

§28.1 Online Linear Optimization

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§28.1.1. Setting

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Different from adversarial linear bandit:

y_t could be observed by the learner rather than $\langle y_t, a_t \rangle$.

§28.1.2. Mirror Descent

- $\gamma > 0$: the learning rate.
- $F: \mathbb{R}^d \rightarrow \bar{\mathbb{R}}$ is a convex function: the potential function regularizer (usually F is Legendre).

$$a_1 = \underset{a \in \mathcal{A}}{\operatorname{argmin}} \cdot F(a)$$

$$a_{t+1} = \underset{a \in \mathcal{A}}{\operatorname{argmin}} \quad \gamma \langle y_t, a \rangle + D_F(a, a_t) \quad (28.2)$$

Remark. A simple case when $(a_t)_{t=1}^n$ is well-defined is when \mathcal{A} is compact and F is Legendre.

§28.1.3 Follow-the-Regularized-Leader

$$a_1 = \underset{a \in \mathcal{A}}{\operatorname{argmin}} \cdot F(a)$$

$$a_{t+1} = \underset{a \in \mathcal{A}}{\operatorname{argmin}} \quad \gamma \sum_{s=1}^t \langle y_s, a \rangle + F(a). \quad (28.3)$$

§ 28.1.4 Equivalence of Mirror Descent and Follow-the-Regularized Leader.

Assumption: F is Legendre on domain $D \subseteq \mathbb{A}$.

Remark. The above assumption implies that the minimize of

$$\bar{\Phi}_t(a) = \gamma \cdot \langle y_t, a \rangle + F(a, a_t)$$

occurs in the interior of $D \subseteq \mathbb{A}$ and $\nabla \bar{\Phi}_t(a_{t+1}) = 0$.

- a_{t+1} in D :

$$\nabla \bar{\Phi}_t(a_{t+1}) = \gamma \cdot y_t + \nabla F(a_{t+1}) - \nabla F(a_t) = 0,$$

which by induction implies that

$$\nabla F(a_{t+1}) = -\sum_{s=1}^t \gamma \cdot y_s + \nabla F(a_t) = -\gamma \sum_{s=1}^t y_s,$$

where the last inequality follows by that $a_t = \operatorname{argmin}_{a \in D} F(a)$,

and again the fact that F is Legendre on $\operatorname{dom}(F) = D \subseteq \mathbb{A}$.

- a_{t+1} in FTRL:

Let $\bar{\Phi}'_t(a) = \gamma \sum_{s=1}^t \langle y_s, a \rangle + F(a)$. Then it holds that

$$\nabla \bar{F}'(a_{t+1}) = \gamma \cdot \sum_{s=1}^t y_s + \nabla F(a_{t+1}),$$

which implies that $\nabla F(a_{t+1}) = -\gamma \sum_{s=1}^t y_s$.

Remark. The equivalence between MD and FTRL only holds when (a) F is Legendre on $D = \text{dom}(F)$, (b) $D \subseteq A$, and (c) learning rate γ is fixed. If a time-varying learning rate $(\gamma_t)_{t \geq 1}$ is adopted, then in MD

$$\nabla F(a_{t+1}) = - \sum_{s=1}^t \gamma_s \cdot y_s$$

but in FTRL

$$\nabla F(a_{t+1}) = -\gamma_t \sum_{s=1}^t y_s$$

Example 28.1 [MD as Online Gradient Descent]

Assume $A = \mathbb{R}^d$ and $F(a) = \frac{1}{2} \|a\|_2^2$. Clearly F is Legendre,

$\nabla F(a) = a$, and $D_F(a_1, a_2) = \frac{1}{2} \|a_1\|_2^2 - \frac{1}{2} \|a_2\|_2^2 - a_2^\top (a_1 - a_2)$. Then

$$a_{t+1} = \nabla F(a_{t+1}) = \nabla F(a_t) - \gamma \cdot y_t = a_t - \gamma \cdot y_t,$$

which is usually called online gradient descent.

Example 28.2 [MD as Online Projected Gradient Descent]

Assume \mathcal{A} is a convex subset of \mathbb{R}^d , and $F(a) = \frac{1}{2}\|a\|_2^2$.

Then MD chooses

$$a_{t+1} = \operatorname{argmin}_{a \in \mathcal{A}} \gamma \cdot \langle y_t, a \rangle + D_F(a, a_t).$$

$$= \operatorname{argmin}_{a \in \mathcal{A}} \gamma \cdot \langle y_t, a \rangle + \frac{1}{2} \|a - a_t\|_2^2.$$

$$= \Pi_{\mathcal{A}}(a_t - \gamma \cdot y_t),$$

where $\Pi_{\mathcal{A}}(a)$ is the Euclidean projection of a onto \mathcal{A} .

The above algorithm is online projected gradient descent.

Example 28.3 [FTRL as Exponential Weight Algorithm]

Assume \mathcal{A} is a probability simplex, and

$$F(x) = \sum_i x_i \cdot \ln x_i - \sum_i x_i$$

is the normalized negative entropy. Then FTRL chooses

$$a_{t+1} = \operatorname{argmin}_{a \in \mathcal{A}} \gamma \cdot \sum_{s=1}^t \langle y_s, a \rangle + \sum_{i=1}^d a_i \cdot \ln a_i - \sum_{i=1}^d a_i,$$

which can be shown to satisfy that

$$a_{t+1,i} = \frac{\exp(-\gamma \cdot L_{t,i})}{\sum_{j=1}^d \exp(-\gamma \cdot L_{t,j})},$$

where $L_t = \sum_{S=1}^t \cdot y_S$.

§ 28.1.5 Implementation

Assume

- \mathcal{A} is compact, and non-empty
- F is Legendre
- $\nabla F(a) - \gamma \cdot y \in \text{int}(\text{dom}(F^*))$, $\forall a \in \mathcal{A} \cap D$ and $y \in L$.

(28.6)

A. Implementation of MD [A Two-Step Process]

The solution of Eq. (28.3) could be found as

$$\hat{a}_{t+1} = \underset{a \in \mathcal{A}}{\operatorname{argmin}} \gamma \cdot \langle y_t, a \rangle + D_F(a, a_t). \quad (28.7)$$

$$a_{t+1} = \underset{a \in \mathcal{A}}{\operatorname{argmin}} D_F(a, \hat{a}_{t+1}).$$

Remark. Since F is Legendre, ∇F is a bijection between $\text{int}(\text{dom}(F))$ and $\text{int}(\text{dom}(F^*))$, which together with Eq. (28.6) implies that

$$\hat{a}_{t+1} = (\nabla F)^{-1}(\nabla F(a_t) - \gamma \cdot y_t).$$

B. Implementation of FTRL.

Assume

- \mathcal{A} is compact and non-empty
- F is Legendre
- $-\gamma \sum_{s=1}^t y_s \in \text{int}(\text{dom}(F^*)) \quad \forall t = 1, \dots, n.$

The leader chosen by FTRL at time $t+1$ is

$$a_{t+1} = \text{Ti}_\mathcal{A}^F(\nabla F^{-1}(-\gamma \sum_{s=1}^t y_s)),$$

where $\text{Ti}_\mathcal{A}^F(a)$ indicates the Bregman projection of a onto \mathcal{A} w.r.t. $D_F(\cdot, \cdot)$.

§ 28.2 Regret Analysis.

Theorem 28.4 [Mirror Descent Regret Bound]

Let $\gamma > 0$, F be Legendre with $D = \text{dom}(F)$, \mathcal{A} be a non-empty convex set with $\text{int}(D) \cap \mathcal{A} \neq \emptyset$. Let $(a_t)_{t=1}^{n+1}$ be the actions chosen by mirror descent, which are assumed to be well-defined. Then, for any $a \in \mathcal{A}$, the regret of M is bounded by

$$R_n(a) \leq \frac{F(a) - F(a_1)}{\gamma} + \sum_{t=1}^n \langle a_t - a_{t+1}, y_t \rangle - \frac{1}{\gamma} \sum_{t=1}^n D(a_{t+1}, a_t).$$

Furthermore, suppose Eq. (28.6) holds and $(\tilde{a}_t)_{t=2}^{n+1}$ are given by Eq. (28.7), then

$$R_n(a) \leq \frac{1}{\gamma} (F(a) - F(a_1) + \sum_{t=1}^n D(a_t, \tilde{a}_{t+1})).$$

Prof. CO Let $\Phi_t(b) = \frac{1}{2} \langle y_t, b \rangle + D_F(b, a_t)$. We start by splitting the instantaneous regret as

$$\langle a_t - a, y_t \rangle = \langle a_t - a_{t+1}, y_t \rangle + \underbrace{\langle a_{t+1} - a, y_t \rangle}_{\text{To bound the second term, note that the 1st-order optimality of } a_{t+1} \text{ shows that}}.$$

To bound the second term, note that the 1st-order optimality of a_{t+1} shows that

$$\langle a - a_{t+1}, \nabla \Phi(a_{t+1}) \rangle \geq 0,$$

这样 split 的原因之一是 a_{t+1} 与 y_t 一起才能构成一阶最优条件

which implies that

$$\langle a - a_{t+1}, \nabla F(a_{t+1}) - \nabla F(a_t) + \frac{1}{2} y_t \rangle \geq 0.$$

Rewriting and using the definition of Bregman divergence leads to

$$\begin{aligned} \langle a_{t+1} - a, y_t \rangle &\leq \frac{1}{2} \cdot \langle a - a_{t+1}, \nabla F(a_{t+1}) - \nabla F(a_t) \rangle \\ &= \frac{1}{2} \cdot (D(a, a_t) - D(a, a_{t+1}) - D(a_{t+1}, a_t)), \end{aligned}$$

where the equality follows by Generalized Pythagoras Identity.

Using the above display, along with the definition of regret,

$$\begin{aligned} R_n &= \sum_{t=1}^n \langle a_t - a, y_t \rangle \\ &= \sum_{t=1}^n \langle a_t - a_{t+1}, y_t \rangle + \sum_{t=1}^n \langle a_{t+1} - a, y_t \rangle \\ &\leq \sum_{t=1}^n \langle a_t - a_{t+1}, y_t \rangle \\ &\quad + \frac{1}{2} \sum_{t=1}^n (D(a, a_t) - D(a, a_{t+1}) - D(a_{t+1}, a_t)) \end{aligned}$$

$$= \sum_{t=1}^n \langle a_t - a_{t+1}, y_t \rangle + \frac{1}{\gamma} [D(a, a_1) - D(a, a_{n+1}) - \sum_{t=1}^n D(a_{t+1}, a_t)]$$

$$\leq \sum_{t=1}^n \langle a_t - a_{t+1}, y_t \rangle + \frac{F(a) - F(a_1)}{\gamma} - \frac{1}{\gamma} \sum_{t=1}^n D(a_{t+1}, a_t), \quad (28.10)$$

where the last inequality follows from the non-negativity of Bregman divergence, and $\nabla F(a_1) = 0$.

④ To bound the first term,

$$\langle a_t - a_{t+1}, y_t \rangle = \frac{1}{\gamma} \langle a_t - a_{t+1}, \nabla F(a_t) - \nabla F(\tilde{a}_{t+1}) \rangle$$

$$= \frac{1}{\gamma} (D(a_{t+1}, a_t) + D(a_t, \tilde{a}_{t+1}) - D(a_{t+1}, \tilde{a}_{t+1}))$$

$$\leq \frac{1}{\gamma} (D(a_{t+1}, a_t) + D(a_t, \tilde{a}_{t+1})).$$

Substituting the above display into Eq. (28.10) concludes the proof of second part of the theorem.

□

Remark. The assumption that $a_1 = \operatorname{argmin}_{a \in A} F(a)$ is only used to bound $D(a, a_1) \leq F(a) - F(a_1)$. For a different initialisation it still holds that

$$R_n(a) \leq \frac{1}{\gamma} (D(a, a_1) + \sum_{t=1}^n D(a_t, \tilde{a}_{t+1})).$$

Theorem 28.5 [Follow-the-Regularized-Leader Regret Bound]

Let $\gamma > 0$, F be convex with domain $D = \text{dom}(F)$, $A \subseteq \mathbb{R}^d$ is a non-empty convex set. Assume $(a_t)_{t=1}^{n+1}$ chosen by FTRL are well-defined. Then $\forall a \in A$, the regret is bounded by

$$R_n(a) \leq \frac{F(a) - F(a_0)}{\gamma} + \sum_{t=1}^n \langle a_t - a_{t+1}, y_t \rangle - \frac{1}{\gamma} \sum_{t=1}^n D(a_{t+1}, a_t).$$

Proof. We first split the regret as in MD as

$$\sum_{t=1}^n \langle a_t - a, y_t \rangle = \sum_{t=1}^n \langle a_t - a_{t+1}, y_t \rangle + \sum_{t=1}^n \langle a_{t+1} - a, y_t \rangle.$$

To bound the second term, let

$$\bar{\Phi}_t(b) = \sum_{s=1}^t \langle b, y_s \rangle + \frac{F(b)}{\gamma}.$$

Then

$$\begin{aligned} & \sum_{t=1}^n \langle a_{t+1} - a, y_t \rangle \\ &= \sum_{t=1}^n \langle a_{t+1}, y_t \rangle - \bar{\Phi}_n(a) + \frac{F(a)}{\gamma}. \\ &= \sum_{t=1}^n (\bar{\Phi}_t(a_{t+1}) - \bar{\Phi}_{t-1}(a_{t+1})) - \bar{\Phi}_n(a) + \frac{F(a)}{\gamma} \\ &= -\bar{\Phi}_0(a_1) + \sum_{t=0}^{n-1} (\bar{\Phi}_t(a_{t+1}) - \bar{\Phi}_t(a_{t+2})) + \bar{\Phi}_n(a_{n+1}) - \bar{\Phi}_n(a) + \frac{F(a)}{\gamma} \\ &\leq \frac{F(a) - F(a_1)}{\gamma} + \sum_{t=0}^{n-1} (\bar{\Phi}_t(a_{t+1}) - \bar{\Phi}_t(a_{t+2})), \end{aligned} \tag{28.Ex.1}$$

where the inequality is due to that a_{t+1} is the minimizer of $\bar{\Phi}_t(\cdot)$. Note that $D\bar{\Phi}_t(x,y) = Df(x,y)$ since $Dg(x,y) = Df(x,y)$ if $g(x) = f(x) + kx$. Then

$$\begin{aligned} \bar{\Phi}_t(a_{t+1}) - \bar{\Phi}_t(a_{t+2}) &= -D_{\bar{\Phi}_t}(a_{t+2}, a_{t+1}) - \nabla \bar{\Phi}_t(a_{t+1})^T (a_{t+2} - a_{t+1}) \\ &\leq -D_{\bar{F}}(a_{t+2}, a_{t+1}), \end{aligned} \quad (28.\text{Ex.2})$$

where the inequality comes from the 1st-order optimality condition of a_{t+1} w.r.t. $\bar{\Phi}_t$. Substituting Eq. (28.Ex.2) into Eq. (28.Ex.1) concludes the proof.

□

Proposition 28.6 [Regret on the Unit Ball]

TBC

Proposition 28.7 [Regret on the Simplex]

TBC

Corollary 28.8 [φ -strongly Strongly Convex Potential Regret Bound]

Let F be a Legendre potential and be φ -strongly convex w.r.t. norm $\|\cdot\|_t$. Then the regret of M1 or FTRL satisfies

$$R_n \leq \frac{\text{diam}_F(A)}{\gamma} + \frac{\gamma}{2\varphi} \cdot \sum_{t=1}^n \|\gamma_t\|_{t^*}^2,$$

where $\|\cdot\|_{t^*}$ is the dual norm of $\|\cdot\|_t$.