

GSRF: The "Safety Brake" for Computer Systems That Can't Get It Wrong

In Simple Terms: What Is This?

Imagine you're building a safety system — like a medical alarm that tells nurses when a patient's heart is in trouble, or a factory shutdown system that stops machines before they explode.

All these systems face the same problem: false alarms vs. missing real danger.

Current systems are like over-eager assistants:

- Too sensitive? → False alarms every day (people stop listening)
- Too cautious? → Misses real danger (catastrophe)

GSRF is like a "safety brake" that can't overshoot. It's designed to be predictably cautious — even if that means it's a bit slower to react sometimes.

Who Is This For?



Medical Device Companies

Problem: Medical monitors sound 100+ false alarms per patient per day. Nurses ignore 85% of them.

How GSRF helps: Makes alarms more trustworthy by filtering out "noise" without missing real emergencies.

Example: A heart monitor that doesn't scream every time a patient moves.



Industrial Factories

Problem: Unnecessary factory shutdowns cost £500,000+ each time.

How GSRF helps: Prevents shutdowns for normal fluctuations while still catching real danger.

Example: A chemical reactor that doesn't shut down during normal temperature swings.

Car Safety Systems

Problem: Cars that brake for shadows (false positives) or don't brake for real obstacles.

How GSRF helps: Makes automatic braking systems more reliable.

Example: A car that won't slam on the brakes for a plastic bag, but will for a child.

Financial Trading Systems

Problem: Automatic trading halts that trigger during normal market noise.

How GSRF helps: Makes trading circuit breakers smarter about when to pause.

Example: Prevents unnecessary market freezes during normal volatility.

How It's Different (The "Bounded" Idea)

Normal Filters:

- Can overshoot (like swinging past where you want to stop)
- Behavior changes with settings
- Need expert tuning for each application

GSRF (Our Filter):

- Cannot overshoot (guaranteed by design)
- Same behavior every time (predictable)
- Simple settings (easier to certify)

Analogy:

- Normal filter = A car that might overshoot the parking spot
 - GSRF = A car with a physical stopper that can't overshoot
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What It Is NOT

✗ NOT a "better" filter for everything

It's actually less accurate than some existing filters for normal applications.

✗ NOT tested on real patients/machines yet

We've only tested it on simulated data so far (deliberately conservative).

✗ NOT a complete safety system

It's just one component — like a better brake pedal, not the whole car.

✗ NOT for everyday applications

You wouldn't use this for Spotify recommendations or weather apps.

The Trade-Off (Important!)

You choose GSRF when:

"I'd rather be a bit slow but never wrong, than fast but sometimes dangerously wrong."

You DON'T choose GSRF when:

"I need the fastest, most accurate response possible, and false alarms don't matter much."

Simple Examples

Medical Alarm System:

- Without GSRF: Alarms constantly for normal movements → nurses ignore them
- With GSRF: Fewer alarms, but every alarm matters → nurses respond

Factory Pressure Monitor:

- Without GSRF: Shuts down 10 times/month for normal pressure changes → £5M/year lost
- With GSRF: Shuts down 2 times/month → saves £4M/year

Car Emergency Braking:

- Without GSRF: Slams brakes for shadows → drivers turn it off
 - With GSRF: Only brakes for real obstacles → drivers trust it
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Why This Matters Now





1. Regulations are tightening — safety systems need to prove they work
 2. "Alarm fatigue" is a real problem — too many false warnings
 3. Certification costs are huge — simpler systems = cheaper certification
 4. Trust matters — when safety systems cry wolf, people stop listening
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Technical Version (One Paragraph)




"GSRF is a mathematically bounded filtering algorithm that guarantees no overshoot beyond defined safety limits. It trades optimal response speed for guaranteed behavioral bounds, making it suitable for safety-critical applications where false positives are more costly than moderate latency. The framework operates within explicit parameter envelopes that ensure stability by construction rather than through careful tuning."

Bottom Line

GSRF is for builders of safety systems who need:

-  Predictable behavior (no surprises)
-  Certifiability (easier to prove to regulators)
-  False alarm reduction (when false alarms cost money/lives)
-  Explainable decisions (can trace why each decision was made)

It's NOT for those who need:

-  Maximum speed/accuracy above all else
 -  General-purpose applications
 -  Untested real-world deployment (yet)
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The "Safety Filter" Analogy

Think of GSRF as a conservative, experienced safety inspector:

- Takes time to be sure
- Never cries wolf
- Always follows the same rules
- You might wish they were faster sometimes
- But you trust them with your life

While other filters are like eager, fast interns:

- React immediately
- Sometimes get it wrong
- Need constant supervision
- Great for non-critical tasks
- Risky for life-or-death decisions

In one sentence: GSRF is a safety-first filter for systems where being predictably cautious is more valuable than being optimally fast.