

# Gebze Technical University

# DEPARTMENT OF COMPUTER ENGINEERING

# CSE344 System Programming

# Homework 4 Report

Burak Yıldırım 1901042609

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## 1 Introduction

### 1.1 Project Description

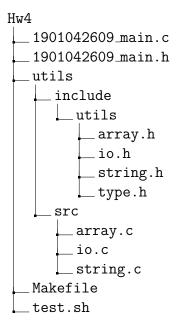
The task of this project is to design and implement a directory copying system using threads.

## 1.2 Compilation

```
CC = gcc
CFLAGS = -w
DFLAGS = -g
TFLAGS = -pthread
UTILS_SRCDIR = utils/src
UTILS_INCDIR = utils/include
TARGET = MWCp
SOURCES = ./1901042609_main.c $(wildcard $(UTILS_SRCDIR)/*.c)
HEADERS = ./1901042609_main.h $(wildcard $(UTILS_INCDIR)/**/*.h)
INCDIRS = -I. -I$(UTILS_INCDIR)
VALGRIND_MEMORY_OPTIONS = --leak-check=full --show-leak-kinds=all --track-origins=yes
VALGRIND_THREAD_OPTIONS = --tool=helgrind --read-var-info=yes
V_BUFFER =
V_WORKER =
V_SRC =
V_DEST =
export V_BUFFER
export V_WORKER
export V_SRC
export V_DEST
OS := $(shell uname)
ifeq ($(OS), Darwin)
        TFLAGS =
endif
all: $(TARGET)
test: $(TARGET)
        ./test.sh $(V_BUFFER) $(V_WORKER) $(V_SRC) $(V_DEST)
$(TARGET): $(SOURCES) $(HEADERS)
        $(CC) $(CFLAGS) -o $@ $(SOURCES) $(INCDIRS) $(TFLAGS)
debug: CFLAGS += $(DFLAGS)
debug: $(TARGET)
clean:
        rm -rf $(TARGET)
valgrind_memory: debug
        valgrind $(VALGRIND_MEMORY_OPTIONS) ./$(TARGET) $(V_BUFFER) $(V_WORKER) $(V_SRC) $(V_DEST)
valgrind_thread: debug
        valgrind $(VALGRIND_THREAD_OPTIONS) ./$(TARGET) $(V_BUFFER) $(V_WORKER) $(V_SRC) $(V_DEST)
```

Executing **make** compiles the project, **make clean** removes the executable, **make test** pressure tests the code by executing it 10 times in a row, **make valgrind\_memory** launches the programs in Valgrind for memory leak checks, and **make valgrind\_thread** launches the programs in Valgrind for thread errors.

## 2 General Structure



This is the folder structure of the project.

- utils: utility functions and macros used by multiple files. The reason for adding an extra utils directory inside the include directory is to be able to call the utils headers like 'utils/io.h', etc.
- 1901042609\_main: main functions and macros.
- Makefile: compile project and clean the executable.
- test.sh: pressure test the code by executing it 10 times in a row.

# 3 Implementation

## 3.1 Structs and Enums

```
typedef enum {
    REGULAR,
    DIRECTORY,
    FIFO,
    UNKNOWN,
    INVALID
} FileType;
```

```
typedef enum {
    FALSE = 0,
    TRUE = 1
} Bool;

typedef struct {
    int src_fd;
    int dest_fd;
    char src[PATH_MAX];
    char dest[PATH_MAX];
}
```

## 3.2 Steps

The main program is implemented following these steps:

- 1. The command line arguments are verified.
- 2. SIGINT is handled.
- 3. cleanup is registered with atexit.
- 4. Source and destination directories are opened. If destination directory doesn't exist, it's created.
- 5. Manager thread is created using pthread\_create.
- 6. Worker threads are created pthread\_create.
- 7. Manager thread is waited using pthread\_join.
- 8. Worker threads are waited using pthread\_join.
- 9. carOwner threads are waited using pthread\_join.
- 10. Elapsed time is calculated and the statistics are printed.
- 11. cleanup function is called to free all the dynamically allocated variables, close the original source and destination folders, and destroy all the mutexes and the condition variables.
- 12. Program finishes.

#### 3.3 Details

All access to the global variables are done between pthread\_mutex\_lock(&general\_mutex) and pthread\_mutex\_unlock(&general\_mutex).

#### 3.3.1 manager

Manager thread runs in a loop until all the files in the source directory and its subdirectories are opened and their file descriptors as well as their names are written to the buffer or until the is\_finished flag is set. While reading the source directory if the current entry is a regular file, it calls the handle\_regular function which does the following:

- open the source file for reading with open.
- create or truncate the destination file with open.
- lock the general mutex.
- check if the current occupancy of the buffer is equal to the buffer size or if there is no available workers.
- if one of them is true wait for buffer\_not\_full\_cond.
- if none of them is true or if the buffer\_not\_full\_cond is signaled, put the file descriptor and name information of the source and the destination files in the buffer and increment the current occupancy of the buffer by 1.
- signal the buffer\_not\_empty\_cond so that a worker can wake up and do the copying.
- unlock the general\_mutex.

If the current entry is a FIFO, it calls handle\_fifo which follows the same steps as handle\_regular with one addition. This time before opening the source file, the FIFO is created with mkfifo at the destination path. The rest is the same. If the current entry is another directory, it calls the handle\_directory which opens the directory, runs in a loop until all of its entries are read or until the is\_finished flag is set, and acts according to the type of the file as mentioned before, e.g. calls handle\_regular for regular files, handle\_fifo for FIFOs, and handle\_directory for directories. This way all of the files in the source directory is copied to the destination directory recursively. After all the files are read, it sets the is\_finished flag to TRUE.

#### 3.3.2 worker

Worker thread runs in an infinite loop until the is\_finished flag is set. At each iteration it waits the buffer\_not\_empty\_cond. After waiting, it checks if the current occupancy of the buffer is 0. If it is, it unlocks the general\_mutex, checks whether the is\_finished flag is set. If the flag is set then it breaks the loop, if the flag is not set then it goes back to the beginning of the loop waiting for buffer\_not\_empty\_cond. If the current occupancy of the buffer is not 0, then it decrements the current occupancy and the available thread number by 1. Then it gets the first element of the buffer, shifts the buffer to the left, and unlocks the general\_mutex. Then it copies the source file to destination file, locks the general\_mutex, increments the available thread number by 1, signals the buffer\_not\_full\_cond, and unlocks the general\_mutex.

#### 3.3.3 Signal Handling

SIGINT In the SIGINT handler, first is\_finished flag is set to TRUE and buffer\_not\_empty\_cond is broadcasted. Then the manager thread and the worker threads are joined. Then the elapsed time is calculated and the statistics are printed. Finally, the cleanup function frees all the dynamically allocated variables, closes the original source and destination folders, and destroys all the mutexes and the condition variables.

# 4 Testing

#### 4.1 Test 1

```
-----STATISTICS-----
Consumers: 10 - Buffer Size: 10
Number of Regular File: 194
Number of FIFO File: 0
Number of Directory: 7
TOTAL BYTES COPIED: 25009680
TOTAL TIME: 00:01.007 (min:sec.mili)
==22153==
==22153== HEAP SUMMARY:
             in use at exit: 0 bytes in 0 blocks
==22153==
==22153==
            total heap usage: 29 allocs, 29 frees, 610,128 bytes allocated
==22153==
==22153== All heap blocks were freed -- no leaks are possible
==22153==
==22153== For counts of detected and suppressed errors, rerun with: -v
==22153== ERROR SUMMARY: 0 errors from 0 contexts (suppressed: 0 from 0)
```

#### 4.2 Test 2

```
------STATISTICS------Consumers: 4 - Buffer Size: 10

Number of Regular File: 140

Number of FIFO File: 0

Number of Directory: 2

TOTAL BYTES COPIED: 24873082

TOTAL TIME: 00:00.049 (min:sec.mili)
```

#### 4.3 Test 3

#### 4.4 SIGINT

```
SIGINT signal received. Printing the statistics so far and exiting...
    -----STATISTICS-----
Consumers: 10 - Buffer Size: 10
Number of Regular File: 257
Number of FIFO File: 0
Number of Directory: 12
Bytes copied so far: 28663292
Elapsed time so far: 00:01.229 (min:sec.mili)
==22229==
==22229== HEAP SUMMARY:
==22229==
            in use at exit: 0 bytes in 0 blocks
==22229== total heap usage: 39 allocs, 39 frees, 938,288 bytes allocated
==22229==
==22229== All heap blocks were freed -- no leaks are possible
==22229==
==22229== For counts of detected and suppressed errors, rerun with: -v
==22229== ERROR SUMMARY: 0 errors from 0 contexts (suppressed: 0 from 0)
```