

view_frames Result

Recorded at time: 143.428

robot2/odom

robot1/odom

Broadcaster: /gazebo

Average rate: 30.322 Hz

Most recent transform: 143.400 (0.028 sec old)

Buffer length: 3.133 sec

Broadcaster: /gazebo

Average rate: 30.313 Hz

Most recent transform: 143.414 (0.014 sec old)

Buffer length: 3.134 sec

robot2/base_footprint

robot1/base_footprint