

# Introduction to Artificial Intelligence: Methods, Models, Algorithms

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# Linear models

$$a(x) = w_0 + \sum_{j=1}^d w_j x^j$$

Weights can be interpreted if features are scaled

# Example

- The prediction value of the apartment
- Features: area, floor, number of rooms

$$a(x) = 10 \cdot (\text{area}) + 1.1 \cdot (\text{floor}) + 20 \cdot (\text{number of rooms})$$

# Example

- Dependence on the floor is hardly linear
- Quadratic features:

$$a(x) = 10 \cdot (\text{area}) + 1.1 \cdot (\text{floor}) + 20 \cdot (\text{number of rooms}) - 0.2 \cdot (\text{area})^2 + 0.5 \cdot (\text{area} \cdot \text{number of rooms}) + \dots$$

# Example

- With cubic features will be even better
- How to interpret the feature  
area · number of rooms<sup>2</sup>?
- A total of 20 such features

# Example

- You can binarysoul features:  $[x^j > t]$
- $(\text{floor} > 1), (\text{floor} > 2), \dots, (\text{floor} > 30)$
- Features will be orders of magnitude more
- Easier to interpret:
  - $2[\text{floor} > 3][\text{area} < 40][\text{number of rooms} < 3]$
- You can use  $L_1$ -regularization

# Logical rules

$[\text{floor} > 3][\text{area} < 40][\text{number of rooms} < 3]$

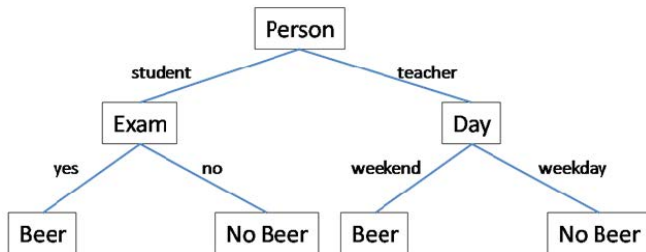
- Easy to explain to the customer (if  $\leq 5$  conditions)
- Allow you to extract knowledge from data
- Not the fact that they are optimal in terms of quality

# Logical rules

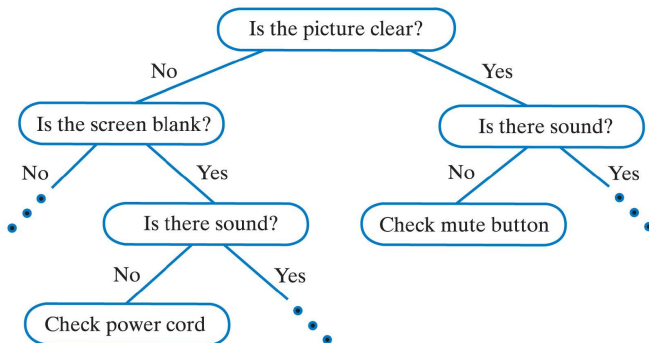
- How to construct them?
- Linear model
- Busting, greedy build-up
- Decision trees



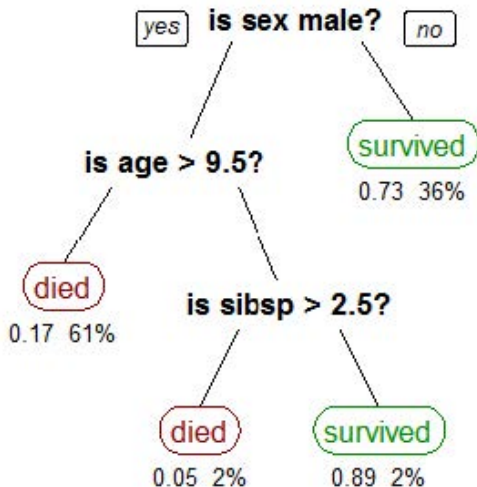
# Decision making



# The scheme of dialogue with the client

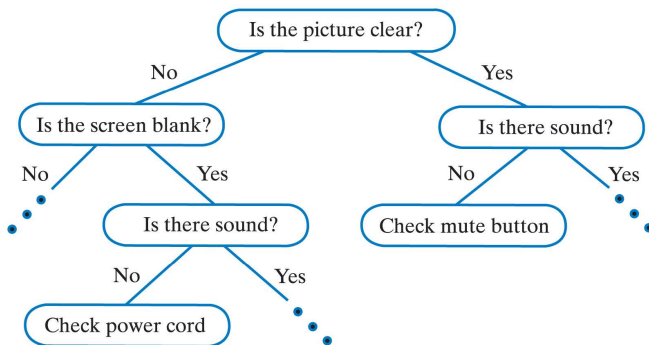


# The passengers of the Titanic



# Decision tree

- Binary tree
- Each inner node contains a condition
- Each leaf contains prediction (solution)



# Conditions

- Most popular options:

$$[x^j \leq t] \text{ and } [x^j = t]$$

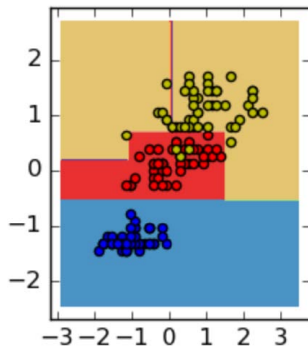
- Examples:

$$[\text{floor} = 5] \text{ or } [\text{area} \leq 30]$$

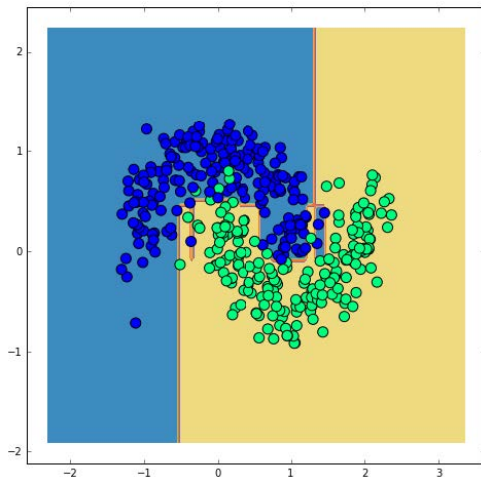
# Prediction in the leaf

- Regression: Real number
- Classification: Class or Class probabilities

# Classification

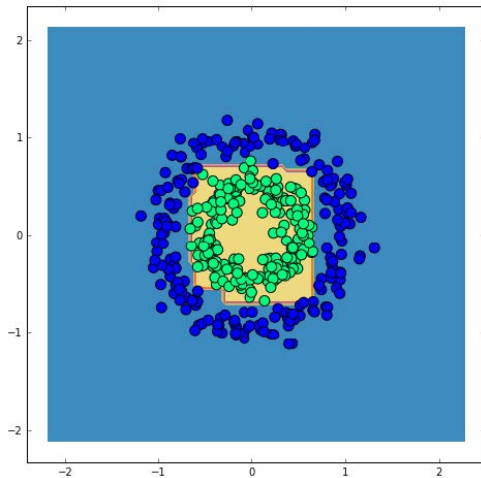


# Classification

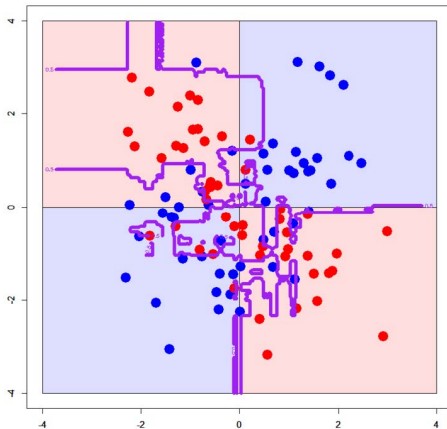




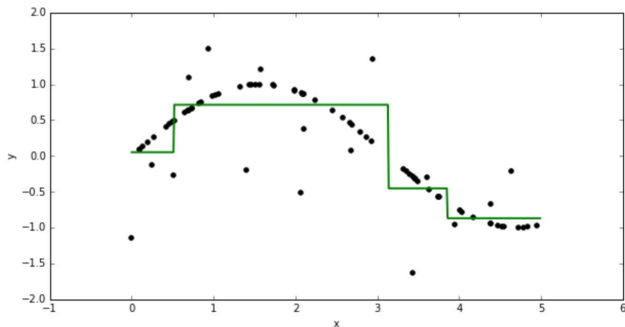
# Classification



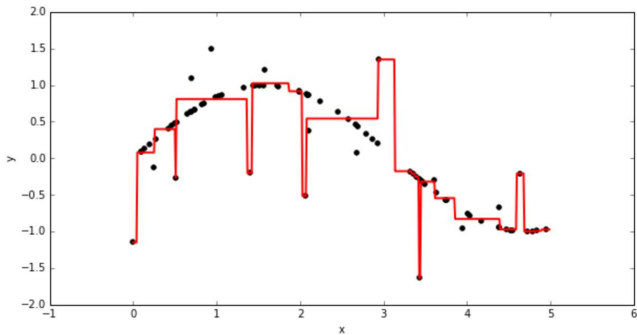
# Classification



# Regression



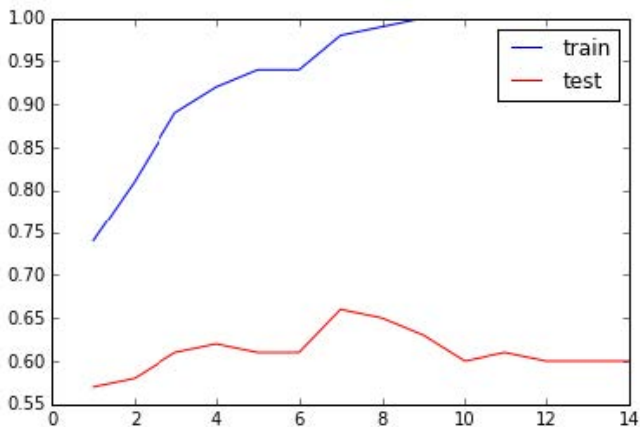
# Regression



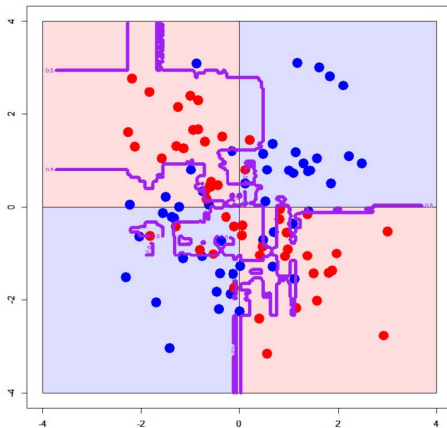
# Decision tree

- Restore complex dependencies
- Can build any complex surface
- The greater the depth the more complex the surface
- Prone to overfitting

# Depth of trees



# Overfitting of trees



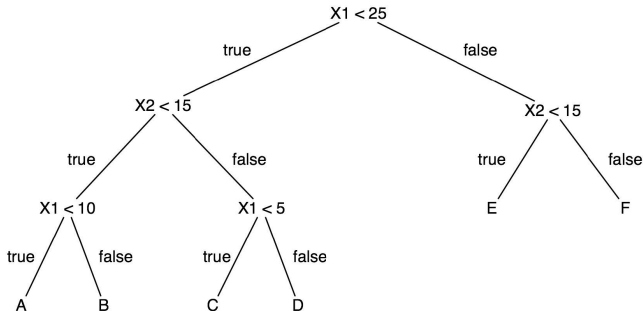
# Overfitting of trees

- The tree can achieve zero error on any sample
- Tackling overfitting: the minimum tree among all with zero error
- NP-complete task
- *Solution*: greedy building

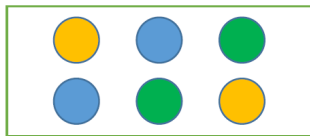


# Greedy formation

- Grow the tree from root to leaves

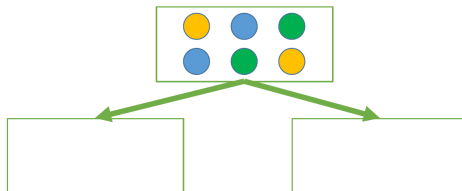


# Greedy formation

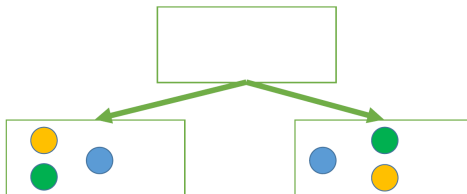


How to split the node?

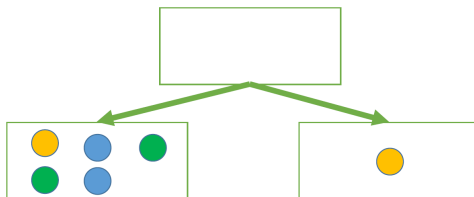
# Greedy formation



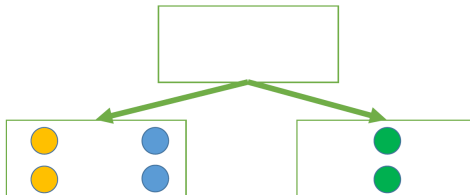
# Greedy formation



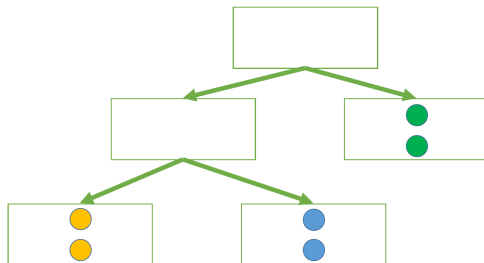
# Greedy formation



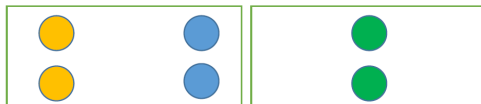
# Greedy formation



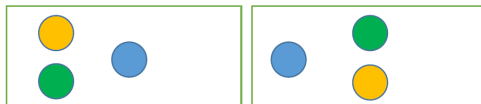
# Greedy formation



# How to compare splits?



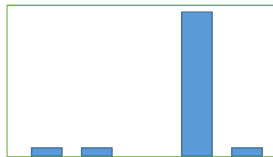
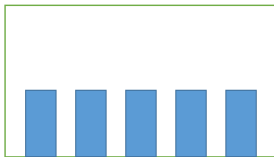
OR





# Entropy

- Measure of uncertainty of distribution



# Entropy

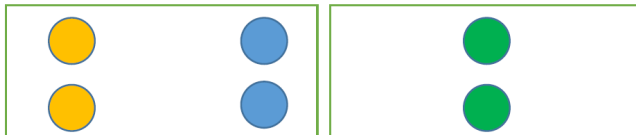
- Discrete distribution
- Accepts  $n$  values with probabilities  $p_1, \dots, p_n$
- Entropy:

$$H(p_1, \dots, p_n) = - \sum_{i=1}^n p_i \log p_i$$

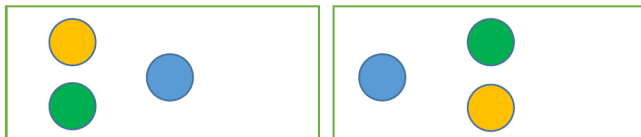
# Entropy

- $(0.2, 0.2, 0.2, 0.2, 0.2) \rightarrow H = 1.60944$
- $(0.9, 0.05, 0.05, 0, 0) \rightarrow H = 0.394398$
- $(0, 0, 0, 1, 0) \rightarrow H = 0$

# Entropy

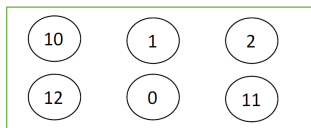


- $(0.5, 0.5, 0)$  and  $(0, 0, 1)$
- $H = 0.693 + 0 = 0.693$

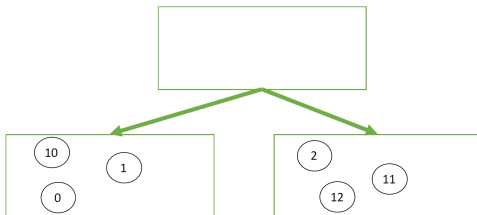


- $(0.33, 0.33, 0.33)$  and  $(0.33, 0.33, 0.33)$
- $H = 1.09 + 1.09 = 2.18$

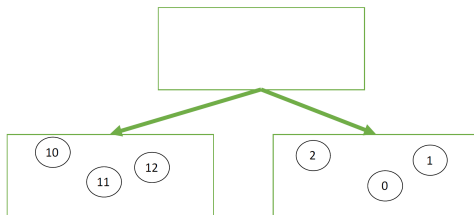
# What about regression?



# What about regression?



# What about regression?



# What about regression?

- Choose the partition with the least total variance
- The smaller the variance, the less uncertainty



# Searching the partition

- Let the node  $m$  be the sample  $X_m$
- $Q(X_m, j, t)$  - is a criteria for the condition error  $[x^j \leq t]$
- Search the parameters  $t$  and  $j$ :

$$Q(X_m, t, j) \rightarrow \min_{j, t}$$

# Searching the partition

- When we find the partition we split the  $X_m$  into two parts:

$$X_l = \{x \in X_m | [x^j \leq t]\}$$

$$X_r = \{x \in X_m | [x^j > t]\}$$

- Repeat the procedure for child nodes

# Stop criterion

- At what point should the splitting of nodes be stopped?
- The single item at the node of ?
- Items of the same class at the node?
- Did the depth exceed a threshold?

## Prediction in the leaf

- For example, I decided to make a node  $m$  leaf
- Which prediction to choose?
- Regression:

$$a_m = \frac{1}{|X_m|} \sum_{i \in X_m} y_i$$

- Classification

$$a_m = \arg \max_{y \in \mathbb{Y}} \sum_{i \in X_m} [y_i = y]$$

## Prediction in the leaf

- For example, I decided to make a node  $m$  leaf
- Which prediction to choose?
- Class probabilities:

$$a_{mk} = \frac{1}{|X_m|} \sum_{i \in X_m} [y_i = k]$$

# Summary

- Sometimes the model needs to be interpreted
- Decision trees are easy to explain
- Decision trees easily overfits
- Tree construction is a greedy algorithm