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Intro:

* Check what kind of referencing should be used

Background:

* Change flywheel model in: ‘dynamics’
* Incorporate that CMP is not restricted to lie inside the polygon

Theoretic Limits:

* Write about velocity plot

Polynomial:

Standing:

* Try some angular momentum tests 360 push
* **Atlas hardware / ball -> check** pd gains foot angular
* Gray angular vs height plot

Walking:

* Make controller compact, neat and tested. Try fix prepare phase. Clean code+matlab
* Run 360 push incremental 0.0 0.1 … 0.7 swing phase -> fix after 0.5
* Add test with longer step length.

Conclusion

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Bibliography

* Entries?
* Citing and citing of names in thesis?

Focus on melting everything together