

Computer Architecture and Operating Systems Lecture 5: Dynamic Memory Allocation

Andrei Tatarnikov

atatarnikov@hse.ru
@andrewt0301

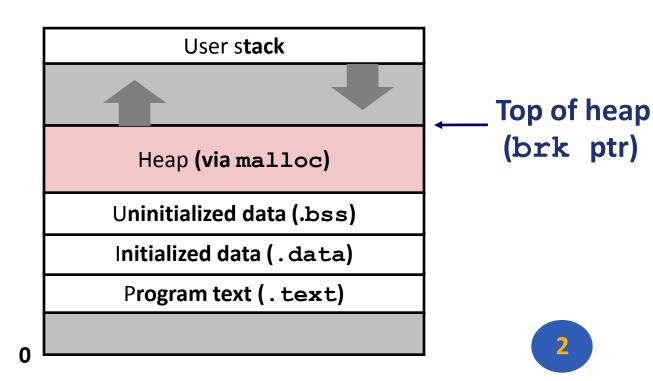
Dynamic Memory Allocation

- Programmers use dynamic memory allocators (such as malloc) to acquire VM at run time.
 - For data structures whose size is only known at runtime.
- Dynamic memory allocators manage an area of process virtual memory known as the *heap*.

Application

Dynamic Memory Allocator

Heap



Dynamic Memory Allocation

- Allocator maintains heap as collection of variable sized *blocks*, which are either *allocated* or *free*
- Types of allocators
 - **Explicit allocator:** application allocates and frees space
 - E.g., malloc and free in C
 - Implicit allocator: application allocates, but does not free space
 - E.g. garbage collection in Java, ML, and Lisp
- Will discuss simple explicit memory allocation today

The malloc Package

```
#include <stdlib.h>
void *malloc(size_t size)
```

- Successful:
 - Returns a pointer to a memory block of at least **size** bytes aligned to an 8-byte (x86) or 16-byte (x86-64) boundary
 - If size == 0, returns NULL
- Unsuccessful: returns NULL (0) and sets errno

```
void free(void *p)
```

- Returns the block pointed at by p to pool of available memory
- p must come from a previous call to malloc or realloc

Other functions

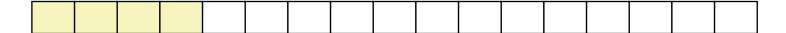
- **calloc:** Version of **malloc** that initializes allocated block to zero.
- realloc: Changes the size of a previously allocated block.
- sbrk: Used internally by allocators to grow or shrink the heap

malloc Example

```
#include <stdio.h>
#include <stdlib.h>
void foo(int n) {
  int i, *p;
  /* Allocate a block of n ints */
  p = (int *) malloc(n * sizeof(int));
  if (p == NULL) {
     perror("malloc");
     exit(0);
  /* Initialize allocated block */
  for (i=0; i<n; i++)
         p[i] = i;
  /* Return allocated block to the heap */
  free(p);
```

Allocation Example

$$p1 = malloc(4)$$



$$p2 = malloc(5)$$

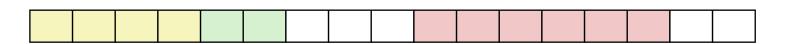


$$p3 = malloc(6)$$



free (p2)

$$p4 = malloc(2)$$



Constraints

- Applications
 - Can issue arbitrary sequence of malloc and free requests
 - free request must be to a malloc'd block
- Allocators
 - Can't control number or size of allocated blocks
 - Must respond immediately to malloc requests
 - *i.e.*, can't reorder or buffer requests
 - Must allocate blocks from free memory
 - *i.e.*, can only place allocated blocks in free memory
 - Must align blocks so they satisfy all alignment requirements
 - 8-byte (x86) or 16-byte (x86-64) alignment on Linux boxes
 - Can manipulate and modify only free memory
 - Can't move the allocated blocks once they are malloc'd
 - i.e., compaction is not allowed

Performance Goal: Throughput

- •Given some sequence of malloc and free requests:
 - $R_0, R_1, ..., R_k, ..., R_{n-1}$
- Goals: maximize throughput and peak memory utilization
 - These goals are often conflicting
- Throughput:
 - Number of completed requests per unit time
 - Example:
 - 5,000 malloc calls and 5,000 free calls in 10 seconds
 - Throughput is 1,000 operations/second

Performance Goal: Peak Memory Utilization

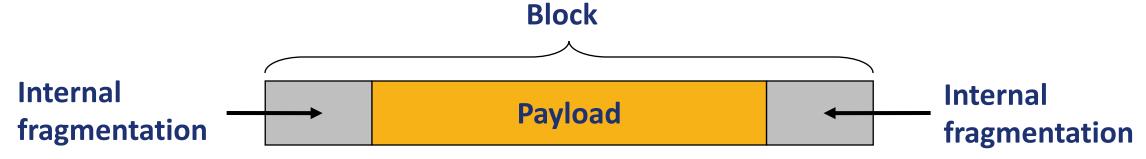
- Given some sequence of malloc and free requests:
 - $R_0, R_1, ..., R_k, ..., R_{n-1}$
- *Def*: Aggregate payload P_k
 - malloc(p) results in a block with a payload of p bytes
 - After request R_k has completed, the aggregate payload P_k is the sum of currently allocated payloads
- Def: Current heap size H_k
 - Assume H_k is monotonically nondecreasing
 - i.e., heap only grows when allocator uses **sbrk**
- Def: Peak memory utilization after k+1 requests
 - $U_k = (\max_{i < k} P_i) / H_k$

Fragmentation

- Poor memory utilization caused by fragmentation
 - *internal* fragmentation
 - external fragmentation

Internal Fragmentation

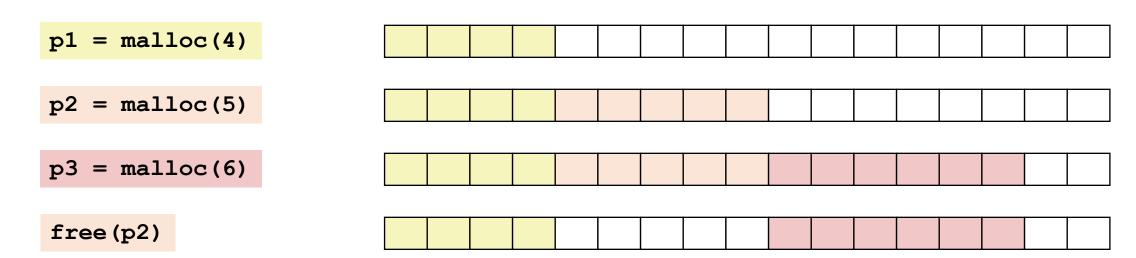
For a given block, internal fragmentation occurs if payload is smaller than block size



- Caused by
 - Overhead of maintaining heap data structures
 - Padding for alignment purposes
 - Explicit policy decisions (e.g., to return a big block to satisfy a small request)
- Depends only on the pattern of previous requests
 - Thus, easy to measure

External Fragmentation

 Occurs when there is enough aggregate heap memory, but no single free block is large enough



p4 = malloc(6)

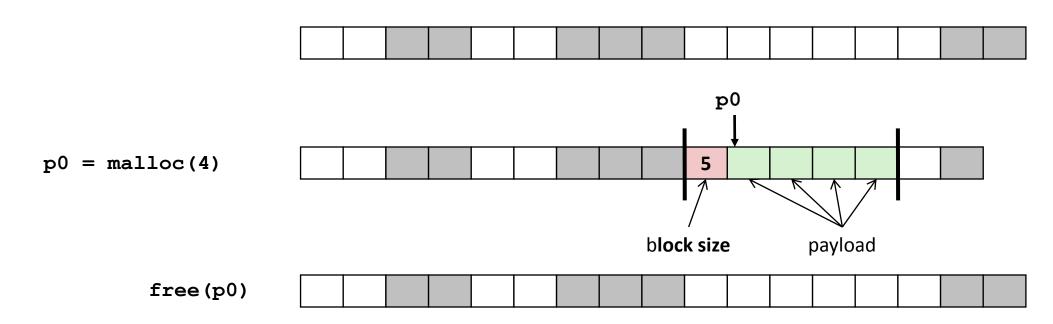
- Oops! (what would happen now?)
- Depends on the pattern of future requests
 - Thus, difficult to measure

Implementation Issues

- How do we know how much memory to free given just a pointer?
- How do we keep track of the free blocks?
- •What do we do with the extra space when allocating a structure that is smaller than the free block it is placed in?
- How do we pick a block to use for allocation -- many might fit?
- How do we reinsert freed block?

Knowing How Much to Free

- Standard method
 - Keep the length of a block in the word preceding the block.
 - This word is often called the *header field* or *header*
 - Requires an extra word for every allocated block



Keeping Track of Free Blocks

Method 1: Implicit list using length—links all blocks



• Method 2: Explicit list among the free blocks using pointers

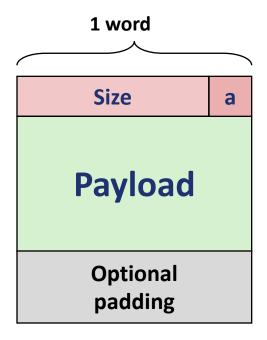


- Method 3: Segregated free list
 - Different free lists for different size classes
- Method 4: Blocks sorted by size
 - Can use a balanced tree (e.g. Red-Black tree) with pointers within each free block, and the length used as a key

Method 1: Implicit List

- For each block we need both size and allocation status
 - Could store this information in two words: wasteful!
- Standard trick
 - If blocks are aligned, some low-order address bits are always 0
 - Instead of storing an always-0 bit, use it as a allocated/free flag
 - When reading size word, must mask out this bit

Format of allocated and free blocks



a = 1: Allocated block

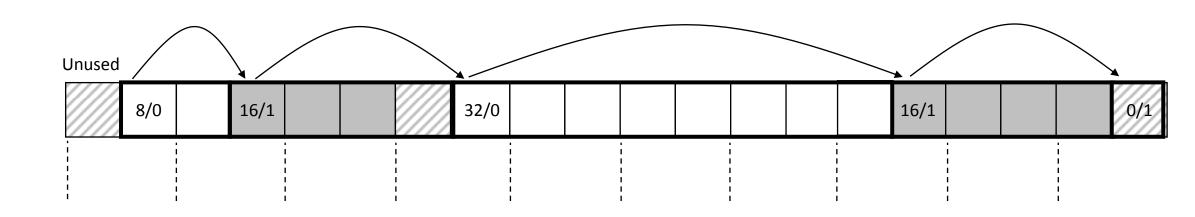
a = 0: Free block

Size: block size

Payload: application data (allocated blocks only)

Detailed Implicit Free List Example

Start of heap



Double-word aligned

Allocated blocks: shaded

Free blocks: unshaded

Headers: labeled with size in bytes/allocated bit

Implicit List: Finding a Free Block

First fit:

Search list from beginning, choose *first* free block that fits:

- Can take linear time in total number of blocks (allocated and free)
- In practice it can cause "splinters" at beginning of list

Next fit:

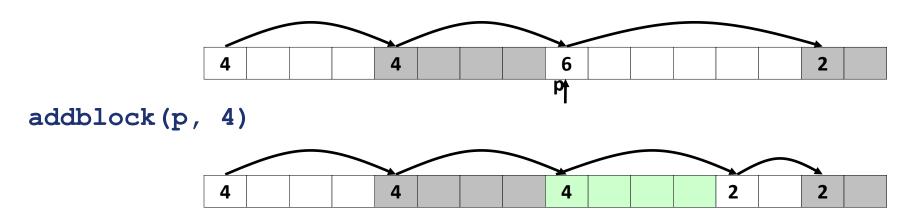
- Like first fit, but search list starting where previous search finished
- Should often be faster than first fit: avoids re-scanning unhelpful blocks
- Some research suggests that fragmentation is worse

Best fit:

- Search the list, choose the best free block: fits, with fewest bytes left over
- Keeps fragments small—usually improves memory utilization
- Will typically run slower than first fit

Implicit List: Allocating in Free Block

- •Allocating in a free block: splitting
 - Since allocated space might be smaller than free space, we might want to split the block

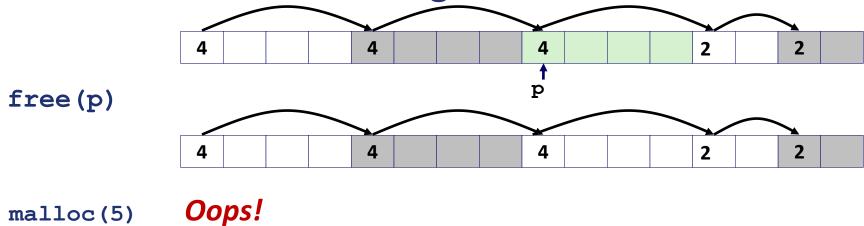


Implicit List: Freeing a Block

- Simplest implementation:
 - Need only clear the "allocated" flag

```
void free_block(ptr p) { *p = *p & -2 }
```

But can lead to "false fragmentation"



There is enough free space, but the allocator won't be able to find it

Implicit List: Coalescing

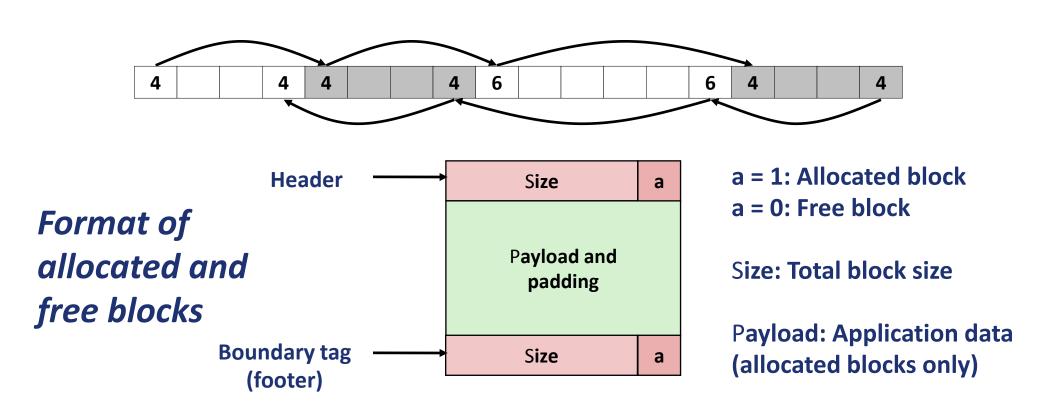
- Join (coalesce) with next/previous blocks, if they are free
 - Coalescing with next block

```
logically
                                  p
free (p)
                                                           gone
                                  6
          void free block(ptr p) {
              *p = *p & -2; // clear allocated flag
             next = p + *p; // find next block
              if ((*next & 1) == 0)
               *p = *p + *next; // add to this block if
                                   // not allocated
```

But how do we coalesce with previous block?

Implicit List: Bidirectional Coalescing

- **Boundary tags** [Knuth73]
 - Replicate size/allocated word at "bottom" (end) of free blocks
 - Allows us to traverse the "list" backwards, but requires extra space
 - Important and general technique!



Constant Time Coalescing

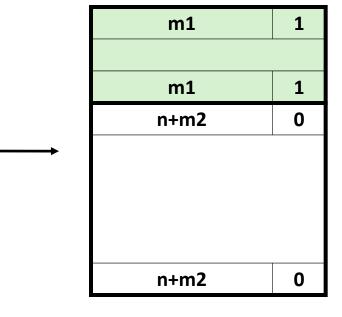


Constant Time Coalescing (Case 1)

m1	1		m1	1
m1	1		m1	1
n	1		n	0
		→		
n	1		n	0
m2	1		m2	1
m2	1		m2	1

Constant Time Coalescing (Case 2)

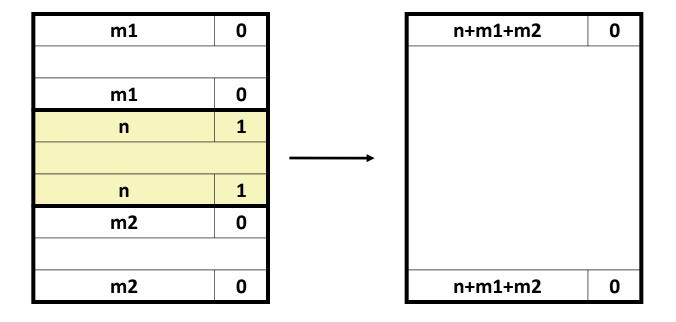
m1	1
m1	1
n	1
n	1
m2	0
m2	0



Constant Time Coalescing (Case 3)

m1	0		n+m1	0
m1	0			
n	1			
		→		
n	1		n+m1	0
m2	1		m2	1
m2	1		m2	1

Constant Time Coalescing (Case 4)



Disadvantages of Boundary Tags

•Internal fragmentation

- Can it be optimized?
 - Which blocks need the footer tag?
 - What does that mean?

Summary of Key Allocator Policies

- Placement policy:
 - First-fit, next-fit, best-fit, etc.
 - Trades off lower throughput for less fragmentation
 - Interesting observation: segregated free lists (next lecture) approximate a best fit placement policy without having to search entire free list
- Splitting policy:
 - When do we go ahead and split free blocks?
 - How much internal fragmentation are we willing to tolerate?
- Coalescing policy:
 - Immediate coalescing: coalesce each time free is called
 - Deferred coalescing: try to improve performance of free by deferring coalescing until needed. Examples:
 - Coalesce as you scan the free list for malloc
 - Coalesce when the amount of external fragmentation reaches some threshold

Implicit Lists: Summary

- Implementation: very simple
- Allocate cost:
 - linear time worst case
- Free cost:
 - constant time worst case
 - even with coalescing
- Memory usage:
 - will depend on placement policy
 - First-fit, next-fit or best-fit
- Not used in practice for malloc/free because of linear-time allocation
 - used in many special purpose applications
- However, the concepts of splitting and boundary tag coalescing are general to all allocators

Any Questions?

```
__start: addi t1, zero, 0x18
    addi t2, zero, 0x21

cycle: beg t1, t2, done
    slt t0, t1, t2
    bne t0, zero, if_less
    nop
    sub t1, t1, t2
    j cycle
    nop

if_less: sub t2, t2, t1
    j cycle

done: add t3, t1, zero
```