

Computer Architecture and Operating Systems Lecture 2: The C Programming Language

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System Calls

- Programming interface to the services provided by the OS
- Typically written in a high-level language (C or C++)
- Mostly accessed by programs via a high-level
 Application Programming Interface (API) rather than direct system call use
- Three most common APIs are Win32 API for Windows, POSIX API for POSIX-based systems (including virtually all versions of UNIX, Linux, and Mac OS X), and Java API for the Java virtual machine (JVM)

Example of System Calls

 System call sequence to copy the contents of one file to another file

> source file destination file Example System Call Sequence Acquire input file name Write prompt to screen Accept input Acquire output file name Write prompt to screen Accept input Open the input file if file doesn't exist, abort Create output file if file exists, abort Loop Read from input file Write to output file Until read fails Close output file Write completion message to screen Terminate normally

Example of Standard API

EXAMPLE OF STANDARD API

As an example of a standard API, consider the read() function that is available in UNIX and Linux systems. The API for this function is obtained from the man page by invoking the command

man read

on the command line. A description of this API appears below:

```
#include <unistd.h>
ssize_t read(int fd, void *buf, size_t count)

return function parameters
value name
```

A program that uses the read() function must include the unistd.h header file, as this file defines the ssize_t and size_t data types (among other things). The parameters passed to read() are as follows:

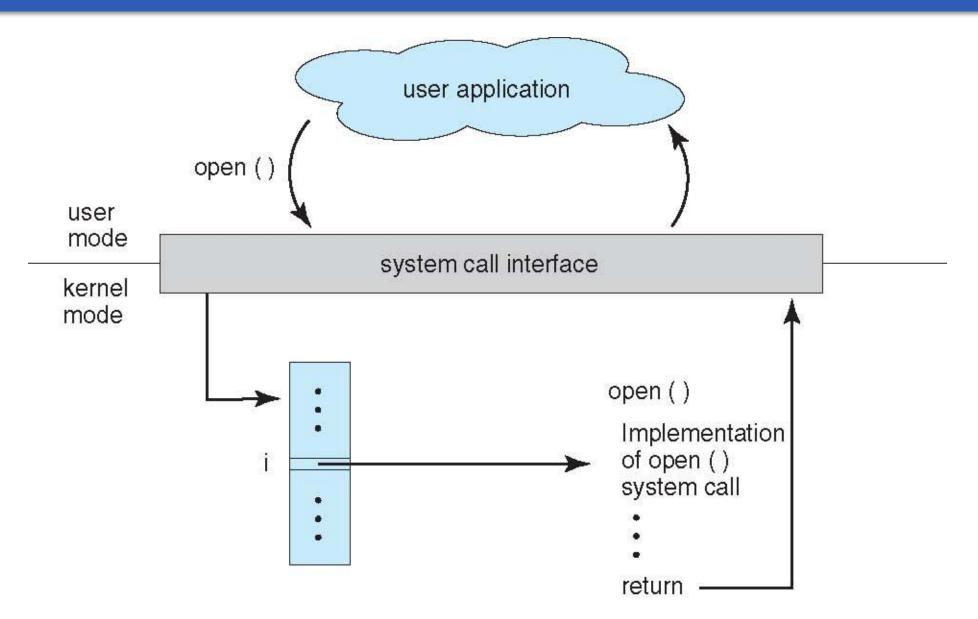
- int fd—the file descriptor to be read
- void *buf—a buffer where the data will be read into
- size_t count—the maximum number of bytes to be read into the buffer

On a successful read, the number of bytes read is returned. A return value of 0 indicates end of file. If an error occurs, read() returns -1.

System Call Implementation

- Typically, a number associated with each system call
 - System-call interface maintains a table indexed according to these numbers
- The system call interface invokes the intended system call in OS kernel and returns status of the system call and any return values
- The caller need know nothing about how the system call is implemented
 - Just needs to obey API and understand what OS will do as a result call
 - Most details of OS interface hidden from programmer by API
 - Managed by run-time support library (set of functions built into libraries included with compiler)

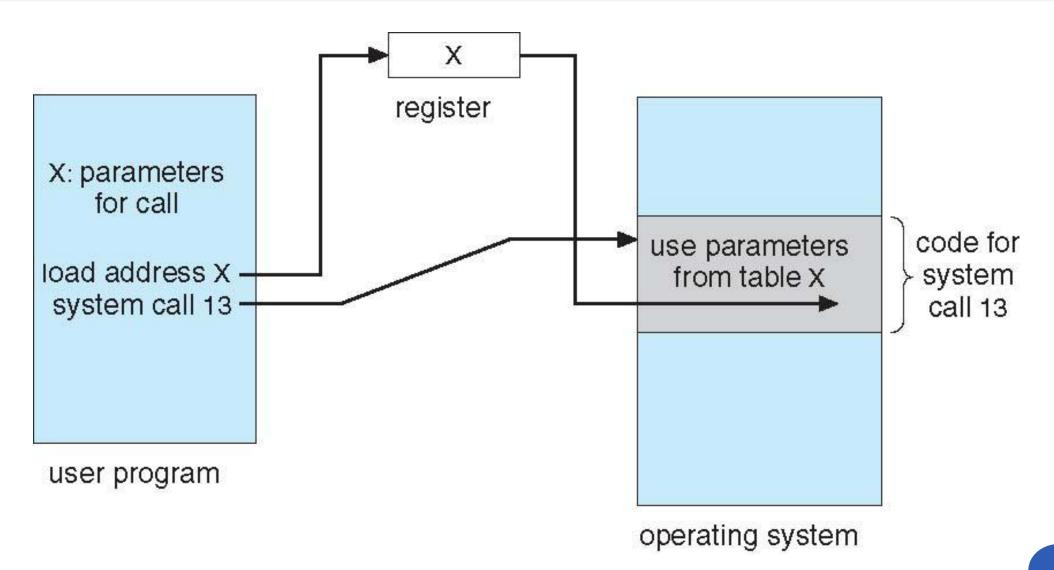
API – System Call – OS Relationship



System Call Parameter Passing

- Often, more information is required than simply identity of desired system call
 - Exact type and amount of information vary according to OS and call
- Three general methods used to pass parameters to the OS
 - Simplest: pass the parameters in registers
 - In some cases, may be more parameters than registers
 - Parameters stored in a block, or table, in memory, and address of block passed as a parameter in a register
 - This approach taken by Linux and Solaris
 - Parameters placed, or pushed, onto the stack by the program and popped off the stack by the operating system
 - Block and stack methods do not limit the number or length of parameters being passed

Parameter Passing via Table



Types of System Calls

- Process control
 - create process, terminate process
 - end, abort
 - load, execute
 - get process attributes, set process attributes
 - wait for time
 - wait event, signal event
 - allocate and free memory
 - Dump memory if error
 - Debugger for determining bugs, single step execution
 - Locks for managing access to shared data between processes

Types of System Calls

- File management
 - create file, delete file
 - open, close file
 - read, write, reposition
 - get and set file attributes
- Device management
 - request device, release device
 - read, write, reposition
 - get device attributes, set device attributes
 - logically attach or detach devices

Types of System Calls (Cont.)

- Information maintenance
 - get time or date, set time or date
 - eget system data, set system data
 - get and set process, file, or device attributes
- Communications
 - create, delete communication connection
 - send, receive messages if message passing model to host name or process name
 - From client to server
 - Shared-memory model create and gain access to memory regions
 - transfer status information
 - attach and detach remote devices

Types of System Calls (Cont.)

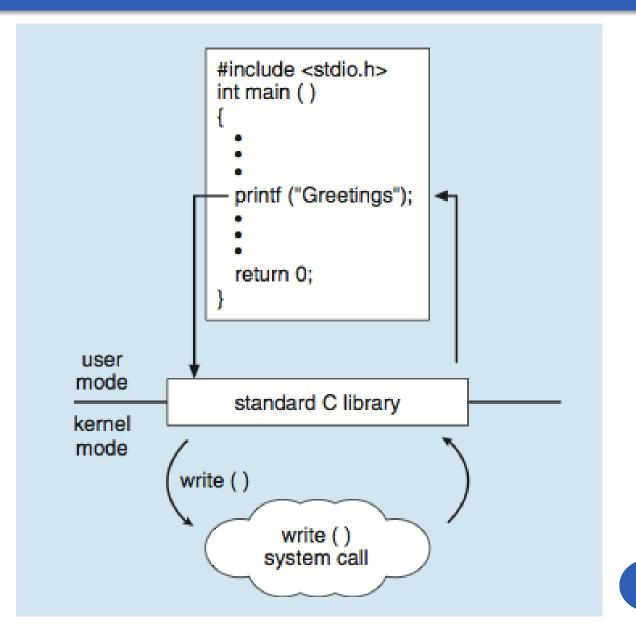
- Protection
 - Control access to resources
 - Get and set permissions
 - Allow and deny user access

Examples of Windows and Unix System Calls

	Windows	Unix
Process Control	<pre>CreateProcess() ExitProcess() WaitForSingleObject()</pre>	<pre>fork() exit() wait()</pre>
File Manipulation	<pre>CreateFile() ReadFile() WriteFile() CloseHandle()</pre>	<pre>open() read() write() close()</pre>
Device Manipulation	SetConsoleMode() ReadConsole() WriteConsole()	ioctl() read() write()
Information Maintenance	<pre>GetCurrentProcessID() SetTimer() Sleep()</pre>	<pre>getpid() alarm() sleep()</pre>
Communication	<pre>CreatePipe() CreateFileMapping() MapViewOfFile()</pre>	<pre>pipe() shmget() mmap()</pre>
Protection	<pre>SetFileSecurity() InitlializeSecurityDescriptor() SetSecurityDescriptorGroup()</pre>	<pre>chmod() umask() chown()</pre>

Standard C Library Example

 C program invoking printf() library call, which calls write() system call



Example: MS-DOS

- Single-tasking
- Shell invoked when system booted
- Simple method to run program
 - No process created
- Single memory space
- Loads program into memory, overwriting all but the kernel
- Program exit -> shell reloaded

free memory command interpreter kernel (a) At system startup

free memory process command interpreter kernel (b)

Example: FreeBSD

- Unix variant
- Multitasking
- User login -> invoke user's choice of shell
- Shell executes fork() system call to create process
 - Executes exec() to load program into process
 - Shell waits for process to terminate or continues with user commands
- Process exits with:
 - code = 0 no error
 - code > 0 error code

process D free memory process C interpreter process B kernel

System Programs

- System programs provide a convenient environment for program development and execution. They can be divided into:
 - File manipulation
 - Status information sometimes stored in a File modification
 - Programming language support
 - Program loading and execution
 - Communications
 - Background services
 - Application programs
- Most users' view of the operation system is defined by system programs, not the actual system calls

System Programs

- Provide a convenient environment for program development and execution
 - Some of them are simply user interfaces to system calls; others are considerably more complex
- File management Create, delete, copy, rename, print, dump, list, and generally manipulate files and directories

Status information

- Some ask the system for info date, time, amount of available memory, disk space, number of users
- Others provide detailed performance, logging, and debugging information
- Typically, these programs format and print the output to the terminal or other output devices
- Some systems implement a registry used to store and retrieve configuration information

System Programs (Cont.)

File modification

- Text editors to create and modify files
- Special commands to search contents of files or perform transformations of the text
- Programming-language support Compilers, assemblers, debuggers and interpreters sometimes provided
- Program loading and execution- Absolute loaders, relocatable loaders, linkage editors, and overlay-loaders, debugging systems for higher-level and machine language
- Communications Provide the mechanism for creating virtual connections among processes, users, and computer systems
 - Allow users to send messages to one another's screens, browse web pages, send electronic-mail messages, log in remotely, transfer files from one machine to another

System Programs (Cont.)

Background Services

- Launch at boot time
 - Some for system startup, then terminate
 - Some from system boot to shutdown
- Provide facilities like disk checking, process scheduling, error logging, printing
- Run in user context not kernel context
- Known as services, subsystems, daemons

Application programs

- Don't pertain to system
- Run by users
- Not typically considered part of OS
- Launched by command line, mouse click, finger poke

Operating System Design and Implementation

- Design and Implementation of OS not "solvable", but some approaches have proven successful
- Internal structure of different Operating Systems can vary widely
- Start the design by defining goals and specifications
- Affected by choice of hardware, type of system
- User goals and System goals
 - User goals operating system should be convenient to use, easy to learn, reliable, safe, and fast
 - System goals operating system should be easy to design, implement, and maintain, as well as flexible, reliable, error-free, and efficient

Operating System Design and Implementation (Cont.)

Important principle to separate

Policy: What will be done?

Mechanism: How to do it?

- Mechanisms determine how to do something, policies decide what will be done
- The separation of policy from mechanism is a very important principle, it allows maximum flexibility if policy decisions are to be changed later (example – timer)
- Specifying and designing an OS is highly creative task of software engineering

Implementation

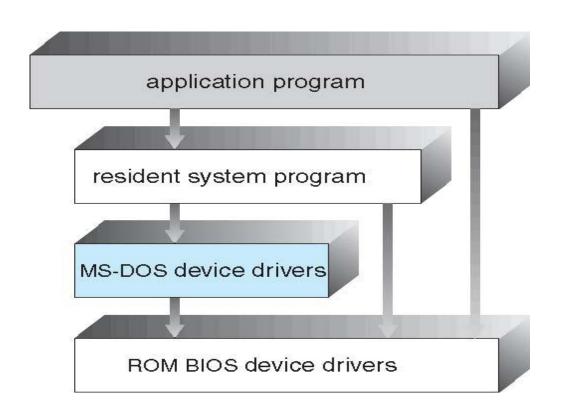
- Much variation
 - Early OSes in assembly language
 - Then system programming languages like Algol, PL/1
 - Now C, C++
- Actually usually a mix of languages
 - Lowest levels in assembly
 - Main body in C
 - Systems programs in C, C++, scripting languages like PERL,
 Python, shell scripts
- More high-level language easier to port to other hardware
 - But slower
- Emulation can allow an OS to run on non-native hardwar

Operating System Structure

- General-purpose OS is very large program
- Various ways to structure ones
 - Simple structure MS-DOS
 - More complex -- UNIX
 - Layered an abstrcation
 - Microkernel -Mach

Simple Structure -- MS-DOS

- MS-DOS written to provide the most functionality in the least space
 - Not divided into modules
 - Although MS-DOS has some structure, its interfaces and levels of functionality are not well separated



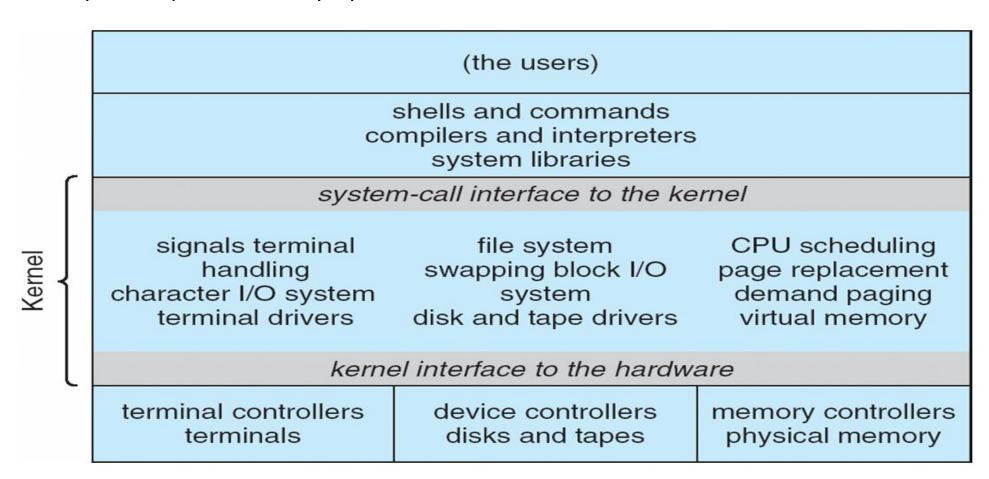
Non Simple Structure -- UNIX

UNIX – limited by hardware functionality, the original UNIX operating system had limited structuring. The UNIX OS consists of two separable parts

- Systems programs
- The kernel
 - Consists of everything below the system-call interface and above the physical hardware
 - Provides the file system, CPU scheduling, memory management, and other operating-system functions; a large number of functions for one level

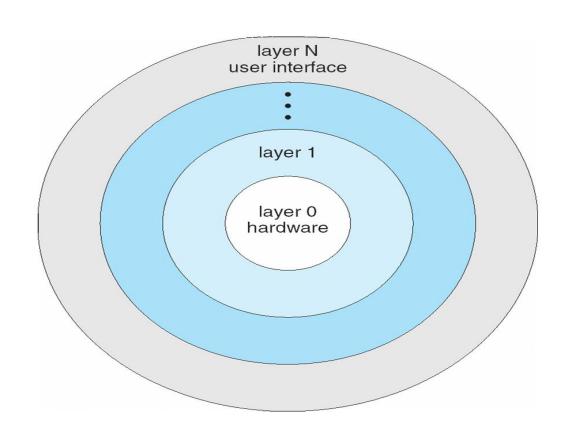
Traditional UNIX System Structure

Beyond simple but not fully layered



Layered Approach

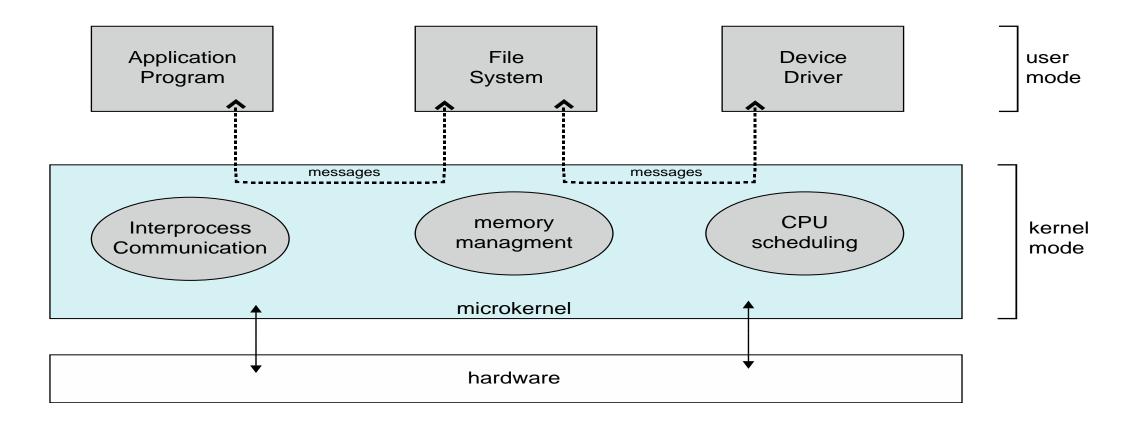
- The operating system is divided into a number of layers (levels), each built on top of lower layers. The bottom layer (layer 0), is the hardware; the highest (layer N) is the user interface.
- With modularity, layers are selected such that each uses functions (operations) and services of only lower-level layers



Microkernel System Structure

- Moves as much from the kernel into user space
- Mach example of microkernel
 - Mac OS X kernel (Darwin) partly based on Mach
- Communication takes place between user modules using message passing
- Benefits:
 - Easier to extend a microkernel
 - Easier to port the operating system to new architectures
 - More reliable (less code is running in kernel mode)
 - More secure
- Detriments:
 - Performance overhead of user space to kernel space communication

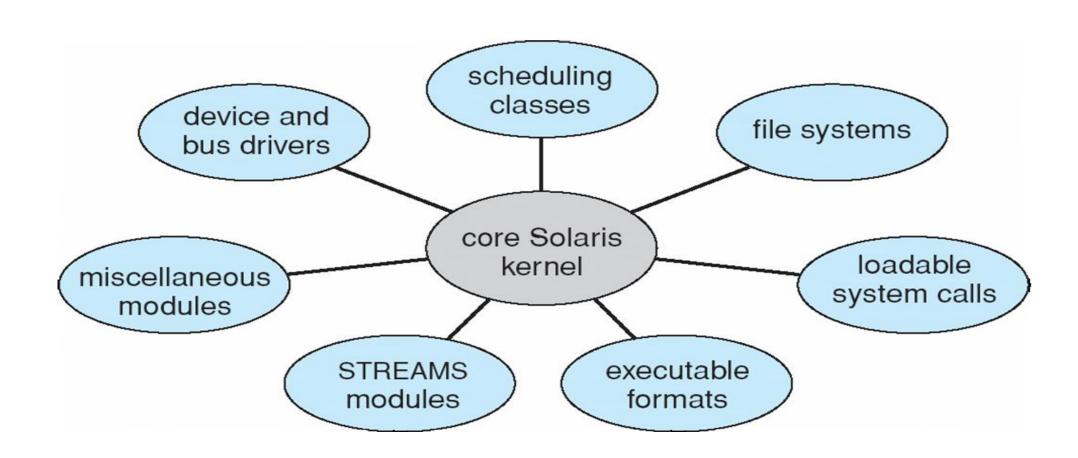
Microkernel System Structure



Modules

- Many modern operating systems implement loadable kernel modules
 - Uses object-oriented approach
 - Each core component is separate
 - Each talks to the others over known interfaces
 - Each is loadable as needed within the kernel
- Overall, similar to layers but with more flexible
 - Linux, Solaris, etc

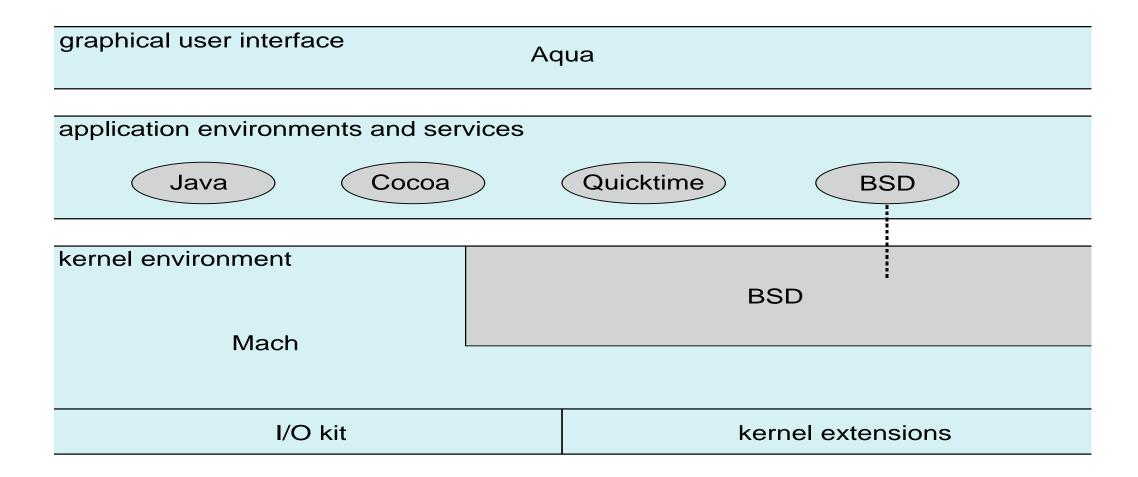
Solaris Modular Approach



Hybrid Systems

- Most modern operating systems are actually not one pure model
 - Hybrid combines multiple approaches to address performance, security, usability needs
 - Linux and Solaris kernels in kernel address space, so monolithic, plus modular for dynamic loading of functionality
 - Windows mostly monolithic, plus microkernel for different subsystem *personalities*
- Apple Mac OS X hybrid, layered, Aqua UI plus Cocoa programming environment
 - Below is kernel consisting of Mach microkernel and BSD Unix parts, plus I/O kit and dynamically loadable modules (called kernel extensions)

Mac OS X Structure



iOS

- Apple mobile OS for iPhone, iPad
 - Structured on Mac OS X, added functionality
 - Does not run OS X applications natively
 - Also runs on different CPU architecture (ARM vs. Intel)
 - Cocoa Touch Objective-C API for developing apps
 - Media services layer for graphics, audio, video
 - Core services provides cloud computing, databases
 - Core operating system, based on Mac OS X kernel

Cocoa Touch

Media Services

Core Services

Core OS

Android

- Developed by Open Handset Alliance (mostly Google)
 - Open Source
- Similar stack to IOS
- Based on Linux kernel but modified
 - Provides process, memory, device-driver management
 - Adds power management
- Runtime environment includes core set of libraries and Dalvik virtual machine
 - Apps developed in Java plus Android API
 - Java class files compiled to Java bytecode then translated to executable than runs in Dalvik VM
- Libraries include frameworks for web browser (webkit), database (SQLite), multimedia, smaller libc

Any Questions?

```
__start: addi t1, zero, 0x18
    addi t2, zero, 0x21

cycle: beq t1, t2, done
    slt t0, t1, t2
    bne t0, zero, if_less
    nop
    sub t1, t1, t2
    j cycle
    nop

if_less: sub t2, t2, t1
    j cycle

done: add t3, t1, zero
```