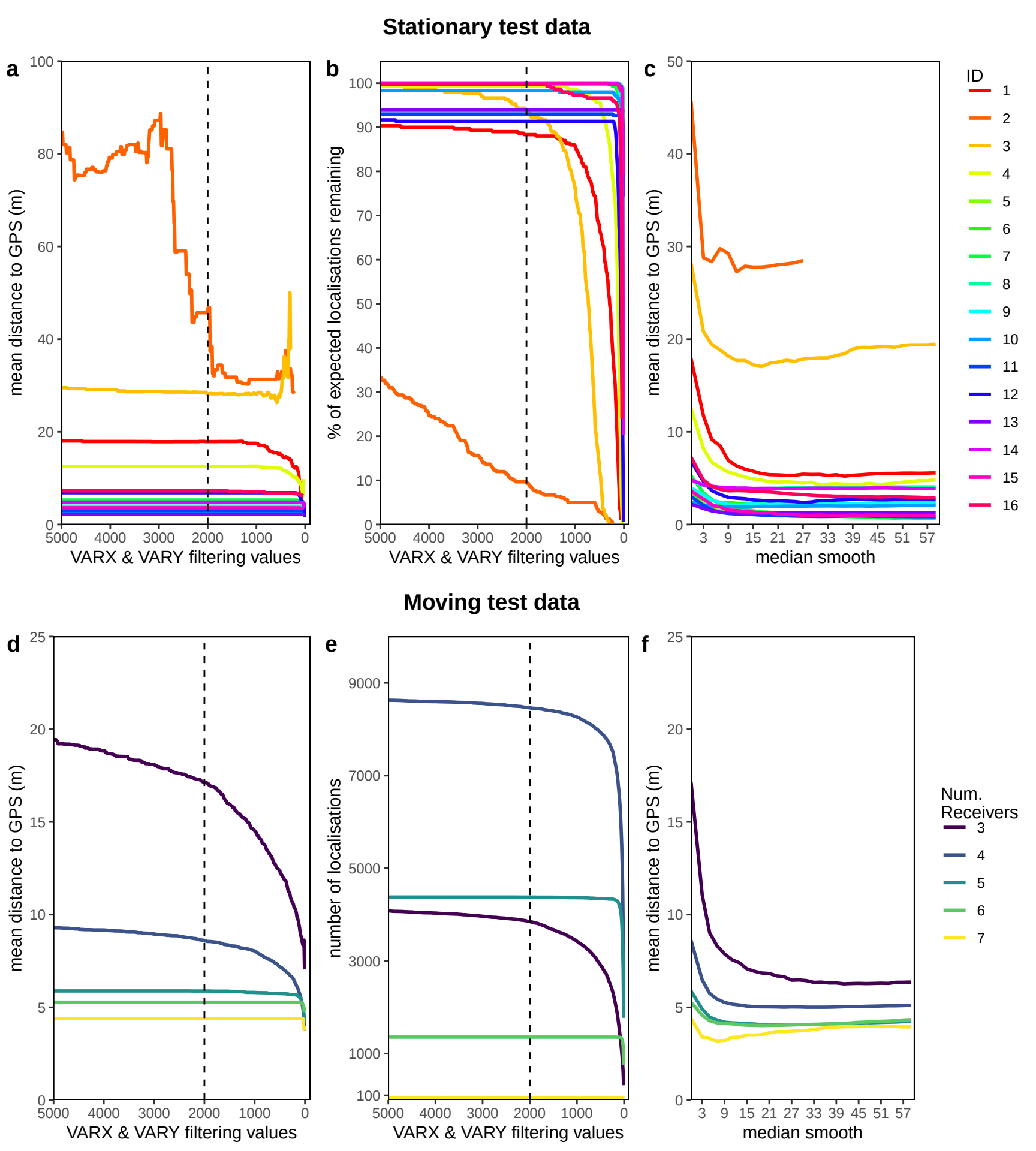
Stationary test data
a
b
c
mean distance to GPS (m)
% of expected localisations remaining
VARX & VARY filtering values
median smooth
ID
1
2
3
4
5
6
7
8
9
10
11
12
13
14
15
16
Moving test data
d
e
f
number of localisations
Num. Receivers
3
4
5
6
7