import import	numpy <b>as</b> np matplotlib.pyplot <b>as</b> plt pandas <b>as</b> pd <b>tlib</b> inline
from go	ogle.colab import files d=files.upload()
Saving 1	Upload widget is only available when the cell has been executed in the current browser session. Please rerun this cell to enable.  1.06.csv to 1.06 (1).csv  대일을 읽어서 DataFrame 객체로 만듦. 인덱스 컬럼은 point로 설정 1.read_csv('1.06.csv') 228]
#v : v=np.ar	<pre>ray(dg['t'])  ray(dg['v1']) tack([v,np.array(dg['v2'])])</pre>
v=np.vs v=np.vs v=np.vs v=np.vs v=np.vs v=np.vs	<pre>tack([v,np.array(dg['v3'])]) tack([v,np.array(dg['v4'])]) tack([v,np.array(dg['v5'])]) tack([v,np.array(dg['v6'])]) tack([v,np.array(dg['v7'])]) tack([v,np.array(dg['v7'])])</pre>
v=np.vs	<pre>tack([v,np.array(dg['v9'])]) tack([v,np.array(dg['v10'])])  correlation, (averaged over all trajectory) r = np.zeros(228)</pre>
autocor	r[0] = np.average(v*v)  n range (227): ocorr[i+1] = np.average(v[:,i+1:]*v[:,:-i-1])
plt.plc #plt.yl	lt.figure(1,figsize=(8,5)) t(t, autocorr,color='black') im([-1e-10, 2e-10]) # Y축의 범위: [ymin, ymax] xis([0, 5, 0, 20]) # X, Y축의 범위: [xmin, xmax, ymin, ymax]
#plt.xl plt.leg plt.xti plt.yti plt.xla	<pre>im(0.5, 25)  rend(fontsize=15)  cks(fontsize=15)  cks(fontsize=15)  bel('Time(s)', fontsize=15)  bel('Auto Covariance (\$s \cdot m^2\$)', fontsize=15)</pre>
plt.sav plt.sho # this	efig('auto_covar_1.06.png') w() shows delta_correlation  es with labels found to put in legend.
2	
Auto Covariance $(s \cdot m^2)$	N. M. A.
-1 -	0 2 4 6 8 10 12 14
	Time(s)  파일을 읽어서 DataFrame 객체로 만듦. 인덱스 컬럼은 point로 설정
df x=np.ar x=np.vs x=np.vs x=np.vs	<pre>ray(df['x1']) tack([x,np.array(df['x2'])]) tack([x,np.array(df['x3'])]) tack([x,np.array(df['x4'])]) tack([x,np.array(df['x5'])])</pre>
y=np.vs y=np.vs y=np.vs y=np.vs	<pre>ray(df['y1']) tack([y,np.array(df['y2'])]) tack([y,np.array(df['y3'])]) tack([y,np.array(df['y4'])]) tack([y,np.array(df['y5'])])</pre>
# Y  p = 10 q = 171	
<pre>if i     arr     xt else</pre>	<pre>rr in enumerate(x): == 0: = arr[p:q] = np.array(arr)</pre>
for i, a	<pre>= np.vstack([xt,arr])  rr in enumerate(y) : == 0 : = arr[p:q]</pre>
yt <b>else</b> arr	<pre>= np.array(arr)</pre>
	p:q]
MSD = r # # MSL <b>for</b> tau	<pre>in range (num-1):</pre>
plt.plc plt.xli plt.leg plt.xti plt.yti	<pre>[tau+1] = np.average((x[:,tau+1:]-x[:,:-tau-1])**2+(y[:,tau+1:]-x[:,:-tau-1])**2) t(tt,MSD,'o-',label='experimental ') m(0.5, 25) rend(fontsize=15) cks(fontsize=15) cks(fontsize=15)</pre>
opt.shc <function -="" 7="" le-10<="" td=""><td>on matplotlib.pyplot.show&gt;    The experimental   Th</td></function>	on matplotlib.pyplot.show>    The experimental   Th
6 - 5 - 4 - 3 -	
2:	
t[50]	5 10 15 20 25
from so yy = nr for tau	<pre>cipy.optimize import curve_fit c.zeros(num) c.in range (num-1):</pre>
def fur retur	tau+1] = np.average((xt[:,tau+1:]-xt[:,:-tau-1])**2+(yt[:,tau+1:]-yt[:,:-tau-1])**2) c(x,a,b,c) : n a*x**2+b*x+c
MSDt =	0 q-pp t[pp] t[pp:qq]-ttemp MSD[pp:qq]
popt	ov = curve_fit(func,ttt,MSDt)  3.04654455e-12, 2.30174261e-12, 1.71931160e-10])
#MSDt =	learn.metrics import r2_score  MSD  _score(MSDt,func(ttt,popt[0],popt[1],popt[2]))
	1376270724  np.sqrt (np.diag (pcov))
xxx = r	p.linspace(ttt[0],ttt[-1],90) np.linspace(0,20,21)
<pre>x2 = np fig = p plt.plc plt.plc</pre>	<pre>inp.linspace(0,20,21) i.linspace(0,15,171)  ilt.figure(1,figsize=(8,5))  it(xxx,func(xxx,popt[0],popt[1]+perr[1],popt[2]),'',color='gray',ms=1,label='error(1\$\sigma\$)')  it(xxx,func(xxx,popt[0],popt[1]-perr[1],popt[2]),color='gray',ms=1)  it(xxx,func(xxx,popt[0],popt[1],popt[2]),'',color='red',ms=1,label='Fitted Function')</pre>
plt.plc plt.xli plt.tex	<pre>t(ttt,MSDt,'o',color='green',ms=1,label='Experimental Data')  m(0.8, 6.5) t(5.0,2e-10,f'\$R^2\$={r2:.4f}',fontsize=15) end(fontsize=15)</pre>
plt.xti plt.yti plt.xla plt.yla #plt.yla	<pre>cks(fontsize=15) cks(fontsize=15) bel('Time(s)', fontsize=15) bel('\$ \langle r^2 \\rangle \$ (m\$^2\$)', fontsize=15) im(1.25e-10,1.8e-10) refig('MSDfitted_1.06.png')</pre>
plt.shc	$v_{0}$ $v_{0}$ $v_{0}$ $v_{0}$ $v_{0}$ $v_{0}$
4.5 - 4.0 - 3.5 -	Fitted Function  • Experimental Data
2.5	$R^2 = 0.9999$
2.0	1 2 3 4 5 6 Time(s)
[ <matple <matple <matple< td=""><td>t(df['x1'],df['y1'],df['x2'],df['y2'],df['x3'],df['y3'], df['x4'],df['y4'], df['x5'],df['y5'])  tlib.lines.Line2D at 0x7f25c05cecd0&gt;, tlib.lines.Line2D at 0x7f25c05ced90&gt;, ttlib.lines.Line2D at 0x7f25c06ocad0&gt;, ttlib.lines.Line2D at 0x7f25c06ocad0&gt;,</td></matple<></matple </matple 	t(df['x1'],df['y1'],df['x2'],df['y2'],df['x3'],df['y3'], df['x4'],df['y4'], df['x5'],df['y5'])  tlib.lines.Line2D at 0x7f25c05cecd0>, tlib.lines.Line2D at 0x7f25c05ced90>, ttlib.lines.Line2D at 0x7f25c06ocad0>, ttlib.lines.Line2D at 0x7f25c06ocad0>,
0.25 - 0.00 -	otlib.lines.Line2D at 0x7f25c05c4710>, otlib.lines.Line2D at 0x7f25c05c49d0>]  5
-0.25 - -0.50 - -0.75 -	And the state of t
-1.00 - -1.25 - -1.50 -	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$
$m = pop_{m}$	
err = p	err[1]
3.335263	.9433308965e-13