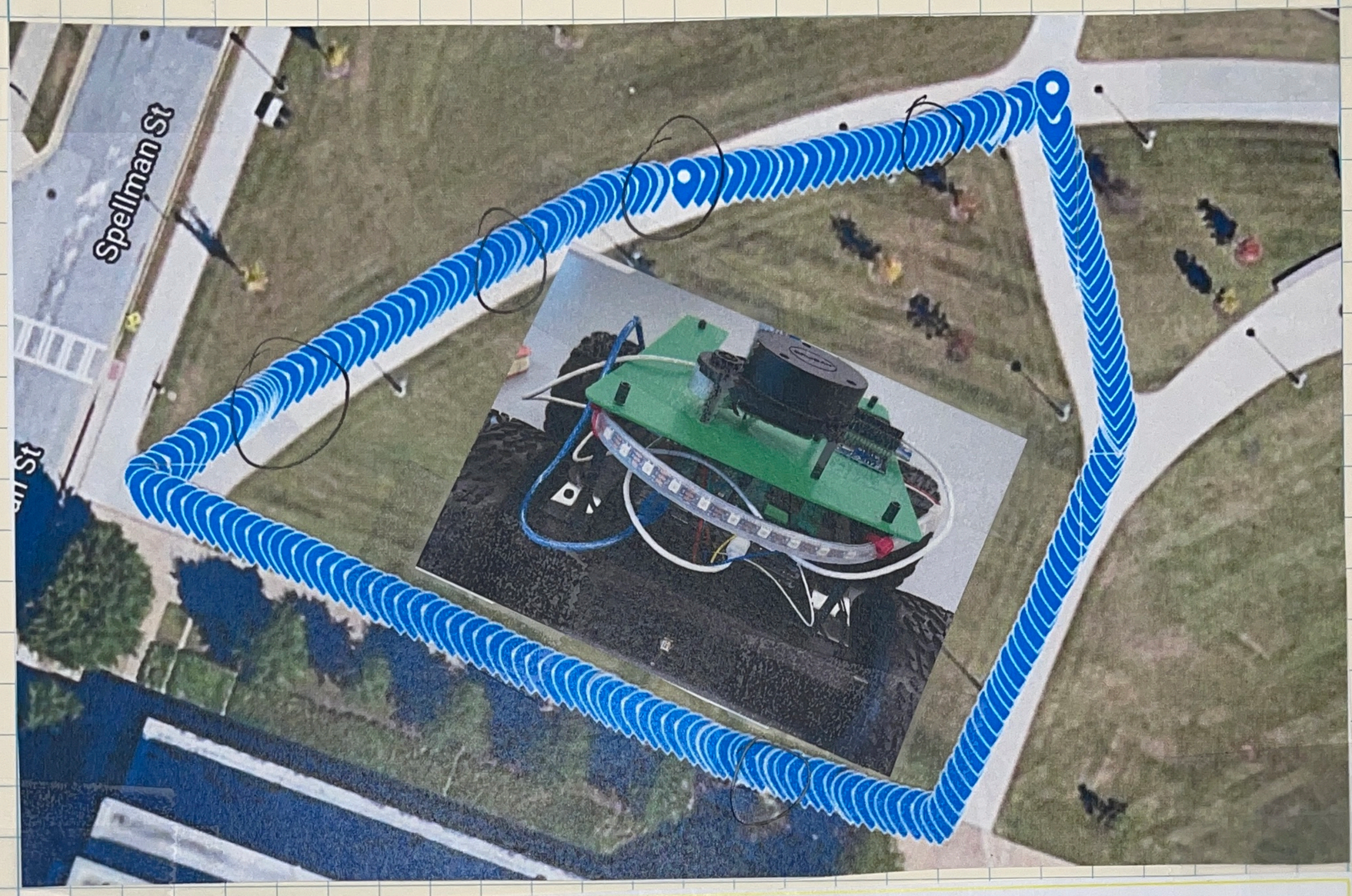
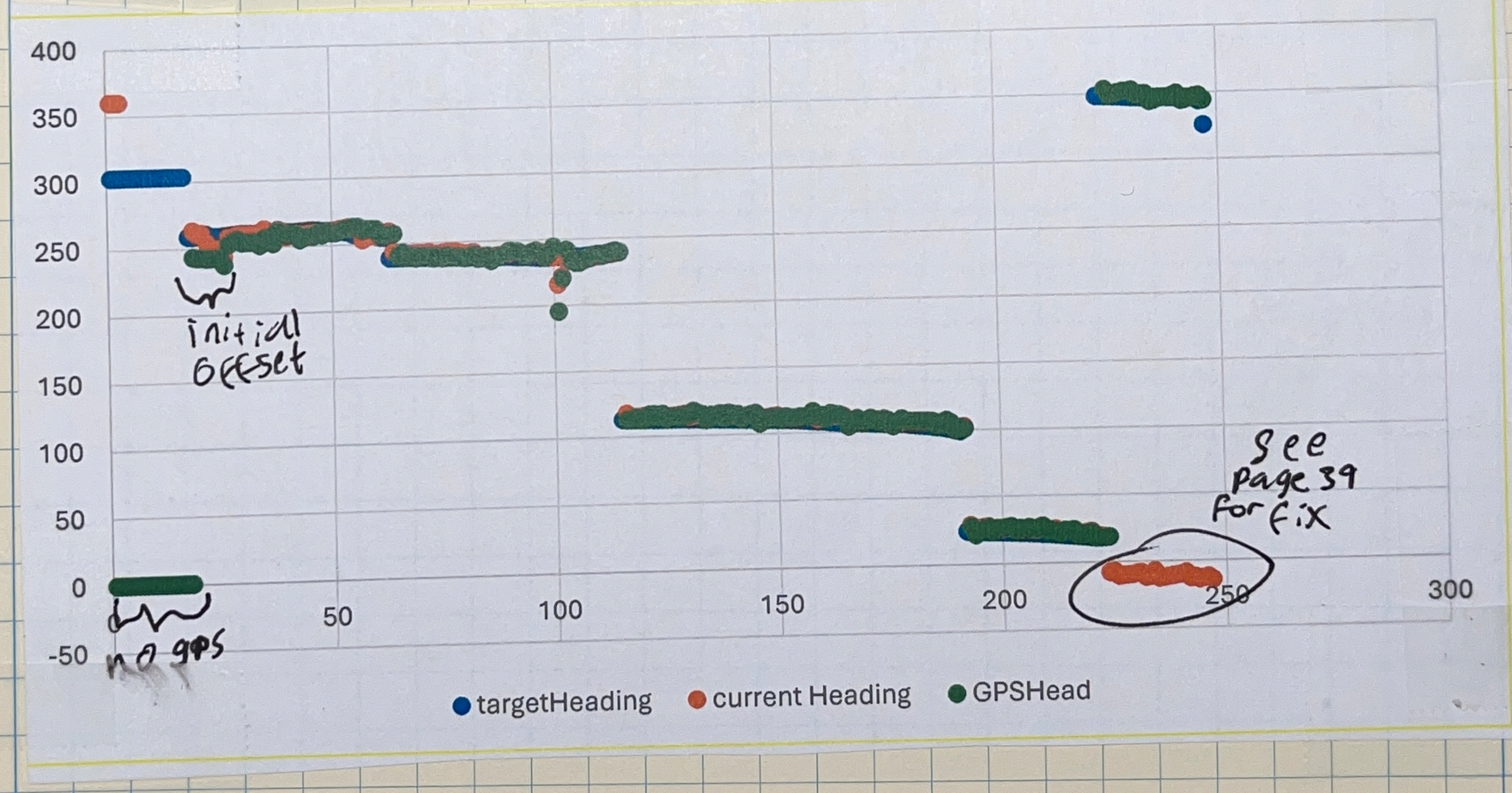
05/31/24
Wednesday
cecki

# Land Testing With Lidar






I sent a signal from the mega running the Lidar to the giga when a red LED would turn on. The giga would respond by turning the motors off.

I circled places where we intentionally stood in front of the robot to cause it to stop. Everything worked as expected!