



## Design Assignment 5

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CPE 301 Fall 2016

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## PART 0

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The assignment took me about 3 hours to do. I had to read the datasheet of the LCD and debug a few times.

### 1. PART A: Description

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My design consists of a C program that receives a pin number from a Keypad and outputs a string to the user using the LCD depending on pin entered. The keypad being used is a 4x4 keypad with 8 ports, 4 which are inputs and 4 outputs to be read from the avr. The code determines the pin being pressed, whenever a column read in is low, this character is then stored into a buffer; a message will be displayed until 3 digits are received. At this point a buffer holding the digits will be read and will determine if the system to be unlocked or locked. If locked the user will be asked to enter the pin again, if unlocked the user will receive a message saying "Access Granted".

### PART B: Code

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#### LCD & KEYPAD:

##### lcd.h

```
/*
 * lcd.h
 */

#ifndef LDC_H
#define LDC_H

#define F_CPU 16000000L
#include <avr/io.h>
#include <util/delay.h>

// Connect LCD data pins to PORTB and control pins to PORTC
// RS = PC.0
// RW = PC.1
// EN = PC.2
#define LCD_CPRT PORTC //LCD COMMANDS PORT
#define LCD_CDDR DDRC //LCD COMMANDS DDR
#define LCD_CPIN PINC //LCD COMMANDS PIN
```

```

#define LCD_RS 0      //LCD RS   (PC.0)
#define LCD_RW 1      //LCD RW   (PC.1)
#define LCD_EN 2      //LCD EN   (PC.2)

/*****
//Function Declarations

/*
 * Send a command to the LCD, make pin RS = 1 and R/W = 0;
 * Send a H-to-L pulse to the E pin to enable the internal
 * latch. Place command in command Reg (output AVR: PortB.0...7)
 */
void lcdCommand (unsigned char cmd){
    sendData(cmd);                //send cmd to data port
    LCD_CPRT &= ~(1<<LCD_RS);    //RS = 0 for command
    LCD_CPRT &= ~(1<<LCD_RW);    //RW = 0 for write
    LCD_CPRT |= (1<<LCD_EN);     //EN = 1 for H-to-L pulse
    _delay_us(1);                //wait to make enable wide
    LCD_CPRT &= ~(1<<LCD_EN);    //EN = 0 for H-to-L pulse
    _delay_us(100);              //wait to make enable wide
}

/*
 * Send data to the LCD, make pin RS = 0 and R/W = 0;
 * Send a H-to-L pulse to the E pin to enable the internal
 * latch. Place data in Data Reg (output AVR: PortB.0...7)
 */
void lcdData(unsigned char data){
    sendData(data);                //send data to data port
    LCD_CPRT |= (1<<LCD_RS);      //RS = 1 for data
    LCD_CPRT &= ~(1<<LCD_RW);    //RW = 0 for write
    LCD_CPRT |= (1<<LCD_EN);     //EN = 1 for H-to-L pulse
    _delay_us(1);                //wait to make enable wide
    LCD_CPRT &= ~(1<<LCD_EN);    //EN = 0 for H-to-L pulse
    _delay_us(100);              //wait to make enable wide
}

/*
 * Initiate the LCD
 */
void lcd_init()
{
    DDRB = 0xFF;
    LCD_CDDR = 0xFF;
    LCD_CPRT &= ~(1<<LCD_EN);    //LCD_EN = 0
    _delay_us(2000);
    //wait for init
    lcdCommand(0x38);            //initialize LCD 2 line, 5x7
    lcdCommand(0x0E);            //display on, cursor on
    _delay_us(2000);              //wait
    lcdCommand(0x06);            //shift cursor right
}

/*
 * Print on to the LCD the 8-bit char value
 * lcdData is used to send the data
 */
void lcd_print(char * str){
    unsigned char i = 0;

```

```

        while (str[i]!=0) {
            lcdData(str[i]); i++;
        }
    }

    /*
     * go to specific LCD locations
     */
    void lcd_gotoxy(unsigned char x, unsigned char y){
        unsigned char firstCharAdr[] = {0x80, 0xC0, 0x94, 0xD4}; // locations of the first
        character of each line

        lcdCommand(firstCharAdr[y-1] + x-1);
        _delay_us(100);
    }

    /*
     * Clear the LCD and reset the cursor to the home position
     */
    void lcd_reset(){
        lcdCommand(0x01); //clear LCD
        lcdCommand(0x02); // return home: returns the cursor to the home position
        _delay_ms(500);
    }

    //send data using portb and portc
    void sendData(unsigned char str){

        PORTB = 0x0;
        PORTC &= ~(1<<PC4); PORTC &= ~(1<<PC5);

        if((str & 0x01) == 0)
            PORTB |= (0<<PB0);
        else
            PORTB |= (1<<PB0);

        if((str & 0x02) == 0)
            PORTB |= (0<<PB1);
        else
            PORTB |= (1<<PB1);

        if((str & 0x04) == 0)
            PORTB |= (0<<PB2);
        else
            PORTB |= (1<<PB2);

        if((str & 0x08) == 0)
            PORTB |= (0<<PB3);
        else
            PORTB |= (1<<PB3);

        if((str & 0x10) == 0)
            PORTB |= (0<<PB4);
        else
            PORTB |= (1<<PB4);

        if((str & 0x20) == 0)

```

```

        PORTB|= (0<<PB5);
    else
        PORTB|= (1<<PB5);

    if((str & 0x40) == 0)
        PORTC|= (0<<PC4);
    else
        PORTC|= (1<<PD4);

    if((str & 0x80) == 0)
        PORTC|= (0<<PC5);
    else
        PORTC|= (1<<PD5);
}

//Test the LCD Functionality
int lcd_test(){
    lcd_init();
    lcd_print("Demo code");           // print some sample code on LCD
    _delay_ms(1000);

    // clear the LCD and print some more text
    lcdCommand(0x01);    //clear LCD
    lcdCommand(0x02);    // return home: returns the cursor to the home position
    lcd_print("Here is some more text that overruns a single line...");    //
    print text that overruns a single line
    _delay_ms(1000);

    // print text at a specific location on LCD (1st line, then 2nd line)
    lcdCommand(0x01);    //clear LCD
    lcdCommand(0x02);    // return home: returns the cursor to the home position
    _delay_ms(1000);
    lcd_gotoxy(1,1);
    lcd_print("Text for line 1.");
    lcd_gotoxy(1,2);
    lcd_print("Text for line 2.");
    while(1);           //stay here forever
    return 0;
}

#endif

```

## Main

```

/*
 * DA5.c
 *
 * Created: 3/1/2017 10:19:00 PM
 * Author : Luis
 */

#include "lcd.h"
#include <avr/io.h>

```

```

//KEYPAD PINS
#define KEYPORT PORTD
#define KEYDDR DDRD
#define KEYPIN PIND

//SET OUTUPT signals

/* Had to map it out differently based on the
// the data sheet

//How it looks on the keypad interface
{
    {'1','2','3','A'},
    {'4','5','6','B'},
    {'7','8','9','C'},
    {'*','0','#','D'}
}
*/

unsigned char keypad[4][4] ={
    {'1','4','7','*'},
    {'2','5','8','0'},
    {'3','6','9','#'},
    {'A','B','C','D'}
};

int main(void)
{
    lcd_init();
    lcd_reset();
    lcd_print("Input Pin");

    unsigned char col,row = 0;
    unsigned char count = 0;
    unsigned char pin[4] = {0};

    while(1)
    {
        start:
        if(count == 0)
        {
            lcd_init();
            lcd_reset();
            lcd_print("Input Pin");
            lcd_gotoxy(1,2);
            col = row = 0;
            pin[4] = pin[3] = pin[2]= pin[1]= 0;
        }

        //Establish the Inputs and outputs
        //to the keypad
        KEYDDR = 0xF0;
        KEYPORT = 0xFF;

        /*
        * Go in at least once,

```

```
* Then PORT7...4 are set low and wait until the pad pressed  
* released.  
  
*/  
do  
{  
    KEYPORT &= 0x0F;  
    col = (KEYPIN & 0x0F);  
  
}while(col != 0x0F);  
  
/*  
 * De-bouncing  
 */  
do  
{  
    do  
    {  
        _delay_ms(20); //call delay  
        col = (KEYPIN & 0x0F); //see if any key is pressed  
    } while (col == 0x0F); //keep checking for key press  
    _delay_ms(20); //call delay for de-bounce  
    col = (KEYPIN & 0x0F); //read columns  
} while (col == 0x0F); //wait for key press  
  
while(1)  
{  
    KEYPORT = 0xEF; //ground row 0  
    _delay_ms(20);  
    col = (KEYPIN & 0x0F); //read the columns  
    if (col != 0x0F) //column detected  
    {  
        row = 0; //save row location  
        break; //exit while loop  
    }  
    KEYPORT = 0xDF; //ground row 1  
    _delay_ms(20);  
    col = (KEYPIN & 0x0F); //read the columns  
    if (col != 0x0F) //column detected  
    {  
        row = 1; //save row location  
        break; //exit while loop  
    }  
    KEYPORT = 0xBF; //ground row 2  
    _delay_ms(20);  
    col = (KEYPIN & 0x0F); //read the columns  
    if (col != 0x0F) //column detected  
    {  
        row = 2; //save row location  
        break; //exit while loop
```

```

    }

    KEYPORT = 0x7F;           //ground row 3
    _delay_ms(20);
    col = (KEYPIN & 0x0F); //read the columns
    if(col!= 0x0F)
    {
        row = 3;              //save row location
        break;                //exit while loop
    }
}

if(count >= 3)
{
    for(int i = 0; i < 3; i = i +1)
    {
        switch(i)
        {
            case 0: if(pin[i] != '5'){
                lcdData(pin);
                _delay_ms(1000);
                printError(pin);
                count = 0;
                goto start;
            }
            break;
            case 1: if(pin[i] != '2'){
                lcdData(pin);
                _delay_ms(1000);
                printError(pin);
                count = 0;
                goto start;
            }
            break;
            case 2: if(pin[i] != '7'){
                lcdData(pin);
                _delay_ms(1000);
                printError(pin);
                count = 0;
                goto start;
            }
            else
                Correct(pin);
            break;
            default: count = 0; goto start; break;
        }
    }

    count = 0;
    goto start;
}

//check column and send result to Port D
if(col == 0x0E)

```



```

        pin[count] = (keypad[row][0]);
    else if(col == 0x0D)
        pin[count] = (keypad[row][1]);
    else if(col == 0x0B)
        pin[count] = (keypad[row][2]);
    else
        pin[count] = (keypad[row][3]);

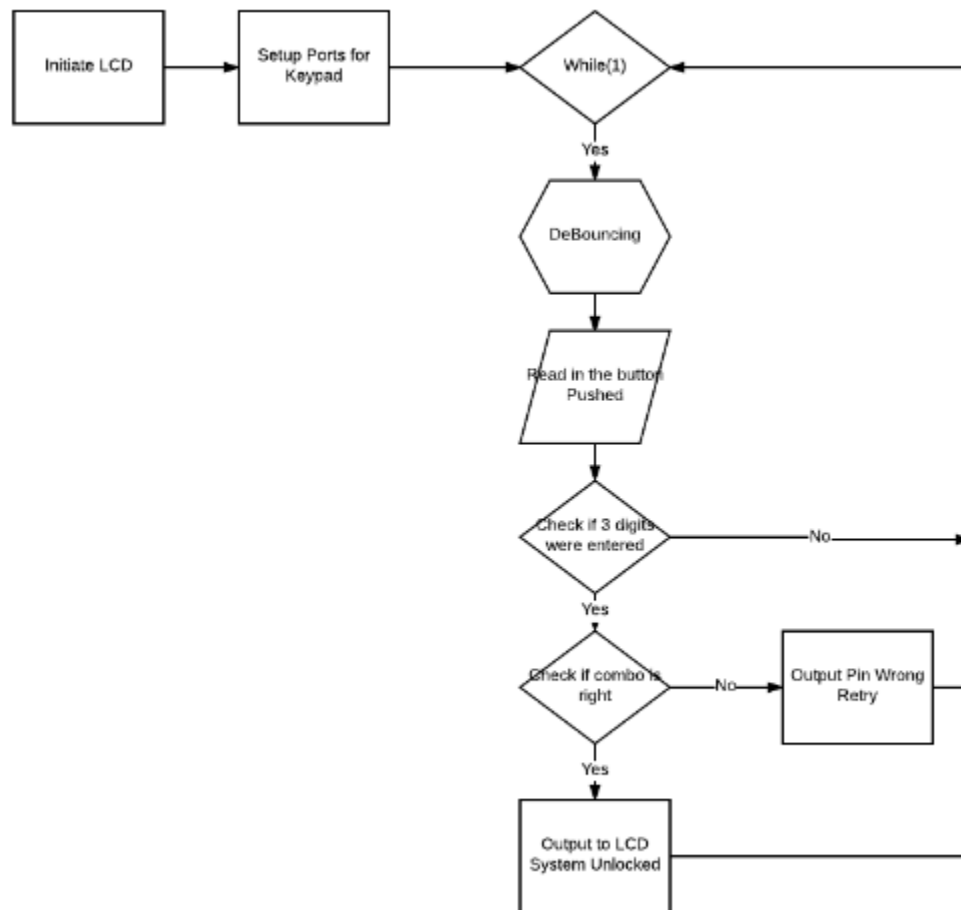
    if(count < 3)
    {
        lcdData(pin[count]);
        _delay_ms(500);
    }
    ++count;
}
return 0;
}

void printError(char *str)
{
    lcd_init();
    lcd_reset();
    lcd_print(str);
    lcd_gotoxy(1,2);
    lcd_print("Wrong Pin!!");
    _delay_ms(2500);
}

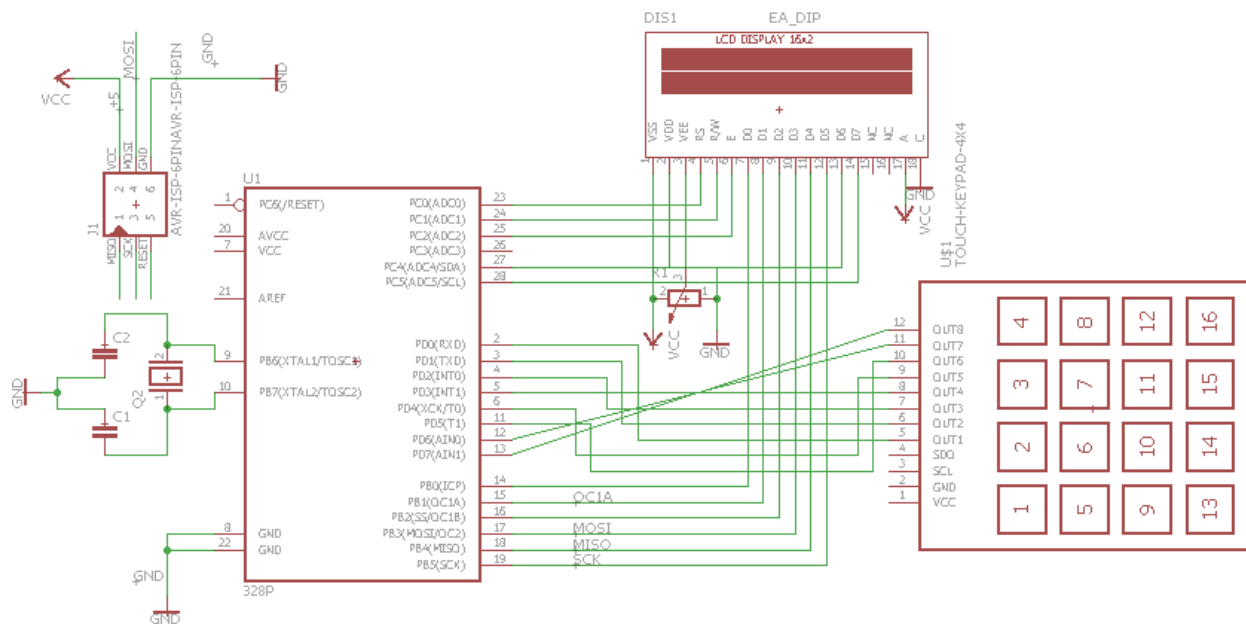
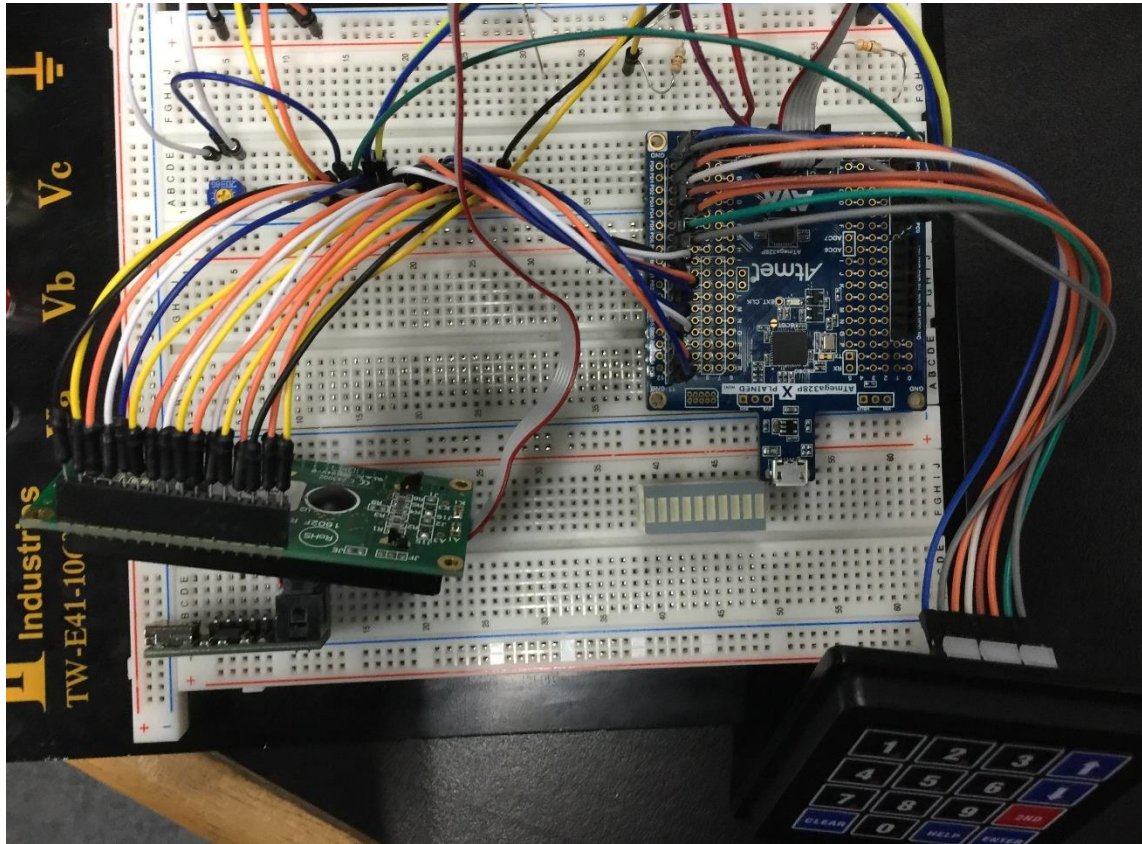
void Correct(char *str){
    lcd_init();
    lcd_reset();
    lcd_print(str);
    lcd_gotoxy(1,2);
    //“System unlocked”
    lcd_print("Access Granted!!");
    //_delay_ms(2500);
    while(1);
}

```

## PART C:Flow Chart



## PART D: Schematic



## **PART E: Video**

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URL Video of Design Assignment 5: <https://youtu.be/XtZO0H5-B0>