

To preprocess we use a slightly modified version of usual DFS, we want in fact for each node to take care of in-time, out-time and level

First of all we initialize a variable `tree_time` to zero, and `root.level` to zero as well.

What we have so far:

```
levels = {} //dictionary to map each level of the tree into the array of nodes at that level.
```

```
levels[0] = [root]
```

```
tree_time = 0
```

```
DFS(u):
```

```
    tree_time += 1
    u.in_time = tree_time
```

```
    for v in Adj[u]
```

```
        v.level = u.level + 1
        DFS(v)
```

```
    tree_time += 1
    u.out_time = tree_time
```

```
    if u.level not in levels
        levels[u.level] = []
    levels[u.level].append(u)
```

So the actual preprocess will be

```
preprocess(tree):
```

```
    DFS(tree)
```

```
    for level in levels
        levels[level].sort
```

```
find_kth_ancestor(a,k):
```

target_level = u.level - k

if target_level < 0
return none

binary search in levels[target_level] for the node with greatest in_time smaller than a.in_time

OBS_1

Binary search will take $O(\log(n))$, since we sorted levels[target_level] while preprocessing.

OBS_2

Why is this correct? First of all, ancestors in_time cannot be larger than current node in_time.

Secondly, let a be the current node, suppose the ancestor of a at target_level (let's call it u) has not the greatest in_time within the nodes at target_level with in_time smaller than a.in_time.

That would mean that there exists a sibling of u visited after u itself, but before a: this is impossible, because DFS wouldn't visit u's siblings until all of u's children were visited.

