 theoretical[2*m] = theta_a;
                                                   double intercept = f_linear->GetParameter(0);
```

cout << "Theoretical K alpha for m = " <<</pre>

cout << "Theoretical K beta for m = " << m+1

m+1 << ": "<< theta_a << endl;

<< ": "<< theta_b << endl;

```
double sd_slope = f_linear->GetParError(1);
double sd_intercept =
    f_linear->GetParError(0);
cout << "Slope of the calibration = " <<
   slope << " +- " << sd_slope << endl;</pre>
cout << "Intercept of the calibration = " <<</pre>
   intercept << " +- " << sd_intercept <<
   endl;
for(int i = 0; i < n_angle; i++){</pre>
 cout << "Experimental Angle For Spike-" <<</pre>
     i+1 << " " << experimental[i] << " +- "
     << sd_experimental[i] << endl;;
 cout << "Theoretical Angle For Spike-" <<</pre>
    i+1 <<" " << theoretical[i] << endl;
c1->Print("xray_gauss.pdf");
c2->Print("xray_calibration.pdf");
```

Macro For Calculating Minimum Wavelengths:

```
TTree *tree = new TTree("tree", "tree");
tree->ReadFile("XRAY_data/30.csv");
double volt = 30*1e3;
double x_min = 0.045e-9;
double x_max = 0.06e-9;
float a, I;
tree->SetBranchAddress("a", &a);
tree->SetBranchAddress("I", &I);
double *count, *angle, *sd_count, *sd_angle;
double *wave, *sd_wave, *extend;
int n = tree->GetEntries();
wave = new double[n];
count = new double[n];
angle = new double[n];
sd_count = new double[n];
sd_angle = new double[n];
sd_wave = new double[n];
extend = new double[n];
double h = 6.62607015e-34;
double light = 299792458.;
double eV = 1.60217663e-19;
double K_a1 = 17479.34 * eV;
double K_a2 = 17374.3 *eV;
double K_a = (2*K_a1 + 1*K_a2)/3;
double K_b = 19608.3 * eV;
double deg2rad = TMath::Pi()/180;
double slope = 0.92199;
double sd_slope = 0.001688;
double intercept = 0.15944;
double sd_intercept = 0.0308526;
double d = 282.0e-12;
double sd_d = 0.1e-12;
for (int i = 0; tree->LoadTree(i) >= 0; i++) {
tree->GetEntry(i);
 count[i] = I;
 angle[i] = a*slope + intercept;
 wave[i] = 2*d*TMath::Sin(deg2rad*angle[i]);
 sd_count[i] = sqrt(count[i]/5);
 sd_angle[i] = sqrt(pow(slope, 2) *pow(0.1, 2) +
 pow(a,2)*pow(sd_slope,2) +
 pow(1,2)*pow(sd_intercept,2));
 sd_wave[i] =
```

```
gStyle->SetOptFit(1111);
TCanvas *c1 = new TCanvas();
TGraphErrors *graph = new
   TGraphErrors(n, wave, count, sd_wave, sd_count);
TF1 *f_linear = new TF1("f_linear","[0] +
    [1] *x", x_min, x_max);
double par_1 = 1e12;
double par_0 = -x_min * par_1;
f_linear->SetParameters(par_0,par_1);
f_linear->SetParNames("Interception", "Slope");
graph->Fit("f_linear","R");
double new_slope = f_linear->GetParameter(1);
double new_intercept =
    f_linear->GetParameter(0);
double sd_new_slope =
    f_linear->GetParError(1);
double sd_new_intercept =
   f_linear->GetParError(0);
for (int i = 0; i < n; i++) {
 extend[i] = new_slope*wave[i] +
     new_intercept;
TGraph *graph2 = new TGraph(n, wave, extend);
graph->SetTitle("Accumulation Rate vs
   Wavelenght; Wavelenght (m); Accumulation
   Rate (Impulse/Sec)");
graph->SetMarkerStyle(20);
graph->Draw("AP");
graph2->SetLineColor(2);
graph2->Draw("Same");
double lambda = -new_intercept/new_slope;
double sd_lambda =
    sqrt (pow (-1/new_slope, 2) *pow (sd_new_intercept, 2)
pow(new_intercept/pow(new_slope,2),2)*pow(sd_new_slope
double freq = light/lambda;
double sd_freq =
   sqrt(pow(light/(lambda*lambda),2)*pow(sd_lambda,2))
cout << "Lambda_Min: " << lambda << " +- "
   << sd_lambda << endl;
cout << "Freq_Max: " << freq << " +- " <<
   sd_freq << endl;
cout << "Volt: " << volt << " +- " << 1e3 <<
   endl;
c1->Print("30.pdf");
```

sqrt (pow(2*TMath::Sin(deg2rad*angle[i]),2)

pow(2*d*TMath::Cos(deg2rad*angle[i])*deg2rad,2)

*pow(sd_d,2) +

*pow(sd_angle[i],2));

Macro for Calculating Planck Constant:

```
const int n = 6;
double q = 1.602176634e-19;
double freq[n] =
    {3.76064e+18,4.64811e+18,5.27529e+18,
5.97956e+18,6.97476e+18,7.07684e+18};
double sd_{freq[n]} = \{6.40308e+17, 8.3406e+17\}
7.82979e+17, 9.95806e+17, 6.10088e+17,
```

```
6.56757e+17};
double energy[n] = \{q*15e3, q*18e3, q*21e3,
   q*24e3, q*27e3, q*30e3};
double sd_energy[n] =
   {q*1e3,q*1e3,q*1e3,q*1e3,q*1e3,q*1e3};
TCanvas *c1 = new TCanvas();
TGraphErrors *graph = new
   TGraphErrors (n, freq, energy, sd_freq, sd_energy);
TF1 *f_linear = new TF1("f_linear","[0] +
    [1] *x", 1e18, 7e18);
f_linear->SetParameters(0,6e-34);
f_linear->SetParNames("Interception", "Planck");
graph->Fit("f_linear", "R");
graph->SetTitle("Energy vs Frequency;
   Frequency(Hertz); Energy(J)");
graph->SetMarkerStyle(20);
graph->Draw("AP");
gStyle->SetOptFit(1111);
double planck = f_linear->GetParameter(1);
double sd_planck = f_linear->GetParError(1);
double h = 6.62607015e-34;
cout << "Experimental Planck Constant: " <<</pre>
   planck << " +- " << sd_planck << endl;</pre>
cout << "Relative Error: " <<</pre>
   abs(planck-h) *100/h << "%"<< endl;
cout << abs(planck-h)/sd_planck << " Sigma</pre>
   Away" << endl;
c1->Print("xray_h.pdf");
```