



CS 103 -09

Perceptron Learning and ADALINE

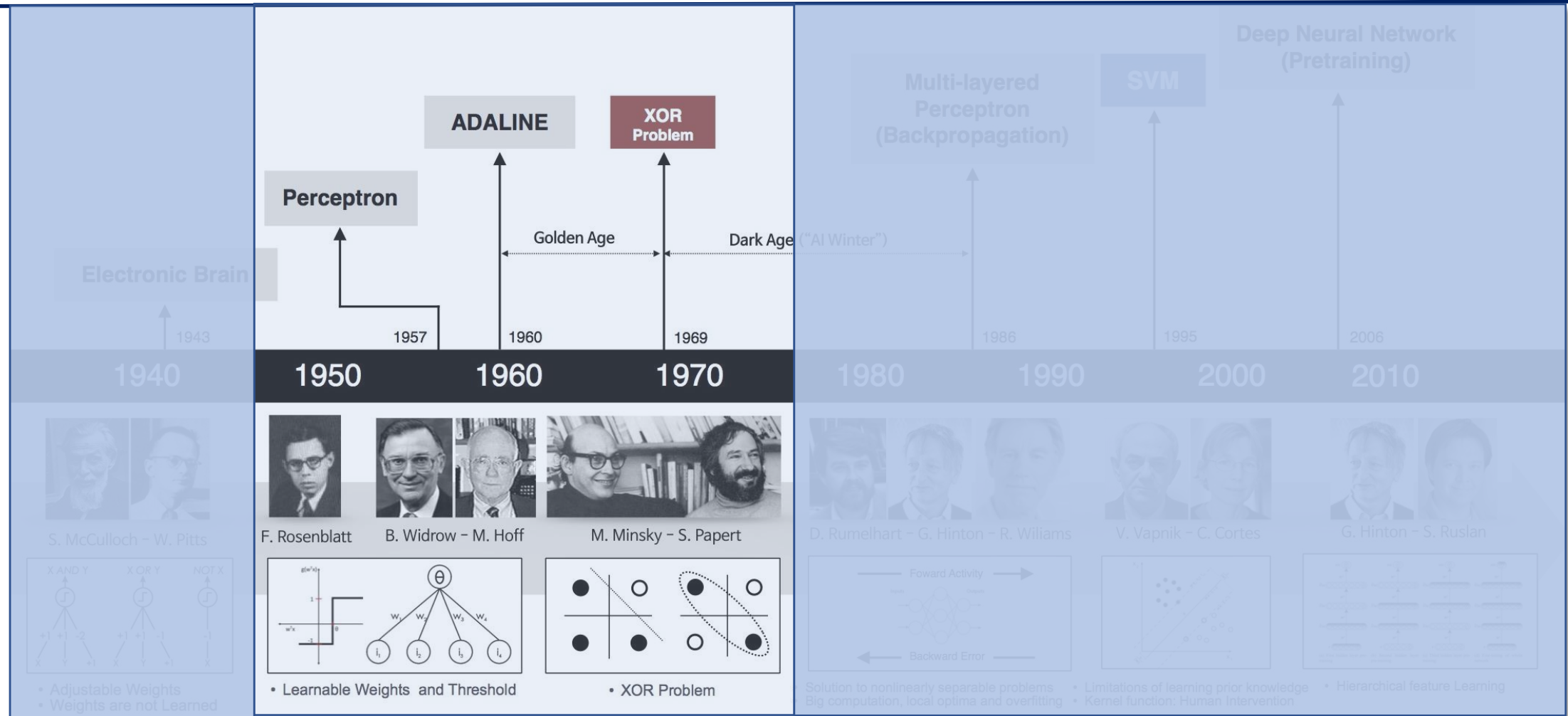
Jimmy Liu 刘江

2020-11-12

Group Project Update



AI algorithm Developments - A Closer Look



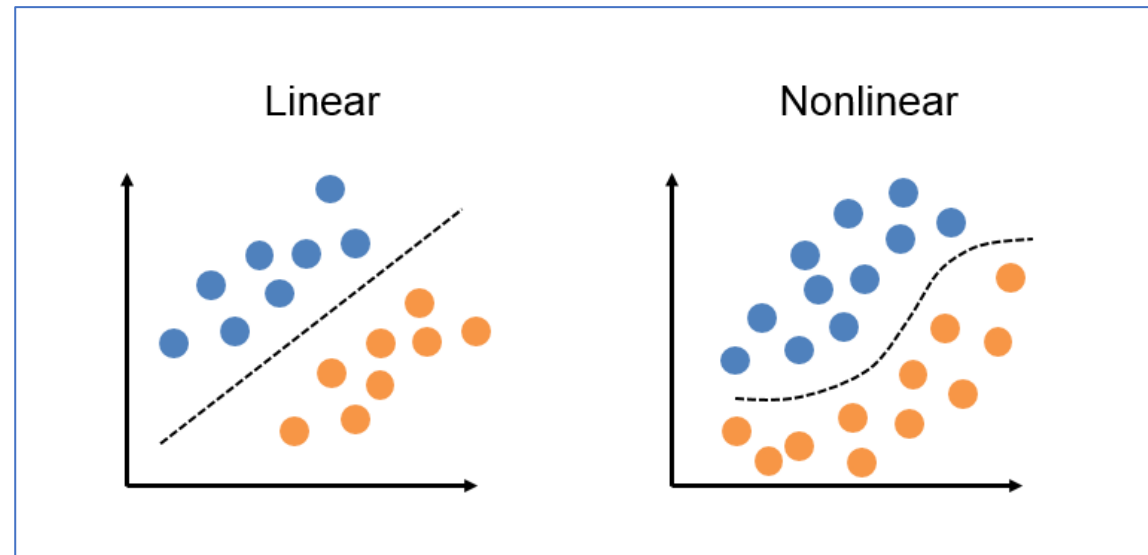
Perceptron

-
- 3
 - 4
 - 1 Perceptron
 - 2 Perceptron Learning
 - 3 ADALINE
 - 4 Limitation of Perceptron

Q1: What Does “A Function is Linearly Separable ”Mean?



Linearly Separable



A function is said to be **linearly separable** when its outputs can be discriminated by a function which is a linear combination of features, that is we can discriminate its outputs by a line or a hyperplane.

Traditional Perceptron Decision Surface

A **threshold perceptron** returns 1 iff the weighted sum of its inputs (including the bias) is positive, i.e.,:

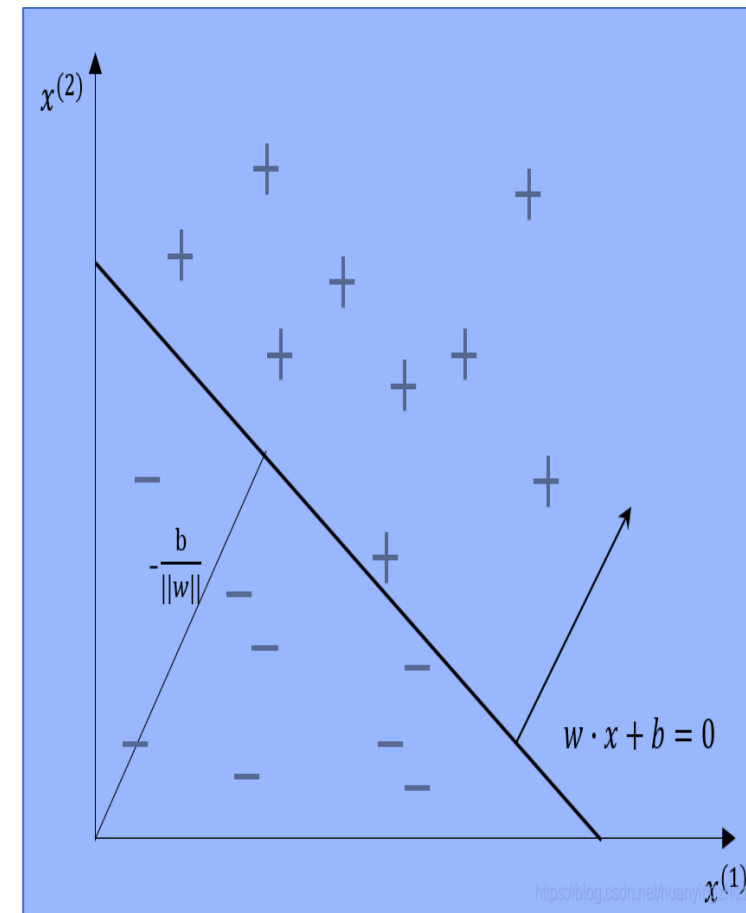
$$\sum_{j=0}^n W_j x_j > 0 \quad \text{or} \quad \mathbf{W} \cdot \mathbf{x} > 0$$

I.e., iff the input is on one side of the **hyperplane it defines**.

Perceptron \rightarrow **Linear Separator**

Linear discriminant function or linear decision surface.

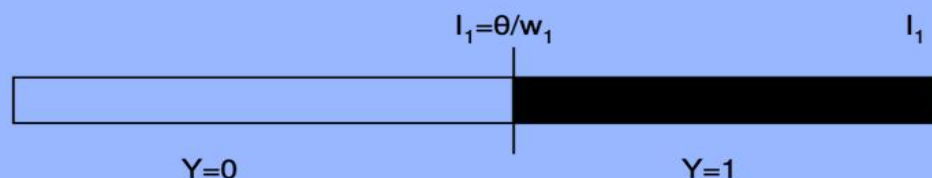
Weights determine slope and bias determines offset.



Decision Surface

Decision surface is the surface at which the output of the unit is precisely equal to the threshold, i.e. $\sum_{i=1 \dots n} w_i I_i = \theta$

In **1-D** the surface is just a point:



In **2-D**, the surface is

$$I_1 \cdot w_1 + I_2 \cdot w_2 - \theta = 0$$

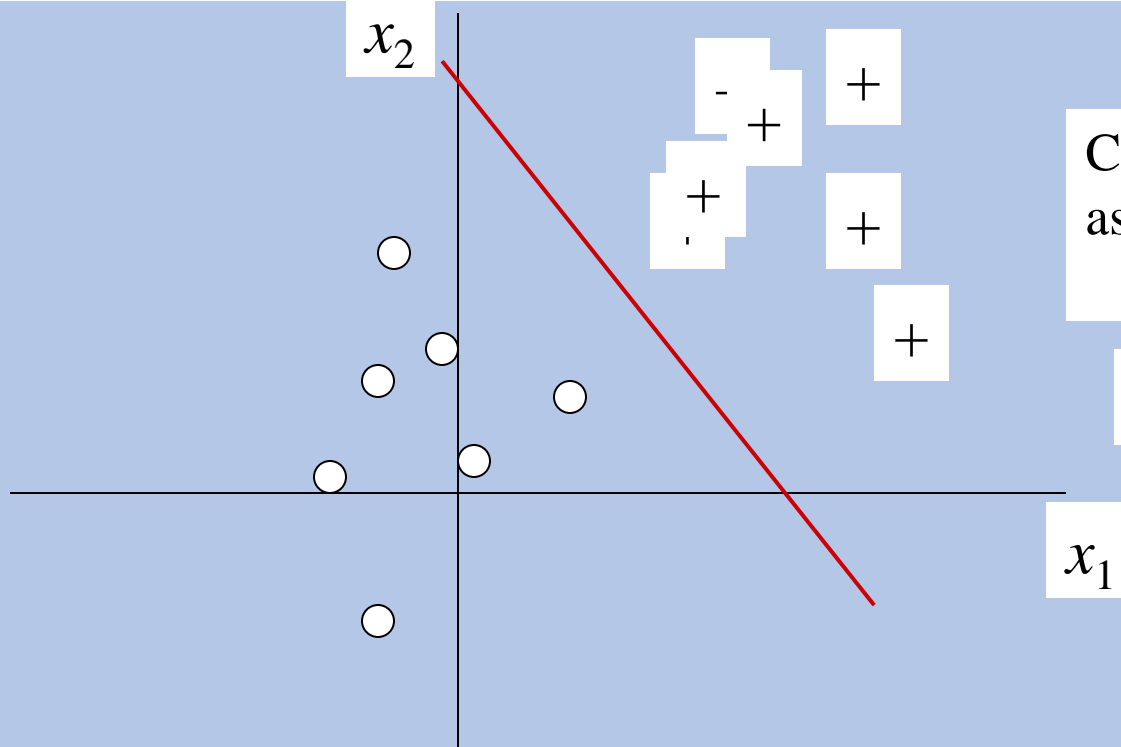
which we can re-write as

$$I_2 = \frac{\theta}{w_2} - \frac{w_1}{w_2} I_1$$

So, in 2-D the decision boundaries are **always** straight lines.

Exercise: Separation Line

Consider example with two inputs, x_1 , x_2 :



Can view trained network as defining a “separation line”.

What is its equation?

$$-w_0 + w_1x_1 + w_2x_2 = 0$$

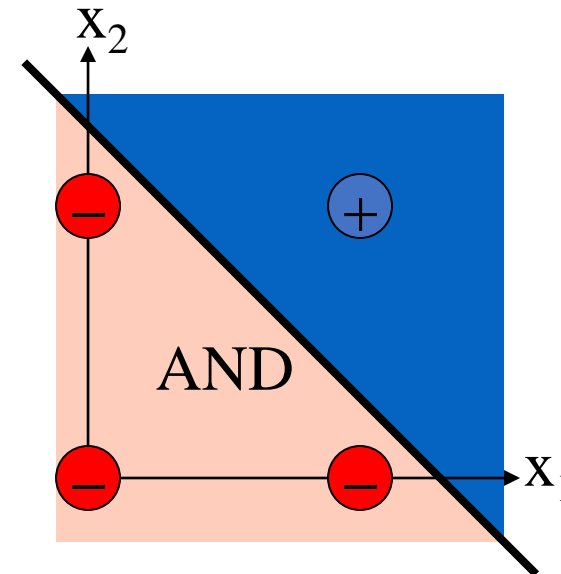
$$x_2 = -\frac{w_1}{w_2}x_1 + \frac{w_0}{w_2}$$

Perceptron used for classification

Exercise: Plot the Separation Lines for “AND”

AND

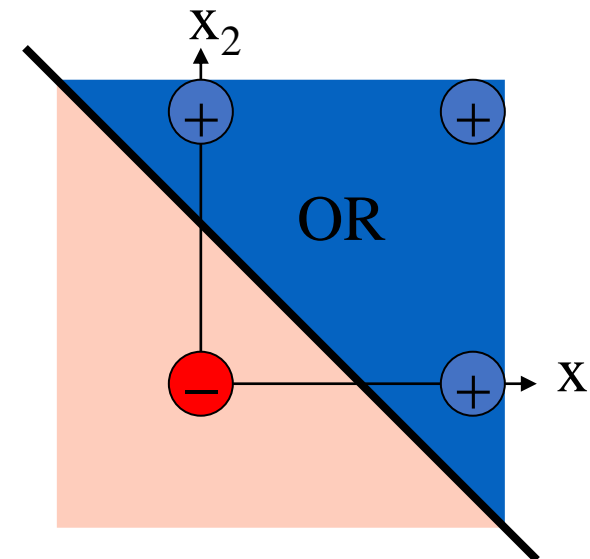
$$\begin{aligned} W_1 &= 1 \\ W_2 &= 1 \\ W_0/\theta &= 1.5 \end{aligned}$$



Exercise: Plot the Separation Lines for “OR”

OR

$$\begin{aligned}W1 &= 1 \\W2 &= 1 \\W0 / \theta &= 0.5\end{aligned}$$

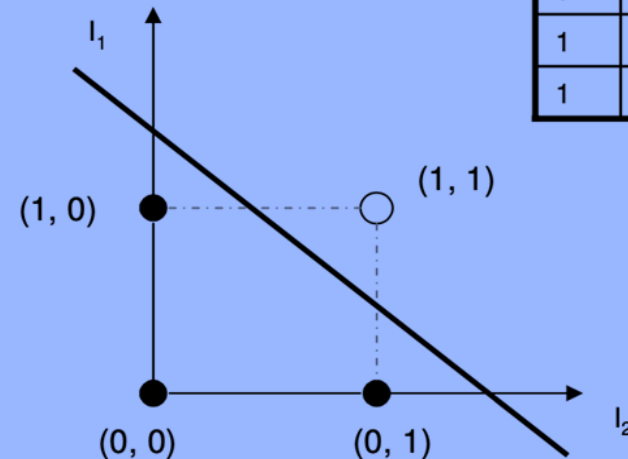


Decision Surfaces/Boundaries for AND and OR

We can now plot the decision boundaries of our logic gates

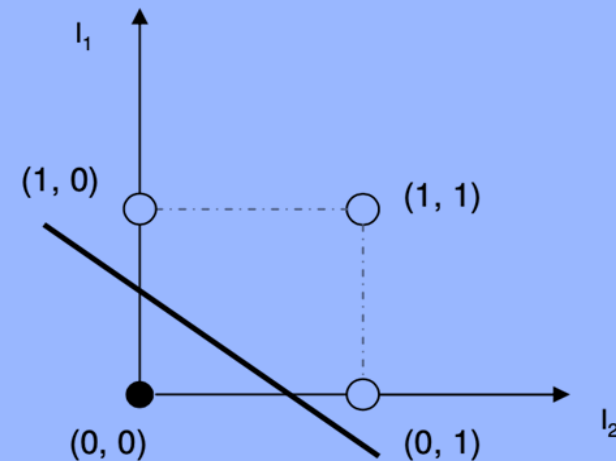
AND
 $w_1=1, w_2=1, \theta=1.5$

AND		
I_1	I_2	out
0	0	0
0	1	0
1	0	0
1	1	1



OR
 $w_1=1, w_2=1, \theta=0.5$

OR		
I_1	I_2	out
0	0	0
0	1	1
1	0	1
1	1	1



How to Learn “OR Perceptron”?

Training Input Samples

Consider learning the logical OR function.
Our examples are:

Sample	x0	x1	x2	label
1	1	0	0	0
2	1	0	1	1
3	1	1	0	1
4	1	1	1	1

Activation Function

$$S = \sum_{k=0}^{k=n} w_k x_k \quad S > 0 \text{ then } O = 1 \quad \text{else} \quad O = 0$$

Recall: Typical Perceptron Weight Updates

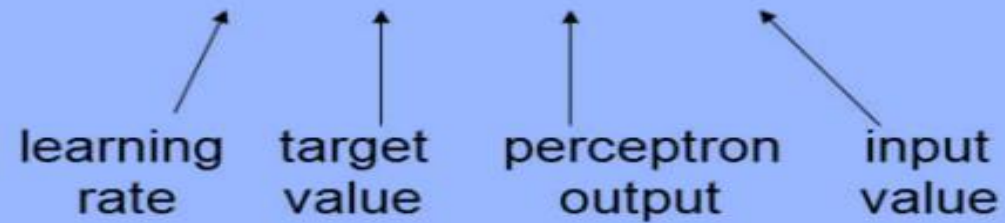
- Weights modified for each example
- Update Rule:

$$w_i \leftarrow w_i + \Delta w_i$$

where

$$\Delta w_i = \eta(t - o)x_i$$

learning rate target value perceptron output input value



OR Perceptron Weight Update Rule

$$S = \sum_{k=0}^{k=n} w_k x_k \quad S > 0 \text{ then } O = 1 \quad \text{else} \quad O = 0$$

Weight Update (We set learning rate =1)

If perceptron output is 0 while it should be 1,
add the input vector to the weight vector (if input = 1, you add 1)
(if input =0, you can assume that you add 0)
If perceptron output is 1 while it should be 0,
subtract the input vector to the weight vector if input x is 1
(if input =0, you subtract 0)

Otherwise do nothing.

OR Perceptron

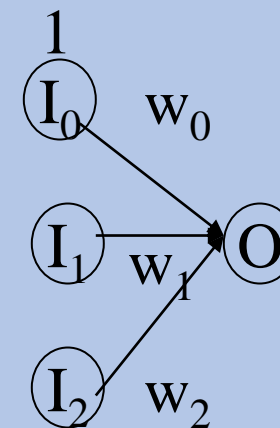
Learn First 2 Examples in Epoch 1

We'll use a single perceptron with three inputs.
We'll start with all weights 0 $W = \langle 0, 0, 0 \rangle$

Example 1 $I = \langle 1 \ 0 \ 0 \rangle$ label=0 $W = \langle 0, 0, 0 \rangle$
Perceptron ($1 \times 0 + 0 \times 0 + 0 \times 0 = 0$, $S=0$) output $\rightarrow 0$
 \rightarrow it classifies it as 0, so correct, **do nothing**

Example 2 $I = \langle 1 \ 0 \ 1 \rangle$ label=1 $W = \langle 0, 0, 0 \rangle$
Perceptron ($1 \times 0 + 0 \times 0 + 1 \times 0 = 0$) output $\rightarrow 0$

\rightarrow it classifies it as 0, while it should be 1, so **add input to weights**
 $W = \langle 0, 0, 0 \rangle + \langle 1, 0, 1 \rangle = \langle 1, 0, 1 \rangle$



OR Perceptron

Learn Next 2 Samples in Epoch 1

Example 3 $I = \langle 1 \ 1 \ 0 \rangle$ label=1 $W = \langle 1, 0, 1 \rangle$

Perceptron $(1 \times 1 + 1 \times 0 + 0 \times 1 > 0)$ output = 1

→ it classifies it as 1, while it should be 1, so **do nothing**

Example 4 $I = \langle 1 \ 1 \ 1 \rangle$ label=1 $W = \langle 1, 0, 1 \rangle$

Perceptron $(1 \times 1 + 1 \times 0 + 1 \times 1 > 0)$ output = 1

→ it classifies it as 1, correct, **do nothing**

$W = \langle 1, 0, 1 \rangle$

OR Perceptron Training and Learning Example

Learn First 2 Samples in Epoch 2

Epoch 2, through the examples, $W = \langle 1, 0, 1 \rangle$.

Example 1 $I = \langle 1, 0, 0 \rangle$ label=0 $W = \langle 1, 0, 1 \rangle$

Perceptron ($1 \times 1 + 0 \times 0 + 0 \times 1 > 0$) output $\rightarrow 1$

\rightarrow it classifies it as 1, while it should be 0,

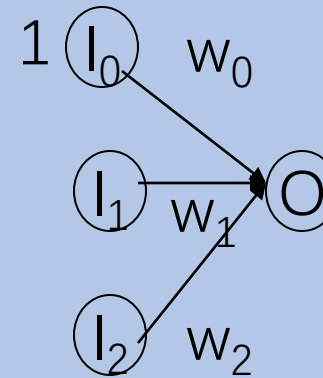
so subtract input from weights

$$W = \langle 1, 0, 1 \rangle - \langle 1, 0, 0 \rangle = \langle 0, 0, 1 \rangle$$

Example 2 $I = \langle 1, 0, 1 \rangle$ label=1 $W = \langle 0, 0, 1 \rangle$

Perceptron ($1 \times 0 + 0 \times 0 + 1 \times 1 > 0$) output $\rightarrow 1$

\rightarrow it classifies it as 1, so correct, do nothing



OR Perceptron Training and Learning Example

Learn Next 2 Samples in Epoch 2

Example 3 $I = \langle 1 \ 1 \ 0 \rangle$ label=1 $W = \langle 0, 0, 1 \rangle$

Perceptron ($1 \times 0 + 1 \times 0 + 0 \times 1 > 0$) output = 0

→ it classifies it as 0, while it should be 1, so

add input to weights

$$W = \langle 0, 0, 1 \rangle + I = \langle 1, 1, 0 \rangle = \langle 1, 1, 1 \rangle$$

Example 4 $I = \langle 1 \ 1 \ 1 \rangle$ label=1 $W = \langle 1, 1, 1 \rangle$

Perceptron ($1 \times 1 + 1 \times 1 + 1 \times 1 > 0$) output = 1

→ it classifies it as 1, correct, do nothing

$$W = \langle 1, 1, 1 \rangle$$

OR Perceptron Training and Learning Example

Learn First 2 Samples in Epoch 3

Epoch 3, through the examples, $W = \langle 1, 1, 1 \rangle$.

Example 1 $I = \langle 1, 0, 0 \rangle$ label=0 $W = \langle 1, 1, 1 \rangle$

Perceptron ($1 \times 1 + 0 \times 1 + 0 \times 1 > 0$) output $\rightarrow 1$

\rightarrow it classifies it as 1, while it should be 0, so

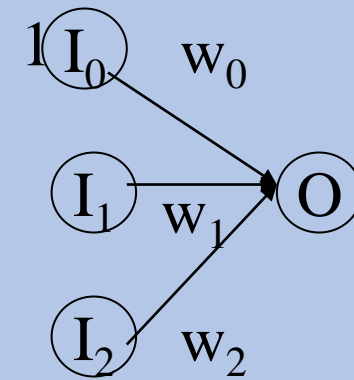
subtract input from weights

$$W = \langle 1, 1, 1 \rangle - I = \langle 1, 0, 0 \rangle = \langle 0, 1, 1 \rangle$$

Example 2 $I = \langle 1, 0, 1 \rangle$ label=1 $W = \langle 0, 1, 1 \rangle$

Perceptron ($1 \times 0 + 0 \times 1 + 1 \times 1 > 0$) output $\rightarrow 1$

\rightarrow it classifies it as 1, so correct, do nothing



OR Perceptron Training and Learning Example

Learn Next 2 Samples in Epoch 3

Example 3 $I = \langle 1 \ 1 \ 0 \rangle$ label=1 $W = \langle 0, 1, 1 \rangle$

Perceptron $(1 \times 0 + 1 \times 1 + 0 \times 1 > 0)$ output = 1

→ it classifies it as 1, correct, **do nothing**

Example 4 $I = \langle 1 \ 1 \ 1 \rangle$ label=1 $W = \langle 0, 1, 1 \rangle$

Perceptron $(1 \times 0 + 1 \times 1 + 1 \times 1 > 0)$ output = 1

→ it classifies it as 1, correct, **do nothing**

$W = \langle 1, 1, 1 \rangle$

OR Perceptron Training and Learning Example

Learn First Samples in Epoch 4

Epoch 4, through the examples, $W = \langle 0, 1, 1 \rangle$.

Example 1 $I = \langle 1, 0, 0 \rangle$ label=0 $W = \langle 0, 1, 1 \rangle$

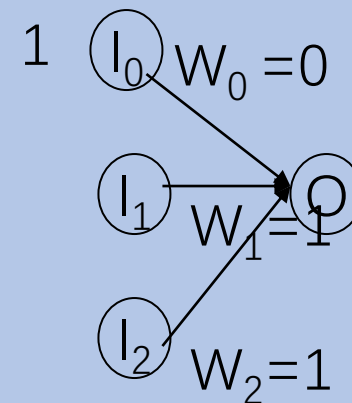
Perceptron ($1 \times 0 + 0 \times 1 + 0 \times 1 = 0$) output $\rightarrow 0$

\rightarrow it classifies it as 0, so correct, **do nothing**

So the final weight vector $W = \langle 0, 1, 1 \rangle$ classifies all examples correctly, and the perceptron has learned the function!

In more realistic cases the bias (W_0) will not be 0.

Also, in general, many more inputs (100 to 1000...)



OR

[illegible]

Epoch	x0	x1	x2	Desired Target	w0	w1	w2	Output	Error	New w0	New w1	New w2
1 example 1	1	0	0	0	0	0	0	0	0	0	0	0
example 2	1	0	1	1	0	0	0	0	1	1	0	1

OR Perceptron Learning Summary

Epoch	x0	x1	x2	Desired Target	w0	w1	w2	Output	Error	New w0	New w1	New w2
1 example 1	1	0	0	0	0	0	0	0	0	0	0	0
example 2	1	0	1	1	0	0	0	0	1	1	0	1
example 3	1	1	0	1	1	0	1	1	0	1	0	1

OR Perceptron Learning Summary

Epoch	x0	x1	x2	Desired Target	w0	w1	w2	Output	Error	New w0	New w1	New w2
1 example 1	1	0	0	0	0	0	0	0	0	0	0	0
example 2	1	0	1	1	0	0	0	0	1	1	0	1
example 3	1	1	0	1	1	0	1	1	0	1	0	1
example 4	1	1	1	1	1	0	1	1	0	1	0	1

Epoch	x0	x1	x2	Desired Target	w0	w1	w2	Output	Error	New w0	New w1	New w2
1 example 1	1	0	0	0	0	0	0	0	0	0	0	0
example 2	1	0	1	1	0	0	0	0	1	1	0	1
example 3	1	1	0	1	1	0	1	1	0	1	0	1
example 4	1	1	1	1	1	0	1	1	0	1	0	1
2 example 1	1	0	0	0	1	0	1	1	-1	0	0	1

OR Perceptron Learning Summary

OR Perceptron Learning Summary

Epoch	x0	x1	x2	Desired Target	w0	w1	w2	Output	Error	New w0	New w1	New w2
1 example 1	1	0	0	0	0	0	0	0	0	0	0	0
example 2	1	0	1	1	0	0	0	0	1	1	0	1
example 3	1	1	0	1	1	0	1	1	0	1	0	1
example 4	1	1	1	1	1	0	1	1	0	1	0	1
2 example 1	1	0	0	0	1	0	1	1	-1	0	0	1
example 2	1	0	1	1	0	0	1	1	0	0	0	1
example 3	1	1	0	1	0	0	1	0	1	1	1	1

Epoch	x0	x1	x2	Desired Target	w0	w1	w2	Output	Error	New w0	New w1	New w2
1 example 1	1	0	0	0	0	0	0	0	0	0	0	0
example 2	1	0	1	1	0	0	0	0	1	1	0	1
example 3	1	1	0	1	1	0	1	1	0	1	0	1
example 4	1	1	1	1	1	0	1	1	0	1	0	1
2 example 1	1	0	0	0	1	0	1	1	-1	0	0	1
example 2	1	0	1	1	0	0	1	1	0	0	0	1
example 3	1	1	0	1	0	0	1	0	1	1	1	1
example 4	1	1	1	1	1	1	1	1	0	1	1	1
3 example 1	1	0	0	0	1	1	1	1	-1	0	1	1

Epoch	x0	x1	x2	Desired Target	w0	w1	w2	Output	Error	New w0	New w1	New w2
1 example 1	1	0	0	0	0	0	0	0	0	0	0	0
example 2	1	0	1	1	0	0	0	0	1	1	0	1
example 3	1	1	0	1	1	0	1	1	0	1	0	1
example 4	1	1	1	1	1	0	1	1	0	1	0	1
2 example 1	1	0	0	0	1	0	1	1	-1	0	0	1
example 2	1	0	1	1	0	0	1	1	0	0	0	1
example 3	1	1	0	1	0	0	1	0	1	1	1	1
example 4	1	1	1	1	1	1	1	1	0	1	1	1
3 example 1	1	0	0	0	1	1	1	1	-1	0	1	1
example 2	1	0	1	1	0	1	1	1	0	0	1	1

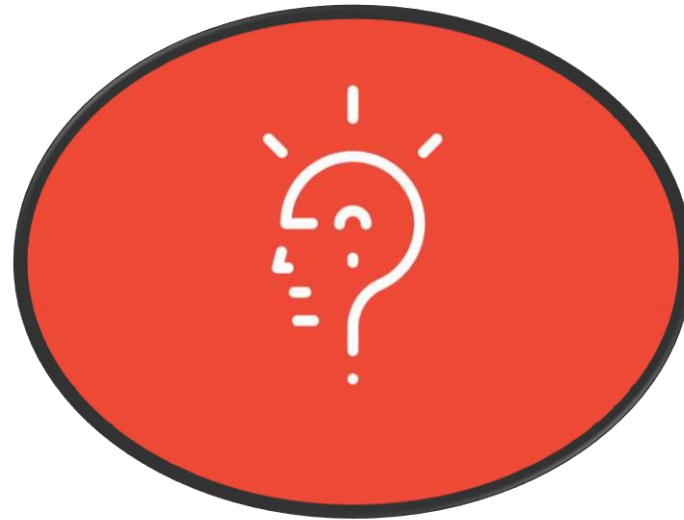
Epoch	x0	x1	x2	Desired Target	w0	w1	w2	Output	Error	New w0	New w1	New w2
1 example 1	1	0	0	0	0	0	0	0	0	0	0	0
example 2	1	0	1	1	0	0	0	0	1	1	0	1
example 3	1	1	0	1	1	0	1	1	0	1	0	1
example 4	1	1	1	1	1	0	1	1	0	1	0	1
2 example 1	1	0	0	0	1	0	1	1	-1	0	0	1
example 2	1	0	1	1	0	0	1	1	0	0	0	1
example 3	1	1	0	1	0	0	1	0	1	1	1	1
example 4	1	1	1	1	1	1	1	1	0	1	1	1
3 example 1	1	0	0	0	1	1	1	1	-1	0	1	1
example 2	1	0	1	1	0	1	1	1	0	0	1	1.
example 3	1	1	0	1	0	1	1	1	0	0	1	1

Epoch	x0	x1	x2	Desired Target	w0	w1	w2	Output	Error	New w0	New w1	New w2
1 example 1	1	0	0	0	0	0	0	0	0	0	0	0
example 2	1	0	1	1	0	0	0	0	1	1	0	1
example 3	1	1	0	1	1	0	1	1	0	1	0	1
example 4	1	1	1	1	1	0	1	1	0	1	0	1
2 example 1	1	0	0	0	1	0	1	1	-1	0	0	1
example 2	1	0	1	1	0	0	1	1	0	0	0	1
example 3	1	1	0	1	0	0	1	0	1	1	1	1
example 4	1	1	1	1	1	1	1	1	0	1	1	1
3 example 1	1	0	0	0	1	1	1	1	-1	0	1	1
example 2	1	0	1	1	0	1	1	1	0	0	1	1.
example 3	1	1	0	1	0	1	1	1	0	0	1	1
example 4	1	1	1	1	0	1	1	1	0	0	1	1

OR Perceptron Learning Summary

Epoch	x0	x1	x2	Desired Target	w0	w1	w2	Output	Error	New w0	New w1	New w2
1 example 1	1	0	0	0	0	0	0	0	0	0	0	0
example 2	1	0	1	1	0	0	0	0	1	1	0	1
example 3	1	1	0	1	1	0	1	1	0	1	0	1
example 4	1	1	1	1	1	0	1	1	0	1	0	1
2 example 1	1	0	0	0	1	0	1	1	-1	0	0	1
example 2	1	0	1	1	0	0	1	1	0	0	0	1
example 3	1	1	0	1	0	0	1	0	1	1	1	1
example 4	1	1	1	1	1	1	1	1	0	1	1	1
3 example 1	1	0	0	0	1	1	1	1	-1	0	1	1
example 2	1	0	1	1	0	1	1	1	0	0	1	1
example 3	1	1	0	1	0	1	1	1	0	0	1	1
example 4	1	1	1	1	0	1	1	1	0	0	1	1
4 example 1	1	0	0	0	0	1	1	0	0	0	1	1

Any Question?



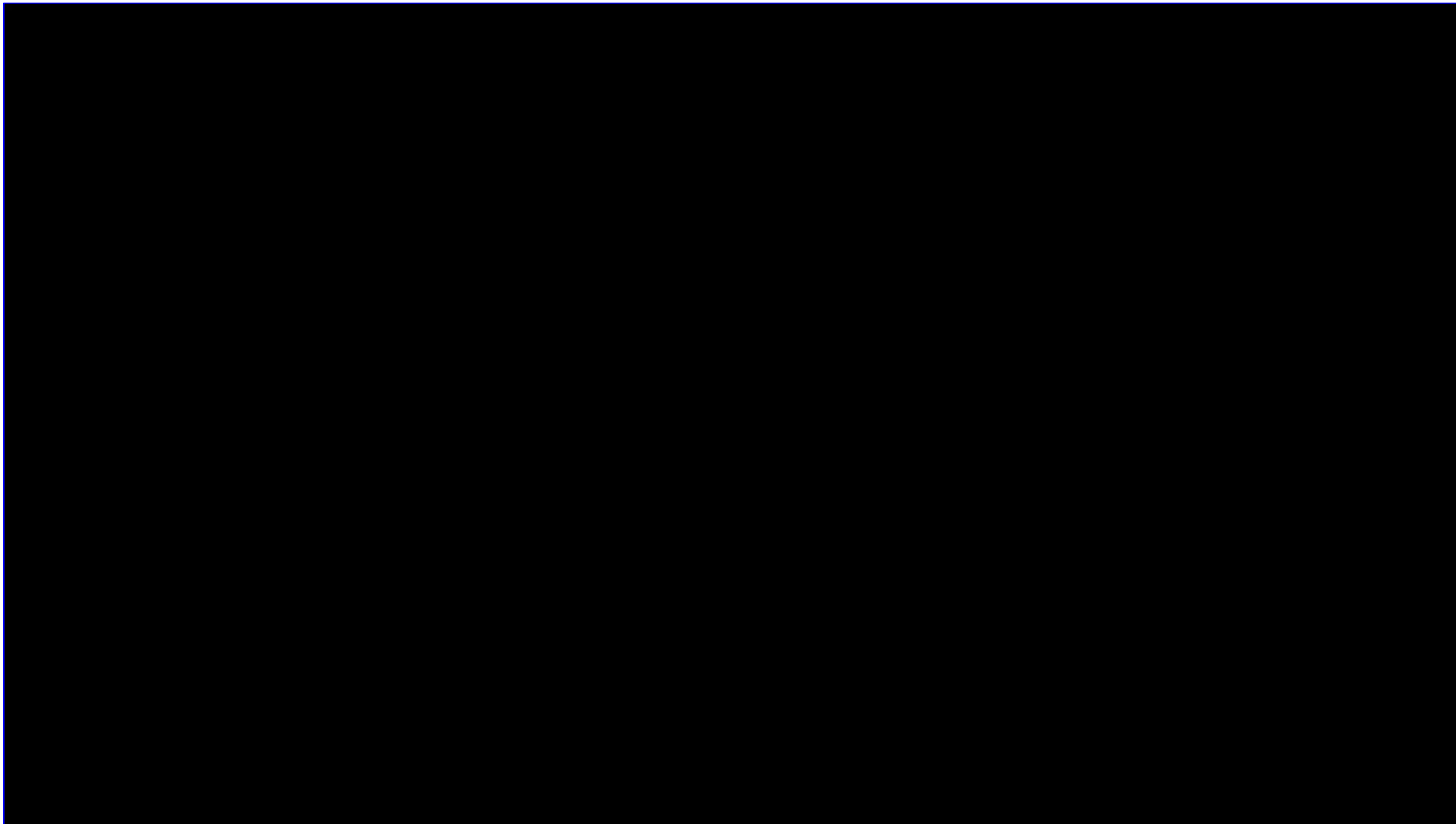
Perceptron

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Q2: What Does “Linear Regression” Mean?

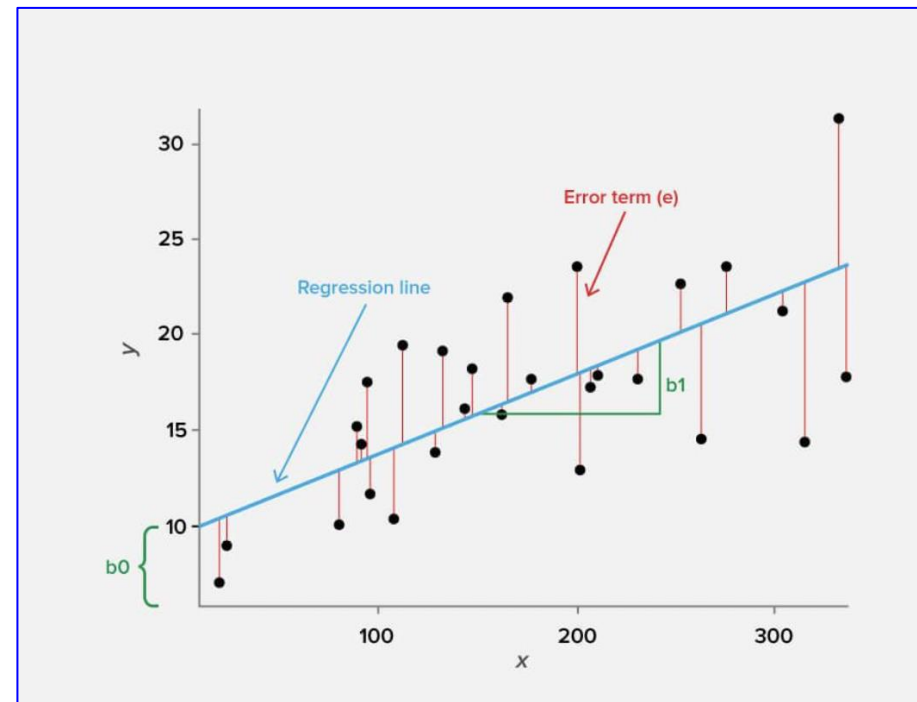
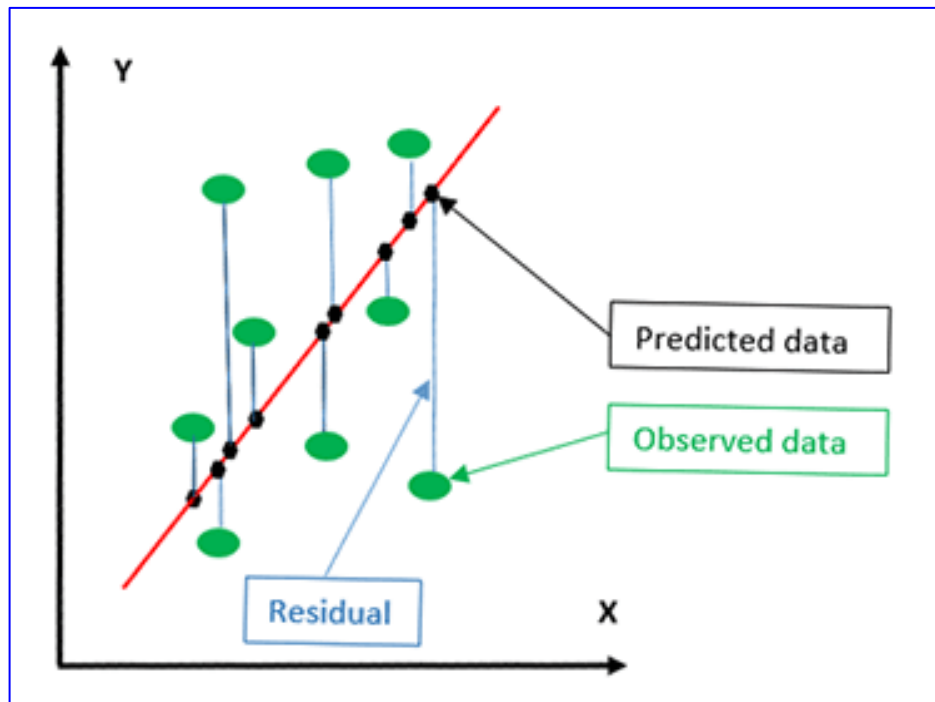


Linear Regression

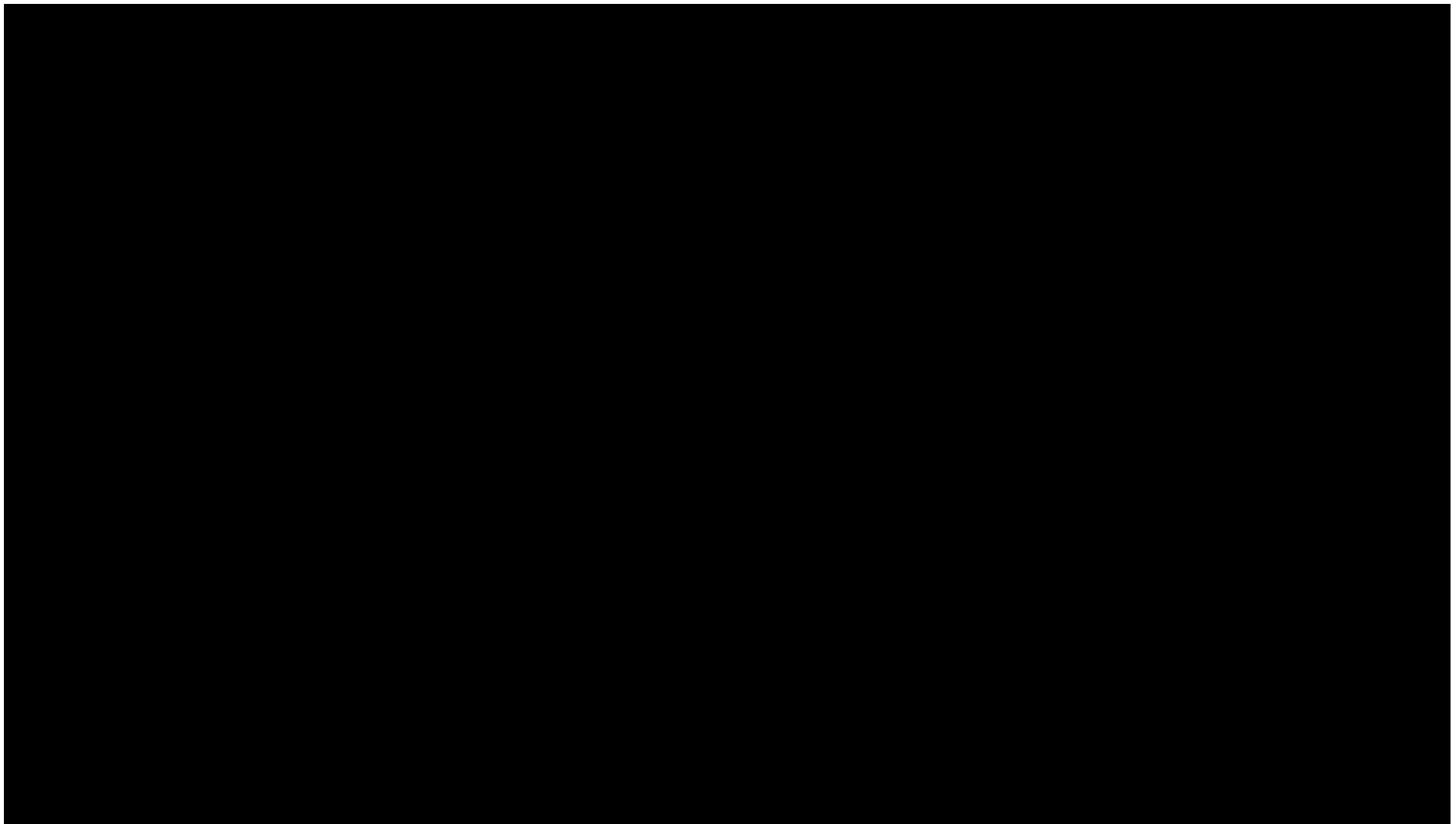


Linear Regression

- Linear Regression is a statistical procedure that determines the equation for the straight line that **best** fits a specific set of data.



Classification and Regression



ADALINE (Adaptive Linear Neuron)

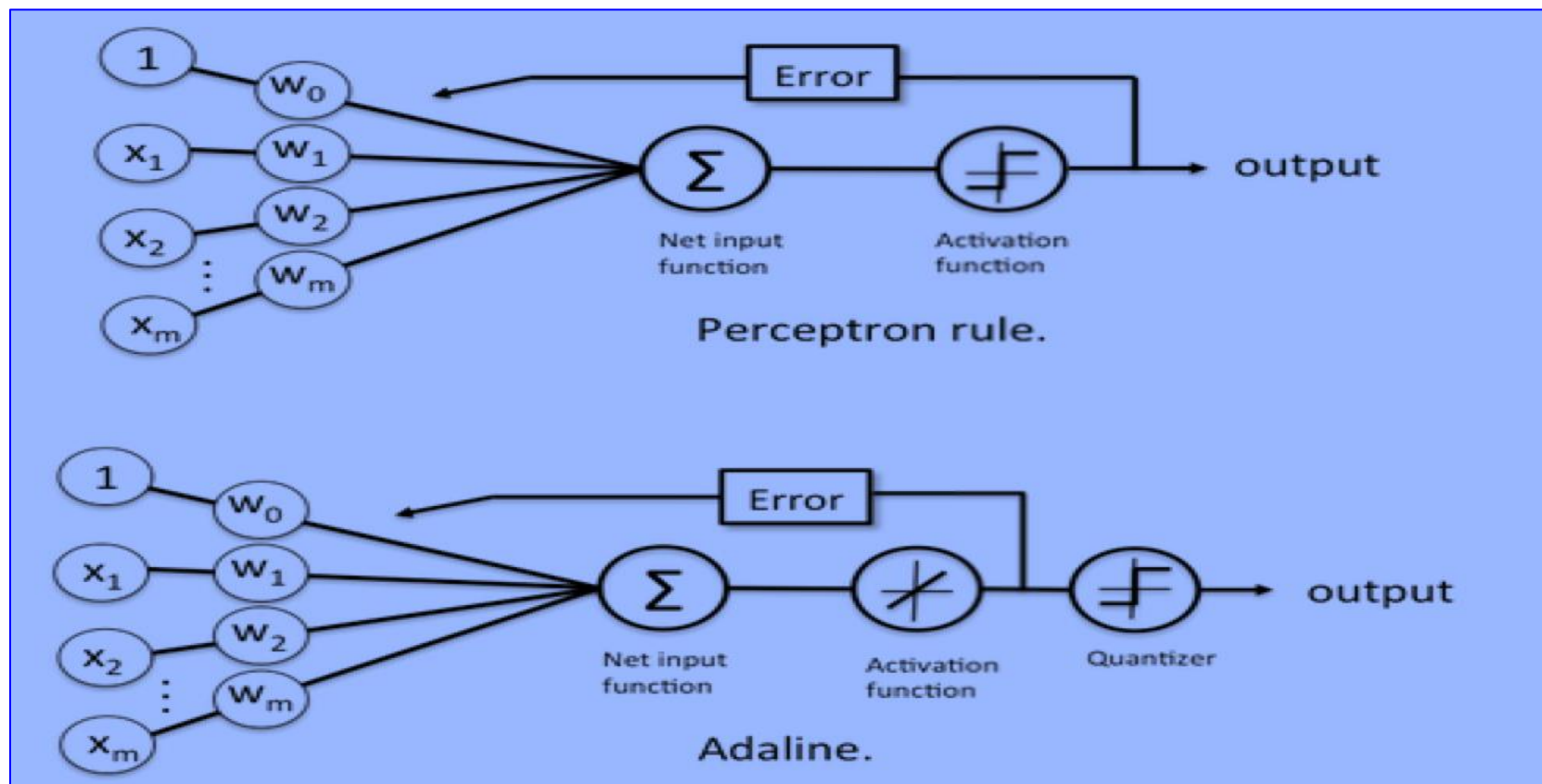


ADALINE is an early **single-layer artificial neural network** based on **Least Mean Squares (LMS)** algorithms. 最小均方算法



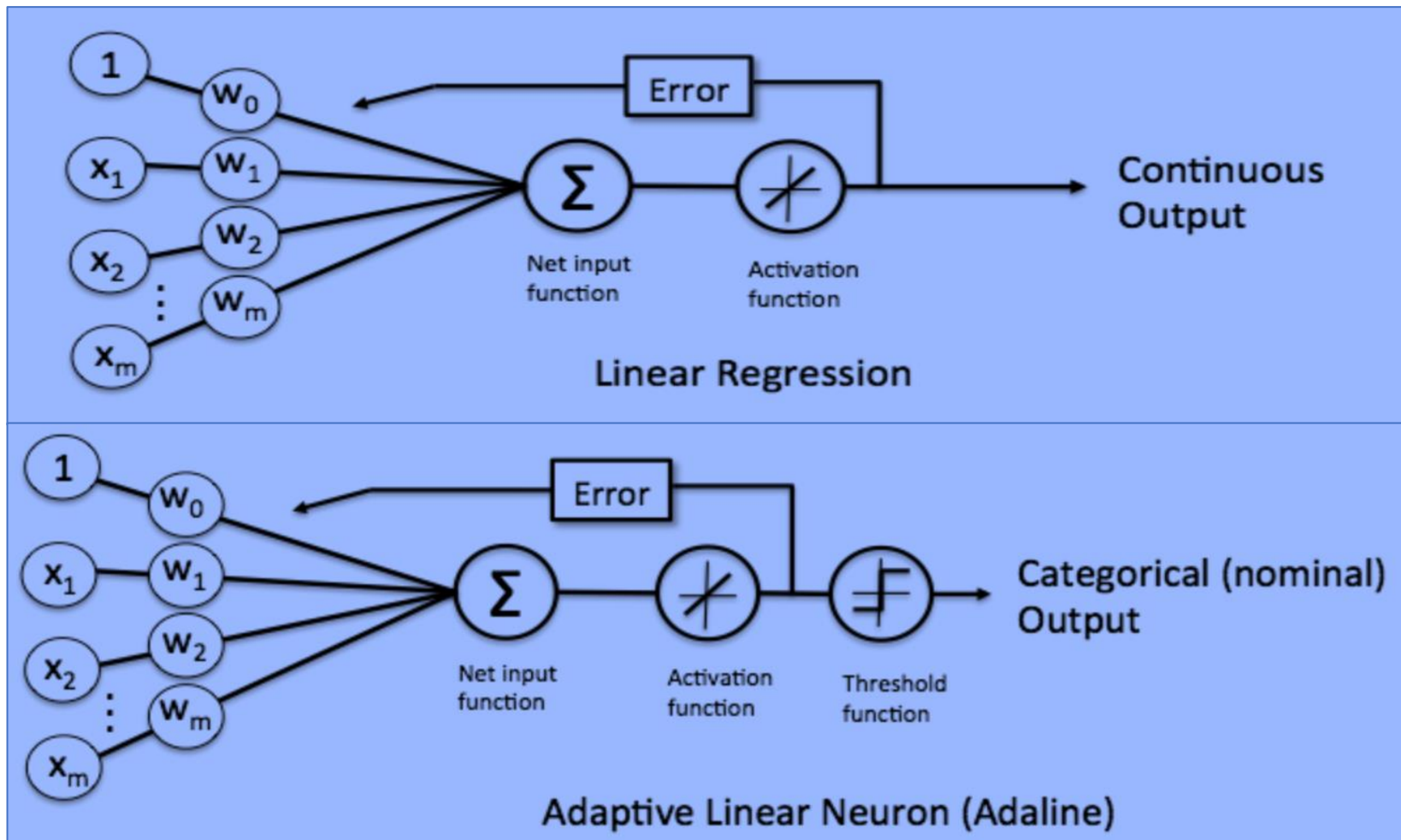
It was invented in 1960 by Stanford University science professor **Bernard Widrow** and his first **Ph.D. student, Ted Hoff**.

Perceptron and ADALINE



In the perceptron, we use the predicted class labels to update the weights, and in ADALINE, we use output to update, it tells us by "how much" we were right or wrong

Linear Regression and ADALINE



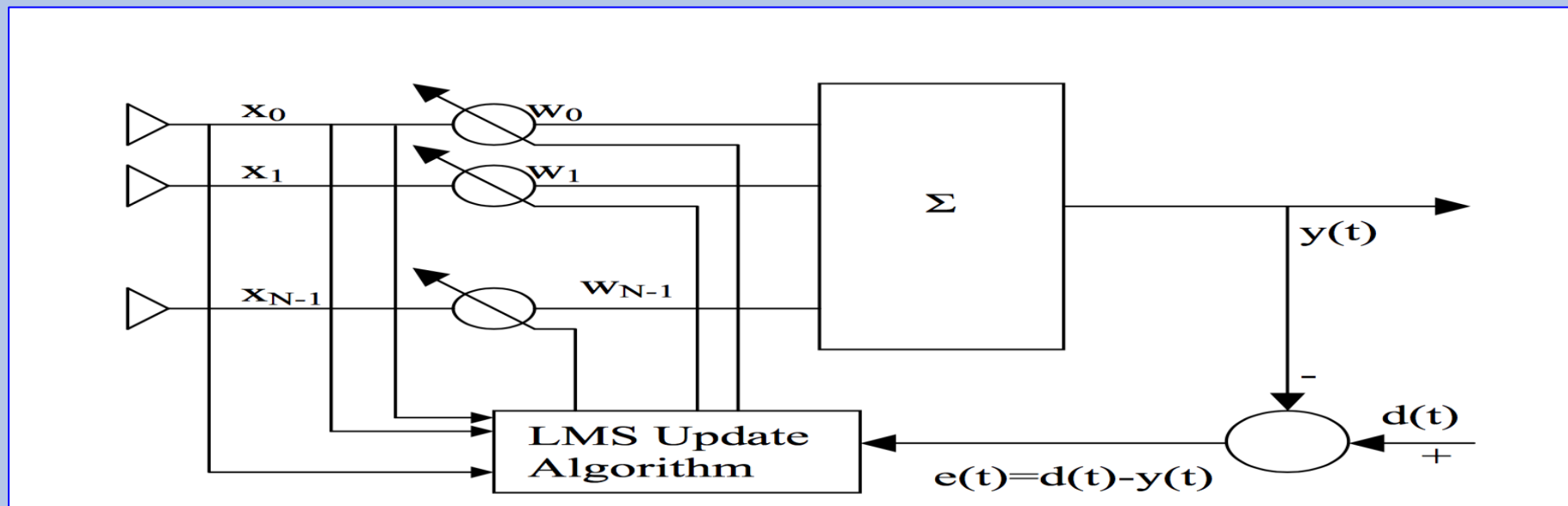
Adaline algorithm is identical to linear regression except for a threshold function that converts the continuous output into a categorical class label

Widrow Hoff Learning Algorithm

- Also known as **Delta Rule**. It follows gradient descent rule for linear regression. It updates the connection weights with the difference between the target and the output value. It is the least mean square learning algorithm falling under the category of the supervised learning algorithm.
- This rule is followed by ADALINE (ADaptive LInear NEuron or NEural Networks) and **MADALINE**. Unlike Perceptron, the iterations of Adaline networks do not always stop, but it converges by reducing the least mean square error. MADALINE is a network of more than one ADALINE.

ADALINE (Adaptive Linear Neuron)

LMS algorithms are a class of **adaptive filter** used to mimic a desired filter by finding the filter coefficients that relate to producing the least mean square of the error signal. It is a **stochastic gradient descent** method, which does not require gradient to be known and it is estimated at every iteration.



* B.Widrow and M.E.Hoff, "Adaptive switching circuits," Proc. Of WESCON Conv. Rec., part 4, pp.96-140, 1960

Delta Learning Rule

- The motive of the delta learning rule is to minimize the error between the output and the target vector. The weights in ADALINE networks are updated by:

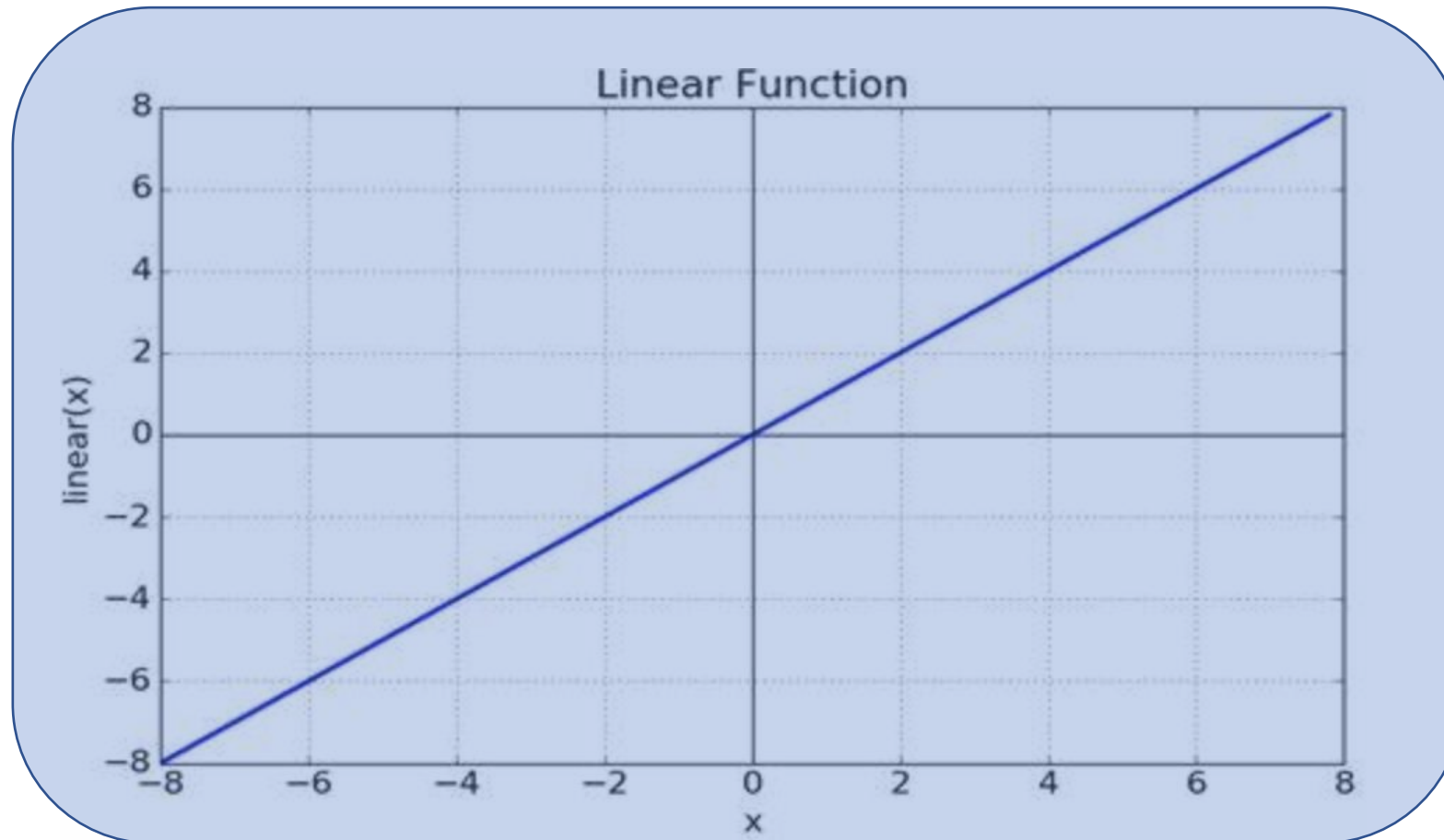
Least Mean Square error (LMS) = $(t - O)^2$,
ADALINE converges when the least mean square error is
reached.

- Learning is an **optimization search** problem in weight space

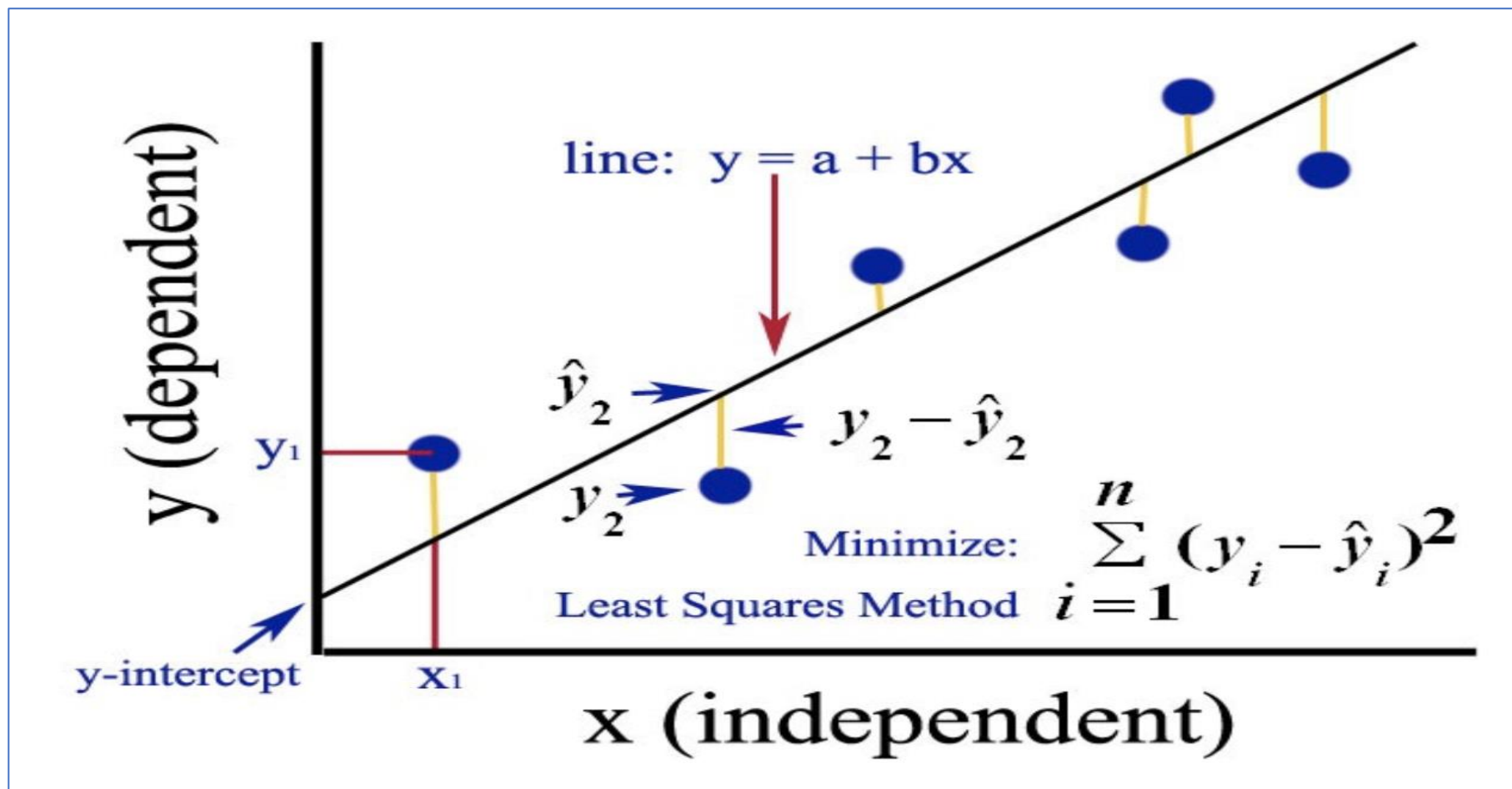
$$\Delta w_i = \eta(t - o)x_i$$

“Artificial” Neuron

Linear Transfer (Activation) Function



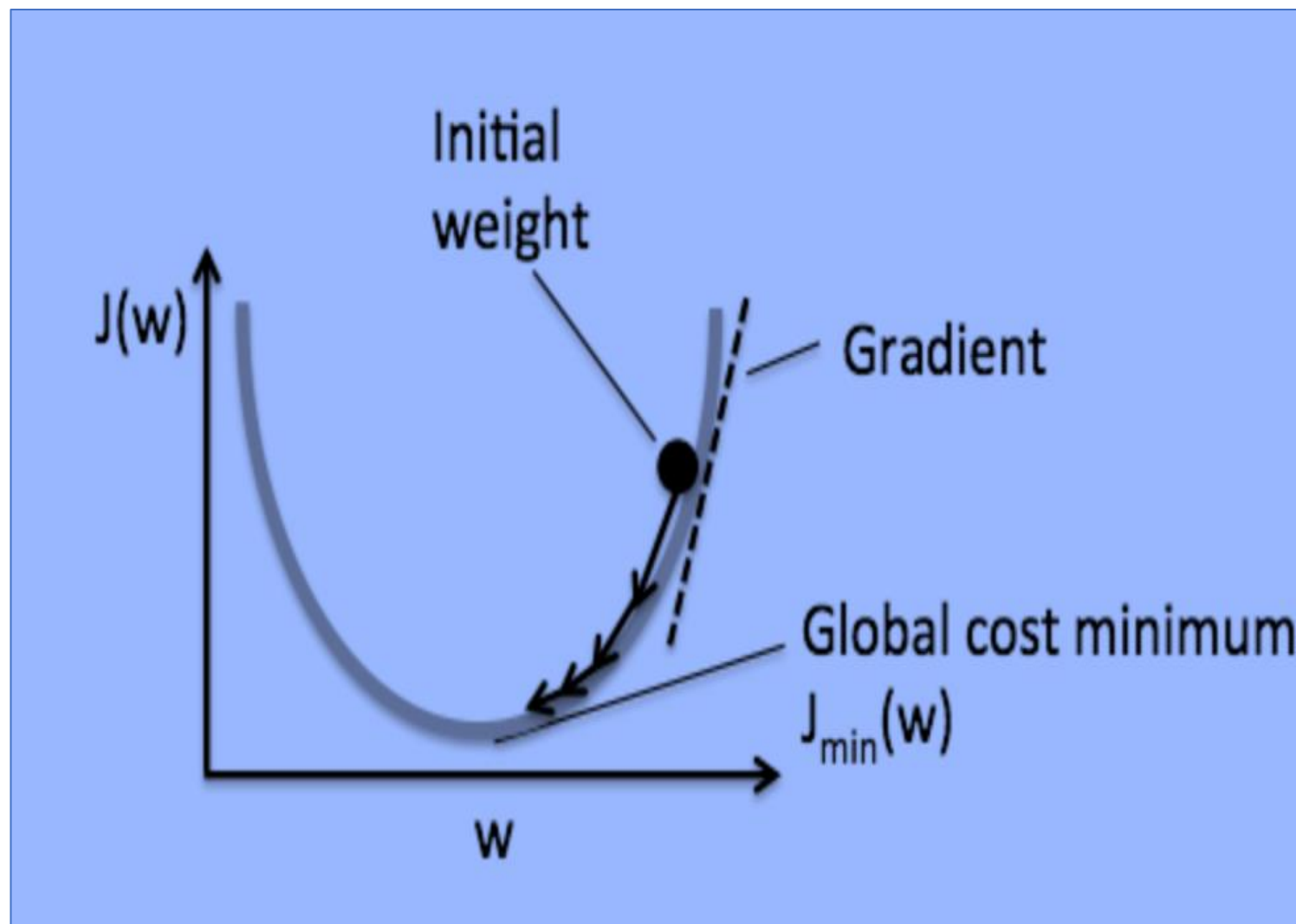
Least Sum of Squared Errors (SSE) for MADALINE



LMS Gradient Descent

Gradient Descent

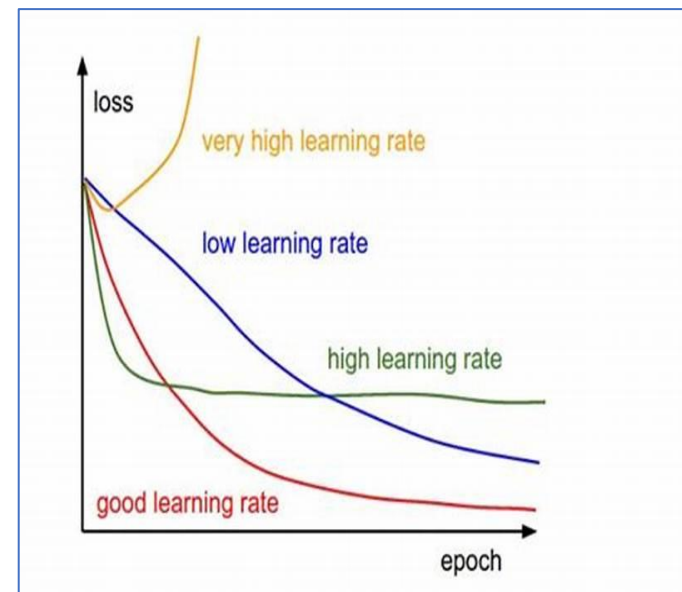
Gradient descent is a first-order iterative optimization algorithm for finding a local minimum of a differentiable function. To find a local minimum of a function using gradient descent, we take steps proportional to the negative of the gradient (or approximate gradient) of the function at the current point. But if we instead take steps proportional to the positive of the gradient, we approach a local maximum of that function; the procedure is then known as gradient ascent. Gradient descent is generally attributed to Cauchy, who first suggested it in 1847, but its convergence properties for non-linear optimization problems were first studied by Haskell Curry in 1944.



LMS Gradient Calculation

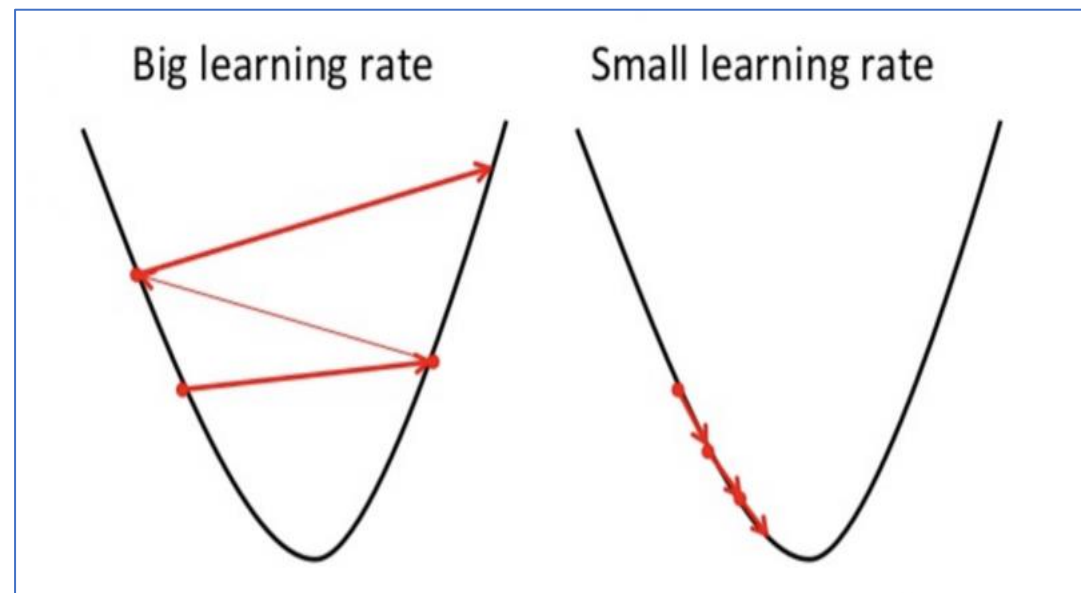
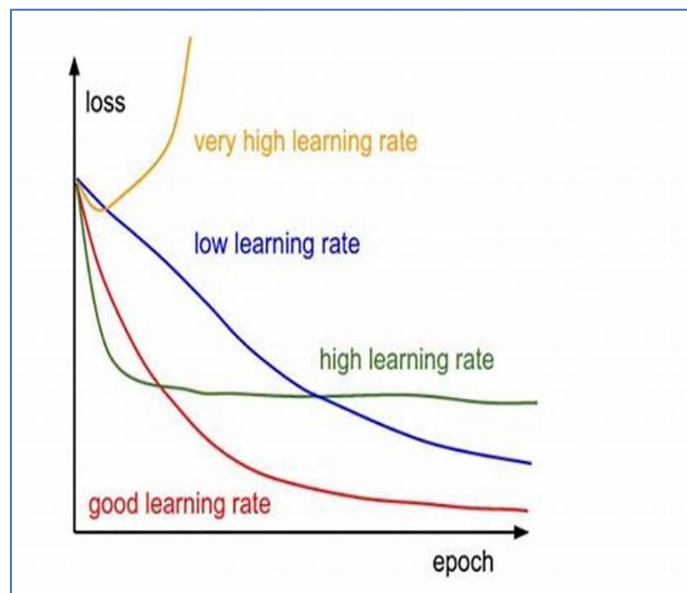
$$w_{t+1} = w_t - \alpha \frac{\partial L}{\partial w_t}$$

$$\begin{aligned} \frac{\partial J}{\partial w_j} &= \frac{\partial}{\partial w_j} \frac{1}{2} \sum_i (y^{(i)} - \phi(z)_A^{(i)})^2 \\ &= \frac{1}{2} \frac{\partial}{\partial w_j} \sum_i (y^{(i)} - \phi(z)_A^{(i)})^2 \\ &= \frac{1}{2} \sum_i (y^{(i)} - \phi(z)_A^{(i)}) \frac{\partial}{\partial w_j} (y^{(i)} - \phi(z)_A^{(i)}) \\ &= \sum_i (y^{(i)} - \phi(z)_A^{(i)}) \frac{\partial}{\partial w_j} \left(y^{(i)} - \sum_i (w_j^{(i)} x_j^{(i)}) \right) \\ &= \sum_i (y^{(i)} - \phi(z)_A^{(i)}) (-x_j^{(i)}) \\ &= - \sum_i (y^{(i)} - \phi(z)_A^{(i)}) x_j^{(i)} \end{aligned}$$

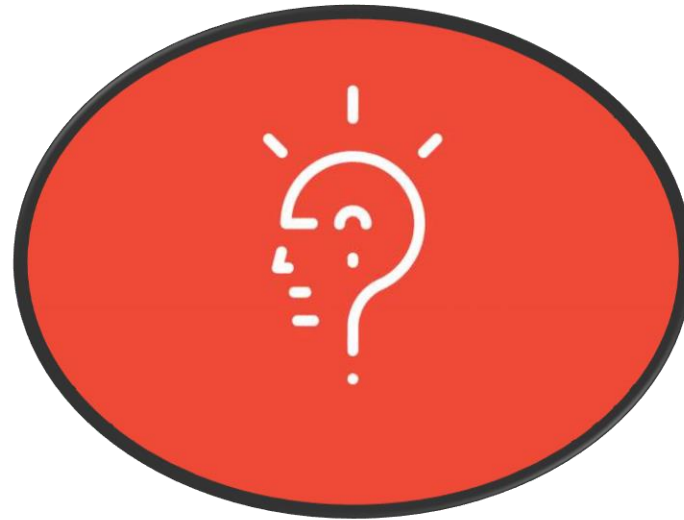


LMS Gradient Calculation

$$w_{t+1} = w_t - \alpha \frac{\partial L}{\partial w_t}$$



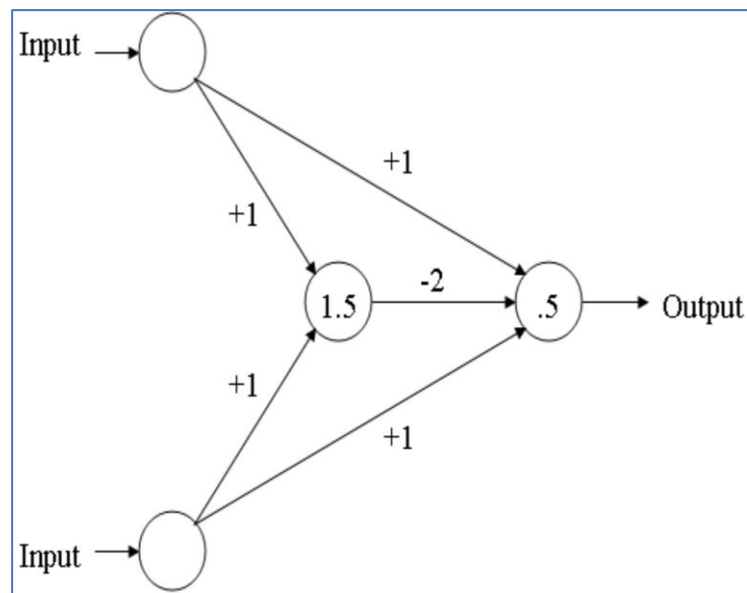
Any Question?



Homework 08

1

Prove the network is an XOR network



Input		Output
x_1	x_2	y
0	0	0
0	1	1
1	0	1
1	1	0

2

Update Your Project Progress in 2 Minutes in Morning Class and 3 Minutes in Afternoon Class Next Lecture



CS 103 -09

Perceptron Learning and ADALINE

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