In [ ]:	<pre>import numpy as np import matplotlib.pyplot as plt import pandas as pd</pre>
In [ ]:	<pre>%matplotlib inline</pre>
	from google.colab import files upload()  Choose Files No file chosen  Upload widget is only available when the cell has been executed in the current browser session. Please rerun this cell to enable.
In [ ]:	Saving 3mv.csv to 3mv (2).csv  # csv 파일을 읽어서 DataFrame 객체로 만듦. 인덱스 컬럼은 point로 설정 dg = pd.read_csv('3mv.csv') dg=dg[:495] v=np.array(dg['v'], dtype='object') t=np.array(dg['t'])
In [ ]:	<pre>#v  uploaded=files.upload()</pre>
	Choose Files No file chosen Saving v.csv to v (1).csv  Upload widget is only available when the cell has been executed in the current browser session. Please rerun this cell to enable.
In [ ]:	<pre>dg = pd.read_csv('v.csv') dg=dg[:495] v=np.array(dg['v2'])] v=np.vstack([v,np.array(dg['v2'])]) v=np.vstack([v,np.array(dg['v3'])]) v=np.vstack([v,np.array(dg['v4'])]) v=np.vstack([v,np.array(dg['v5'])]) v=np.vstack([v,np.array(dg['v6'])]) v=np.vstack([v,np.array(dg['v6'])]) v=np.vstack([v,np.array(dg['v8'])]) v=np.vstack([v,np.array(dg['v8'])]) v=np.vstack([v,np.array(dg['v9'])]) t=np.vstack([v,np.array(dg['v10'])]) t=np.array(dg['t']) #v</pre>
In []:	* sutcocrrelation, (averaged over all trajectory) autocorr[0] = np.average(v*v)  for i in range (494):     autocorr[i+1] = np.average(v[:,i+1:]*v[:,:-i-1])  fig = plt.fiqure(1, figaize=(8,5))     plt.plts(t, autocorr.color='black')     plt.ylim(-le-10, 2e-10)
In [ ]:	0
	Uploaded=files.upload()  Choose Files No file chosen Saving 3m.csv to 3m (1).csv  Upload widget is only available when the cell has been executed in the current browser session. Please rerun this cell to enable.
In [ ]:	# csv 파일을 읽어서 DataFrame 객체로 만듦. 인덱스 컬럼은 point로 설정  df = pd.read_csv('3m.csv')  df=df[:495]  df  x=np.array(df['x1'])  x=np.vstack([x,np.array(df['x2'])])  x=np.vstack([x,np.array(df['x3']]))  x=np.vstack([x,np.array(df['x3']]))  x=np.vstack([x,np.array(df['x5']]))  y=np.array(df['y1'])  y=np.array(df['y1'])  y=np.vstack([y,np.array(df['y2']]))  y=np.vstack([y,np.array(df['y3']]))  y=np.vstack([y,np.array(df['y4']]))  y=np.vstack([y,np.array(df['y5']]))  # x  # y
In [ ]:	<pre>for i, arr in enumerate(x) :     if i == 0 :         arr = arr[10:300]         xt = np.array(arr)     else :         arr = arr[10:300]         xt = np.vstack([xt,arr])  for i, arr in enumerate(y) :     if i == 0 :         arr = arr[10:300]         yt = np.array(arr)     else :         arr = arr[10:300]         yt = np.vstack([yt,arr])</pre>
In []:	# Mean Square Displacement  MSD = np.zeros(495)  # # MSD[0]=0  # t=t[1:]  for tau in range (494):
	2.00 1.75 1.50 1.00 0.75 0.50 0.25 0.00 5 10 15 20 25
In [ ]:	<pre>from scipy.optimize import curve_fit  yy = np.zeros(290) for tau in range (289):     yy[tau+1] = np.average((xt[:,tau+1:]-xt[:,:-tau-1])**2+(yt[:,tau+1:]-yt[:,:-tau-1])**2)  def func(x,a,b):     return a*x+b  tt = t[10:300] MSDt = MSD[10:300] popt, pcov = curve_fit(func,tt,MSDt)</pre>
oucij.	popt array([7.39926169e-13, 4.56254096e-12])
In [ ]:	<pre>from sklearn.metrics import r2_score MSDt = MSD[10:300] r2 = r2_score(MSDt,popt[0]*tt+0.5e-11) r2</pre>
Out[]:	<pre>0.9874829648199883  perr = np.sqrt(np.diag(pcov))</pre>
Out[]:	perr array([1.57883954e-15, 1.84958427e-14])
In [ ]:	<pre>xxx = np.linspace(0,30,31) xxxx = np.linspace(0,20,21)  fig = plt.figure(1,figsize=(8,5)) plt.plot(xxx,func(xxx,popt[0],popt[1]),color='red',ms=1) plt.plot(xxxx,func(xxxx,popt[0],popt[1]),color='black',ms=1,label='fitted function') plt.plot(xxxx,func(xxxx,popt[0],popt[1]),'',ms=1,color='blue',label='error') plt.plot(xxxx,func(xxxx,popt[0],popt[1]),'',ms=1,color='blue') plt.plot(xxxx,func(xxxx,popt[0],popt[1]),'',ms=1,color='blue') plt.plot(xxxx,func(xxxx,popt[0],popt[1]),'',ms=1,color='blue') plt.xilno(.5, 20) plt.xilno(.5, 20) plt.xilno(.5, 20) plt.xilno(.5, 20) plt.text(15,0.1e-11,f'\$R^2\$=(r2:.4f)',fontsize=15) plt.ext(15,0.1e-11,f'\$R^2\$=(r2:.4f)',fontsize=15) plt.xilno(!Time(s)',fontsize=15) plt.xilno(!Time(s)',fontsize=15)</pre>
	$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$
In []: Out[]:	plt.plot(df['x1'],df['y1'],df['y2'],df['y3'],df['y3'],df['y4'],df['y4'],df['y5'])  [ <matplotlib.lines.line2d 0x7f405a2243d0="" at="">,</matplotlib.lines.line2d>
In [ ]:	<pre>m = popt[0] m</pre>
Out[]:	7.399261694829944e-13  err = perr[0]
	err = perr[0] err 1.5788395405908946e-15