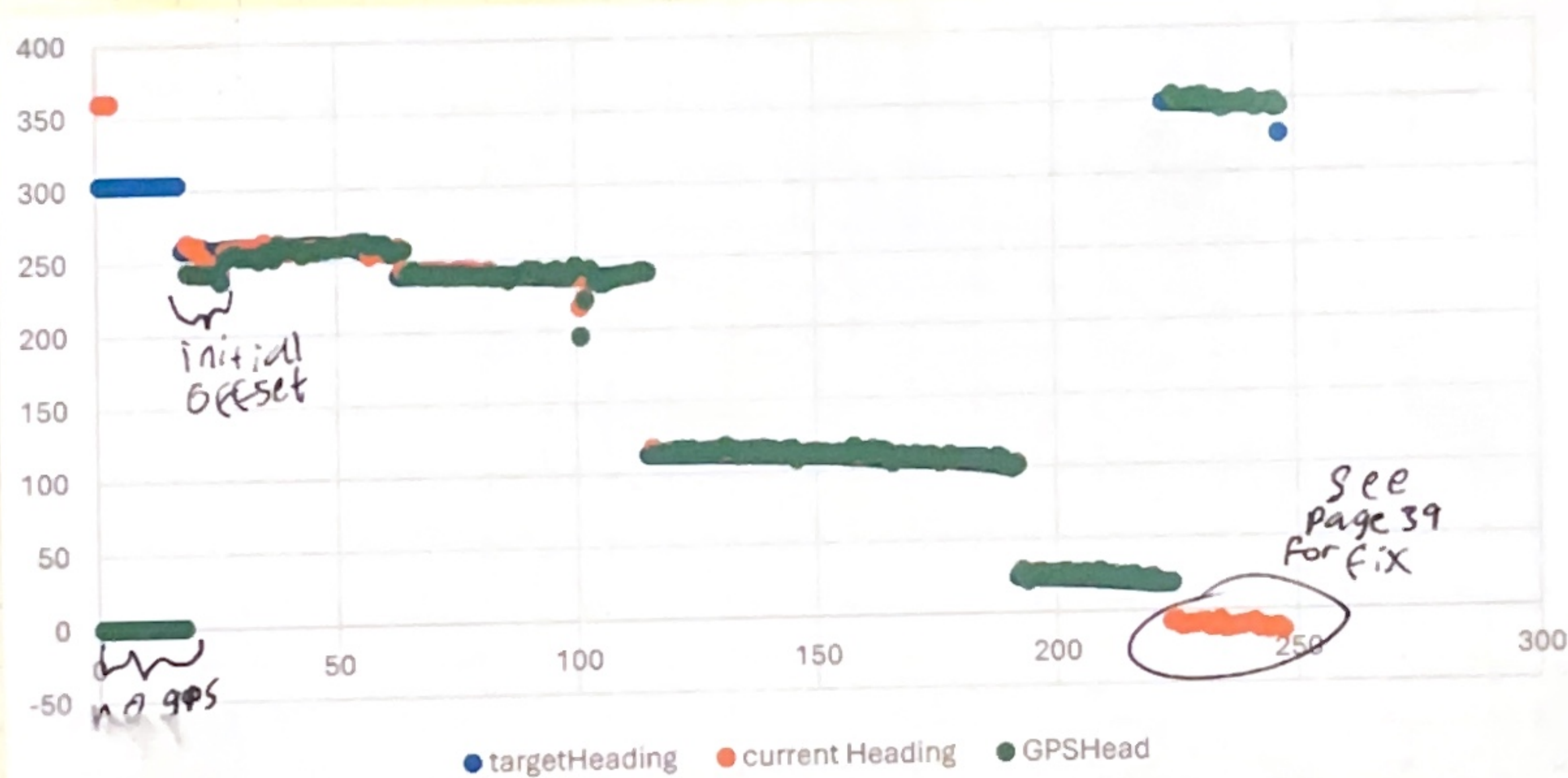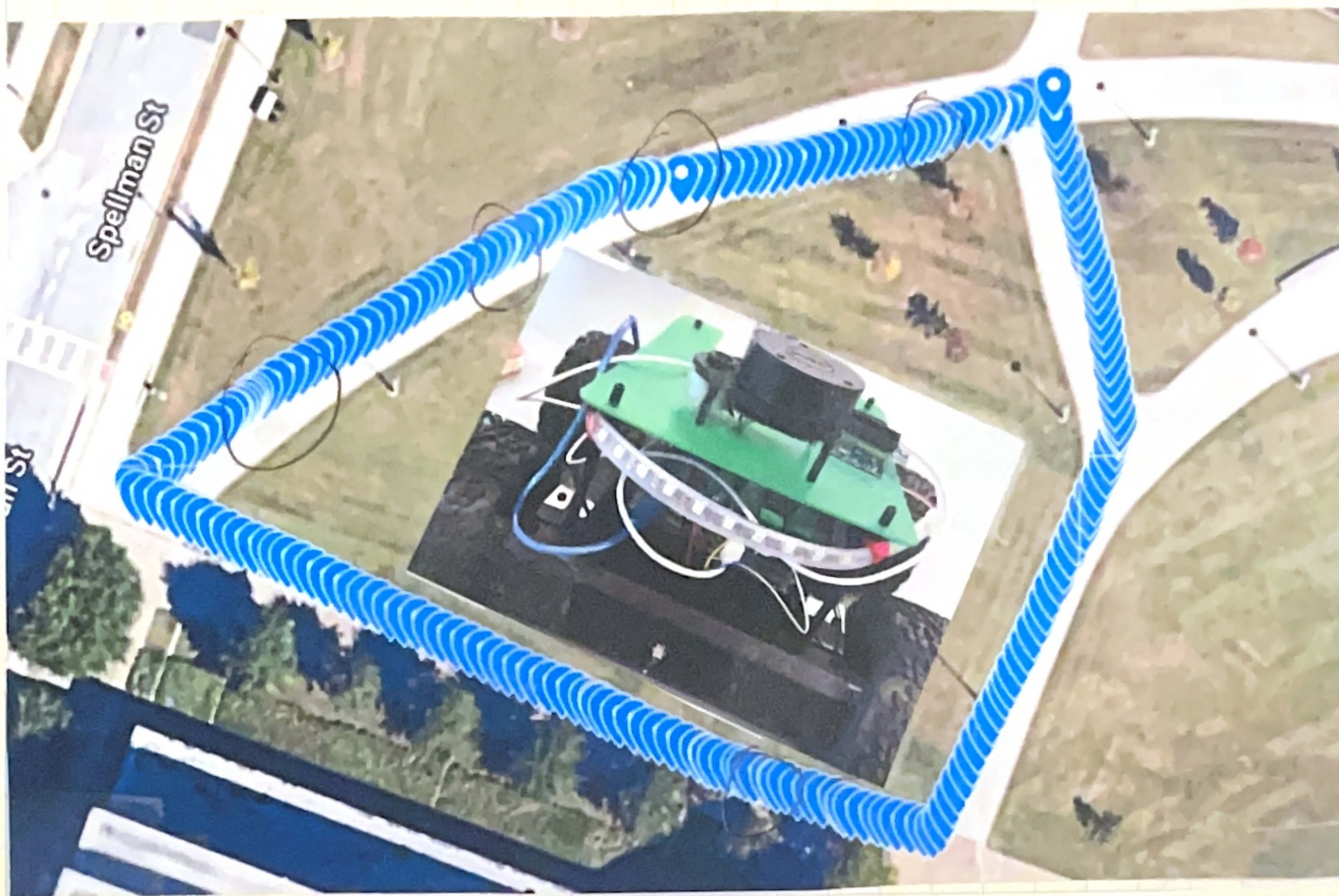Wavers creek





Page 39 for fix

I attached the Lidar system to WIL.
Watching the LED's, the lidar saw mostly nothing
but if I got close enough some LED's would
turn on.

Examing the GPS Data shows that our actual
traveled path was very different than what the
GPS saw. I've marked the actual path in Pen.

Wesley Cecil





initial offset

no gps

See page 39 for fix

• targetHeading  • current Heading  • GPSHead

I sent a signal from the mega running the lidar to the giga when a red LED would turn on. The giga would respond by turning the motors off.

I circled places where we intentionally stood in front of the robot to cause it to stop. Everything worked as expected!