Hazard Analysis & Risk Assessment

Hazard ID				Situational Analysi	s		
	Operational Mode	Operational Scenario	Environmental Details	Situation Details	Other Details (optional)	Item Usage (function)	Situation Description
HA-001	OM03 - Normal driving	OS04 - Highway	EN06 - Rain (slippery road)	SD02 - High speed	SD07 - N/A	IU01 - Correctly used	Normal driving on a highway during rain (slippery road) with high speed and correctly used system.
HA-002	OM03 - Normal driving	OS03 - Country Road	EN01 - Normal conditions	SD02 - High speed	SD07 - N/A	IU02 - Incorrectly used	Normal driving on a country road during normal conditions with high speed and incorrectly used system.
HA-003	OM03 - Normal driving	OS02 - City Road	EN01 - Normal conditions	SD01 - Low speed	SD07 - N/A	IU01 - Correctly used	Normal driving on a city road during normal conditions with high speed and correctly used system.
HA-004	OM03 - Normal driving	OS02 - City Road	EN01 - Normal conditions	SD01 - Low speed	SD07 - N/A	IU01 - Correctly used	Normal driving on a city road during normal conditions with any speed and correctly used system.

Hazard ID	Hazard Identification							
	Function	Deviation	Deviation Details	Hazardous Event (resulting effect)	Event Details	Hazardous Event Description		
HA-001	Lane Departure Warning (LDW) function shall apply an oscillating steering torque to provide the driver with haptic feedback	DV04 - Actor effect is too much	The LDW function applies an oscillating torque with very high torque (above limit).	EV00 - Collision with other vehicle	High haptic feedback can affect driver's ability to steer as intended. The driver loose control and could collide with another nearby vehicle or the side of the road.	The amount of oscillating torque applied to the steering wheel by the Lane Departure Warning item is too significant and above the limit.		
HA-002	Lane Keeping Assistance (LKA) function shall apply the steering torque when active in order to stay in ego lane	DV03 - Function always activated	The driver is misusing the system by exploiting the LKA function as a fully autonomous function and keeps it always active.	EV00 - Collision with other vehicle	The driver takes both hands off the wheel indefinitely and looses attentiveness. As a result, the driver can not react to events happening on the road such as cars merging into the ego lane.	The LKA does not disengage and the function exits its operational domain.		
HA-003	Lane Keeping Assistance (LKA) function shall apply the steering torque when active in order to stay in ego lane	DV13 - Sensor sensitivity is too low	The lane on the road is not correctly marked and the Camera Sensor unit does not detect it.	EV02 - Collision with pedestrian	The car leaves it ego lane after not detecting a lane and run over a pedestrian walking nearby.	The LKA does not detect a lane because of software sensibility threshold.		
HA-004	Lane Keeping Assistance (LKA) function shall apply the steering torque when active in order to stay in ego lane	DV06 - Actor action too early	The system starts following the wrong set of line right after activation.	EV-02 - Side collision with other traffic	The LKA functionality is activated and takes immediate effect. It tries to keep the car inbetween a set of lanes on the road which the driver didn't want to follow.	The LKA functionality triggers an abrupt and unexpected lane change which results in a potential collision with obstacles or vehicles.		

Hazard ID			Hazardou	s Event Classification		
	Exposure (of situation)	Rationale (for exposure)	Severity (of potential harm)	Rationale (for severity)	Controllability (of hazardous event)	Rationale (for controllability)
HA-001	E2 - Low probability	The probability to maintain a high speed on the highway over a slippery road is less than 3% of the operating time of the vehicle.	S3 - Life-threatening or fatal injuries	Collisions at high speed would most probably cause fatal injuries.	C3 - Difficult to control or uncontrollable	It would become challenging to keep the hands on the wheel. The steering wheel oscillations could be impacting the trajectory of the car.
HA-002	E3 - Medium probability	Destined to the US Market, country road are frequent, driving is likely to have low or inexistent understanding of the Lane Keeping Assistance function.	S3 - Life-threatening or fatal injuries	Collisions at high speed would most probably cause fatal injuries.	C3 - Difficult to control or uncontrollable	Understanding of the immediate situation after taking the eyes off the road could take up to 5 seconds before being able to control of the vehicle in a safe manner. At high speed 5 seconds translates to an extremely long driven distance.
HA-003	E4 - High probability	Almost every drive happens near a pedestrian area at some point along the way.	S2 - Severe and life- threatening injuries	Collisions at low to medium speed could result in life-threatening injuries.	C3 - Difficult to control or uncontrollable	The difficulty to control the car in that situation results form the fact that the driver must react instantaneously in order to avoid the collision once he/she has noticed the missed lane detection.
HA-004	E4 - High probability	Every day we choose to steer away from the main lane marking in order to leave the main road form a smaller one for example.	S2 - Severe and life- threatening injuries	Abrupt lane change can result in a collision with other vehicles.	C3 - Difficult to control or uncontrollable	Abrupt lane change can surprise the driver who might react erratically and panic.

Hazard ID		Determination of ASIL and Safety Goals
	ASIL Determination	Safety Goal
HA-001	С	The amplitude of the oscillating steering torque from the Lane Departure Warning function shall be limited and could never exceed a defined safety threshold.
HA-002	С	The LKA function shall be time limited to keep the driver focused on the driving task.
HA-003	С	Function disengagements shall be notified to the driver by significant and simultaneous warnings in the form of visual, acoustic and haptic feedbacks.
HA-004	С	The LKA function shall only be available to the driver on the highway where the lines of the ego lanes are clearly defined. The LKA function shall only start applying torque on the steering wheel after it has been activated for some time and its output was matching the driver effective behavior.

Hazard ID	'		S	Situational Analysis						Hazard Ide	ontification				Howard	lous Event Classification			Determination of ASII	and Safaty Cools	
nazaru ib	Operational Mode	Operational Scenario	Environmental Details	Situation Details	Other Details	Item Usage	Situation Description	Function	Deviation	Deviation Details	Hazardous Event	Event Details Hazardous Event	Exposure	Rationale	Severity (of potential harm)	Rationale	Controllability	Rationale	ASIL	and Safety Goals Safety Goal	+
	operational mode	operational occination		(optional)	(optional)	(function)					(resulting effect)	Description	(of situation)	(for exposure)		(for severity)	(of hazardous event)	(for controllability)	Determination		
HA-001	Normal Driving	City Road	Normal Conditions	Low Speed	Night time + Obstacle on the	Correctly Used	Normal Driving on a City Road in Normal	Low beam illuminates the	Function not activated	Both headlights stop working	Front collision with obstacle	Vehicle crashes into the Total loss of low beam	E4 - High probability	night driving in the city is a regular	S1 - Light and moderate injuries	In city traffiic, speed of vehicle is expected to be low	C0 - Controllable in general	At city speed, most drivers will be able to	QM	Total Loss of Beam Shall	
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EXAMPLES - Headlam	System																				+
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Hazard ID				Situation Analysis						Hazard Ide	entification				Hazard	lous Event Classification			Determination of ASII	_ and Safety Goals	
	Operational Mode	Operational Scenario	Environmental Details	Situation Details (optional)	Other Details (optional)	Item Usage (function)	Situation Description	Function	Deviation	Deviation Details	Hazardous Event (resulting effect)	Event Details Hazardous Event Description	Exposure (of situation)	Rationale (for exposure)	Severity (of potential harm)	Rationale (for severity)	Controllability (of hazardous event)	Rationale (for controllability)	ASIL Determination	Safety Goal	
HA-001	OM03 - Normal Driving	OS01 - City Road	FN01 - Normal conditions		Night time + Obstacle on the	IU01 - Correctly used	Normal Driving on City Road during Normal Normal Driving on City Road during Snowfall Normal Driving on Highway during Snowfall Normal Driving on Country Road during Normal Normal Driving on Country Road during Snowfall	Low beam illuminates the	DV01 - Function not activated	Both headlights stop working	EV04 - Front collision with obstacle	Vehicle crashes into the Total loss of low beam	F4 - High probability	night driving in the city is a regular	S1 - Light and moderate injuries	In city traffiic, speed of vehicle is expected to be low	C0 - Controllable in general	At city speed, most drivers will be able to	OM	Total loss of low beam	
HA-002	OM03 - Normal Driving	OS01 - City Road	EN01 - Normal conditions EN04 - Snowfall (degraded view)	SD03 - Low speed	Night time + Obstacle on the	IU01 - Correctly used	Normal Driving on City Road during Snowfall	Low beam illuminates the	DV01 - Function not activated	Both headlights stop working	EV04 - Front collision with obstacle	Vehicle crashes into the Total loss of low beam	E1 - Very low probability	night driving in the city on	S1 - Light and moderate injuries	In city traffiic, speed of vehicle is expected to be low	C1 - Simply controllable	On completely unilluminated city roads,	QM	Total loss of low beam	
HA-003	OM03 - Normal Driving	OS03 - Highway	EN04 - Snowfall (degraded view) EN04 - Snowfall (degraded view)	SD03 - Low speed SD03 - Low speed SD03 - High speed	Night time + Obstacle on the	IU01 - Correctly used	Normal Driving on Highway during Snowfall	Low beam illuminates the	DV01 - Function not activated	Both headlights stop working	EV04 - Front collision with obstacle	Vehicle crashes into the Total loss of low beam	E2 - Low probability	High driving is part of regular	S3 - Life-threatening or fatal injuries	On highway speed of vehicle is expected to be high	C2 - Normally controllable	When driving on highway with low beam, it	A	Total loss of low beam	
HA-004	OM03 - Normal Driving	OS02 - Country Road OS02 - Country Road	EN01 - Normal conditions	SD02 - High speed SD04 - High speed	Night time + Oncoming	IU01 - Correctly used	Normal Driving on Country Road during Normal	Low beam illuminates the	DV01 - Function not activated	Both headlights stop working	EV08 - Collision with other vehicle	Vehicle crashes into the Total loss of low beam	E4 - High probability	country driving is part of regular	S3 - Life-threatening or fatal injuries	On country roads speed of vehicle is expected to be high	C1 - Simply controllable	When driving on highway with low beam, it Since there is usually no other form of	В	Total loss of low beam	
HA-004 HA-005	OM03 - Normal Driving	OS02 - Country Road	EN04 - Snowfall (degraded view)	SD04 - High speed	Night time + Obstacle on the	IU01 - Correctly used	Normal Driving on Country Road during Snowfall	Low beam illuminates the	DV01 - Function not activated	Both headlights stop working Both headlights stop working Both headlights stop working Both headlights stop working	EV04 - Front collision with obstacle	Vehicle crashes into the Total loss of low beam	E2 - Low probability	country driving is part of regular	S3 - Life-threatening or fatal injuries	On country roads speed of vehicle is expected to be high	C3 - Difficult to control or uncontrollable	Since there is usually no other form of	В	Total loss of low beam	
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mazaru	I & Risk Analysis Defin	itions			
Operationa	al Mode				
ID	Mode	Remarks	Reference		
OM01	Parked	Car is parked, ignition is off	OM01 - Parked		
OM02	Ignition on	Car is parked, ignition is on	OM02 - Ignition on		
OM03	Normal driving	Car is driving	OM03 - Normal driving		
OM04	Backward driving	Car is driving Car is driving	OM04 - Backward driving		
OM05	Degraded driving	Limp home mode	OM04 - Backward driving OM05 - Degraded driving		
OMOS	Towing (active)	'			
OMO	Towing (active)	Towing another car	OM06 - Towing (active)		
OM07	Towing (passive)	Beeing towed by another car	OM07 - Towing (passive)		
	Service	Vehicle is in repair garage	OM08 - Service		
OM09	N/A	not applicable or not relevant	OM09 - N/A		
Operationa					
	Scenario	Remarks	Reference		
OS01	Any Road	road type	OS01 - Any Road		
OS02	City Road	road type	OS02 - City Road		
OS03	Country Road	road type	OS03 - Country Road		
	Highway	road type	OS04 - Highway		
	Mountain Pass	road type	OS05 - Mountain Pass		
OS06	Off Road	road type	OS06 - Off Road		
OS07	Road with gradient	road attribute	OS07 - Road with gradient		
OS08	Road with bump	road attribute	OS08 - Road with bump		
0500	Road tunnel	road attribute	OS09 - Road tunnel		
0000	Road with construction site	road attribute	OS10 - Road turner OS10 - Road with construction site		
OS10	NI/A				
0011	IN/A	not applicable or not relevant	OS11 - N/A		
Situation D					
	Scenario	Remarks	Reference		
SD01	Low speed	driving attribute	SD01 - Low speed		
SD02	High speed	driving attribute	SD02 - High speed		
SD03	Normal acceleration	driving attribute	SD03 - Normal acceleration		
SD04	High acceleration	driving attribute	SD04 - High acceleration		
SD05	Normal braking	driving attribute	SD05 - Normal braking		
SD06	High braking	driving attribute	SD06 - High braking		
SD07	N/A	not applicable or not relevant	SD07 - N/A		
Item Usage)				
	Mode	Remarks	Reference		
IU01	Correctly used	Intended usage	IU01 - Correctly used		
ILIO2	Incorrectly used	Unintended usage (foreseeable)	IU02 - Incorrectly used		
IU03	NI/A	not applicable or not relevant	IU03 - N/A		
1000	IN/A	The applicable of het relevant	1003 - IN/A		
Environ	ntal Details				
		Damadra	D. f		
	Scenario	Remarks	Reference		
EN01	Normal conditions	weather attribute	EN01 - Normal conditions		
	Sun blares (degraded view)	weather attribute			
ENUZ	E / L L L L L L L L L L L L L L L L L L		EN02 - Sun blares (degraded view)		
EN03	Fog (degraded view)	weather attribute	EN03 - Fog (degraded view)		
EN03 EN04	Fog (degraded view) Snowfall (degraded view)	weather attribute weather attribute	EN03 - Fog (degraded view) EN04 - Snowfall (degraded view)		
EN03 EN04 EN05	Fog (degraded view) Snowfall (degraded view) Cross-wind (lateral force)	weather attribute weather attribute weather attribute	EN03 - Fog (degraded view) EN04 - Snowfall (degraded view) EN05 - Cross-wind (lateral force)		
EN03 EN04 EN05 EN06	Fog (degraded view) Snowfall (degraded view) Cross-wind (lateral force) Rain (slippery road)	weather attribute weather attribute weather attribute road attribute	EN03 - Fog (degraded view) EN04 - Snowfall (degraded view) EN05 - Cross-wind (lateral force) EN06 - Rain (slippery road)		
EN03 EN04 EN05 EN06 EN07	Fog (degraded view) Snowfall (degraded view) Cross-wind (lateral force) Rain (slippery road) Snow (slippery road)	weather attribute weather attribute weather attribute	EN03 - Fog (degraded view) EN04 - Snowfall (degraded view) EN05 - Cross-wind (lateral force) EN06 - Rain (slippery road) EN07 - Snow (slippery road)		
EN03 EN04 EN05 EN06 EN07 EN08	Fog (degraded view) Snowfall (degraded view) Cross-wind (lateral force) Rain (slippery road) Snow (slippery road) Glace (slippery road)	weather attribute weather attribute weather attribute road attribute	EN03 - Fog (degraded view) EN04 - Snowfall (degraded view) EN05 - Cross-wind (lateral force) EN06 - Rain (slippery road)		
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Deviation					
ID	Deviation (Guideword)	Remarks	Reference		
DV01	Function not activated	Activation error	DV01 - Function not activated		
DV02	Function unexpectedly activated	Activation error	DV02 - Function unexpectedly activated		
DV03	Function always activated	Activation error	DV03 - Function always activated		
DV04	Actor effect is too much	Quantitative error	DV04 - Actor effect is too much		
DV05	Actor effect is too less	Quantitative error	DV05 - Actor effect is too less		
DV06	Actor action too early		DV06 - Actor action too early		
DV07	Actor action too late	Timing error Timing error	DV07 - Actor action too early DV07 - Actor action too late		
DV08	Actor action before		DV08 - Actor action before		
DV09		Sequence error			
DV10	Actor action after Actor effect is reverse	Sequence error	DV09 - Actor action after DV10 - Actor effect is reverse		
DV10		Logical error			
DV11	Actor effect is wrong	Logical error	DV11 - Actor effect is wrong		
DV12 DV13	Sensor sensitivity is too high	Quantitative error	DV12 - Sensor sensitivity is too high		
DV13	Sensor sensitivity is too low	Quantitative error	DV13 - Sensor sensitivity is too low		
	Sensor detection too early	Timing error	DV14 - Sensor detection too early		
DV15 DV16	Sensor detection too late	Timing error	DV15 - Sensor detection too late		
	Sensor detection before	Sequence error	DV16 - Sensor detection before		
DV17	Sensor detection after	Sequence error	DV17 - Sensor detection after		
DV18	Sensor detection is reverse	Logical error	DV18 - Sensor detection is reverse		
DV19	Sensor detection is wrong	Logical error	DV19 - Sensor detection is wrong		
DV20	N/A	not applicable or not relevant	DV20 - N/A		
<u> </u>	ents (possibe effects)				
ID TO	Hazardous Event	Remarks	Reference		
EV-07	None		EV-07 - None		
EV-06	Front collision with oncoming traffic		EV-06 - Front collision with oncoming traffic		
EV-05	Front collision with ahead traffic		EV-05 - Front collision with ahead traffic		
EV-04					
EV-03	Front collision with obstacle		EV-04 - Front collision with obstacle		
	Rear collision with trailing traffic		EV-03 - Rear collision with trailing traffic		
EV-02	Rear collision with trailing traffic Side collision with other traffic		EV-03 - Rear collision with trailing traffic EV-02 - Side collision with other traffic		
EV-01	Rear collision with trailing traffic Side collision with other traffic Side collision with obstacle		EV-03 - Rear collision with trailing traffic EV-02 - Side collision with other traffic EV-01 - Side collision with obstacle		
EV-01 EV00	Rear collision with trailing traffic Side collision with other traffic Side collision with obstacle Collision with other vehicle		EV-03 - Rear collision with trailing traffic EV-02 - Side collision with other traffic EV-01 - Side collision with obstacle EV00 - Collision with other vehicle		
EV-01 EV00 EV01	Rear collision with trailing traffic Side collision with other traffic Side collision with obstacle Collision with other vehicle Collision with train		EV-03 - Rear collision with trailing traffic EV-02 - Side collision with other traffic EV-01 - Side collision with obstacle EV00 - Collision with other vehicle EV01 - Collision with train		
EV-01 EV00 EV01 EV02	Rear collision with trailing traffic Side collision with other traffic Side collision with obstacle Collision with other vehicle Collision with train Collision with pedestrian		EV-03 - Rear collision with trailing traffic EV-02 - Side collision with other traffic EV-01 - Side collision with obstacle EV00 - Collision with other vehicle EV01 - Collision with train EV02 - Collision with pedestrian		
EV-01 EV00 EV01 EV02 EV03	Rear collision with trailing traffic Side collision with other traffic Side collision with obstacle Collision with other vehicle Collision with train Collision with pedestrian Car spins out of control		EV-03 - Rear collision with trailing traffic EV-02 - Side collision with other traffic EV-01 - Side collision with obstacle EV00 - Collision with other vehicle EV01 - Collision with train EV02 - Collision with pedestrian EV03 - Car spins out of control		
EV-01 EV00 EV01 EV02 EV03 EV04	Rear collision with trailing traffic Side collision with other traffic Side collision with obstacle Collision with other vehicle Collision with train Collision with pedestrian Car spins out of control Car comes off the road		EV-03 - Rear collision with trailing traffic EV-02 - Side collision with other traffic EV-01 - Side collision with obstacle EV00 - Collision with other vehicle EV01 - Collision with train EV02 - Collision with pedestrian EV03 - Car spins out of control EV04 - Car comes off the road		
EV-01 EV00 EV01 EV02 EV03 EV04 EV05	Rear collision with trailing traffic Side collision with other traffic Side collision with obstacle Collision with other vehicle Collision with train Collision with pedestrian Car spins out of control Car comes off the road Car catches file		EV-03 - Rear collision with trailing traffic EV-02 - Side collision with other traffic EV-01 - Side collision with obstacle EV00 - Collision with other vehicle EV01 - Collision with train EV02 - Collision with pedestrian EV03 - Car spins out of control EV04 - Car comes off the road EV05 - Car catches file		
EV-01 EV00 EV01 EV02 EV03 EV04	Rear collision with trailing traffic Side collision with other traffic Side collision with obstacle Collision with other vehicle Collision with train Collision with pedestrian Car spins out of control Car comes off the road		EV-03 - Rear collision with trailing traffic EV-02 - Side collision with other traffic EV-01 - Side collision with obstacle EV00 - Collision with other vehicle EV01 - Collision with train EV02 - Collision with pedestrian EV03 - Car spins out of control EV04 - Car comes off the road		
EV-01 EV00 EV01 EV02 EV03 EV04 EV05	Rear collision with trailing traffic Side collision with other traffic Side collision with obstacle Collision with other vehicle Collision with train Collision with pedestrian Car spins out of control Car comes off the road Car catches file		EV-03 - Rear collision with trailing traffic EV-02 - Side collision with other traffic EV-01 - Side collision with obstacle EV00 - Collision with other vehicle EV01 - Collision with train EV02 - Collision with pedestrian EV03 - Car spins out of control EV04 - Car comes off the road EV05 - Car catches file		
EV-01 EV00 EV01 EV02 EV03 EV04 EV05	Rear collision with trailing traffic Side collision with other traffic Side collision with obstacle Collision with other vehicle Collision with train Collision with pedestrian Car spins out of control Car comes off the road Car catches file		EV-03 - Rear collision with trailing traffic EV-02 - Side collision with other traffic EV-01 - Side collision with obstacle EV00 - Collision with other vehicle EV01 - Collision with train EV02 - Collision with pedestrian EV03 - Car spins out of control EV04 - Car comes off the road EV05 - Car catches file		
EV-01 EV00 EV01 EV02 EV03 EV04 EV05	Rear collision with trailing traffic Side collision with other traffic Side collision with obstacle Collision with other vehicle Collision with train Collision with pedestrian Car spins out of control Car comes off the road Car catches file		EV-03 - Rear collision with trailing traffic EV-02 - Side collision with other traffic EV-01 - Side collision with obstacle EV00 - Collision with other vehicle EV01 - Collision with train EV02 - Collision with pedestrian EV03 - Car spins out of control EV04 - Car comes off the road EV05 - Car catches file		
EV-01 EV00 EV01 EV02 EV03 EV04 EV05	Rear collision with trailing traffic Side collision with other traffic Side collision with obstacle Collision with other vehicle Collision with train Collision with pedestrian Car spins out of control Car comes off the road Car catches file		EV-03 - Rear collision with trailing traffic EV-02 - Side collision with other traffic EV-01 - Side collision with obstacle EV00 - Collision with other vehicle EV01 - Collision with train EV02 - Collision with pedestrian EV03 - Car spins out of control EV04 - Car comes off the road EV05 - Car catches file		
EV-01 EV00 EV01 EV02 EV03 EV04 EV05	Rear collision with trailing traffic Side collision with other traffic Side collision with obstacle Collision with other vehicle Collision with train Collision with pedestrian Car spins out of control Car comes off the road Car catches file		EV-03 - Rear collision with trailing traffic EV-02 - Side collision with other traffic EV-01 - Side collision with obstacle EV00 - Collision with other vehicle EV01 - Collision with train EV02 - Collision with pedestrian EV03 - Car spins out of control EV04 - Car comes off the road EV05 - Car catches file		
EV-01 EV00 EV01 EV02 EV03 EV04 EV05	Rear collision with trailing traffic Side collision with other traffic Side collision with obstacle Collision with other vehicle Collision with train Collision with pedestrian Car spins out of control Car comes off the road Car catches file		EV-03 - Rear collision with trailing traffic EV-02 - Side collision with other traffic EV-01 - Side collision with obstacle EV00 - Collision with other vehicle EV01 - Collision with train EV02 - Collision with pedestrian EV03 - Car spins out of control EV04 - Car comes off the road EV05 - Car catches file		
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Evposuro						
Exposure						
ID	Description	Duration (of situation)	Frequency (of situation)	Reference		
E0	Incredible			E0 - Incredible		
E1	Very low probability	Not specified	Occurs less often than once a year for the great majority of drivers	E1 - Very low probability		
E2	Low probability	<1 % of average operating time	Occurs a few times a year for the great majority of drivers	E2 - Low probability		
E3	Medium probability	1 % to 10 % of average operating time	Occurs once a month or more often for an average driver	E3 - Medium probability		
E4	High probability	>10 % of average operating time	Occurs during almost every drive on average	E4 - High probability		
Severity						
ID	Description	Remarks	Probability of Injuries	Reference		
S0	No injuries	No injuries	AIS 0 and less than 10 % probability of AIS 1-6	S0 - No injuries		
S1	Light and moderate injuries	Light and moderate injuries	More than 10 % probability of AIS 1-6 (and not S2 or S3)	S1 - Light and moderate injuries		
S2	Severe and life-threatening injuries	Severe and life-threatening injuries (survival probable)	More than 10 % probability of AIS 3-6 (and not S3)	S2 - Severe and life-threatening injuries		
S3	Life-threatening or fatal injuries	Life-threatening injuries (survival uncertain), fatal injuries	More than 10 % probability of AIS 5-6	S3 - Life-threatening or fatal injuries		
Controllability						
ID	Description	Remarks		Reference		
C0	Controllable in general	Controllable in general		C0 - Controllable in general		
C1	Simply controllable	99 % or more of all drivers or other traffic participants are usually at	ole to avoid harm	C1 - Simply controllable		
C2	Normally controllable	90 % or more of all drivers or other traffic participants are usually at	ole to avoid harm	C2 - Normally controllable		
C3	Difficult to control or uncontrollable	Less than 90 % of all drivers or other traffic participants are usually	able, or barely able, to avoid harm	C3 - Difficult to control or uncontrollable		

	Controllability	Exposure	Severity						
	Controllability	Lxposure	S0	S1	S2	S3			
	C1	E1	QM	QM	QM	QM			
		E2	QM	QM	QM	QM			
		E3	QM	QM	QM	Α			
		E4	QM	QM	Α	В			
		E1	QM	QM	QM	QM			
	C2	E2	QM	QM	QM	Α			
	62	E3	QM	QM	Α	В			
		E4	QM	Α	В	С			
		E1	QM	QM	QM	Α			
	Ca	E2	QM	QM	Α	В			
	C3	E3	QM	Α	В	С			
		E4	QM	В	С	D			