# Matroids in Lean: Status Update

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8 January 2025

## Totally Unimodular Matrices

#### In Mathlib:

- Definition of TU matrices
- ► TUness is preserved under:
  - transposition
  - taking of submatrices, incl. adjoining parallel rows/columns
  - adjoining zero rows/columns
  - unit rows/columns

#### In repo:

Finite block-diagonal matrix with TU blocks is TU

#### Next up:

- TUness is preserved under pivoting
- Generalize to infinite matrices

### Matroid API

#### Additions:

- ► Notions: circuit, loop, coloop, separator
- Constructors: circuit matroid, vector matroid
- ► Classes: representable matroids, graphic and cographic matroids

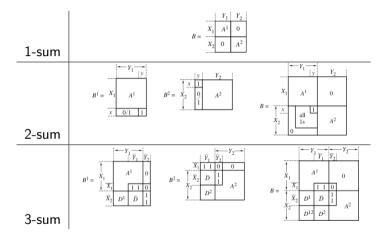
### Changes:

- ▶ Binary matroid definition now uses vector matroid
- ▶ Different, more general approach to 1-, 2-, and 3-sums\*

### Next up:

Fill in blanks: sorry's and missing useful lemmas

## Old Approach to k-Sums



[Truemper 1998]; binary matroids  $M_1$ ,  $M_2$ ,  $M_1 \oplus_k M_2$  have standard matrix representation  $B_1$ ,  $B_2$ ,  $B_3$ 

### New Approach: 1-Sum

- $lackbox{ [Oxley 2011]: } M_1 \oplus_1 M_2 \text{ for general matroids } M_1 = (E_1, \mathcal{I}_1), \ M_2 = (E_2, \mathcal{I}_2)$
- ▶ Assumption:  $E_1 \cap E_2 = \emptyset$
- ▶ Ground set:  $E_1 \cup E_2$
- ▶ Independent sets:  $\{I_1 \cup I_2 \mid I_1 \in \mathcal{I}_1, I_2 \in \mathcal{I}_2\}$
- ► In MathLib: Matroid.disjointSum

### New Approach: 2-Sum

- $lackbox{ [Oxley 2011]: } M_1 \oplus_2 M_2 \text{ for general matroids } M_1 = (E_1, \mathcal{I}_1), M_2 = (E_2, \mathcal{I}_2)$
- ► Assumptions:
  - $|E_1|, |E_2| \ge 2$
  - ►  $E_1 \cap E_2 = \{p\}$
  - ightharpoonup p is not a loop or a coloop in  $M_1$  or  $M_2$
- ▶ Ground set:  $E_1 \cup E_2 \setminus \{p\}$
- Circuits:

$$\mathcal{C}\left(M_{1}\backslash\left\{p\right\}\right)\cup\mathcal{C}\left(M_{2}\backslash\left\{p\right\}\right)\cup\left\{C_{2}\cup\left.C_{2}\backslash\left\{p\right\}\mid p\in\mathcal{C}_{1}\in\mathcal{C}\left(M_{1}\right),\ p\in\mathcal{C}_{2}\in\mathcal{C}\left(M_{2}\right)\right\}$$

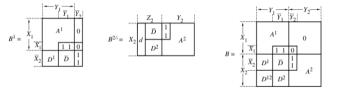
In repo: Matroid.TwoSum

### New Approach: 3-Sum

- $lackbox{ [Oxley 2011]: } M_1 \oplus_3 M_2 \text{ is for binary matroids } M_1 = (E_1, \mathcal{I}_1), M_2 = (E_2, \mathcal{I}_2)$
- Assumptions:
  - $|E_1|, |E_2| \ge 7$
  - $ightharpoonup E_1 \cap E_2 = T$ , T is a triangle in  $M_1$  and  $M_2$
  - Neither  $M_1$  nor  $M_2$  has cocircuit contained in T
- ▶ Ground set:  $E = E_1 \Delta E_2$
- ▶ Circuits:  $C(M_1 \setminus T) \cup C(M_2 \setminus T) \cup C_{\Delta}$  where  $C_{\Delta}$  = minimal sets of form  $C_1 \Delta C_2$  where  $C_i$  is a circuit of  $M_i$ ,  $C_1 \cap T = C_2 \cap T$ , and  $C_i \cap T$  has exactly one element
- ▶ Note: 1-sum and 2-sum are special cases
- In repo: BinaryMatroid.DeltaSum

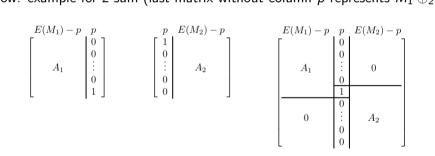
### Note on New 3-Sum

- $\triangleright$  3-sum in [Oxley] corresponds to  $\triangle$ -sum in [Truemper]
- ▶ Regularity results and decomposition theorem hold for both



## New Approach: Regularity of k-Sum

- Matroid is regular iff it can be represented over any field
- ▶ If  $M_1$  and  $M_2$  are regular, they can be represented over any field
- lacktriangle After wlog conversion, can connect representations of  $M_1$  and  $M_2$  with  $M_1\oplus_k M_2$
- ▶ Thus  $M_1 \oplus_k M_2$  can be represented over any field, hence is regular
- ▶ Below: example for 2-sum (last matrix without column p represents  $M_1 \oplus_2 M_2$ )



### Next Steps

#### For old approach:

- ► TUness is preserved under pivoting
- ► TUness of explicit matrix representations of 2-sum and 3-sum

#### For new approach:

- Characterization of regular matroids
- ▶ Matrix representations for 2-sum and 3-sum

#### Nice to have:

- Updated statement of hard direction of Seymour's theorem
  - Prove up to Kuratowsky's theorem?
- ► TUness properties for infinite matrices
- Circuit matroid construction for infinite case