# cis111-2025-1-e4Project2: Edge Detection for Black & White Images

#### **Common Material**

Consider cis000\_common package.

- 1. Update StudentInfo with your info.
- 2. Read .pdf files in cis000\_common.

#### Introduction

Edge detection is a fundamental technique in **image processing** and **computer vision**, used to identify boundaries between different regions in an image. These edges often represent significant changes in pixel intensity, which can be useful in applications like **object detection**, **medical imaging**, **and autonomous vehicles**.

In this project, you will implement the **Laplace Edge Detection** algorithm using a **4-kernel** approach specifically designed for **black & white (binary) images** (where pixels are either 0=black or 255=white).

#### **Problem Definition**

Given a **2D black & white image** (a binary matrix where pixels are either 0 or 255 ), your task is to:

- 1. Apply the **4-kernel Laplace operator** to detect edges.
- 2. Handle image borders (using zero-padding or mirroring).
- 3. Binarize the output (convert edge pixels to 255 and non-edges to 0).
- 4. **Display/print** the edge-detected image.

#### Input:

- A 2D binary array (int[][] image) where:
  - o ø = Black

- o 255 = White
- Image dimensions (width, height).

#### **Output:**

• A new 2D binary array (int[][] edges ) where edges are 255 and non-edges are 0.

## **Laplace 4-Kernel for Binary Images**

The Laplace 4-kernel detects edges by comparing a pixel with its four neighbors (top, bottom, left, right).

#### **Kernel Structure:**

0	-1	0
-1	4	-1
0	-1	0

#### How It Works on Binary Images:

- If a pixel is **surrounded by the same color**, the Laplace response is 0 (no edge).
- If a pixel differs from its neighbors, the response is non-zero (edge detected).

#### **Mathematical Formulation:**

For a binary pixel at (x, y):

$$L(x,y) = 4 \cdot I(x,y) - I(x-1,y) - I(x+1,y) - I(x,y-1) - I(x,y+1)$$

- If L(x,y) != 0, the pixel is an edge (255).
- Else, it's not an edge ( 0 ).

### Implementation Steps of edgeDetector Method

#### Step 1: Define the Laplace Kernel

```
final int[][] LAPLACE_KERNEL = {
    {0, -1, 0},
    {-1, 4, -1},
    {0, -1, 0}
};
```

This step is complete; proceed with the remaining tasks.

#### **Step 2: Apply Convolution & Binarize**

- Loop through each pixel (excluding borders).
- Compute the Laplace response.
- If response  $\neq 0$ , set output to 255 (edge), else 0.

#### **Step 3: Handle Borders**

- Zero-padding: Treat out-of-bound pixels as 0 (black).
- Mirroring: Reflect edge pixels.

#### Step 4: Display Result

Print the edge-detected binary matrix.

## Implementation Steps of edgePlot Method

After obtaining the edge-detected binary matrix, represent it visually using . for edges (255) and spaces for non-edges (0). Store this ASCII representation in a String and return it from the method.