1 First assembly program

```
section .data

section .text

global _start

_start:

MOV eax, 1

MOV ebx, 1

INT 80h
```

View the program here.

Breaking down the program:

- ullet .data o This section is used for declaring and initializing variables.
- .section \rightarrow This section contains the actual code of the program.
- $_$ start \rightarrow This is the entry point of the program.
- MOV eax, $1 \rightarrow$ Moves the immediate value 1 to the register eax.
- MOV ebx, $1 \rightarrow$ Moves the immediate value 1 to the register ebx.
- INT 80h \rightarrow An interrupt with the value 80h(h stands for hexadecimal).
- \bullet In x86 architecture, interrupt $0x80 ({\rm or}~80h$ is commonly used for making system calls in Linux.
 - The value 1 in **eax** corresponds to the **sys_exit** system call in Linux.
 - The value 1 in **ebx** is interpreted as the exit status code.
- \bullet INT 80h triggers an interrupt which transfers the control to the Linux kernel to execute the system call.

Simple explanation

This program is going to trigger an interrupt which will transfer the control to the kernel which will perform an action based on the value that is put into **eax**(in this case it's 1). So, basically **eax** tells the operating system what we want to do when the interrupt 80 is caught. So, in this case, we want the operating system to run the exit system call when the interrupt is caught. The exit system call will end the program and will set an exit status code. The status code is going to be whatever value we put into **ebx**(in this case, the status code will be 1).

So, in summary, register **eax** is telling us what system call we want to do. Register **ebx** tells what we want to output as our status code. **INT 80h** triggers an interrupt which tells the operating system to exit the program using **eax** set to 1.

There are some system calls mentioned along with their numbers here.

2 Compiling the assembly program

```
$ nasm -f elf -o asm1.o asm1.asm
```

Basically we are compiling our assembly program to an object file using the file format $\it elf.$

Next, we use the GNU linker to link the object file and create an executable:

```
$ ld -m elf_i386 -o asm1 asm1.o
```

• -m elf_i386 \rightarrow Indicates the target architecture. Here it is set to elf_i386 which means the x86 architecture(32-bit).

After linking the object file, we have our executable file which is asm1.

```
priyanuj@grafter:~/Desktop/NASM/programs$ ls
asm1 asm1.asm asm1.o
```

Figure 1: The executable asm1

We can run this executable:

\$./asm1

Since we set an exit status code in **ebx**, after running this executable, we can view that exit status code. In Linux, the \$? stores the exit status code of any command.

```
priyanuj@grafter:~/Desktop/NASM/programs$ ./asm1
priyanuj@grafter:~/Desktop/NASM/programs$ echo $?
1
```

Figure 2: The exit status code in \$?

3 Using GDB with our executable

First, we will open GDB with our executable:

```
$ gdb ./asm1
```

3.1 Opening the assembly layout in GDB

```
(gdb) layout asm
```

This opens the assembly layout where we can view the assembly code of our currently executing function.



Figure 3: layout asm

3.2 Setting breakpoints

Now, we will set a break point at _start label.

```
(gdb) break _start
```

Next, we will run the program:

```
(gdb) r
```

Figure 4: Break points set

Execution stopped at the _start label.

3.3 Executing one instruction at a time

Now, we will use the **stepi** command of GDB to execute each instruction, one at a time.

(gdb) stepi

```
B+ 0x8049000 <_start> mov $0x1, %eax  
> 0x8049005 <_start+5> mov $0x1, %ebx  
0x804900c add %al, (%eax)  
0x804900c add %al, (%eax)  
0x804900c add %al, (%eax)  
0x8049010 add %al, (%eax)  
0x8049012 add %al, (%eax)  
0x8049014 add %al, (%eax)  
0x8049016 add %al, (%eax)  
0x8049018 add %al, (%eax)  
0x804901a add %al, (%eax)  
0x804901c add %al, (%eax)  
0x8049020 add %al, (%eax)  
0x8049020 add %al, (%eax)  
0x8049020 add %al, (%eax)  
0x8049021 add %al, (%eax)  
0x8049022 add %al, (%eax)  
0x8049024 add %al, (%eax)  
0x8049025 add %al, (%eax)  
0x8049026 add %al, (%eax)  
0x8049028 add %al, (%eax)  
0x80490
```

Figure 5: Executing one instruction at a time

3.4 Viewing the value stored in a register

The instruction **MOV eax**, 1 got executed and execution stopped at the instruction after it. To prove that 1 indeed got stored into **eax**, we will use the following command:

```
(gdb) info registers eax
```

This gives us the following output:

Figure 6: Checking if eax actually stores 1 or not

So, **eax** stores the value 1.

We can also see what is stored in the **ebx** register.

For that, we use the same command:

```
(gdb) info registers ebx
```

```
(gdb) info registers ebx
ebx 0x0 0
(gdb)
```

Figure 7: Checking the value of the **ebx** register

Now, we again use the **stepi** command to execute the instruction **MOV ebx**, **1** and then run the **info registers** command again:

```
(gdb) stepi
0x0804900a in _start ()
(gdb) info registers ebx
ebx _ 0x1 1
```

Figure 8: Updated value of ebx

4 stepi command

This command is used to execute a single machine instruction and then stop, allowing the user to step through a program at the assembly instruction level.

This command is a part of GDB's low-level debugging features.

It's useful for understanding the execution flow of a program at the machine code level.