

# Advanced C++ programming

## ♦ Introduction to C++

- C++: from C and beyond
- Classes, objects and lifetime (vs. JAVA)
- Oriented-Object Programming (inheritance, polymorphism)

## ♦ Memory management & object manipulation

- References, operators, « copy » object construction
- « move » object construction, lambda functions

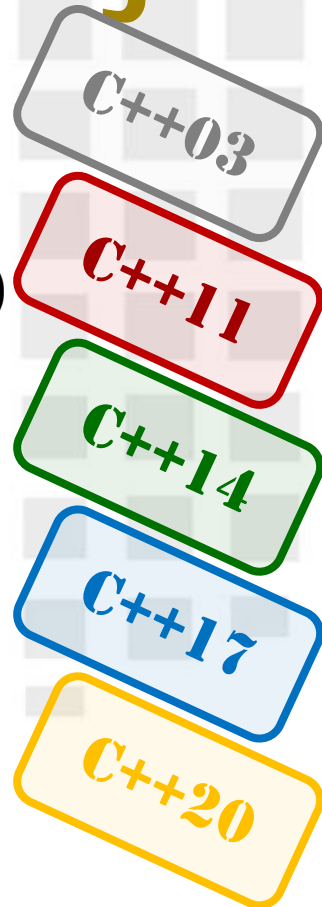
## ♦ Template vs OO programming

- Slot 6 → Template functions and classes

## ♦ The Standard Template Library

- Containers, iterators and algorithms
- Using sequence & associative containers ...

## ♦ Smart pointers (STL & Boost)



# Introducing « templates »

C++ 11 / C++ 14

`tr1::` (si C++0x)

Smart pointers  
(`shared_ptr`)

Random number engines  
(`poisson`, `gamma`, ...)

Mathematical specials  
(`bessel`, `laguerre`, ...)

Regular  
expressions

Higher level entities  
(`binders`, `wrapper`, ...)

New data types  
(`tuple`, `hash table`, ...)

Meta-programming  
(`type_traits`, ...)

Boost

C++ 98

C++  
(Template)

C++  
(Object)

C89

Standard Template  
Library (STL)

I/O library  
(`iostream`)

Exceptions  
Handling

Localization library  
(`wchar_t`, `wchar_ts`)

Numerics library (`math`)  
(`complex`, `valarray`)

Graph library

Meta Programming Library (MPL)



# « Templates » ?

- **Goal**

- ▶ Do not write similar C++ code several times, when only the entity types change
  - Key idea: consider a « type » as another parameter...

- **When this happens, you create:**

- Template functions
- Template classes

- **On the road to meta-programming...**

- You ask much more to the compiler...



# Template functions (1/2)

- **Avoid redundancies**

- Same algorithm, different types
- Maintenance issues?

```
double min (double a , double b) {  
    return a > b ? b : a ;  
}
```

```
int min (int a , int b) {  
    return a > b ? b : a ;  
}
```

...

- **Introduction of template functions**

- ▶ New keywords:

- « **template** »: indicates the compiler how to create functions having the same code but operating on generic object types
    - « **typename** »: gives a « name » to the generic type

```
template <typename T>  
T min (T a , T b) {  
    return a > b ? b : a ;  
}
```



# Template functions (2/2)

## • How does it work ?

```
template <typename T>
T min (T a , T b) {
    return a > b ? b : a ;
}
```

- Using a template function, the **compiler** “writes down” the specific code for all the required functions (with a specific type) before compiling them



```
double c = min (10.4 , 23.5) ;
int     d = min (10 , 23) ;
```

```
double min_double (double , double) ;
int    min_int    (int , int) ;
```

- two functions « min » are written down by the **compiler**
- each « min » function deals with one specific type: double then int
- Once written down, the compiler operates as usual:
  - ▶ all checking performed when compiling, **not at runtime**



compilation

```
Point C = min (A , B) ;
```

The compiler will output an error when compiling the “min function dedicated to Point objects”, if operator “>” is not defined for Point class



# Using template functions (1/5)

```
template <typename T>  
T min (T a , T b) {  
    return a > b ? b : a ;  
}
```

## • Exact matching types rule

- Template functions arguments (the values/variables passed when calling the function) must exactly match the types given with the template declaration



compilation

```
double c = min (10.4 , 23) ;
```

- 10.4 is a floating value (type: double), 23 is an integer (type: int)
- function « double min (double a , int b) » does not exist!

➔ Solution: tell the compiler to produce and use a specific templated function



```
double c = min<double> (10.4 , 23) ;
```

- “double min (double, double)” will be written down, then compiled
- type casting may then occur as usual (here, 23 will be cast to double)



# Using template functions (2/5)

- Several template types: OK

```
template <typename T1 , typename T2>
T1 func (T1 one , T2 two , T1 three) {...}
```

```
template <typename T>
T min (T a , T b) {
    return a > b ? b : a ;
}
```

- Overloading template functions: OK

```
template <typename T>
T min (T a , T b , T c) {
    T i = min (a , b) ;
    return min (i , c) ;
}
```

```
min (5 , 10 , 15) ;
min (4.5 , 15.75 , 8.25) ;
min (2 , 3.5 , 3.75) ;
```

- Explicit template specialization (partial or full): OK

- You may give an extra specific version for specific types, bypassing the templated version for these types

► The compiler selects the most specific version

```
template <>
string min (string a , string b) {
    return a.length() > b.length() ? b : a ; }
```

```
min (5 , 10) ;
min (4.5 , 8.75) ;
min ("tomate" , "chou")
```



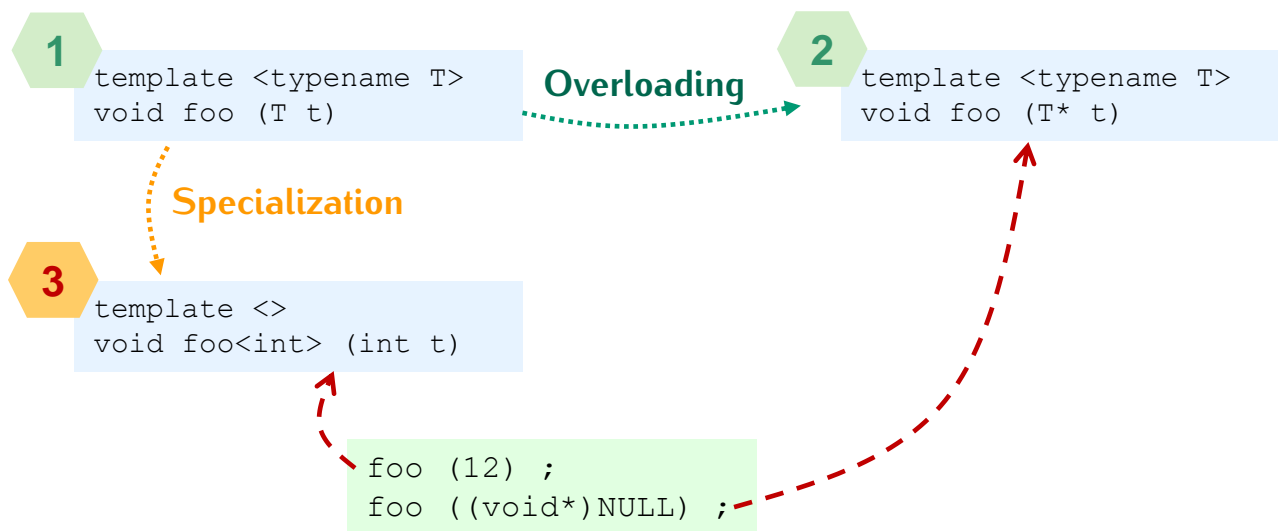
# Using template functions (3/5)

- **Mixing overloading and specialization**

- ▶ How does the compiler behave?

The compiler deals with **overloading first**, then selects the most specific template version

- Example 1:





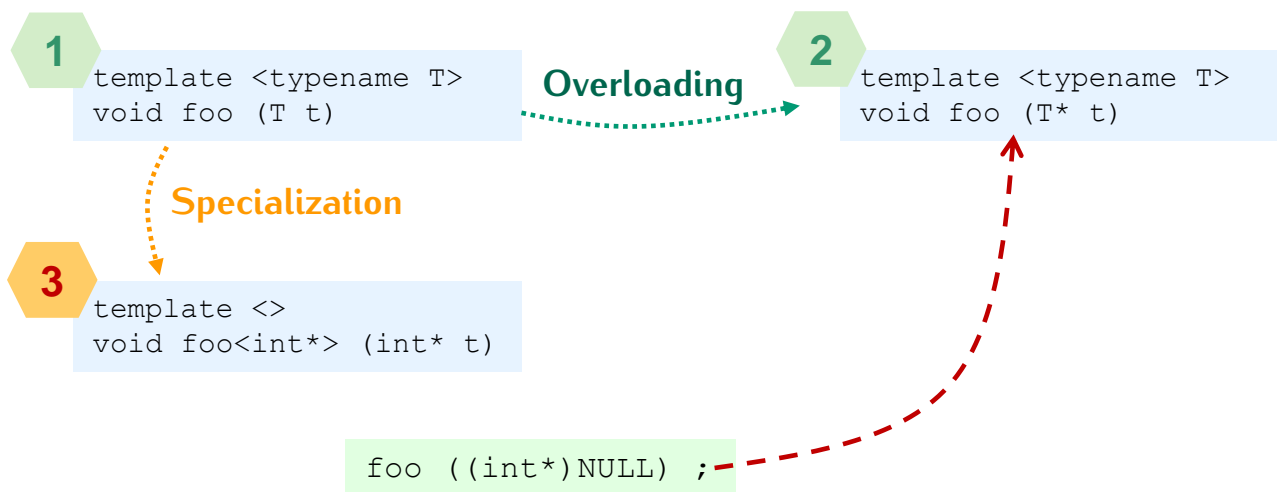
# Using template functions (3/5)

- **Mixing overloading and specialization**

- ▶ How does the compiler behave?

The compiler deals with **overloading first**, then selects the most specific template version

- Example 2:



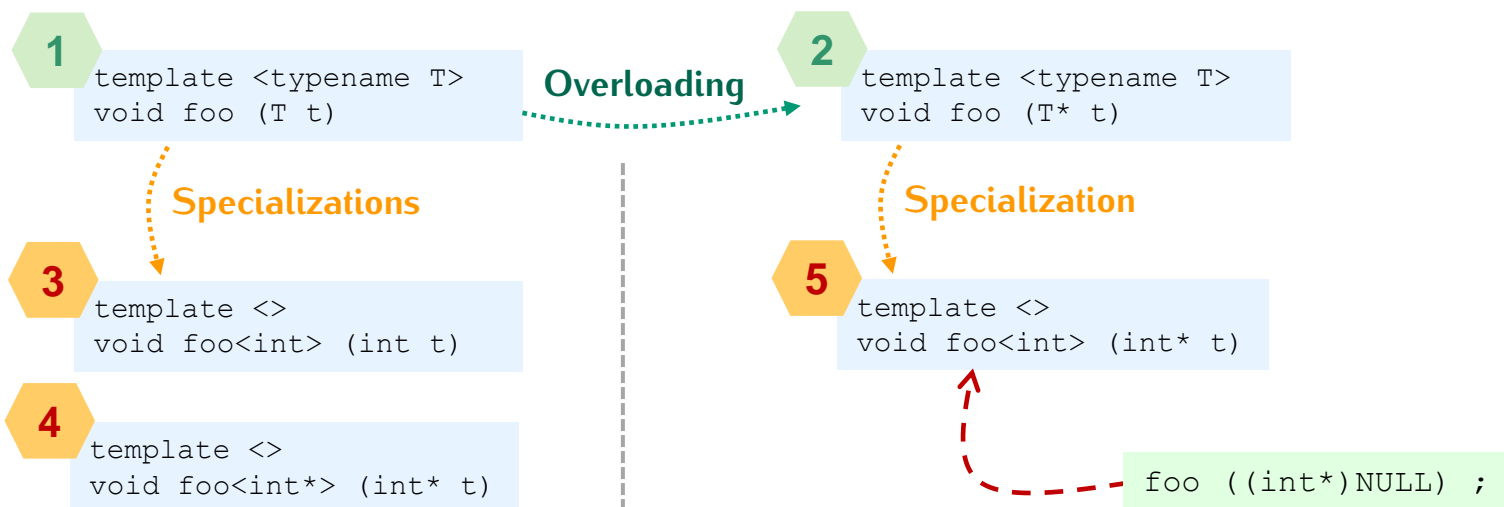
# Using template functions (3/5)

- **Mixing overloading and specialization**

- ▶ How does the compiler behave?

The compiler deals with **overloading first**, then selects the most specific template version

- Example 3:



# Using template functions (4/5)

- **template<...>** must list all template types
  - for parameters, for returned value, inside the function
  - Example: « universal » conversion function between types

```
template <typename T , typename W>  
T transform(W a) {  
    return (T)a ;  
}
```

```
transform<Point>(10) ;
```

Type casting  $W \rightarrow T$  must exist  
(if not, error when compiling)

- **template<...>** also accepts
  - numerical value types: `int`, `short`, `char`
  - pointers

```
template <typename T , int N=2>  
T get (T* v) {  
    return v[N] ;  
}
```



# Using template functions (5/5)

- A method can also be a template method

- ▶ The compiler will **only write down** (insert into the class) the actually called specific methods

```
class A {  
    int i ;    // Class attribute (data)
```

```
public:
```

```
    // This is a template method: the compiler will provide all the specific methods "add"  
    // according to actual calls to "add" (with specific types for "inc")
```

```
    template <class T>
```

```
    void add (T inc) ;
```

```
};
```

```
// Method implementation
```

```
template <class T>
```

```
void A::add (T inc) {
```

```
    // Add "inc" to "A::i"
```

```
    // error when compiling
```

```
    // if "inc" cannot be cast to int
```

```
    i = i + (int)inc ;
```

```
    return ;
```

```
}
```

```
A obj ;
```

```
// Compiler provides "void A::add(int)" to class A  
obj.add(10) ;
```

```
// Compiler provides "void A::add(double)" to class A  
obj.add(20.5) ;
```

```
// Compiler tries to provide "void A::add(char*)" to class A  
// but fails as its code cannot compile  
obj.add ("toto") ;
```



# Template classes (1/4)

- Same requirements

- ▶ Avoid useless redundancies while authorizing specialization for **class** definition

- Example: generic `Point` class?

- same structure, different internal types
  - same behavior

```
class PointDouble {  
    double x , y ;  
}
```

```
class PointInt {  
    int x , y ;  
}
```

➔ Solution : coordinates type  $\equiv$  template type? **YES**

```
template <typename T>  
class Point {  
    T x , y ;  
}
```

```
Point<double> P ;  
Point<int> I ;
```



type of P: `Point<double>`  
type of I: `Point<int>`



# Template classes (2/4)

- Extending the example...

- Make the dimension of a point generic ? 2D, 3D, 4D, ...

```
template <typename T , int N>  
class Point {  
    T v[N] ;  
}
```

```
Point<double,3> P ;  
Point<int,2> I ;
```



type of P: Point<double,3>  
type of I: Point<int,2>

- Default template type value

```
template <typename T , int N=2>  
class Point {  
    T v[N] ;  
}
```

```
Point<double> P ;  
Point<int,4> I ;
```



type of P: Point<double,2>  
type of I: Point<int,4>



# Template classes (3/4)

- File organization
    - Template class
- Point** is fully defined in "Point.h" file

```
#include "Point.h"
```

```
// Constructor [1]
```

```
Point<int,3> P3 ;
```

```
// Constructor [2]
```

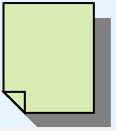
```
Point<int,3> M3 (P3) ;
```

```
// Constructor [1]
```

```
Point<int> I2 ;
```

```
// Constructor [3]
```

```
// Error when compiling if  
// constructor [3] does not exist  
Point<double,2> D2 (I2) ;
```



**Point.h**

```
template <typename T , int N=2>
class Point
{
public :
    T v[N] ;

    // [1] Default constructor (to write if wanted: it will not
    // exist automatically as other constructors are defined)
    Point () {
        for (int k = 0 ; k < N ; k++) v[k] = 0 ;
    }

    // [2] Copy constructor (same dimension / coordinates type)
    Point (const Point<T,N>& P) ;

    // [3] Copy constructor (from a same dimension Point
    // but with different coordinates type)
    template <typename W> Point (const Point<W,N>& P) ;

} ;

template <typename T , int N>
Point<T,N>::Point (const Point<T,N>& P) {
    for (int k = 0 ; k < N ; k++) v[k] = P.v[k] ;
}

template <typename T , int N>
template <typename W>
Point<T,N>::Point (const Point<W,N>& P) {
    for (int k = 0 ; k < N ; k++) v[k] = transform<T>(P.v[k]) ;
}
```



# Template classes (4/4)

- No standalone compilation for template class "Point"



The compiler must know the full source code of a template class (here `Point`) to write down the source code of its specific version (here `Point<int,3>`) and compile it!

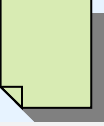
```
#include "Point.h"
```

```
// Constructor [1]
Point<int,3> P3 ;
```

```
// Constructor [2]
Point<int,3> M3 (P3) ;
```

```
// Constructor [1]
Point<int> I2 ;
```

```
// Constructor [3]
// Error when compiling if
// constructor [3] does not exist
Point<double,2> D2 (I2) ;
```



**Point.h**

```
template <typename T , int N=2>
class Point
{
public :
    T v[N] ;

    // [1] Default constructor (to write if wanted: it will not
    // exist automatically as other constructors are defined)
    Point () {
        for (int k = 0 ; k < N ; k++) v[k] = 0 ;
    }

    // [2] Copy constructor (same dimension / coordinates type)
    Point (const Point<T,N>& P) ;

    // [3] Copy constructor (from a same dimension Point
    // but with different coordinates type)
    template <typename W> Point (const Point<W,N>& P) ;

} ;

template <typename T , int N>
Point<T,N>::Point (const Point<T,N>& P) {
    for (int k = 0 ; k < N ; k++) v[k] = P.v[k] ;
}

template <typename T , int N>
template <typename W>
Point<T,N>::Point (const Point<W,N>& P) {
    for (int k = 0 ; k < N ; k++) v[k] = transform<T>(P.v[k]) ;
}
```





# Building a binary executable



main.cpp

```
#include "MaClasse.h"

int main (int argc, char* argv[])
{
    MaClasse<int> c ;

    c.run() ;

    return 0 ;
}
```

MaClasse.h

```
#ifndef _MACLASSE
#define _MACLASSE
#include <math>

template <typename T>
class MaClasse {
public :
    T hauteur ;

    double run () ;
}

template <typename T>
double MaClasse::run () {
    return std::cos(0) ;
}
#endif
```

math.h

```
namespace std {
...
    double cos (double) ;
...
}
```

libm.so

```
01010110111
10100010010
01010000101
```

1

Compilation :

`g++ -c main.cpp`

main.o

```
0101011
1010001
0101000
```

2

Edition de liens :

`g++ -o mon_prog main.o -lm`



mon\_prog

```
01010110111
10100010010
01010000101
```

`-std=c++11 -Wall`



# Introducing constraints (1/3)


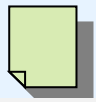
## • Why giving several versions ?

 ⇒ tell explicitly which models are authorized

## • Get along with everything generic

- always possible
- BUT no help given

```
// Copy constructor (from everything>)
template <typename Obj>
Point (const Obj& P) {
    for (int k = 0 ; k < N ; k++)
        v[k] = P.v[k] ;
}
```

```
template <typename T , int N=2>
class Point
{
public :
    T v[N] ;

    // [1] Default constructor (to write if wanted: it will not
    // exist automatically as other constructors are defined)
    Point () {
        for (int k = 0 ; k < N ; k++) v[k] = 0 ;
    }

    // [2] Copy constructor (same dimension / coordinates type)
    Point (const Point<T,N>& P) ;

    // [3] Copy constructor (from a same dimension Point
    // but with different coordinates type)
    template <typename W> Point (const Point<W,N>& P) ;

};

template <typename T , int N>
Point<T,N>::Point (const Point<T,N>& P) {
    for (int k = 0 ; k < N ; k++) v[k] = P.v[k] ;
}

template <typename T , int N>
template <typename W>
Point<T,N>::Point (const Point<W,N>& P) {
    for (int k = 0 ; k < N ; k++) v[k] = transform<T>(P.v[k]) ;
}
```



# Introducing constraints (2/3)

- Going further to specify constraints on template type
  - SFINAE mechanism when compiling
    - ▶ “Substitution failure is not an error”

**Verbose  
+  
not easy  
to read**

```
class Base {} ;
class Derived : public Base {} ;
```

```
// Substitution OK when T is a type derived from Base
template<typename T,
        std::enable_if_t<std::is_baseof_v<Base, T>, bool> Dummy = true
>
void foo (T t) {}
```

```
// Substitution OK when T is not a type derived from Base
template<typename T,
        std::enable_if_t<not std::is_baseof_v<Base, T>, bool> Dummy = true
>
void foo (T t) {}
```

```
int main() {
    Derived der ;
    foo(der) ;
    foo(123) ;
}
```

**C++11**

**C++14**

**C++17**

- Improvements as C++ evolves but...

- ▶ still exposing compiler internal mechanisms making the **code and compiler error messages difficult to read!**



# Introducing constraints (3/3)

- How to easily tell the kind of template that may be provided (the compiler will check)?

## ► New keyword “**concept**”



```
#include <string>
#include <cstdint>
#include <concepts>
using namespace std::literals;

// Declaration of the concept "Hashable", which is satisfied by
// any type T such that for values a of type T:
// - the expression std::hash<T>{}(a) compiles
// - its result is convertible to std::size_t
template<typename T>
concept Hashable = requires(T a) {
    { std::hash<T>{}(a) } -> std::convertible_to<std::size_t>;
};

struct meow {} ;           // "meow" does not satisfy Hashable concept

template<Hashable T>        // Constrained C++20 function template
void f(T);                 // T must be Hashable

int main() {
    f("abc"s);             // OK, std::string satisfies Hashable
    f(meow{});             // Error: meow does not satisfy Hashable
}
```

// Alternative way to **apply**  
// the same constraint:

```
template<typename T>
    requires Hashable<T>
void f(T);
```



# Interesting features (1/3)



## • Variadic templates

- Take an **arbitrary number** of template arguments of any type

```
void print () { }

template <typename T, typename... Types>
void print (const T& firstArg , const Types&... args) {
    cout << firstArg << endl ;
    print (args...) ;
}

print (7.5 , "hello" , std::bitset<16>(377) , 42) ;
```

- Allow collections of different types objects: **std::tuple<>**

```
typedef std::tuple <int , string , double> product_t ;

product_t mag (100 , "Science" , 6.5) ;

// Full access to every element of the tuple object
int id = std::get<0>(mag) ;
std::get<1>(mag) = "USA Today" ;

// Another way to build a tuple
auto mag2 = std::make_tuple (101 , "TV mag", 8.5) ;
```

**std::tuple <>**

template<typename... V>  
class tuple ;



# Interesting features (2/3)



## • Template aliases

- **using** : allow “typedef” for templates

```
template <typename T>
using vec = std::vector<T> ;

// vec is an alias for std::vector<>
vec<int> collection ;
```

```
typedef void (*Type)(double) ;
using OtherType = void (*) (double) ;
```

```
template<size_t N , size_t M>
class Matrix { // ....
} ;
```

```
typedef Matrix<N,1> Vector<N> ;
```

```
template <int N>
using Vector = Matrix<N,1> ;
```



compilation

## • Extern templates

- Tell the compiler not to instantiate a template as you know it will be instantiated somewhere else  $\Rightarrow$  compile time **optimization**

```
template <typename X> class A {
public :
    void test(X) ;
} ;
```

```
// AA sera connue mais pas instanciée ici : extern dit
// que l'instanciation sera faite plus loin ou dans un
// autre module  $\neq$  template class AA<int> { ... } ;
extern template class AA<int> ;
```



# Interesting features (3/3)

## • Type inference & new syntax for functions

```
// How to write the type of
// the returned object ???
template<class T, class U>
??? add (T x, U y) {
    return x+y ;
}
```

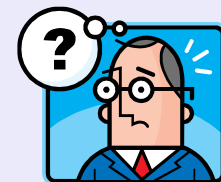


```
// When reading decltype(x+y),
// the compiler has never seen
// x or y: error
template<class T, class U>
decltype(x+y) add (T x, U y) {
    return x+y ;
}
```



compilation

```
// Correct solution but difficult to read
template<class T, class U>
decltype(*(T*)(0)+*(U*)(0)) add (T x, U y) {
    return x+y ;
}
```



C++11

```
// Using the function new syntax
template<class T, class U>
auto add (T x, U y) -> decltype(x+y) {
    return x+y ;
}
```

```
// Other solution using type inference on
// function return value
template<class T, class U>
decltype(auto) add (T x, U y) {
    return x+y ;
}
```

C++14



# Generic programming (1/3)

- **Introducing the “concept” notion**
  - 1 concept  $\equiv$  a set of “services” or properties, a type must provide or satisfy ( $\approx$  OOP interface)
  - A concept allows to specify how an entity may be **used**.
- **C++ implementation ( $\neq$  JAVA generics)**
  - Through **templates** mechanisms
    - ▶ no inheritance: two classes satisfying a concept must only implement a common set of method signatures
    - ▶ naming the used concept / entities is very **important** as it helps understanding the purpose / actual use of the entity
  - Everything’s checked and done when **compiling**





# Generic programming (2/3)

## • OOP vs. Generic Programming

### Runtime polymorphism

```
// Oriented Object Programming
struct Base
{
    virtual void Foo() = 0 ;
} ;

struct A : public Base
{ void Foo() ; } ;

struct B : public Base
{ void Foo() ; } ;

// The "Foo" method of actual "obj"
// type is chosen using the virtual
// function table
// at RUNTIME
void Bar (Base& obj)
{ obj.Foo() ; }
```

```
// Generic programming
struct A {
    inline void Foo() ;
} ;

struct B {
    inline void Foo() ;
} ;

template<typename T>
void Bar (T& obj) {
    obj.Foo() ;
}
```

```
// The compiler produces two specific "Bar"
// functions: "void Bar(A&)" and "void Bar(B&)"
// if these are actually called. Everything's done
// when COMPILING
```

### Compilation polymorphism



```
A a ;
B b ;
```

```
Bar (a) ;
Bar (b) ;
```



# Generic programming (3/3)

- **OOP vs. Generic Programming**

- Oriented Object Programming (**inheritance**)

- When calling a function, the provided value types must **match** or **derive** from the types given in the declaration
- Use of virtual methods: runtime actual method selection ► extra cost

- Generic Programming (**templates**)

- When calling a function, the provided value types must only **implement the methods** that are called on them, in the function
- Use of template mechanism:
  - Everything's done when compiling ► no extra cost at runtime
  - All types must be known when compiling

- **Two different approaches**

- The STL uses the “Generic Programming” approach



# Practice



## • Template functions



- Writing a template function
- Building a program that uses template functions
- Using template functions with objects

## • Going further with template classes...



- A “Tree” template class ?

