Chap. 7 The Upper Confidence Bound Algorithm	
[· Version Oil	
· The contents are adapted from UIUC IE 498, Chap.7	
in Bandit Algorithm book, and Chap. 6 in reinforceme	int
bearning book.	
§7.0 Setting	
· FSG bandit.	
§7.1 Algorithm	
$ \frac{\partial \mathcal{L}_{i,i} + \sqrt{2 \cdot \ln n \cdot k \cdot \delta^{-1}}}{T_{i}(t-1)}, T_{i}(t-1) \ge 0 $	
∞ , $T_i(t-1) = 0$	
Algorithm [UCB Algorithm]	
• for t=1,, n do	
· Choose action At=argmax UCBi(t).	
· Observe reward Xt and update upper confidence bounds.	
§7.2 Analyst	

Theorem 7.1 [Gay-independent Regret Bound] It holds that the regret of UCB algorithm is upper bounded by OCTENIUNEIS) +K), w.p. at beast 1-8. Prost. Twe start by proving the optimism. By Hoeffaling inequality, it holds that P(Mt-1, i + 2:ln(kn 18) > Mi) > 1- 5k, for some fixed to [n], Let Et, i= { ût-1, i + 2·lu(kn:18) } ui }.

Then

$$P(\exists t \in [n], \exists i \in [k]: \bar{E}_{ti}, holds) \leq \frac{\delta}{kT} (kT)$$

 $= \delta$,

by union bound. Let E= \(\cap\) \(\cap\) \(\text{Eti}\) be the 'good event'.

② Now we take a look oit the per-step regret. W.C.o.g., we assume arm I is the optimal arm. Condition on E, it holds that

 $u^* - u_{A+} \leq VCB_1(t) - u_{A+}$ $\leq VCB_{A+}(t) - u_{A+}$

CI + Witni - Wi.

< 2CI.

3 Summing over all steps leads to

$$\sum_{t=1}^{N} \cdot u^* - \sum_{t=1}^{n} \cdot u_{\text{obt}} \leq \sum_{t=1}^{n} \left| \frac{dn(nbis)}{T_{\text{obs}}(t-1)} \right|$$

Theorem 7,2 [Gap-dependent Regret Bound]

It holds that the regret of UCB algorithm is upper bounded by

$$\bigcirc \left(\sum_{1:\Delta : >0} \frac{\ln \left(nk16 \right)}{\Delta :} + \sum_{1:\Delta : >0} \Delta_{i} \right).$$

w.p. at beast 1-6.

Proof. Note that $Ti(n) = \max\{t \in T_n\}$. It is clearly that

s.t. $Ti(T_i) = Ti(n)$ and $A_{T_i} = i$. It is clearly that

$$\frac{\int 2 \cdot \ln(nkls)}{T_i(n)} > \Delta i,$$

which is due to that OCBi(Ti)? U^* is the necessary condition that arm i is pulled at time step Ti. Eq.(1) implies that

$$Ti(n) \lesssim \frac{\ln(neld)}{\Delta i^2}$$

Thus it holds that w.p. 1-8

$$R(n) = \sum_{i,si>0} D_i \cdot T_i(n)$$

which together with the fact that the algorithm pull each arm once in the first k steps concludes the proof.