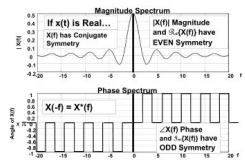


What IS the Fourier Series?

Unlike the Fourier Series:

- It is a _____ of frequency $X(f)$
 - Not a collection of particular, discrete, harmonically related frequencies $X(f_k)$
 - Uses ALL frequencies to recreate signal
- Represents _____ signals

Symmetries in Fourier Spectrum



Signal Symmetries

- $x(t)$ is Real and has Even Symmetry:
- $X(f)$ is _____ and has _____ Symmetry
 - $\angle X(f)$ is _____ or _____
- $x(t)$ is Real and has Odd Symmetry:
- $X(f)$ is _____ and has _____ Symmetry
 - $\angle X(f)$ is _____

Existence of Fourier Transforms

- A non-periodic signal $x(t)$ can be represented by a unique Fourier Transform IF:
- $x(t)$ is "absolutely integrable"
$$\int_{-\infty}^{\infty} |x(t)| dt < \infty$$
 (Integral over ALL time t)
 - $x(t)$ has a finite number of maxima & minima.
 - $x(t)$ has a finite number of finite discontinuities.

Existence of Fourier Transforms

- However, some signals that don't meet these strict requirements still have valid Fourier Transforms. (Ex: $x(t)=u(t)$ is not abs. integrable $\int_{-\infty}^{\infty} u(t) dt = \infty$)
- F.T. of an "absolutely integrable" signal
 - F.T. of a "not absolutely integrable" signal exponentially ($e^{-\sigma t}$), if it does not grow exponentially ($e^{+\sigma t}$).
 - F.T. of a signal that grows exponentially or faster

FT AND FS Relationship:

Methods of Computing Fourier Transforms and Inverse Transforms

- Converting known exponential Fourier Series coefficients of a periodic signal version $x_p(t)$
$$X_p[k] \Rightarrow X(f) = T \sum_{k=-\infty}^{\infty} X_p[k] \delta(f - kf_0)$$

Fourier Series of A Periodic Signal $x_p(t)$ made up of 1 Period of the periodic signal $x(t)$

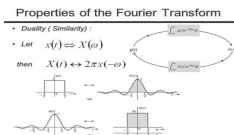
FT: Properties

Duality: Similarity Theorem

Fourier Transform: $X(f) = \int_{-\infty}^{\infty} x(t) e^{-j2\pi ft} dt$ Inverse Fourier Transform: $x(t) = \int_{-\infty}^{\infty} X(f) e^{j2\pi ft} df$

If $FT\{x(t)\} = X(f)$
 $X(f)$ has different functional form than $x(t)$
Then $FT\{X(f)\} = x(-t)$

For functions with Even Symmetry in $x(t)$:
 $x(t) = x(-t)$ $X(f) = X(-f)$
So $FT\{X(f)\} = x(f)$



Time / Frequency Scaling

- There is a coupled and inverse relationship ("duality") between the width of a signal representation in the Time Domain vs. the FT Frequency Domain

Time Scaling Property:
$$X(\alpha f) \xleftrightarrow{FT} \frac{1}{|\alpha|} X(f/\alpha)$$

Frequency Scaling Property:
$$X(\beta f) \xleftrightarrow{FT} \beta X(f/\beta)$$

Time / Frequency Scaling

An extension of this concept is the Time/Frequency Limit Theorem:

A signal can not have BOTH a finite time duration ("time-limited") AND a finite length frequency spectrum ("band-limited").
A signal can be either "time-limited" or "band-limited"...or neither...

Finite in time Infinite freq. spectrum

FT: ENERGY

Energy in Non-Periodic Signals

We can compute the energy in an aperiodic signal from the time-domain waveform itself:

Total Energy =
$$\int_{-\infty}^{\infty} x^2(t) dt =$$

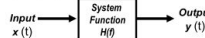
OR from its Fourier Transform frequency spectrum:
And we should get the same answer!!
"Parseval's Theorem"
(again)

---FT: input a sinusoid

System Response to Periodic Input Signals

From the Fourier Series, we saw that:

One Term of the Fourier Series of Input Signal
 $X(t) = c_n \cos(2\pi f_n t + \phi_n)$



System Response to the Fourier Series Term of Input Signal
 $y(t) = |H(f_n)| c_n \cos(2\pi f_n t + \phi_n + \angle H(f_n))$

LT: Definition

Limitations of the Fourier Transform

- Fourier Transform is _____ for a number of interesting signals
Fourier Transform does not converge for them
- Fourier System Analysis: $Y(f) = X(f)H(f)$ only allows us to determine the _____ of _____
 - Only solve Differential Equations with no IC's
 - Can not determine Zero Input Responses

Two Forms of the Laplace Transform

Unilateral Laplace transform:

$$\mathcal{L}[x(t)] = X(s) = \int_0^{\infty} x(t) e^{-st} dt$$

For Causal Systems...and Causal Input Signals

Bilateral Laplace transform:

$$\mathcal{L}[x(t)] = X(s) = \int_{-\infty}^{\infty} x(t) e^{-st} dt$$

For Non-Causal Systems...or Non-Causal Input Signals

Region of Convergence (ROC)

For the Laplace Transform to exist, the Transform integral must converge, limiting the values of s (or σ) that we can use to only those for which:

$$\int_{-\infty}^{\infty} |x(t) e^{-\sigma t}| dt < \infty \quad (\text{absolutely integrable})$$

- Choosing σ too small could make it too weak to force convergence
- Choosing negative values for σ would take a converging function and make it go to $-\infty$

How do we choose and specify the allowed range of σ ??

Methods of Computing Laplace Transforms

- Using the integral Transform definitions

$$X(s) = \int_0^{\infty} x(t) e^{-st} dt$$

- Converting known Fourier Transforms for causal signals: $X(f) \Rightarrow X(s)$
 - a) Drop any $j\omega$'s in the Fourier Transform
 - b) Change $j\omega \Rightarrow s$ ($j\omega \Rightarrow s$)

- Using known Laplace Transform pairs (from Tables) and modifications from L.T. Properties

Region of Convergence (ROC)

The ROC of a unilateral Laplace transform (causal signal) is a right side half-plane.

LT: Properties

Time Scaling

$$LT\{x(at)\} = \int_0^{\infty} x(at) e^{-st} dt$$

Change variables: Let $\lambda = at$ $t = \lambda/a$ Limits of integration: As $t \rightarrow 0$, $\lambda \rightarrow 0$; As $t \rightarrow \infty$, $\lambda \rightarrow \infty$ if $a > 0$; $\lambda \rightarrow -\infty$ if $a < 0$

$$\begin{aligned} LT\{x(at)\} &= \int_0^{\infty} x(\lambda) e^{-s\lambda/a} d\lambda / a \\ &= \frac{1}{a} \int_0^{\infty} x(\lambda) e^{-(s/a)\lambda} d\lambda \\ &= \frac{1}{a} X(s/a) \end{aligned}$$

Time Reversal

$$LT\{x(-t)\} = \int_{-\infty}^0 x(-t) e^{-st} dt \quad \text{if } x(t) \text{ is causal}$$

Change variables: Let $\lambda = -t$ $t = -\lambda$ Limits of integration: As $t \rightarrow 0$, $\lambda \rightarrow 0$; As $t \rightarrow -\infty$, $\lambda \rightarrow \infty$

$$\begin{aligned} LT\{x(-t)\} &= \int_{\infty}^0 x(\lambda) e^{-s(-\lambda)} d\lambda / (-1) \\ &= \int_0^{\infty} x(\lambda) e^{-s\lambda} d\lambda = X(s) \end{aligned}$$

Can't do time reversal with 1-sided Laplace Transform

Time Shift Property

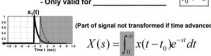
Fourier Transform:

$$X_c(f) = FT\{x(t-t_0)\} = e^{-j2\pi f t_0} X(f)$$

Unilateral Laplace Transform:

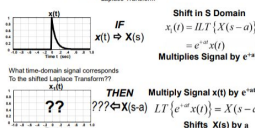
$$X_c(s) = LT\{x(t-t_0)u(t-t_0)\} = e^{-s t_0} X(s)$$

- Need the explicit unit step function: $t_0 > 0$



S Domain Shift: The S Domain "Dual" of the Time-Shift Property

Time Domain $x(t)$ \longleftrightarrow S Domain $X(s)$
Laplace Transform



Convolution Property

- The most important property of the LAPLACE TRANSFORM for System Analysis:

$$x(t) * h(t) \xleftrightarrow{\mathcal{L}} X(s) H(s)$$

The CONVOLUTION of two causal Functions in the Time Domain... Results in MULTIPLICATION of the Laplace Transforms in the S Domain... (Product of Complex Functions)

Property holds for BOTH the Unilateral AND Bilateral Laplace Transforms
Can use the 1-sided LT's Only IF both $x(t)$ and $h(t)$ are _____

LT: Transfer Function - poles and zeros

$H(s)$ is a "rational function"

- ratio of functions of the same variable

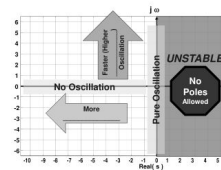
$$H(s) = \frac{b_n s^n + b_{n-1} s^{n-1} + \dots + b_0 s^0}{s^m + a_{m-1} s^{m-1} + \dots + a_0 s^0} = \frac{Num(s)}{Denom(s)}$$

It is a

"rational function" if the order of the denominator polynomial (N) is equal to or greater than the order of the numerator polynomial (M)
 $N \geq M$

"rational function" if the order of the denominator polynomial (N) is greater than the order of the numerator polynomial (M)
 $N > M$

Poles in the S Plane



Stability Requirements

TIME DOMAIN - Diff Equation LAPLACE S-PLANE - H(s)

1) Highest y derivative order N ≥ Highest x deriv. order M
 $N \geq M$

2) All roots of the Characteristic equation must have negative real parts

(1) H(s) must be a _____
 $N \geq M$
of _____ ≥ # of _____
(2) All _____ of H(s) must have negative real parts ($\sigma < 0$)
- All Poles in the (left of the jω axis)

Stability and the ROC of H(s)

The Region of Convergence for a System Function H(s) can not include any

The ROC of a right-sided time function (incl. Causal) takes the form of $\text{Re}\{s\} = \sigma > \sigma_0$

- ROC is to the right of some σ_0

The ROC of a Causal System [causal h(t)] is $\text{Re}\{s\} = \sigma > \text{Re}\{p_r\}$

where p_r is the _____

- ROC is to the right of the rightmost pole

For a Stable, Causal System, the ROC must include _____

LT: Partial Fraction Expansion

Partial Fraction Expansion:

Special Cases:

- Repeated Roots (Poles)

The coefficients for these pole terms are determined by multiplication of $(s - p_i)$ only by the highest power of the repeated pole term, and evaluating at the pole value.

$$\begin{aligned} H(s) &= \frac{N(s)}{(s-p_1)(s-p_2)\dots} = \frac{K_1}{(s-p_1)} + \frac{K_2}{(s-p_2)} + \dots \\ H(s) &= \frac{N(s)}{(s-p_1)^2} = \frac{K_1}{(s-p_1)} + \frac{K_2}{(s-p_1)^2} \\ H(s) &= \frac{N(s)}{(s-p_1)^3} = \frac{K_1}{(s-p_1)} + \frac{K_2}{(s-p_1)^2} + \frac{K_3}{(s-p_1)^3} \end{aligned}$$

Partial Fraction Expansion:

Special Cases:

- Repeated Roots (Poles)

The coefficients for decreasing powers of the repeated pole term are determined from derivatives of the previous function, again evaluated at the pole value.

$$\begin{aligned} \frac{d}{ds} H(s) &= \frac{d}{ds} \left[\frac{N(s)}{(s-p_1)(s-p_2)\dots} \right] \\ &= \frac{d}{ds} \left[\frac{K_1}{(s-p_1)} + \frac{K_2}{(s-p_2)} + \dots \right] \\ &= \frac{d}{ds} \left[\frac{K_1}{(s-p_1)} \right] + \frac{d}{ds} \left[\frac{K_2}{(s-p_2)} \right] + \dots \\ &= \frac{d}{ds} \left[\frac{K_1}{(s-p_1)} \right] + \frac{d}{ds} \left[\frac{K_2}{(s-p_2)} \right] + \dots \\ &= \frac{d}{ds} \left[\frac{K_1}{(s-p_1)} \right] + \frac{d}{ds} \left[\frac{K_2}{(s-p_2)} \right] + \dots \\ &= \frac{d}{ds} \left[\frac{K_1}{(s-p_1)} \right] + \frac{d}{ds} \left[\frac{K_2}{(s-p_2)} \right] + \dots \end{aligned}$$

al Fraction Expansion:

asbs:

ated Roots (Poles)

e root appears " k " times, the general expression for coefficient of the descending powers of the pole is given by:

$$\frac{1}{k!} \frac{d^k}{ds^k} H(s) \bigg|_{s=p_i}$$

k = power (exponent) of the pole in the partial fraction term that goes with A_k

Inverse Laplace Transform

Non-"Strictly Proper" Rational Functions:

Inverse Laplace Transform

Functions with Time Shifts (e^{as}):

