

8 Taxicab

8.1 Converting a String

You can use the conversion function `atoi(s)` to convert the string `s` into an `int` value. To use `atoi`, `<stdlib.h>` should be included. The following code shows how to use `atoi`:

```
1 #include <stdio.h>
2 #include <stdlib.h>
3
4 int main()
5 {
6     char *s[] = {"100", "-12"};
7     int sz = sizeof s / sizeof s[0], sum = 0;
8
9     for (int i = 0; i < sz; i++) {
10         sum += atoi(s[i]);
11     }
12     printf("sum = %d\n", sum);
13
14     return 0 ;
15 }
```

Note that there are additional conversion functions in `<stdlib.h>` such as `atol` for long, `atoll` for long long, and `atof` for double.

8.2 Programming Lab 8: taxicab.c

Given a sequence of instructions for the taxicab driven by an AI robot, find the final position and orientation of the taxicab. An instruction is one of the following characters: F (forward), B (backward), L (turn left), and R (turn right). The first two instructions (F and B) can have an additional integer argument n ($0 < n < 10$) denoting the number of unit distances for the movement. The turning instructions (L and R) are always turning by 90° . The initial location of the taxicab is the origin, $(0,0)$, and it is originally directed to the east (the x -direction).

For example, given the following sequence of instructions

F 5, L, F 2, L, B 3, R, and F 1,

the final location is $(8,3)$ and the orientation is the north (the y -direction).

The input consists of one or more lines in standard input. Each line contains a single instruction for the taxicab. For instructions F and B, the argument n is separated by space. Your program should print two lines in standard output. The first line should contain the x and y coordinates separated by space, and the second line, the final orientation in one of the characters in “NEWS”: N for north, E for east, W for west, and S for south.

Additional requirements for bonus points

- Do not use `if` statement but a `switch` statement with the minimal number of `break` statements inside.
- Use `enum` constants to represent the orientation of the taxicab.

Input	Output
F 5 L F 2 L B 3 R F 1	8 3 N
F 1 R R F 1	0 0 W