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## **XLBoard- External IPG Accelerometer**

**Power Inputs Control Ports** SDA

## **MIS2DHTR Accelerometer**



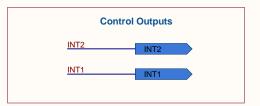
**Decoupling Caps** Input 0.1uF 10uF

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I2C/SPI mode selection with pin CS: 1: SPI idle mode / I2C communication enabled 0: SPI communication mode / I2C disable SDO: SPI serial data output (SDO) SA0: I2C less significant bit of the device address

SDA: I2C serial data (SDA) SDI: SPI serial data input (SDI) SDO: 3-wire interface serial data output (SDO)

The threshold and timing of the two interrupt pins (INT1 and INT2) can be programmed by the user through the I2C/SPI interface.



The Slave Address (SAD) associated to the MIS2DH is 001100xb.

The SDO/SA0 pin can be used to modify the less significant bit of the address.

If the SA0 pad is connected to the voltage supply, LSB is '1' (address 0011001b), else if it is connected to ground, the LSB value is '0' (address 0011000b).

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[→] FOCUS	Project: Hornet/XL Board		
Schematic: IMU			Version: 1
Design by: Martina Barreiro		Date: *	
Reviewed by:		Date:	
Comments:			

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