

Convex bilinear inversion of sparse vectors

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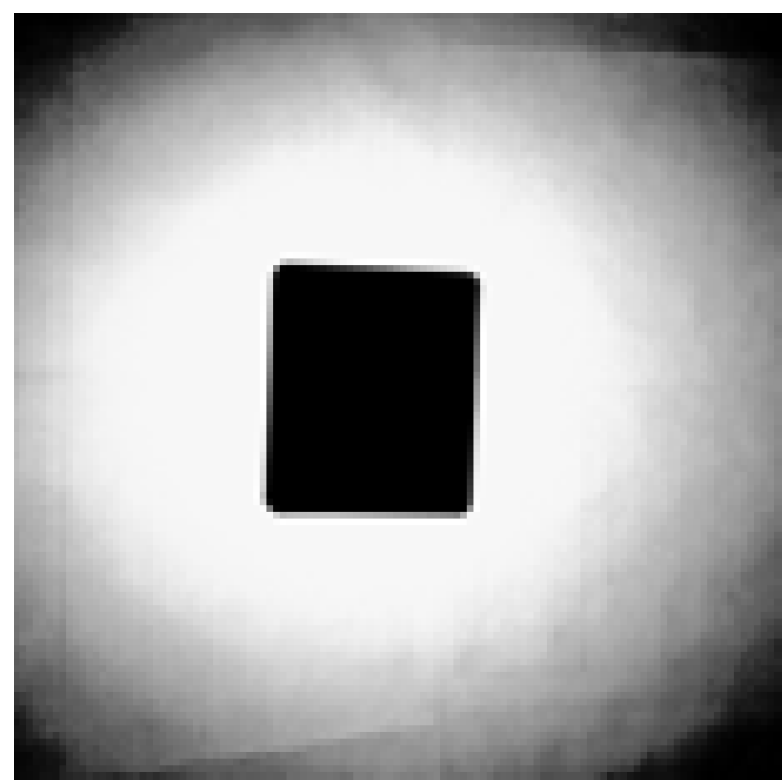
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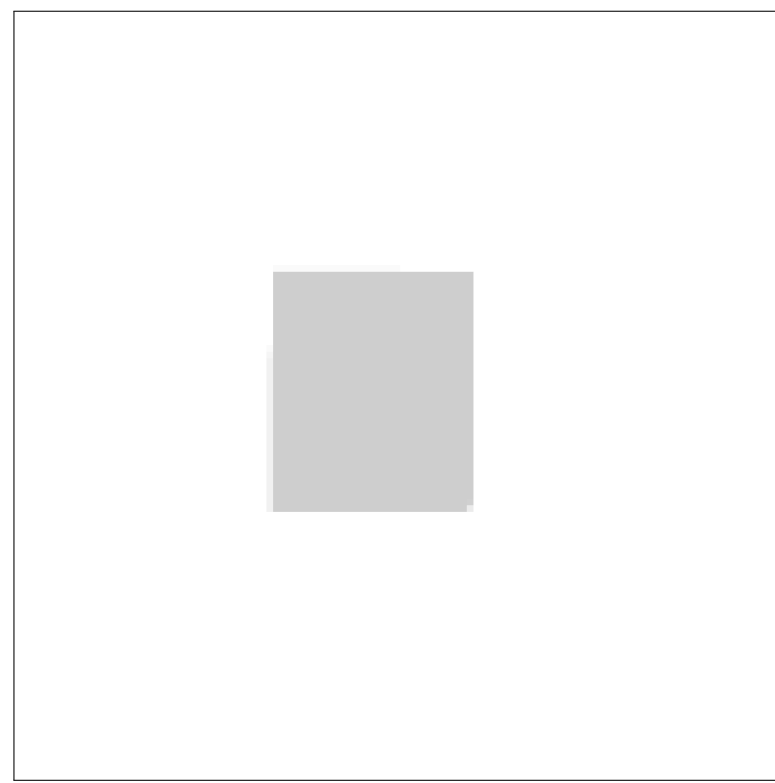
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Mousepad data



(a) Distorted image



(b) Recovered image

Panel (a) shows an image of a mousepad. The goal is to recover the piecewise constant block that correspond to the mousepad. Robust ℓ_1 -BranchHull (3) is used to recover the signal. Panel (b) shows the output of (3).

Problem Statement

The bilinear inverse problem we consider is:

Let $\mathbf{y}, \mathbf{w}^\flat, \mathbf{x}^\flat \in \mathbb{R}^L$ such that

$$\mathbf{y} = \mathbf{w}^\flat \circ \mathbf{x}^\flat. \quad (1)$$

Let $\mathbf{B} \in \mathbb{R}^{L \times K}, \mathbf{C} \in \mathbb{R}^{L \times N}$ such that

$$\begin{aligned} \mathbf{w}^\flat &= \mathbf{B}\mathbf{h}^\flat, \\ \mathbf{x}^\flat &= \mathbf{C}\mathbf{m}^\flat. \end{aligned}$$

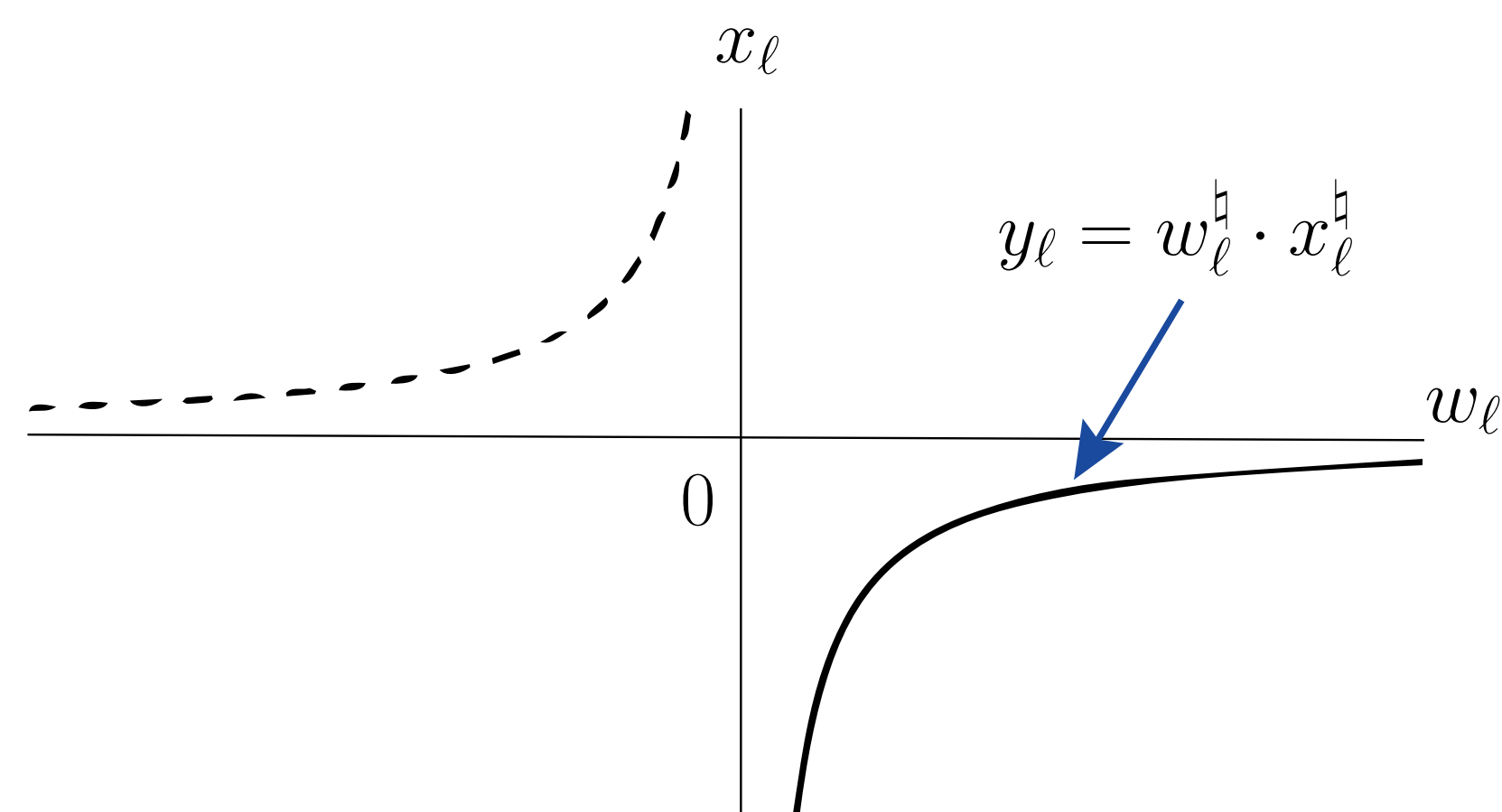
Let $\|\mathbf{h}^\flat\|_0 = S_1, \|\mathbf{m}^\flat\|_0 = S_2$.

Given $\mathbf{y}, \mathbf{B}, \mathbf{C}$ and $\mathbf{s} = \text{sign}(\mathbf{w}^\flat)$,

Find $(\mathbf{h}^\flat, \mathbf{m}^\flat)$ up to the scaling ambiguity.

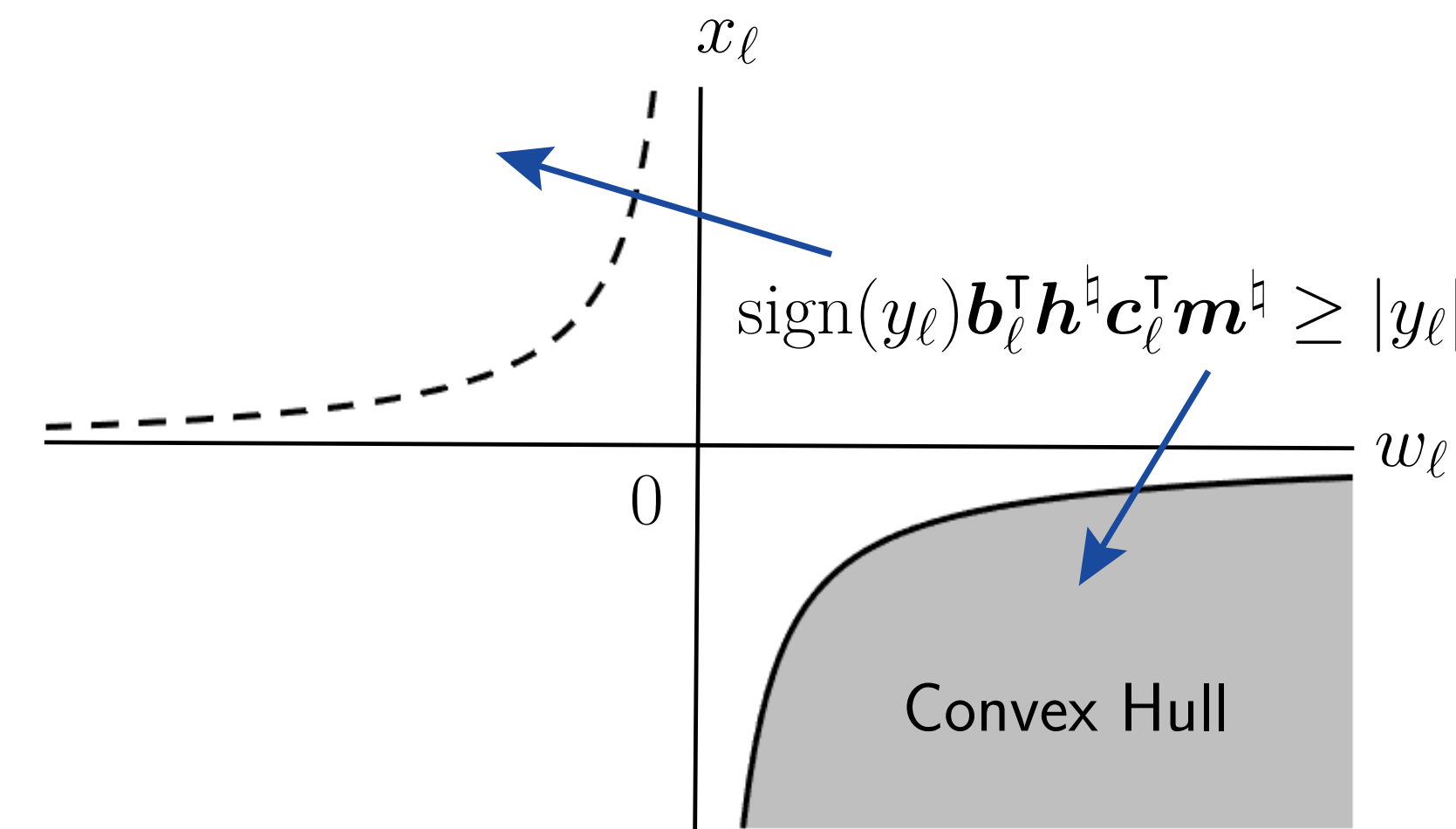
Identifiability from bilinear measurements

Let $\mathbf{y} \in \mathbb{R}^L$ be a bilinear measurement of \mathbf{w}^\flat and \mathbf{x}^\flat in \mathbb{R}^L such that $y_\ell = w_\ell^\flat \cdot x_\ell^\flat$ for $\ell \in [L]$.



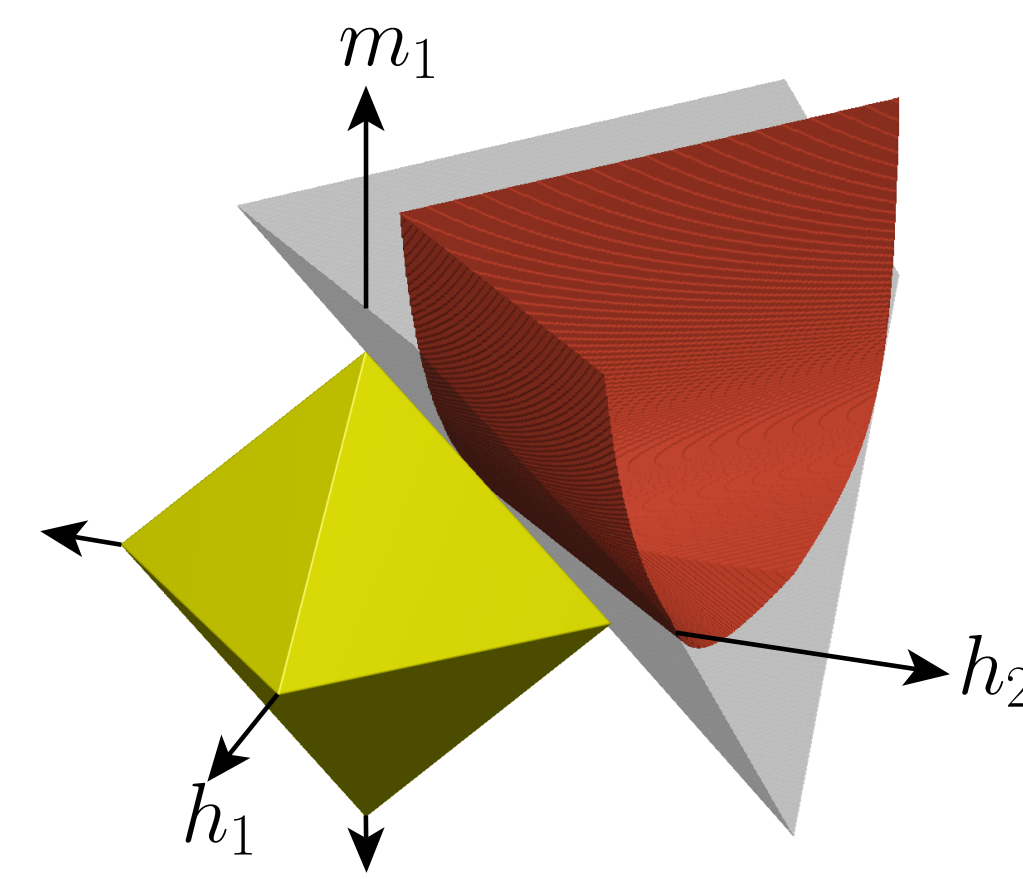
- Without additional structural assumption on \mathbf{w}^\flat and \mathbf{x}^\flat , both $(\mathbf{w}^\flat, \mathbf{x}^\flat)$ and $(\mathbf{1}, \mathbf{w}^\flat \circ \mathbf{x}^\flat)$ solves the problem. We assume \mathbf{w}^\flat and \mathbf{x}^\flat live in known subspaces.
- For any $c \neq 0$, $(c\mathbf{w}^\flat, c^{-1}\mathbf{x}^\flat)$ solves the problem

Convex program



We introduce a convex program written in the natural parameter space for the bilinear inverse problem. The convex program ℓ_1 -BranchHull (ℓ_1 -BH) program is used to recover $(\mathbf{h}^\flat, \mathbf{m}^\flat)$.

$$\begin{aligned} (\mathbf{h}^*, \mathbf{m}^*) &:= \underset{(\mathbf{h}, \mathbf{m}) \in \mathbb{R}^{K+N}}{\text{argmin}} \quad \|\mathbf{h}\|_1 + \|\mathbf{m}\|_1 \quad (\ell_1\text{-BH}) \\ \text{subject to} \quad &\text{sign}(y_\ell) \mathbf{b}_\ell^\top \mathbf{h} \mathbf{c}_\ell^\top \mathbf{m} \geq |y_\ell| \\ &s_\ell \mathbf{b}_\ell^\top \mathbf{h} \geq 0, \quad \ell = 1, 2, \dots, L. \end{aligned}$$



In the above figure,

- the feasible set (red) is the intersection of L convex sets,
- the objective function (yellow) intersects the feasible set at a point (\mathbf{h}, \mathbf{m}) with $\|\mathbf{h}\|_1 = \|\mathbf{m}\|_1$, and
- the gray hyperplane segments correspond to linearization of the hyperbolic measurements.

Effective sparsity condition

We provide a recovery guarantee theorem for the class of sparse vectors \mathbf{h}^\flat and \mathbf{m}^\flat with comparable sparsity levels. Precisely, the vectors \mathbf{h}^\flat and \mathbf{m}^\flat have comparable effective sparsity if there exists an absolute constant C such that

$$\frac{\|\mathbf{h}^\flat\|_1}{\|\mathbf{h}^\flat\|_2} = \alpha \frac{\|\mathbf{m}^\flat\|_1}{\|\mathbf{m}^\flat\|_2} \quad (2)$$

with $\frac{1}{C} \leq \alpha \leq C$.

Recovery Theorem

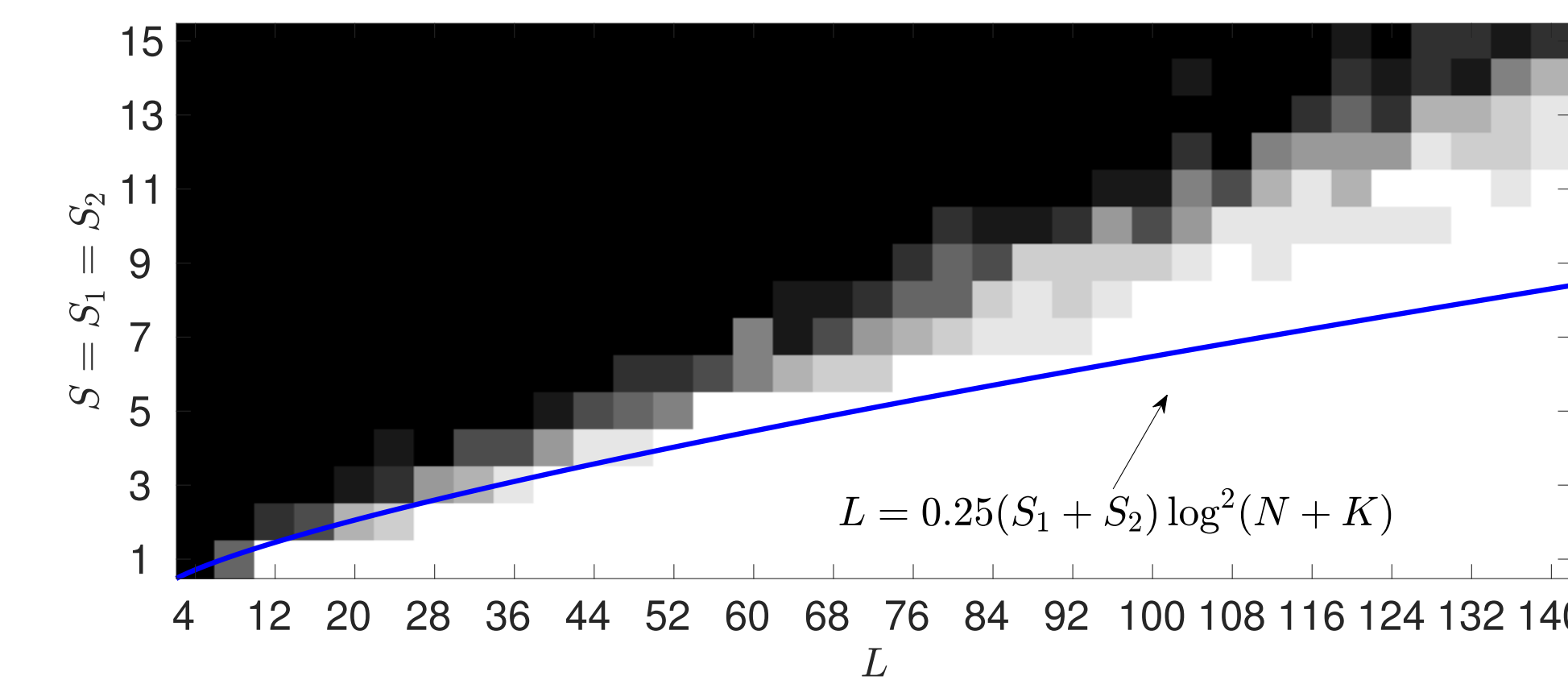
Let \mathbf{B} and \mathbf{C} have i.i.d. $\mathcal{N}(0, 1)$ entries.

If $(\mathbf{h}^\flat, \mathbf{m}^\flat)$ satisfy (2) and $L \geq C_t(S_1 + S_2) \log^2(K + N)$, then the unique minimizer $(\mathbf{h}^*, \mathbf{m}^*)$ of (ℓ_1 -BH) satisfies

$$(\mathbf{h}^*, \mathbf{m}^*) = \left(\mathbf{h}^\flat \sqrt{\frac{\|\mathbf{m}^\flat\|_1}{\|\mathbf{h}^\flat\|_1}}, \mathbf{m}^\flat \sqrt{\frac{\|\mathbf{h}^\flat\|_1}{\|\mathbf{m}^\flat\|_1}} \right)$$

with probability at least $1 - e^{-cLt^2}$. Here, c are absolute constants and C_t depends on $t > 0$.

Phase Plot



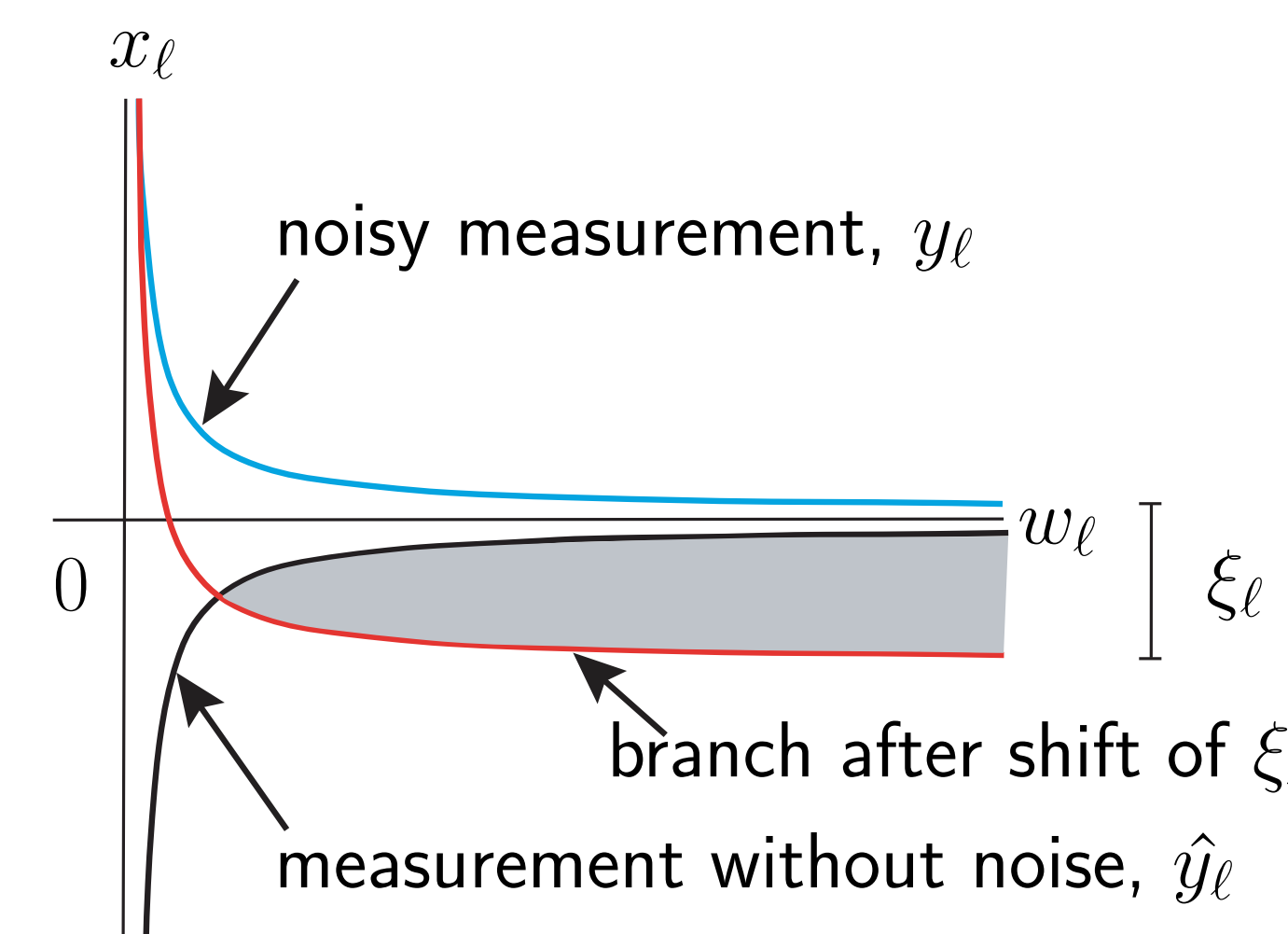
The empirical recovery probability for imbalanced synthetic data. The shades of black and white represents the fraction of successful simulation.

Robust formulation

Let $\boldsymbol{\nu} \in \mathbb{R}^L$ be multiplicative noise so that

$$\mathbf{y} = (\mathbf{w}^\flat \circ \mathbf{x}^\flat) \circ (\mathbf{1} + \boldsymbol{\nu}) = \hat{\mathbf{y}} \circ (\mathbf{1} + \boldsymbol{\nu})$$

If $\nu_\ell < -1$, the shape of the feasible set changes. $\boldsymbol{\xi}$ shifts noisy measurement to ensure a consistent feasible set.



$$\begin{aligned} \underset{(\mathbf{h}, \mathbf{m}, \boldsymbol{\xi}) \in \mathbb{R}^{K+N+L}}{\text{minimize}} \quad & \|\mathbf{P}\mathbf{h}\|_1 + \|\mathbf{m}\|_1 + \lambda \|\boldsymbol{\xi}\|_1 \quad (3) \\ \text{subject to} \quad & \text{sign}(y_\ell) \mathbf{b}_\ell^\top \mathbf{h} (\mathbf{c}_\ell^\top \mathbf{m} + \xi_\ell) \geq |y_\ell| \\ & t_\ell \mathbf{b}_\ell^\top \mathbf{h} \geq 0, \quad \ell = 1, 2, \dots, L. \end{aligned}$$

ADMM implementation

The ADMM scheme that solves (3) can be presented in closed form.

$$\text{Let } \mathbf{u} = \begin{pmatrix} \mathbf{x} \\ \mathbf{w} \\ \boldsymbol{\xi} \end{pmatrix}, \quad \mathbf{z} = \begin{pmatrix} \mathbf{m} \\ \mathbf{h} \\ \lambda \boldsymbol{\xi} \end{pmatrix}.$$

$$\text{Let } \mathbf{E} = \begin{pmatrix} \mathbf{C} & \mathbf{0} & \mathbf{0} \\ \mathbf{0} & \mathbf{B} & \mathbf{0} \\ \mathbf{0} & \mathbf{0} & \lambda^{-1} \mathbf{I}_L \end{pmatrix}, \quad \mathbf{Q} = \begin{pmatrix} \mathbf{I}_N & \mathbf{0} & \mathbf{0} \\ \mathbf{0} & \mathbf{P} & \mathbf{0} \\ \mathbf{0} & \mathbf{0} & \mathbf{I}_L \end{pmatrix}.$$

$$\text{Let } \mathcal{C} = \left\{ \mathbf{u} \in \mathbb{R}^{3L} \mid \text{sign}(y_\ell)(\xi_\ell + x_\ell)w_\ell \geq |y_\ell|, s_\ell w_\ell \geq 0, \ell \in [L] \right\}.$$

The ADMM steps are:

$$\mathbf{u}_{k+1} = \text{proj}_{\mathcal{C}}(\mathbf{E}\mathbf{z}_k - \boldsymbol{\alpha}_k), \quad (4)$$

$$\mathbf{v}_{k+1} = S_{1/\rho}(\mathbf{Q}\mathbf{z}_k - \boldsymbol{\beta}_k), \quad (5)$$

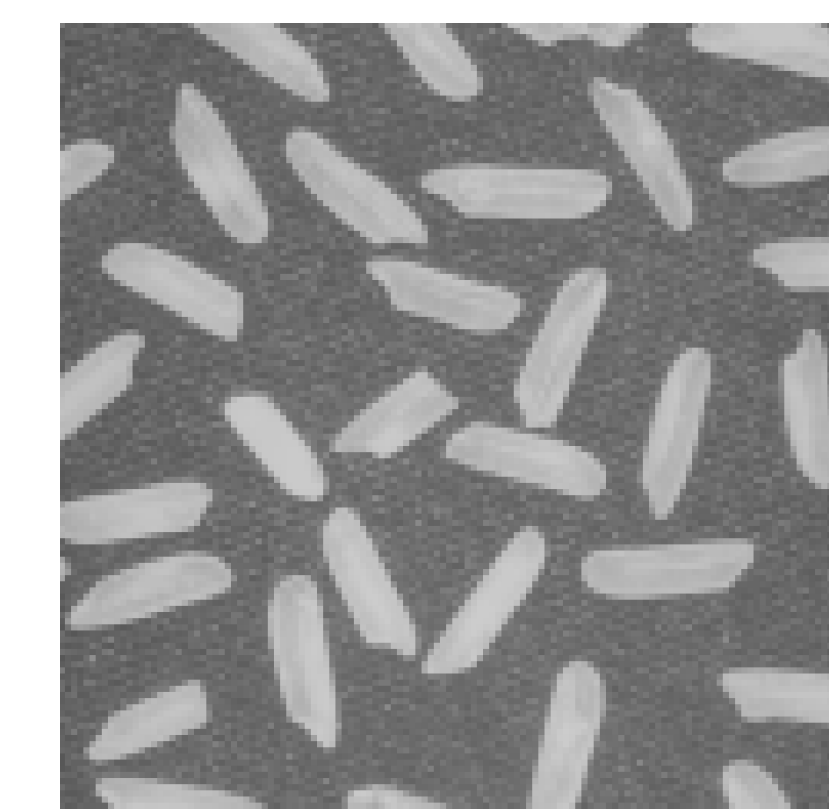
$$\mathbf{z}_{k+1} = (\mathbf{E}^\top \mathbf{E} + \mathbf{Q}^\top \mathbf{Q})^{-1} (\mathbf{E}^\top (\boldsymbol{\alpha}_k + \mathbf{u}_{k+1}) + \mathbf{Q}^\top (\boldsymbol{\beta}_k + \mathbf{v}_{k+1})), \quad (6)$$

$$\boldsymbol{\alpha}_{k+1} = \boldsymbol{\alpha}_k + \mathbf{u}_{k+1} - \mathbf{E}\mathbf{z}_{k+1},$$

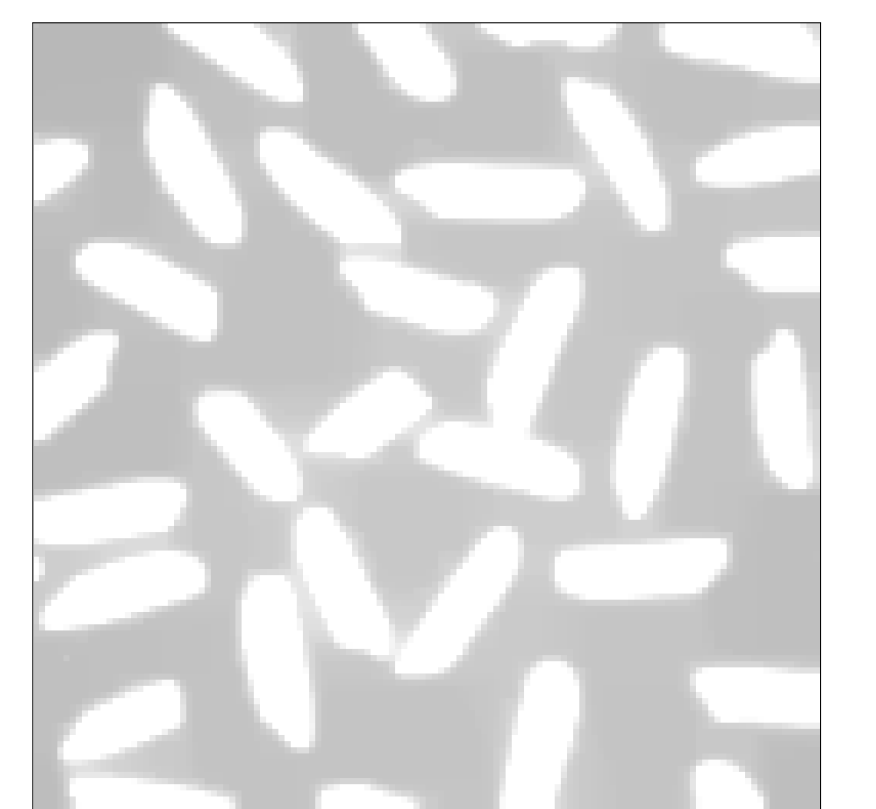
$$\boldsymbol{\beta}_{k+1} = \boldsymbol{\beta}_k + \mathbf{v}_{k+1} - \mathbf{Q}\mathbf{z}_{k+1}.$$

where $\text{proj}_{\mathcal{C}}(\mathbf{z})$ is the projection of \mathbf{z} onto \mathcal{C} and $S_c(\cdot)$ the soft-thresholding operator.

Rice grain data



(a) Distorted image



(b) Recovered image

Panel (a) shows an image of rice grains. The goal is to remove distortions and recover a piecewise constant image that outlines the rice grains. Robust ℓ_1 -BranchHull (3) is used to recover the signal. Panel (b) shows the output of (3).

Key Points

ℓ_1 -BranchHull is a convex algorithm that is/has:

- posed in the natural parameter space,
- initialization free and does not require approximate solutions, and
- optimal sample complexity up to a log factor.