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Integrating the New BNO and GPS Code

The robot was about a meter off of these waypoints. Mostly in the grass.

More testing would help. Sometimes we get 0 in the data.

```
130  if (millis() - pollingStartTime > 1000)
131  {
132    myGPSData = readNavPVT();
133    pollingStartTime = millis();
134
135    // Set the "current" position to point 1 in the GPS pair.
136    myGPSPair.lat1_L = myGPSData.lat;
137    myGPSPair.lon1_L = myGPSData.lon;
138
139    // Get the information we need to control the robot
140    distanceBetween = myHeadingControl.GetDistanceBetween(myGPSPair);
141    targetHeading   = myHeadingControl.GetTargetHeading(myGPSPair);
142    currentHeading  = getHeading2() - averageGPSError;
143    currentHeading  = fixHeading(currentHeading);
144    headingError    = myHeadingControl.GetHeadingError(currentHeading, targetHeading);
145    gpsError        = currentHeading - (myGPSData.heading / 100000.0);  // could flip
146
```

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