

# **DL Seminar**

**Attention Mechanism** 



인공지능 Lab 김지성 인공지능 Lab 엄희송 인공지능 Lab 유재창

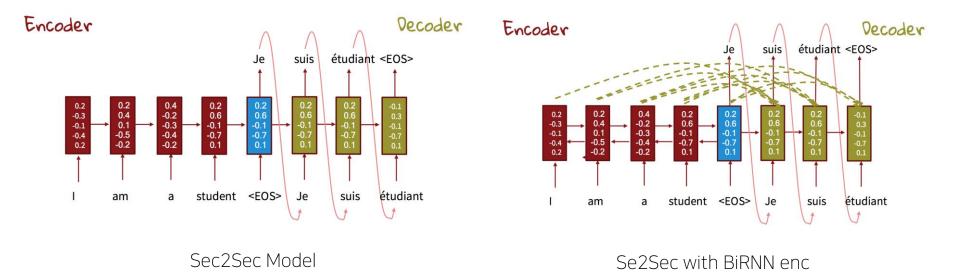
# Index



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#### Introduction

#### Seq2Seq



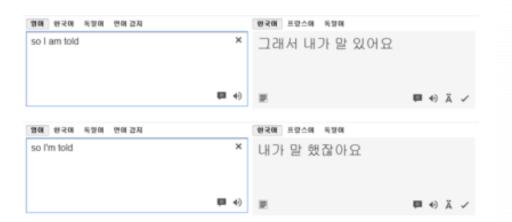
- 문장 길이가 길고 층이 깊으면, 인코더에서는 정보 손실이 , 디코더에서는 bottle-neck문제 발생
- 이 문제를 해결하기 위해 Attention Machanism이 제안됨
- Bi-directional 네트워크와 함께 사용함

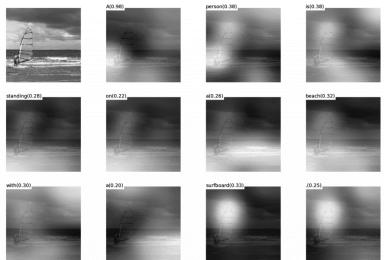


Idea

독일어 "Ich mochte ein bier "를 영어 "I'd like a beer "로 번역하는 S2S 모델에서 인코더가 'bier'를 받아서 벡터로 만든 결과(인코더 출력)는 디코더가 'beer'를 예측할 때 쓰는 벡터(디코더 입력)와 유사할 것

#### When Use This





NLP Image captioning

#### Mechanism - Encoder

$$\begin{split} \overrightarrow{h}_i &= \begin{cases} (1-\overrightarrow{z}_i) \circ \overrightarrow{h}_{i-1} + \overrightarrow{z}_i \circ \overrightarrow{\underline{h}}_i &, \text{ if } i>0\\ 0 &, \text{ if } i=0 \end{cases} \\ \overrightarrow{\underline{h}}_i &= \tanh\left(\overrightarrow{W}\overline{E}x_i + \overrightarrow{U}\left[\overrightarrow{r}_i \circ \overrightarrow{h}_{i-1}\right]\right) \\ \overrightarrow{z}_i &= \sigma\left(\overrightarrow{W}_z\overline{E}x_i + \overrightarrow{U}_z\overrightarrow{h}_{i-1}\right) \\ \overrightarrow{r}_i &= \sigma\left(\overrightarrow{W}_r\overline{E}x_i + \overrightarrow{U}_r\overrightarrow{h}_{i-1}\right). \end{split}$$

Bi-directional RNN encoder

Forward RNN :  $\vec{f} = (\overrightarrow{h_1}, ..., \overrightarrow{h_{T_x}})$ .  $x_1$ 부터  $x_{T_x}$  순으로 Backward RNN  $\vec{f} = (\overleftarrow{h_1}, ..., \overleftarrow{h_{T_x}})$ .  $x_{T_x}$ 부터  $x_1$  순으로

두 개를 합친  $h_j = [\overline{h_j^T}; \overline{h_j^T}]^T$  벡터를 모아 행렬로 저장.

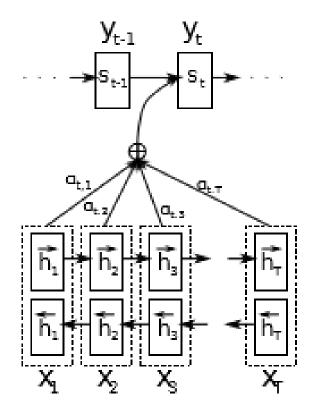


Figure 1: The graphical illustration of the proposed model trying to generate the t-th target word  $y_t$  given a source sentence  $(x_1, x_2, \ldots, x_T)$ .

#### Mechanism - Decoder

$$p(y_{i}|y_{1},...,y_{i-1},x) = g(y_{i-1},s_{i},c_{i})$$

$$s_{i} = f(s_{i-1},y_{i-1},c_{i})$$

$$c_{i} = \sum_{j=1}^{T_{x}} \alpha_{ij}h_{j}$$

$$\alpha_{ij} = \frac{exp(e_{ij})}{\sum_{k=1}^{T_{x}} exp(e_{ik})}$$

$$e_{ij} = a(s_{i-1},h_{j})$$

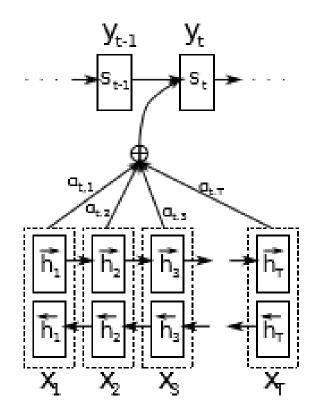


Figure 1: The graphical illustration of the proposed model trying to generate the t-th target word  $y_t$  given a source sentence  $(x_1, x_2, \ldots, x_T)$ .

#### Mechanism - Decoder

$$a(s_{i-1}, h_j) = v_a^T \tanh(W_a s_{i-1} + U_a h_j)$$

유사도를 도출할 수 있는 모델이면 모두 사용 가능

$$s_{i-1}^{T} \bar{h}_{j}(dot)$$
  
 $s_{i-1}^{T} W_{a} \bar{h}_{j}(general)$ 

Initial state  $s_0 = tanh(W_s \overline{h_1})$ 

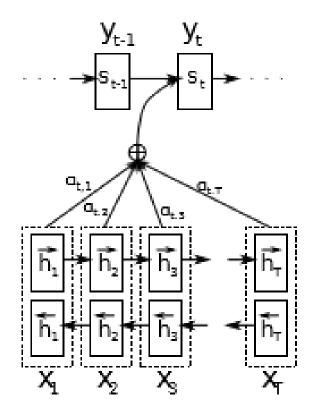


Figure 1: The graphical illustration of the proposed model trying to generate the t-th target word  $y_t$  given a source sentence  $(x_1, x_2, \ldots, x_T)$ .

#### Mechanism - Decoder

$$e_{ij} = a(s_{i-1}, h_j)$$

$$\alpha_{ij} = \frac{exp(e_{ij})}{\sum_{k=1}^{Tx} exp(e_{ik})}$$

 $lpha_{ij}$  : softmax를 통해 확률값으로 보정해줌

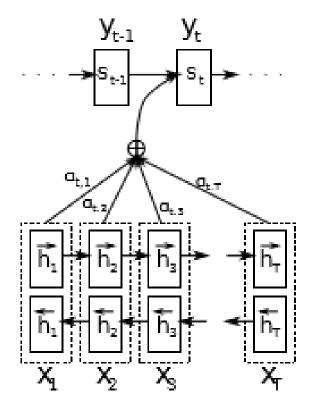


Figure 1: The graphical illustration of the proposed model trying to generate the t-th target word  $y_t$  given a source sentence  $(x_1, x_2, \ldots, x_T)$ .

Mechanism - Decoder

$$c_i = \sum_{j=1}^{T_x} \alpha_{ij} h_j$$

 $c_i$ : i번째 단어를 추측하기 위해 생성된 context vector

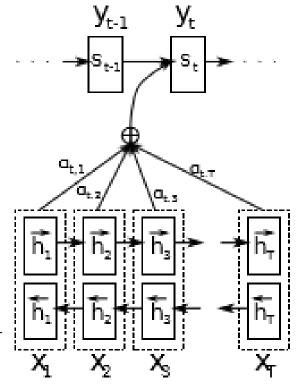


Figure 1: The graphical illustration of the proposed model trying to generate the t-th target word  $y_t$  given a source sentence  $(x_1, x_2, \ldots, x_T)$ .

#### Mechanism - Decoder

$$s_i = f(s_{i-1}, y_{i-1}, c_i)$$

f: nonlinear function. Seq2seq모델에서 사용하는 LSTM 또는 GRU 등.

 $s_i$ : i번째 디코더 RNN 셀에서의 hidden state

 $c_i$ : i번째 단어를 추측하기 위해 생성된 context vector

$$s_i = (1 - z_i) \circ s_{i-1} + z_i \circ \tilde{s}_i,$$

$$\tilde{s}_{i} = \tanh (WEy_{i-1} + U[r_{i} \circ s_{i-1}] + Cc_{i}) 
z_{i} = \sigma (W_{z}Ey_{i-1} + U_{z}s_{i-1} + C_{z}c_{i}) 
r_{i} = \sigma (W_{r}Ey_{i-1} + U_{r}s_{i-1} + C_{r}c_{i})$$

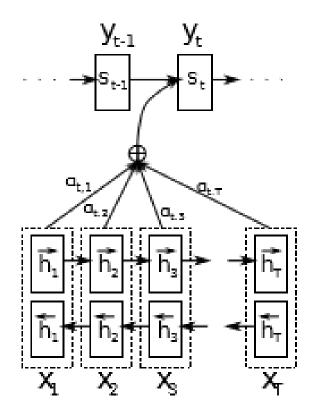


Figure 1: The graphical illustration of the proposed model trying to generate the t-th target word  $y_t$  given a source sentence  $(x_1, x_2, \dots, x_T)$ .

#### Mechanism - Decoder

$$p(y_i|y_1,...,y_{i-1},x) = g(y_{i-1},s_i,c_i)$$

g: a nonlinear, potentially multi-layered, function that outputs the probability of  $y_i$ 

How to Construct Deep Recurrent Neural Networks (Pascanu et al., 2014)

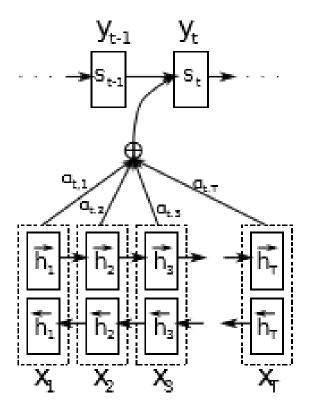


Figure 1: The graphical illustration of the proposed model trying to generate the t-th target word  $y_t$  given a source sentence  $(x_1, x_2, \ldots, x_T)$ .

#### Mechanism - Decoder

$$p(y_{i}|y_{1},...,y_{i-1},x) = g(y_{i-1},s_{i},c_{i})$$

$$s_{i} = f(s_{i-1},y_{i-1},c_{i})$$

$$c_{i} = \sum_{j=1}^{T_{x}} \alpha_{ij}h_{j}$$

$$\alpha_{ij} = \frac{exp(e_{ij})}{\sum_{k=1}^{T_{x}} exp(e_{ik})}$$

$$e_{ij} = a(s_{i-1},h_{j})$$

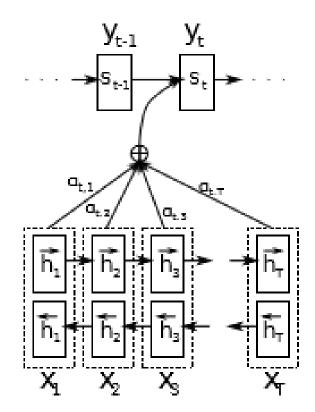
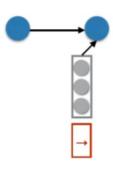


Figure 1: The graphical illustration of the proposed model trying to generate the t-th target word  $y_t$  given a source sentence  $(x_1, x_2, \dots, x_T)$ .

#### Calculate Flow



Initial state  $s_0 = tanh(W_s \overleftarrow{h_1})$ 

$$p(y_{i}|y_{1},...,y_{i-1},x) = g(y_{i-1},s_{i},c_{i})$$

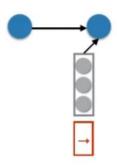
$$s_{i} = f(s_{i-1},y_{i-1},c_{i})$$

$$c_{i} = \sum_{j=1}^{T_{x}} \alpha_{ij}h_{j}$$

$$\alpha_{ij} = \frac{exp(e_{ij})}{\sum_{k=1}^{T_{x}} exp(e_{ik})}$$

$$e_{ij} = a(s_{i-1},h_{j})$$

#### Calculate Flow

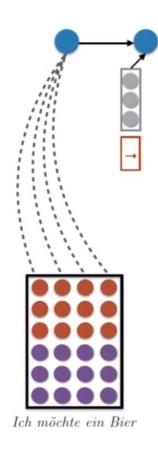




Initial state 
$$s_0 = tanh(W_s \overleftarrow{h_1})$$

$$\begin{split} p(y_i|y_1, \dots, y_{i-1}, x) &= g(y_{i-1}, s_i, c_i) \\ s_i &= f(s_{i-1}, y_{i-1}, c_i) \\ c_i &= \sum_{j=1}^{T_x} \alpha_{ij} h_j \\ \alpha_{ij} &= \frac{exp(e_{ij})}{\sum_{k=1}^{T_x} exp(e_{ik})} \\ e_{ij} &= a(s_{i-1}, h_j) \end{split}$$

#### Calculate Flow



Initial state  $s_0 = tanh(W_s \overleftarrow{h_1})$ 

$$p(y_{i}|y_{1},...,y_{i-1},x) = g(y_{i-1},s_{i},c_{i})$$

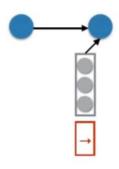
$$s_{i} = f(s_{i-1},y_{i-1},c_{i})$$

$$c_{i} = \sum_{j=1}^{T_{x}} \alpha_{ij}h_{j}$$

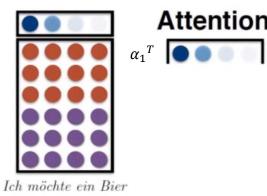
$$\alpha_{ij} = \frac{exp(e_{ij})}{\sum_{k=1}^{T_{x}} exp(e_{ik})}$$

$$e_{ij} = a(s_{i-1},h_{j})$$

#### Calculate Flow



Initial state  $s_0 = tanh(W_s\overline{h_1})$ 



## Attention history:

$$p(y_{i}|y_{1},...,y_{i-1},x) = g(y_{i-1},s_{i},c_{i})$$

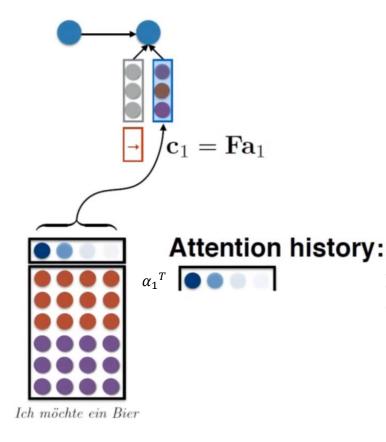
$$s_{i} = f(s_{i-1},y_{i-1},c_{i})$$

$$c_{i} = \sum_{j=1}^{T_{x}} \alpha_{ij}h_{j}$$

$$\alpha_{ij} = \frac{exp(e_{ij})}{\sum_{k=1}^{T_{x}} exp(e_{ik})}$$

$$e_{ij} = a(s_{i-1},h_{j})$$

#### Calculate Flow



Initial state  $s_0 = tanh(W_s \overleftarrow{h_1})$ 

$$p(y_{i}|y_{1},...,y_{i-1},x) = g(y_{i-1},s_{i},c_{i})$$

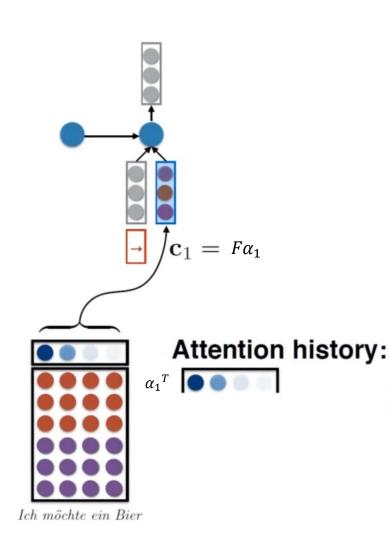
$$s_{i} = f(s_{i-1},y_{i-1},c_{i})$$

$$c_{i} = \sum_{j=1}^{T_{x}} \alpha_{ij}h_{j}$$

$$\alpha_{ij} = \frac{exp(e_{ij})}{\sum_{k=1}^{T_{x}} exp(e_{ik})}$$

$$e_{ij} = a(s_{i-1},h_{j})$$

#### Calculate Flow



Initial state  $s_0 = tanh(W_s \overleftarrow{h_1})$ 

$$p(y_i|y_1, ..., y_{i-1}, x) = g(y_{i-1}, s_i, c_i)$$

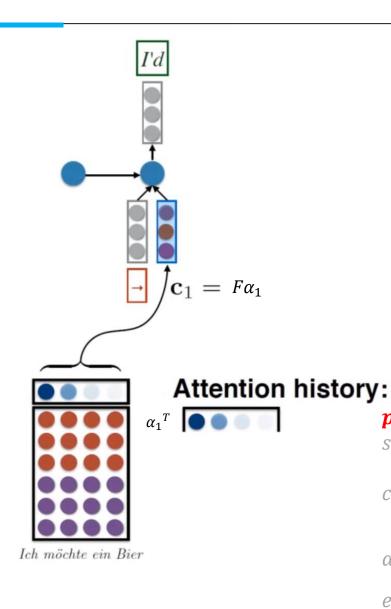
$$s_i = f(s_{i-1}, y_{i-1}, c_i)$$

$$c_i = \sum_{j=1}^{T_x} \alpha_{ij} h_j$$

$$\alpha_{ij} = \frac{exp(e_{ij})}{\sum_{k=1}^{T_x} exp(e_{ik})}$$

$$e_{ij} = \alpha(s_{i-1}, h_j)$$

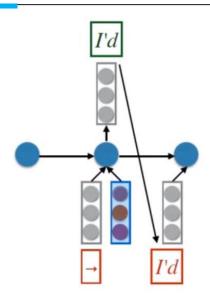
#### Calculate Flow



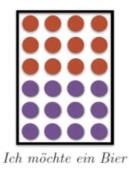
We got s\_1 and y\_1

$$\begin{aligned} & p(y_i|y_1, ..., y_{i-1}, x) = g(y_{i-1}, s_i, c_i) \\ & s_i = f(s_{i-1}, y_{i-1}, c_i) \\ & c_i = \sum_{j=1}^{T_x} \alpha_{ij} h_j \\ & \alpha_{ij} = \frac{exp(e_{ij})}{\sum_{k=1}^{T_x} exp(e_{ik})} \\ & e_{ij} = a(s_{i-1}, h_j) \end{aligned}$$

#### Calculate Flow



# Attention history:



$$\alpha_1^T$$

$$p(y_{i}|y_{1},...,y_{i-1},x) = g(y_{i-1},s_{i},c_{i})$$

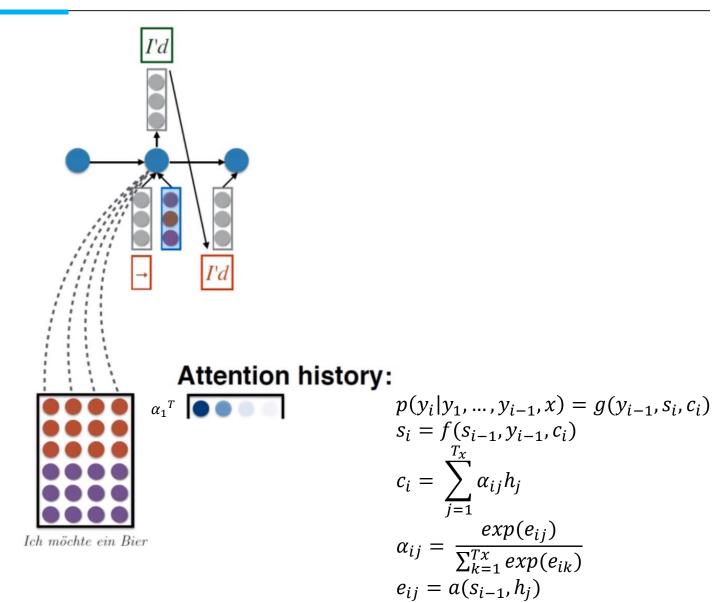
$$s_{i} = f(s_{i-1},y_{i-1},c_{i})$$

$$c_{i} = \sum_{j=1}^{T_{x}} \alpha_{ij}h_{j}$$

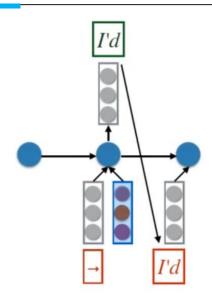
$$\alpha_{ij} = \frac{exp(e_{ij})}{\sum_{k=1}^{T_{x}} exp(e_{ik})}$$

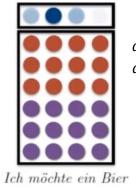
$$e_{ij} = a(s_{i-1},h_{j})$$

#### Calculate Flow



#### Calculate Flow





# Attention history:

$$\begin{pmatrix} T \\ T \\ Z \end{pmatrix}$$

$$p(y_{i}|y_{1},...,y_{i-1},x) = g(y_{i-1},s_{i},c_{i})$$

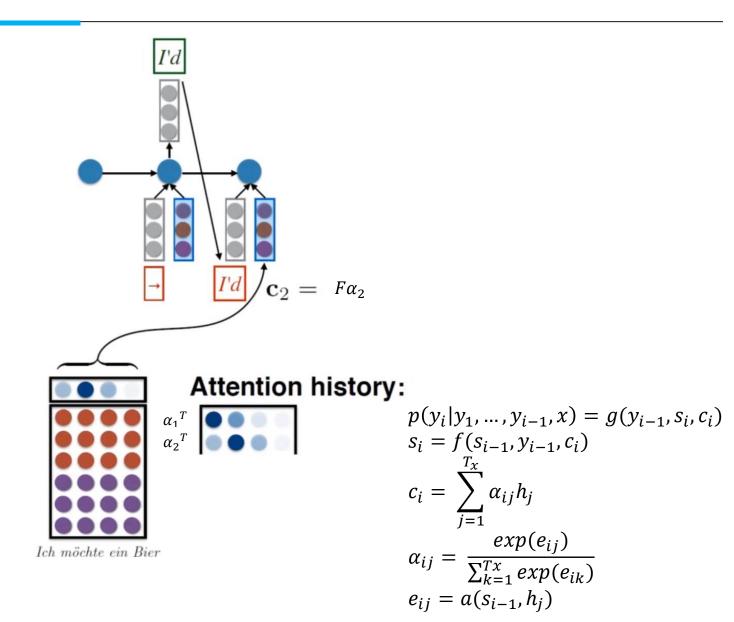
$$s_{i} = f(s_{i-1},y_{i-1},c_{i})$$

$$c_{i} = \sum_{j=1}^{T_{x}} \alpha_{ij}h_{j}$$

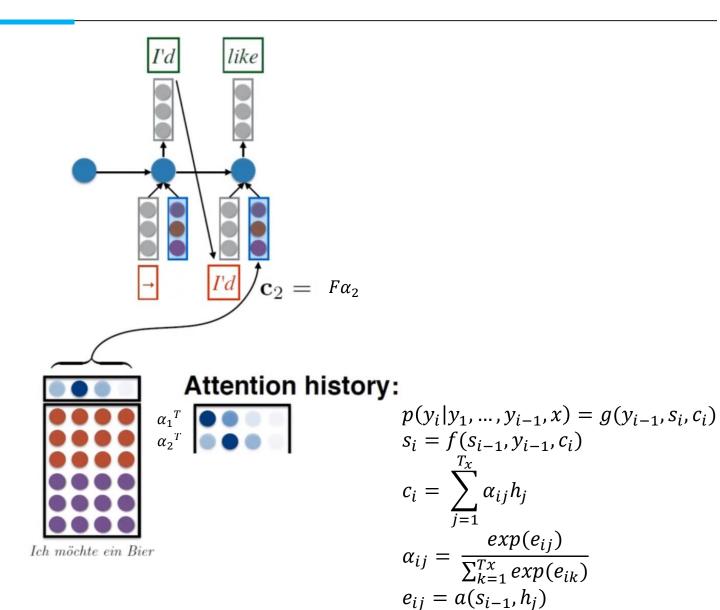
$$\alpha_{ij} = \frac{exp(e_{ij})}{\sum_{k=1}^{T_{x}} exp(e_{ik})}$$

$$e_{ij} = a(s_{i-1},h_{j})$$

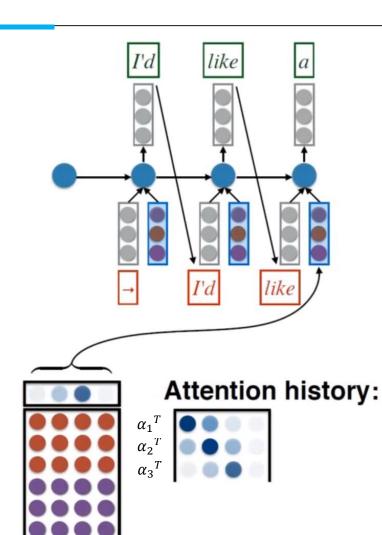
#### Calculate Flow



#### Calculate Flow



#### Calculate Flow



Ich möchte ein Bier

$$p(y_{i}|y_{1},...,y_{i-1},x) = g(y_{i-1},s_{i},c_{i})$$

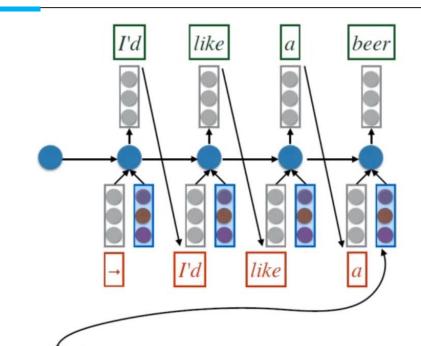
$$s_{i} = f(s_{i-1},y_{i-1},c_{i})$$

$$c_{i} = \sum_{j=1}^{T_{x}} \alpha_{ij}h_{j}$$

$$\alpha_{ij} = \frac{exp(e_{ij})}{\sum_{k=1}^{T_{x}} exp(e_{ik})}$$

$$e_{ij} = a(s_{i-1},h_{j})$$

#### Calculate Flow



# Attention history: $\begin{array}{c|c} \alpha_1^T \\ \alpha_2^T \\ \alpha_3^T \\ \alpha_4^T \end{array}$

Ich möchte ein Bier

$$p(y_{i}|y_{1},...,y_{i-1},x) = g(y_{i-1},s_{i},c_{i})$$

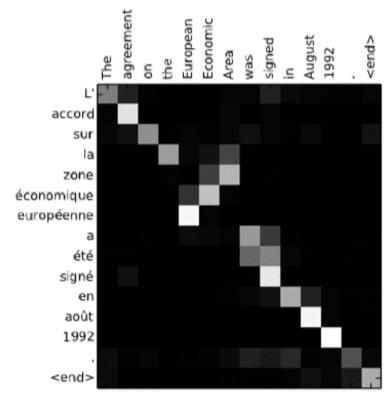
$$s_{i} = f(s_{i-1},y_{i-1},c_{i})$$

$$c_{i} = \sum_{j=1}^{T_{x}} \alpha_{ij}h_{j}$$

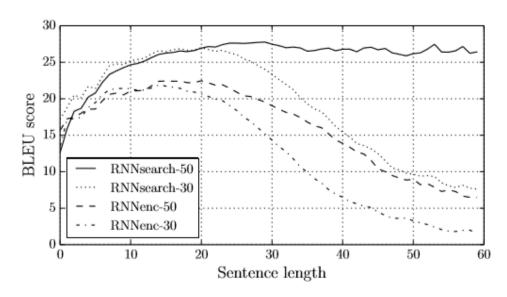
$$\alpha_{ij} = \frac{exp(e_{ij})}{\sum_{k=1}^{T_{x}} exp(e_{ik})}$$

$$e_{ij} = a(s_{i-1},h_{j})$$

#### Performance



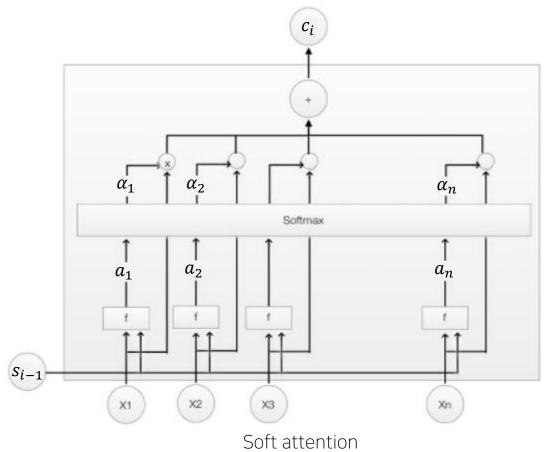
Attention visualization



Curve BLEU score by Sentence length

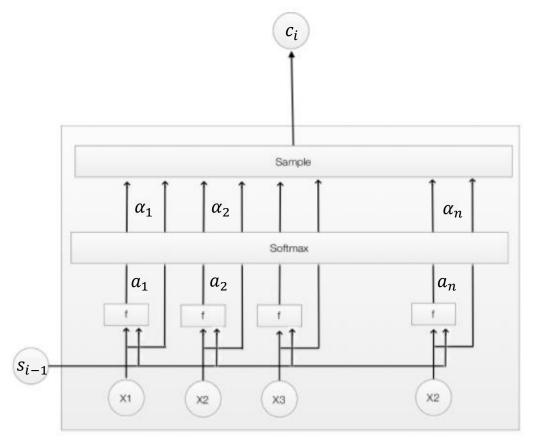
# Improve

## Soft & Hard Mechanism



# Improve

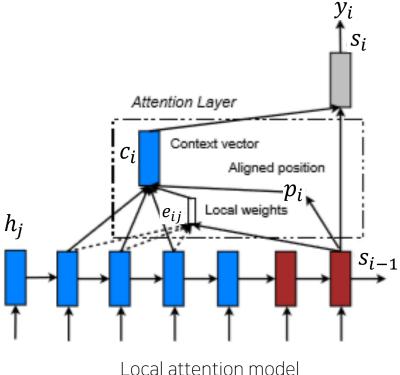
#### Soft & Hard Mechanism



Hard attention

### Improve

#### Global & Local



Local m – monotonic local.  $p_i = i$ Local p - predictive local.  $p_i = S \cdot sigmoid(v_p^T tanh(W_p s_{i-1}))$ align을 계산할 때  $p_i$ 를 중점으로 고정된 window size 크기로 계산 + 가우시안 분포  $e_{ij} = a(s_{i-1}, h_j) \exp(-\frac{(s-p_i)^2}{2\sigma^2})$ 

#### Mechanism - Local

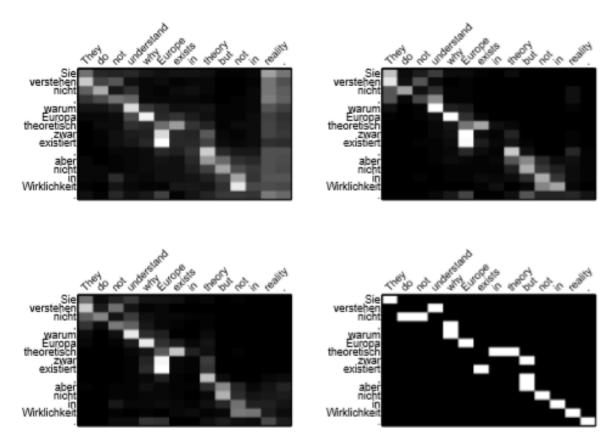
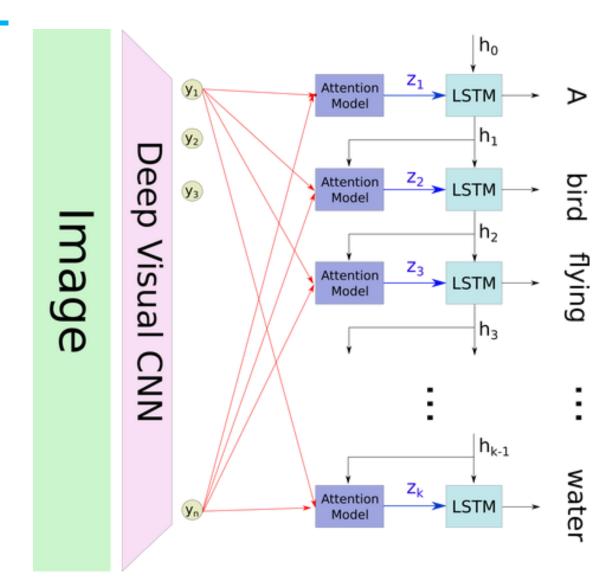
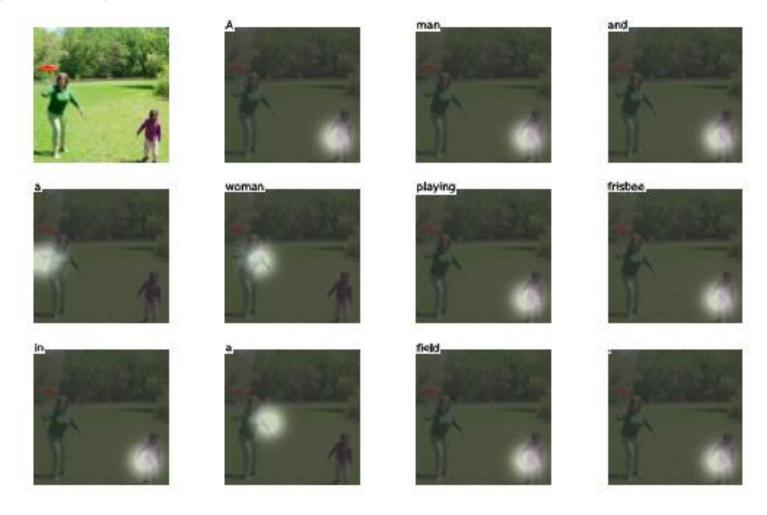


Figure 7: **Alignment visualizations** – shown are images of the attention weights learned by various models: (top left) global, (top right) local-m, and (bottom left) local-p. The *gold* alignments are displayed at the bottom right corner.

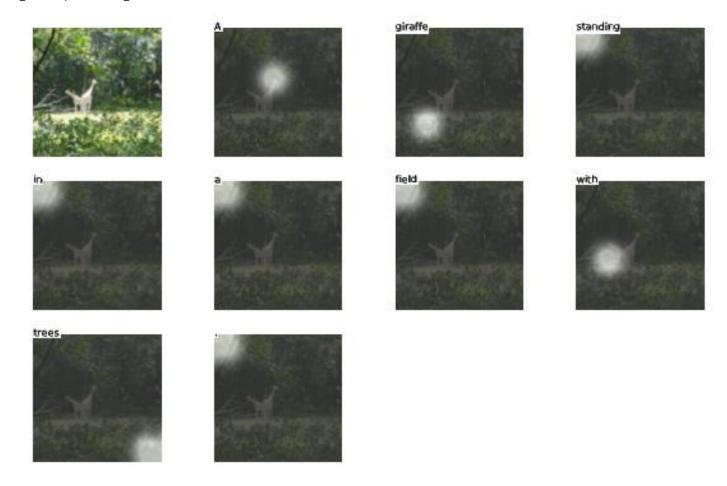




(a) A man and a woman playing frisbee in a field.

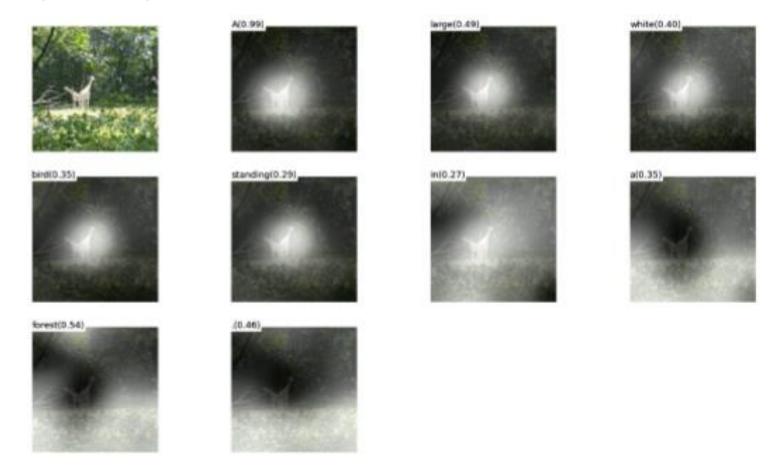


(b) A woman is throwing a frisbee in a park.



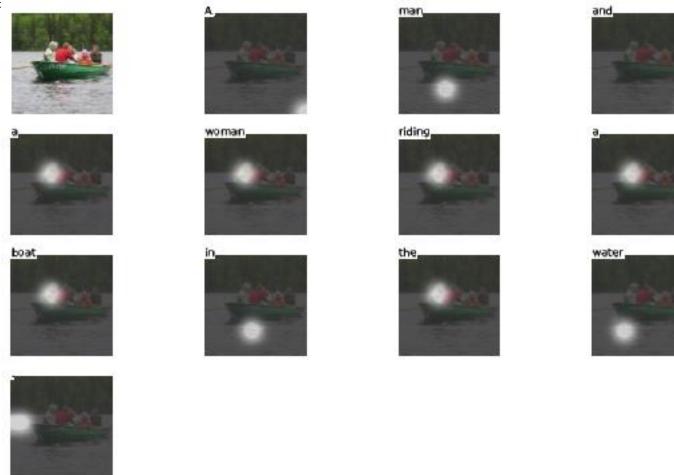
(a) A giraffe standing in the field with trees.

### Attention for Image Captioning

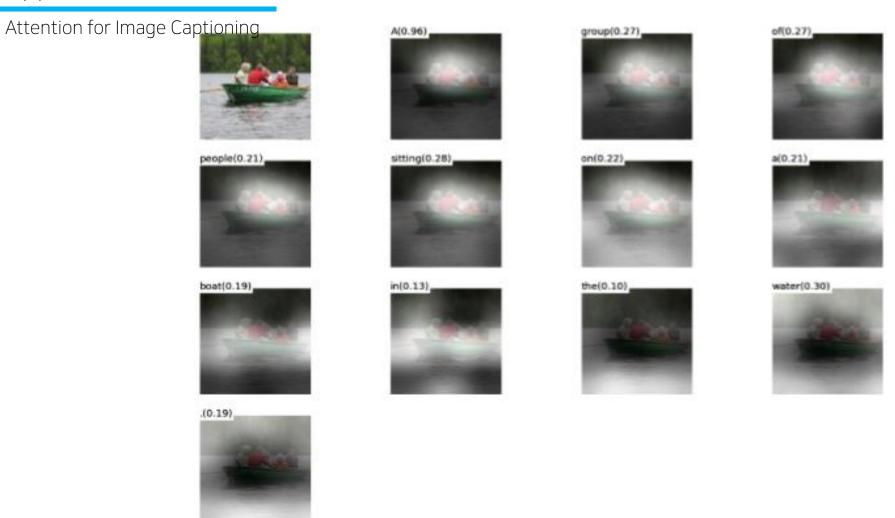


(b) A large white bird standing in a forest.

Attention for Image Ca-+:----



(a) A man and a woman riding a boat in the water.



(b) A group of people sitting on a boat in the water.

# Neural Turing Machine & Memory-based QA Models

by ent423, ent261 correspondent updated 9:49 pm et, thu march 19,2015 (ent261) a ent114 was killed in a parachute accident in ent45, ent85, near ent312, a ent119 official told ent261 on wednesday. he was identified thursday as special warfare operator 3rd class ent23,29, of ent187, ent265. "ent23 distinguished himself consistently throughout his career, he was the epitome of the quiet professional in all facets of his life, and he leaves an inspiring legacy of natural tenacity and focused

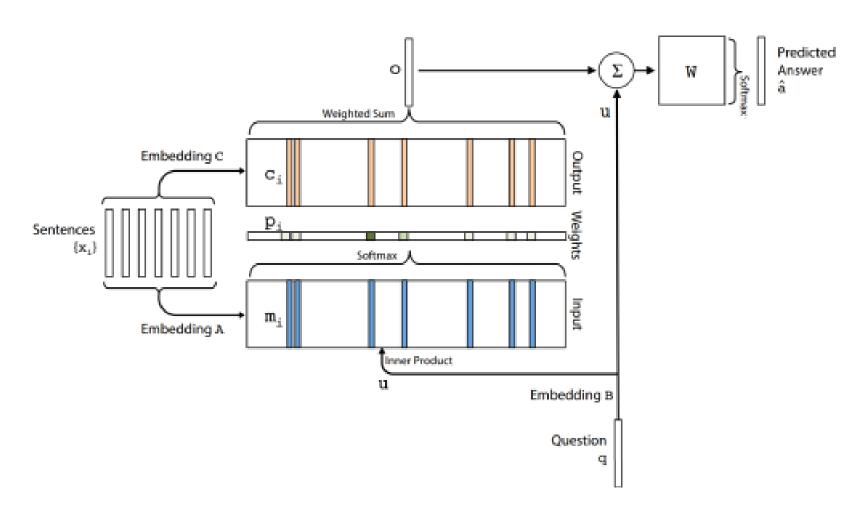
(ent223) ent63 went familial for fall at its fashion show in ent231 on sunday, dedicating its collection to ``mamma" with nary a pair of ``mom jeans "in sight .ent164 and ent21, who are behind the ent196 brand, sent models down the runway in decidedly feminine dresses and skirts adorned with roses, lace and even embroidered doodles by the designers own nieces and nephews .many of the looks featured saccharine needlework phrases like ``ilove you,

by ent270, ent223 updated 9:35 am et, mon march 2, 2015

ent119 identifies deceased sailor as X, who leaves behind a wife

X dedicated their fall fashion show to moms

Neural Turing Machine & Memory-based QA Models



```
The silvent marketing of the control of the control
```

```
# Embedding layer
with tf.name_scope('Embedding_layer'):
    embeddings_var = tf.Variable(tf.random_uniform([vocabulary_size, EMBEDDING_DIM], -1.0, 1.0), trainable=True)
    tf.summary.histogram('embeddings var', embeddings var)
    batch_embedded = tf.nn.embedding_lookup(embeddings_var, batch_ph)
# (Bi-)RNN layer(-s)
rnn outputs, = bi rnn(GRUCell(HIDDEN SIZE), GRUCell(HIDDEN SIZE),
                        inputs=batch_embedded, sequence_length=seq_len_ph, dtype=tf.float32)
tf.summary.histogram('RNN_outputs', rnn_outputs)
# Attention layer
with tf.name_scope('Attention_layer'):
    attention_output, alphas = attention(rnn_outputs, ATTENTION_SIZE, return_alphas=True)
    tf.summary.histogram('alphas', alphas)
# Dropout
drop = tf.nn.dropout(attention output, keep prob ph)
# Fully connected layer
with tf.name_scope('Fully_connected_layer'):
    W = tf.Variable(tf.truncated normal([HIDDEN SIZE * 2, 1], stddev=0.1)) # Hidden size is multiplied by 2 for Bi-RNN
    b = tf.Variable(tf.constant(0., shape=[1]))
   y_hat = tf.nn.xw_plus_b(drop, W, b)
   y hat = tf.squeeze(y hat)
    tf.summary.histogram('W', W)
with tf.name_scope('Metrics'):
    # Cross-entropy loss and optimizer initialization
    loss = tf.reduce_mean(tf.nn.sigmoid_cross_entropy_with_logits(logits=y_hat, labels=target_ph))
    tf.summary.scalar('loss', loss)
    optimizer = tf.train.AdamOptimizer(learning rate=1e-3).minimize(loss)
    # Accuracy metric
    accuracy = tf.reduce mean(tf.cast(tf.equal(tf.round(tf.sigmoid(y_hat)), target_ph), tf.float32))
    tf.summary.scalar('accuracy', accuracy)
```

### Code



```
# Embedding layer
with tf.name scope('Embedding layer'):
    embeddings_var = tf.Variable(tf.random_uniform([vocabulary_size, EMBEDDING_DIM], -1.0, 1.0), trainable=True
    tf.summary.histogram('embeddings_var', embeddings_var)
    batch embedded = tf.nn.embedding lookup(embeddings var, batch ph)
# (Bi-)RNN layer(-s)
rnn outputs, = bi rnn(GRUCell(HIDDEN SIZE), GRUCell(HIDDEN SIZE),
                        inputs=batch embedded, sequence length=seq len ph, dtype=tf.float32)
tf.summary.histogram('RNN outputs', rnn outputs)
# Attention layer
with tf.name_scope('Attention_layer'):
    attention output, alphas = attention(rnn outputs, ATTENTION SIZE, return alphas=True)
    tf.summary.histogram('alphas', alphas)
```

- Batch size만큼 Look up table을 보고 Word들의 값에 따라 각각을 벡터 값으로 바꿈
- 바꾼 batch\_embedded를 Rnn Layer의 input으로 넣고 Rnn Layer의 output을 Attention Layer의 input으로 넣음.



```
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```

```
if isinstance(inputs, tuple):
    # In case of Bi-RNN, concatenate the forward and the backward RNN outputs.
    inputs = tf.concat(inputs, 2)
if time major:
    \# (T,B,D) \Rightarrow (B,T,D)
    inputs = tf.array_ops.transpose(inputs, [1, 0, 2])
hidden_size = inputs.shape[2].value # D value - hidden size of the RNN layer
# Trainable parameters
w omega = tf.Variable(tf.random normal([hidden size, attention size], stddev=0.1))
b_omega = tf.Variable(tf.random_normal([attention_size], stddev=0.1))
u_omega = tf.Variable(tf.random_normal([attention_size], stddev=0.1))
with tf.name_scope('v'):
    # Applying fully connected layer with non-linear activation to each of the B*T timestamps;
    # the shape of v is (B,T,D)*(D,A)=(B,T,A), where A=attention_size
    v = tf.tanh(tf.tensordot(inputs, w omega, axes=1) + b omega)
# For each of the timestamps its vector of size A from `v` is reduced with `u` vector
vu = tf.tensordot(v, u_omega, axes=1, name='vu') # (B,T) shape
alphas = tf.nn.softmax(vu, name='alphas')
                                                 # (B,T) shape
# Output of (Bi-)RNN is reduced with attention vector; the result has (B,D) shape
output = tf.reduce sum(inputs * tf.expand dims(alphas, -1), 1)
if not return alphas:
    return output
else:
    return output, alphas
```

### Code

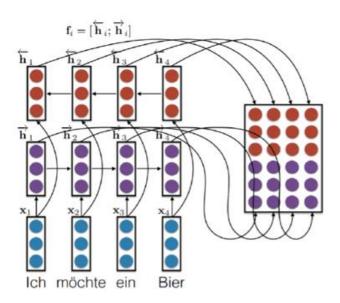
RNN model with Attention





```
if isinstance(inputs, tuple):
```

# In case of Bi-RNN, concatenate the forward and the backward RNN outputs.
inputs = tf.concat(inputs, 2)



Forward 와 backward RNN output을 concat함.



```
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```

```
if isinstance(inputs, tuple):
    # In case of Bi-RNN, concatenate the forward and the backward RNN outputs.
    inputs = tf.concat(inputs, 2)
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    inputs = tf.array_ops.transpose(inputs, [1, 0, 2])
hidden size = inputs.shape[2].value # D value - hidden size of the RNN layer
# Trainable parameters
w omega = tf.Variable(tf.random normal([hidden size, attention size], stddev=0.1))
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output = tf.reduce sum(inputs * tf.expand dims(alphas, -1), 1)
if not return alphas:
    return output
else:
    return output, alphas
```





```
hidden_size = inputs.shape[2].value # D value - hidden size of the RNN layer

# Trainable parameters
w_omega = tf.Variable(tf.random_normal([hidden_size, attention_size], stddev=0.1))
b_omega = tf.Variable(tf.random_normal([attention_size], stddev=0.1))
u_omega = tf.Variable(tf.random_normal([attention_size], stddev=0.1))
```

- Hidden\_size는 input의 shape가 (batch\_size, Max\_time, cell.output\_size) 이므로 cell.output\_size = cell\_fw.output\_size + cell\_bw.output\_size이다.
- W, B, U는 학습 파라미터



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```

```
if isinstance(inputs, tuple):
    # In case of Bi-RNN, concatenate the forward and the backward RNN outputs.
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# Trainable parameters
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with tf.name_scope('v'):
    # Applying fully connected layer with non-linear activation to each of the B*T timestamps;
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vu = tf.tensordot(v, u_omega, axes=1, name='vu') # (B,T) shape
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# Output of (Bi-)RNN is reduced with attention vector; the result has (B,D) shape
output = tf.reduce sum(inputs * tf.expand dims(alphas, -1), 1)
if not return alphas:
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else:
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```



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```
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    # the shape of `v` is (B,T,D)*(D,A)=(B,T,A), where A=attention_size
    v = tf.tanh(tf.tensordot(inputs, w_omega, axes=1) + b_omega)
```

$$a(s_{i-1}, h_j) = v_a^T \tanh(W_a S_{i-1} + U_a h_j)$$

• Seq2seq모델에 attention모델을 적용한 것이 아니고 many to one의 Rnn 모델에 attention을 적용한 것이므로 Si-1가 없고, 따라서 tanh(w\*hj + b)라고 생각.



```
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```

```
if isinstance(inputs, tuple):
    # In case of Bi-RNN, concatenate the forward and the backward RNN outputs.
    inputs = tf.concat(inputs, 2)
if time major:
    \# (T,B,D) \Rightarrow (B,T,D)
    inputs = tf.array_ops.transpose(inputs, [1, 0, 2])
hidden_size = inputs.shape[2].value # D value - hidden size of the RNN layer
# Trainable parameters
w omega = tf.Variable(tf.random normal([hidden size, attention size], stddev=0.1))
b_omega = tf.Variable(tf.random_normal([attention_size], stddev=0.1))
u_omega = tf.Variable(tf.random_normal([attention_size], stddev=0.1))
with tf.name_scope('v'):
    # Applying fully connected layer with non-linear activation to each of the B*T timestamps;
    # the shape of v is (B,T,D)*(D,A)=(B,T,A), where A=attention_size
    v = tf.tanh(tf.tensordot(inputs, w omega, axes=1) + b omega)
vu = tf.tensordot(v, u_omega, axes=1, name='vu')  # (B,T) shape
alphas = tf.nn.softmax(vu, name='alphas')
                                                  # (B,T) shape
# Output of (Bi-)RNN is reduced with attention vector; the result has (B,D) shape
output = tf.reduce sum(inputs * tf.expand dims(alphas, -1), 1)
if not return alphas:
    return output
else:
    return output, alphas
```



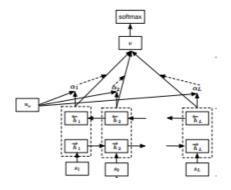


```
# For each of the timestamps its vector of size A from `v` is reduced with `u` vector
vu = tf.tensordot(v, u_omega, axes=1, name='vu') # (B,T) shape
alphas = tf.nn.softmax(vu, name='alphas') # (B,T) shape
```

$$\begin{aligned} a\big(s_{i-1},h_j\big) &= v_a^T \mathrm{tanh}(W_a S_{i-1} + U_a h_j) \\ e_{ij} &= a(s_{i-1},h_j) \\ \alpha_{ij} &= \frac{\exp(e_{ij})}{\sum_{k=1}^{T_X} \exp(e_{ik})} \end{aligned}$$

• 이전에 구한 v값과 u를 곱한후 softmax함수를 취하는 부분.

```
# Output of (Bi-)RNN is reduced with attention vector; the result has (B,D) shape
output = tf.reduce_sum(inputs * tf.expand_dims(alphas, -1), 1)
```



• 위와 같은 구조로 매번 context vector를 구하지 않으므로

$$c_i = \sum_{j=1}^{T_x} lpha_{ij} h_j$$
 가 아닌 c의 값을 weighted sum하는 부분.



```
# Embedding layer
with tf.name_scope('Embedding_layer'):
    embeddings_var = tf.Variable(tf.random_uniform([vocabulary_size, EMBEDDING_DIM], -1.0, 1.0), trainable=True)
    tf.summary.histogram('embeddings var', embeddings var)
    batch_embedded = tf.nn.embedding_lookup(embeddings_var, batch_ph)
# (Bi-)RNN layer(-s)
rnn_outputs, _ = bi_rnn(GRUCell(HIDDEN_SIZE), GRUCell(HIDDEN_SIZE),
                        inputs=batch_embedded, sequence_length=seq_len_ph, dtype=tf.float32)
tf.summary.histogram('RNN_outputs', rnn_outputs)
# Attention layer
with tf.name_scope('Attention_layer'):
    attention_output, alphas = attention(rnn_outputs, ATTENTION_SIZE, return_alphas=True)
    tf.summary.histogram('alphas', alphas)
# Dropout
drop = tf.nn.dropout(attention output, keep prob ph)
# Fully connected layer
with tf.name_scope('Fully_connected_layer'):
    W = tf.Variable(tf.truncated_normal([HIDDEN_SIZE * 2, 1], stddev=0.1)) # Hidden size is multiplied by 2 for Bi-RNN
    b = tf.Variable(tf.constant(0., shape=[1]))
   y_hat = tf.nn.xw_plus_b(drop, W, b)
    y hat = tf.squeeze(y hat)
    tf.summary.histogram('W', W)
with tf.name scope('Metrics'):
    # Cross-entropy loss and optimizer initialization
    loss = tf.reduce_mean(tf.nn.sigmoid_cross_entropy_with_logits(logits=y_hat, labels=target_ph))
    tf.summary.scalar('loss', loss)
    optimizer = tf.train.AdamOptimizer(learning rate=1e-3).minimize(loss)
    # Accuracy metric
    accuracy = tf.reduce mean(tf.cast(tf.equal(tf.round(tf.sigmoid(y_hat)), target_ph), tf.float32))
    tf.summary.scalar('accuracy', accuracy)
```

### Code

### RNN model with Attention



```
# Fully connected layer
with tf.name_scope('Fully_connected_layer'):
    W = tf.Variable(tf.truncated_normal([HIDDEN_SIZE * 2, 1], stddev=0.1)) # Hidden size is multiplied by 2 for Bi-RNN
    b = tf.Variable(tf.constant(0., shape=[1]))
    y_hat = tf.nn.xw_plus_b(drop, W, b)
    y_hat = tf.squeeze(y_hat)
    tf.summary.histogram('W', W)
```

• 예측한 결과 값이 y\_hat 이됨.

```
with tf.name_scope('Metrics'):
    # Cross-entropy loss and optimizer initialization
    loss = tf.reduce_mean(tf.nn.sigmoid_cross_entropy_with_logits(logits=y_hat, labels=target_ph))
    tf.summary.scalar('loss', loss)
    optimizer = tf.train.AdamOptimizer(learning_rate=1e-3).minimize(loss)

# Accuracy metric
    accuracy = tf.reduce_mean(tf.cast(tf.equal(tf.round(tf.sigmoid(y_hat)), target_ph), tf.float32))
    tf.summary.scalar('accuracy', accuracy)
```

• y\_hat과 target\_ph를 비교하여 loss값을 계산하고 accuracy를 계산.

감사합니다.