

steering_trajectory
_following_test.recordActual
HandTrajectories

```
graph LR; A["steering_trajectory  
_following_test.recordActual  
HandTrajectories"] --> B["steering_trajectory  
_following_test.getPosition  
RightHand"]; A --> C["steering_trajectory  
_following_test.getPosition  
LeftHand"]
```

steering_trajectory
_following_test.getPosition
RightHand

steering_trajectory
_following_test.getPosition
LeftHand