int main()

{

enable\_servos();

motor (1,500);//turn right 90

motor (0,0);

msleep (1500);

motor (1,600); //drive to cups

motor (0,600);

msleep (4000);

set\_servo\_position(0,1600); //move arm

set\_servo\_position(1,1600); //open claw

//add more code to move cup to beverage station

return 0;

}