```
clear; clc;
```

Problem 3 Levenberg-Marquardt

```
% DERIVING GRADIENTS
syms x_1 x_2
% f_sym = (1-x_1)^2 + 100*(x_2-x_1^2)^2;
u = (1/2)*(x_1^2 + x_2^2 - 25);
f_sym = exp(u^2) + sin(4*x_1 - 3*x_2)^4 + 0.5*(2*x_1 + x_2 - 10)^2
```

f_sym =

$$e^{\left(\frac{x_1^2}{2}+\frac{x_2^2}{2}-\frac{25}{2}\right)^2} + \frac{(2\,x_1 + x_2 - 10)^2}{2} + \sin(4\,x_1 - 3\,x_2)^4$$

```
f = matlabFunction(f_sym); f = @(x) f(x(1), x(2));

grad = [diff(f_sym, x_1); diff(f_sym, x_2)]
```

grad =

$$\begin{pmatrix} 16\cos(4\,x_1 - 3\,x_2)\,\sigma_2 + 4\,x_1 + 2\,x_2 + 2\,x_1\,e^{\sigma_1^2}\,\sigma_1 - 20 \\ -12\cos(4\,x_1 - 3\,x_2)\,\sigma_2 + 2\,x_1 + x_2 + 2\,x_2\,e^{\sigma_1^2}\,\sigma_1 - 10 \end{pmatrix}$$

where

$$\sigma_1 = \frac{x_1^2}{2} + \frac{x_2^2}{2} - \frac{25}{2}$$

$$\sigma_2 = \sin(4\,x_1 - 3\,x_2)^3$$

```
f_grad = matlabFunction(grad); f_grad = @(x) f_grad(x(1), x(2));

grad = [diff(grad(1), x_1) diff(grad(1), x_2);
        diff(grad(2), x_1) diff(grad(2), x_2)]
```

grad =

$$\begin{pmatrix} 192\,\sigma_5\,\sigma_4 + \sigma_2 + 2\,x_1{}^2\,e^{\sigma_6} - 64\,\sigma_3 + 4\,x_1{}^2\,e^{\sigma_6}\,\sigma_6 + 4 & \sigma_1 \\ \sigma_1 & 108\,\sigma_5\,\sigma_4 + \sigma_2 + 2\,x_2{}^2\,e^{\sigma_6} - 36\,\sigma_3 + 4\,x_2{}^2\,e^{\sigma_6}\,\sigma_6 + 1 \end{pmatrix}$$

where

$$\sigma_1 = 48\,\sigma_3 - 144\,\sigma_5\,\sigma_4 + 2\,x_1\,x_2\,e^{\sigma_6} + 4\,x_1\,x_2\,e^{\sigma_6}\,\sigma_6 + 2$$

$$\sigma_2 = 2\,e^{\sigma_6}\left(\frac{x_1{}^2}{2} + \frac{x_2{}^2}{2} - \frac{25}{2}\right)$$

$$\sigma_3 = \sin(4\,x_1 - 3\,x_2)^4$$

$$\sigma_4 = \sin(4\,x_1 - 3\,x_2)^2$$

$$\sigma_5 = \cos(4\,x_1 - 3\,x_2)^2$$

$$\sigma_6 = \left(\frac{x_1{}^2}{2} + \frac{x_2{}^2}{2} - \frac{25}{2}\right)^2$$

```
f_grad2 = matlabFunction(grad); f_grad2 = @(x) f_grad2(x(1), x(2));

% SETUP
x0 = [4; -1]; x = x0;
% x0 = [2; 3]; x = x0;
xout = x0;
dx = Inf;
fCalls = [0 0 0];
t0 = 0.1;
iters = 0;
tic
filename = 'hw3p3_4LM.png';

% START CONDITIONS
lambda = 1e3; gamma = 2;
lambdaList = lambda;
J = f(x); Jlast = J;
g = f_grad(x);
H = f_grad2(x);
fCalls = fCalls + [1 1 1];
lamMin = min(eig(H));

% ITERATING
while ~(norm(g) < 1e-8 && lamMin > 0)

    % FINDING TEST POINT
    xtest = x + (H + lambda*eye(length(x))) \ -g;
```

```
    % TESTING
    J = f(xtest);
    fCalls(1) = fCalls(1) + 1;
    if J > Jlast
        lambda = lambda*gamma;
%         if lambda < 1 || lambda > 1e12; break; end
        iters = iters + 1;

        if iters == 1000; break; else; continue; end
    end

    % ACCEPTING STEP
    x = xtest;
    Jlast = J;
    lambda = lambda / gamma^2;

%     UPDATING GRADIENTS
%     J = f(x);
    g = f_grad(x);
    H = f_grad2(x);
    fCalls = fCalls + [0 1 1];
    lamMin = min(eig(H));
    xout = cat(2, xout, x);

%     lambda = max(max(-lamMin + 1e-8, 1e3), lambda);

    iters = iters+1;
    lambdaList(end+1) = lambda;
    if iters == 1000; break; end
end
time = toc;

% PLOTTING
x1_space = -5:0.1:5;
x2_space = -5:0.1:5;
z_space = zeros(length(x1_space));
for i = 1:length(x1_space)
    for j = 1:length(x1_space)
        z_space(j, i) = f([x1_space(i), x2_space(j)]);
    end
end
time = toc;

% Contour
contourf(x1_space, x2_space, z_space, [logspace(0, 24, 40)], ...
    'HandleVisibility',"off", 'LineStyle',"none")
hold on
set(gca, 'ColorScale', 'log');
caxis([2, 1e24])
scatter(xout(1, :), xout(2, :), 'ro', 'filled', 'DisplayName', ...
    ['LM Steps', newline, '\lambda_0 = ', sprintf('%0.6g', lambdaList(1)), newline, '\g
plot(xout(1, :), xout(2, :), 'r--', 'HandleVisibility',"off")
scatter(xout(1, 1), xout(2, 1), 50, 'go', 'filled', 'DisplayName',"Initial Position")
C = colorbar('peer', gca, "eastoutside", 'Ticks', logspace(1, 25, 7));
```

```
scatter(x(1, end), x(2, end), 300, 'yp', 'filled', 'DisplayName', sprintf('x_{min} =\n
hold off
legend('Location', 'southwest')
title(sprintf('Minimizing Rosenbrock Function \n[#f #g #H] = [%i %i %i]\nf = %0.8g\nRun
exportgraphics(gcf, filename, 'Resolution', 200);
```